

Control experiment Thu May 28 02:51 PM

Notes

This is a bunch of notes!!

Stats

Experiment time: 10.0 seconds

Overshoot by axis:

X : 0.0

Y : 0.0

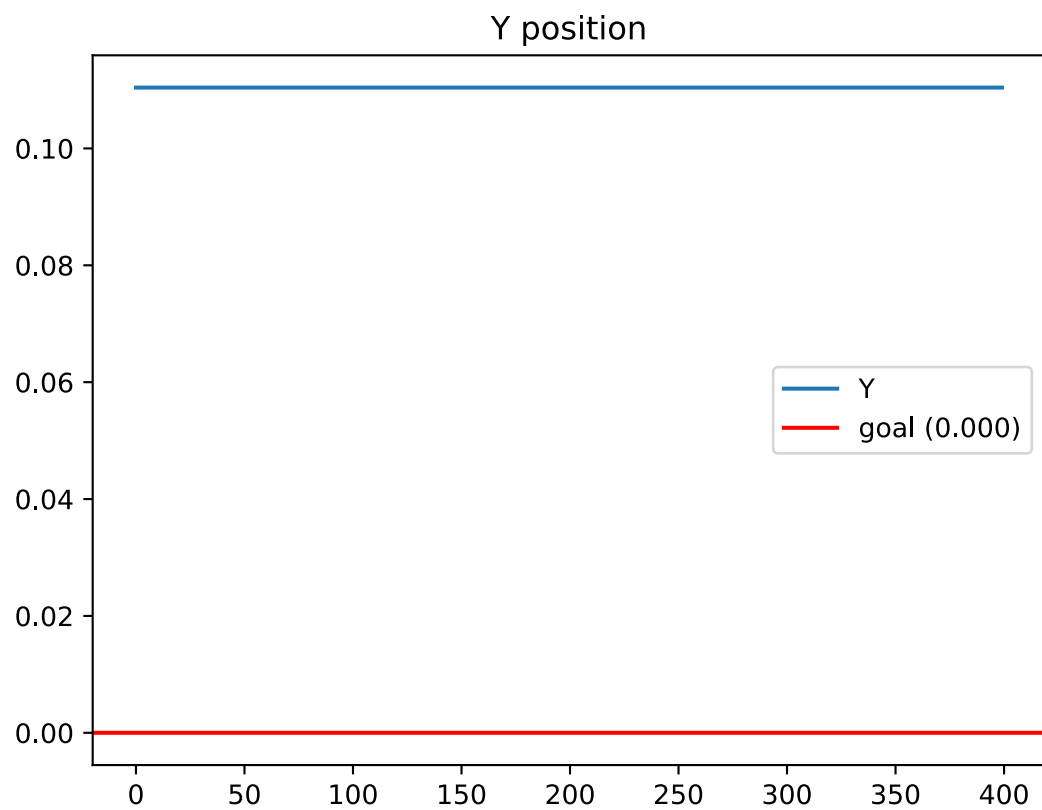
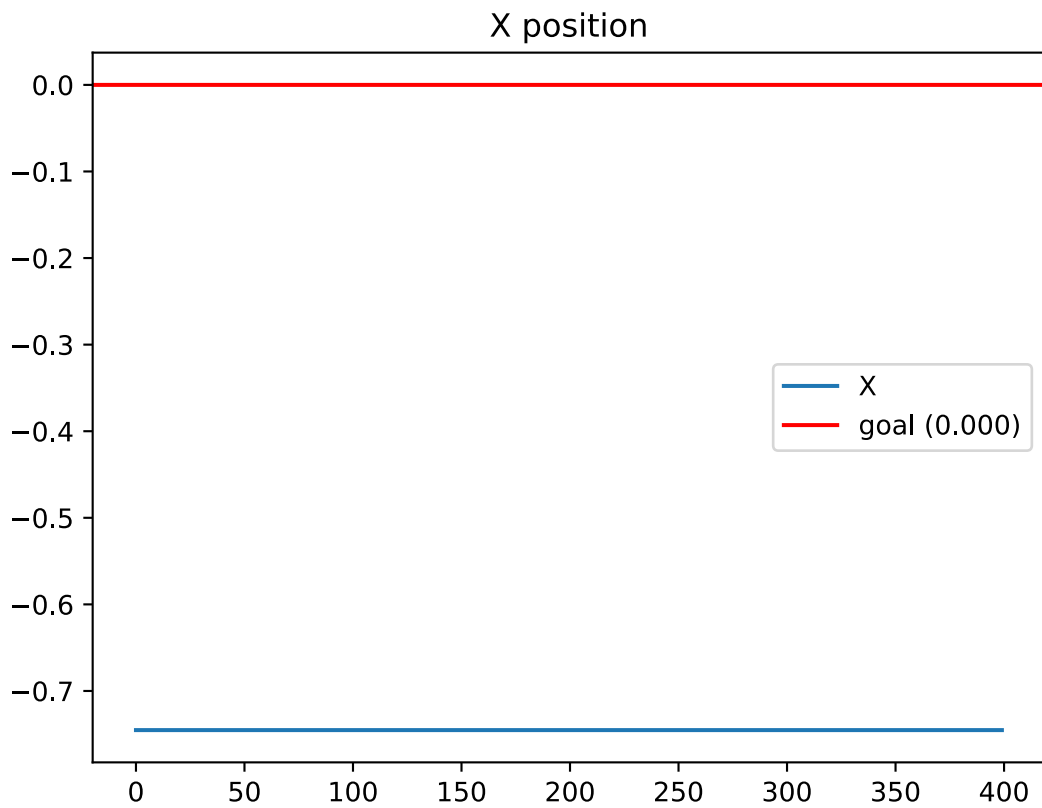
Z : 0.0

