# Optimization Techniques Section 1

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### What is optimization?

(mathematical) optimization problem

$$\begin{array}{ll} \text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq b_i, \quad i = 1, \dots, m \end{array}$$

- $x = (x_1, \dots, x_n)$ : optimization variables
- f<sub>0</sub>: R<sup>n</sup> → R: objective function
- $f_i: \mathbb{R}^n \to \mathbb{R}, \ i=1,\ldots,m$ : constraint functions

optimal solution  $x^*$  has smallest value of  $f_0$  among all vectors that satisfy the constraints

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# Optimization example (Constraint Optimization)

- Find the largest possible rectangular area you can enclose, assuming you have L meters of fencing.
- $f(x)=x^*((L/2)-x)$

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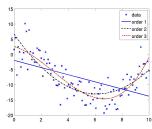
### Optimization examples

### portfolio optimization

- · variables: amounts invested in different assets
- · constraints: budget, max./min. investment per asset, minimum return
- · objective: overall risk or return variance

### data fitting

- · variables: model parameters
- · constraints: prior information, parameter limits
- · objective: measure of misfit or prediction error



### **Portfolio Optimization**



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### **Optimization Techniques**

- Derivative Techniques
  - Gradient descent
  - Newton Raphson
  - -LM
  - BFGS
- Non Derivative Techniques
  - Hill climbing
  - Genetic algorithms
  - Simulated annealing

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### Linear, nonlinear, convex functions

• f is a function R<sup>n</sup>→R

For every  $x1,x2 \in R^n$  (x1, x2 are n dimensional points)

• f is linear if

```
f(x1+x2)=f(x1)+f(x2) and f(r*x1)=r*f(x1)
```

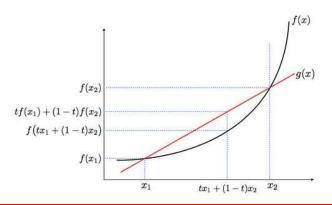
- f(x)=2\*x is linear and affine.
- f(x)=2\*x+3 is affine but not linear.
- A linear function fixes the origin, whereas an affine function need not do so. An affine function is the composition of a linear function with a translation.
- f(x)=3 is constant, but not linear.

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## Linear, nonlinear, convex functions

• f is convex if

 $\lambda * f(x1) + \beta * f(x2) \ge f(\lambda * x1 + \beta * x2)$ . where  $\lambda + \beta = 1$ ,  $\lambda \ge 0$ ,  $\beta \ge 0$ 

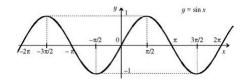


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### Linear, nonlinear, convex functions

- f(x1)=3\*x1+3
- f(x1,x2)=a\*x1+b\*x2+c
- f(x1,x2)=x2^2+x1^2+3\*x1
- $f(x)=\sin(x)$  is convex when  $x \in [?,?]$
- Concave?



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# How to find minimum point? Commonsense

- Use derivative
- Go to the negative direction of derivative
- But, step size?

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## General Algorithm

- initial guess
- While (improvement is significant) and (maximum number of iterations is not exceeded)
  - improve the result

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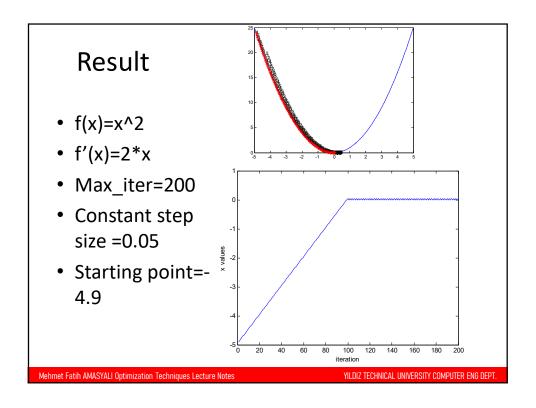
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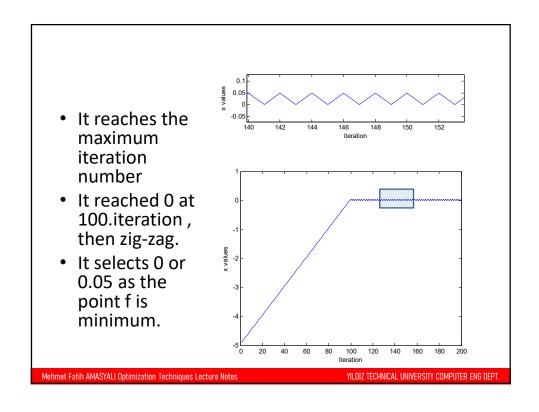
### **Gradient Descent**

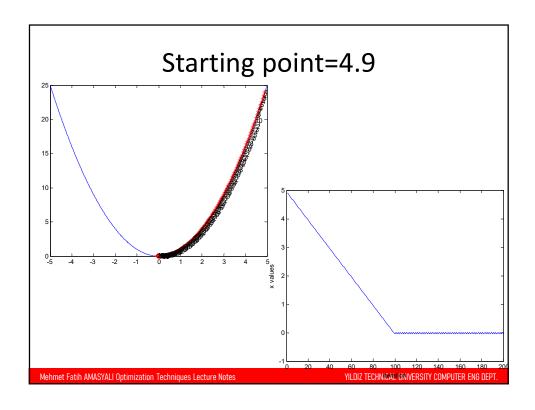
- Using only derivative sign
- · Using also magnitude of the derivative
- Effect of the step size
- Effect of the starting point
- Local minimum problem

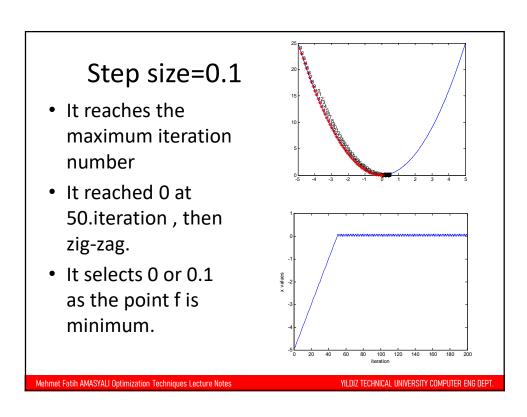
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```
% The gradient descent algorithm with
                                          i=1;
constant stepsize
                                           while abs(x_new - x_old) > precision &&
                                           max iter>=i
% f(x)=x^2, with derivative f'(x)=2x
                                             Xs(i)=x_new;
                                             Ys(i)=x_new^2;
clear all;
                                             hold on;
close all;
                                             plot(Xs(i),Ys(i),'r*');
                                             text(Xs(i),Ys(i),int2str(i));
% plot objective function
x=-5:0.01:5;
                                             x_old = x_new;
y=zeros(1,length(x));
                                             df = 2 * x_old;
                                             x_new = x_old - eps * sign(df); % gradient sign
for i=1:length(x)
 y(i)=x(i)^2;
                                             i=i+1;
end
                                           end
plot(x,y);
                                           figure;
                                           plot(Xs(1:i-1));
                                          xlabel('iteration');
x_old = 0;
x new = -4.9;
                                          ylabel('x values');
% The algorithm starts at x=-4.9
eps = 0.05; % step size
precision = 0.00001; % stopping condition1
max iter=200; % stopping condition2
                                                        gradient_desc_1.m
Xs=zeros(1,max iter);
Ys=zeros(1,max_iter);
```



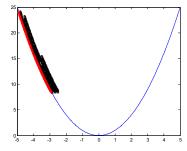


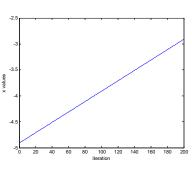




### Step size=0.01

- It reaches the maximum iteration number
- It does not reached to 0.
- It selects -2.91 as the minimum point.
- It will zig-zag.





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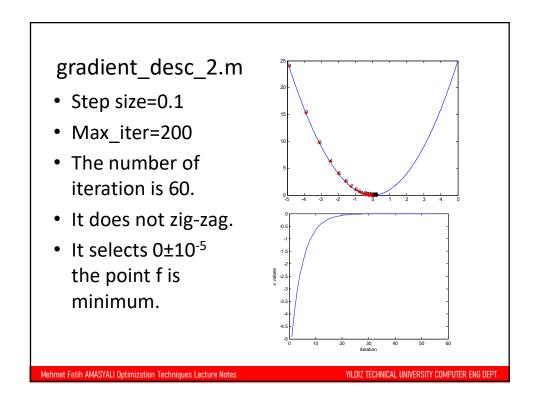
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### **Gradient Descent**

- Using also the magnitude of the derivative
- x new = x old eps \* df;
- instead of x\_new = x\_old eps \* sign(df);
- Can we reduce the required number of iterations?

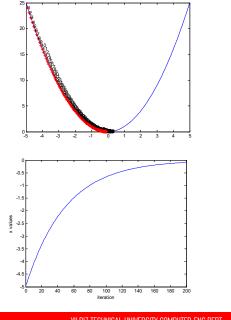
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# gradient\_desc\_2.m • Step size=0.05 • Max\_iter=200 • The number of iteration is 120. • It does not zig-zag. • It selects 0±10-5 the point f is minimum.



### gradient\_desc\_2.m

- Step size=0.01
- Max\_iter=200
- It reaches the maximum iteration number.
- It does not zig-zag.
- It selects 0±10<sup>-2</sup> as the point f is minimum.
- It requires the more iteration.

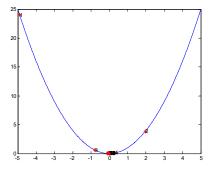


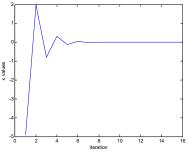
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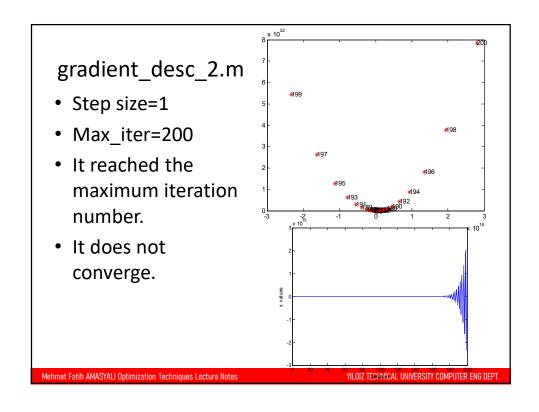
### gradient\_desc\_2.m

- Step size=0.7
- Max\_iter=200
- The number of iteration is 16.
- It does not zig-zag.
- It selects 0±10<sup>-5</sup> the point f is minimum.





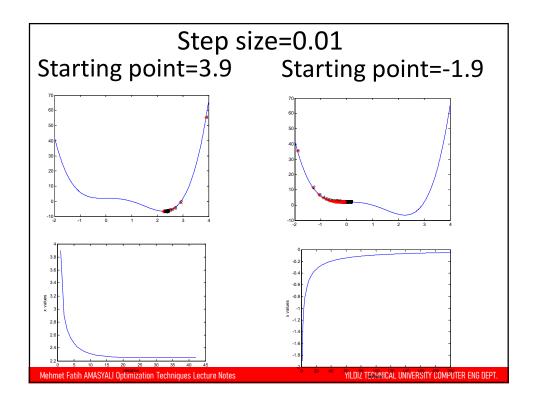
# gradient\_desc\_2.m • Step size=0.99 • Max\_iter=200 • It reached the maximum iteration number. • It zig-zag, but zig-zag magnitude decreases. • It selects 0±10<sup>-1</sup> the point f is minimum. • It requires more iteration.

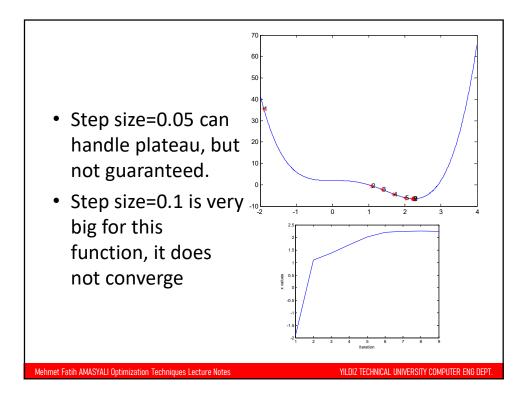


# Starting point matters?

- $f(x)=f(x)=x^4-3x^3+2$  with derivative  $f'(x)=4x^3-9x^2$
- It has two extreme points x=0, x=9/4
- gradient\_desc\_3.m

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### Gradient descent

- Static zig-zag (hopeless) vs. slow converge (with hope)
- Very Small step size → slow converge, plateau problem
- Very big step size → do not converge
- Big and small step sizes depend on the objective function.

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