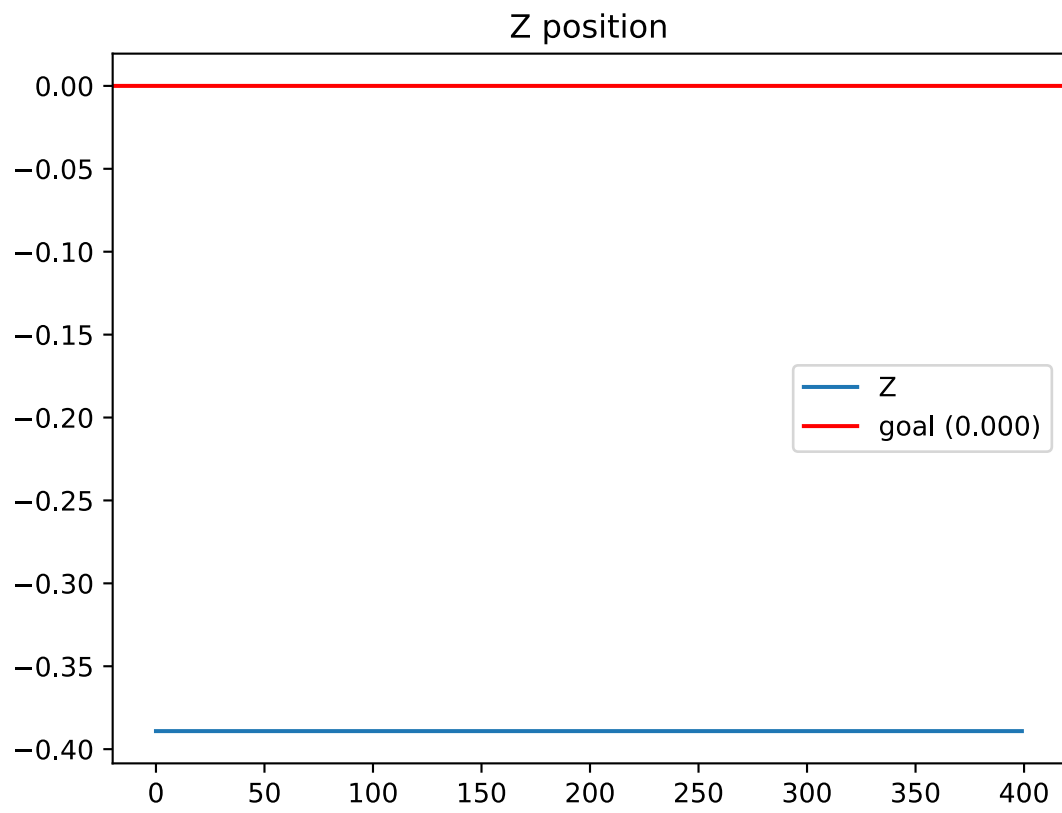
Roll : 0.0

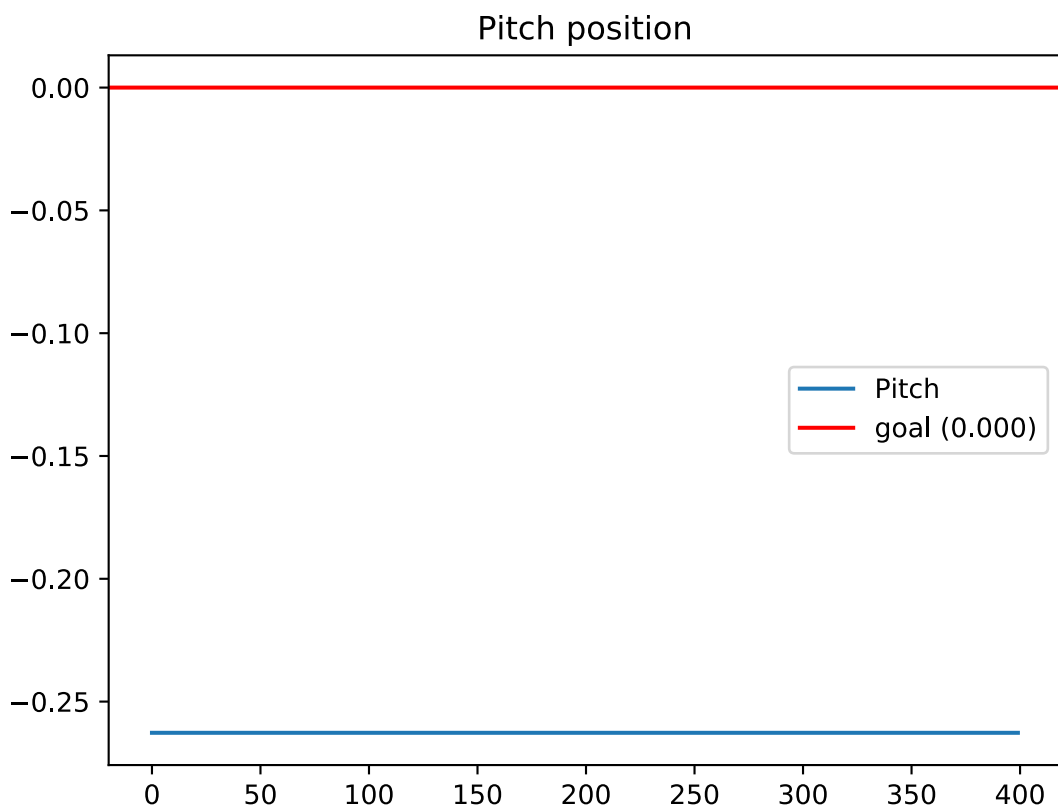
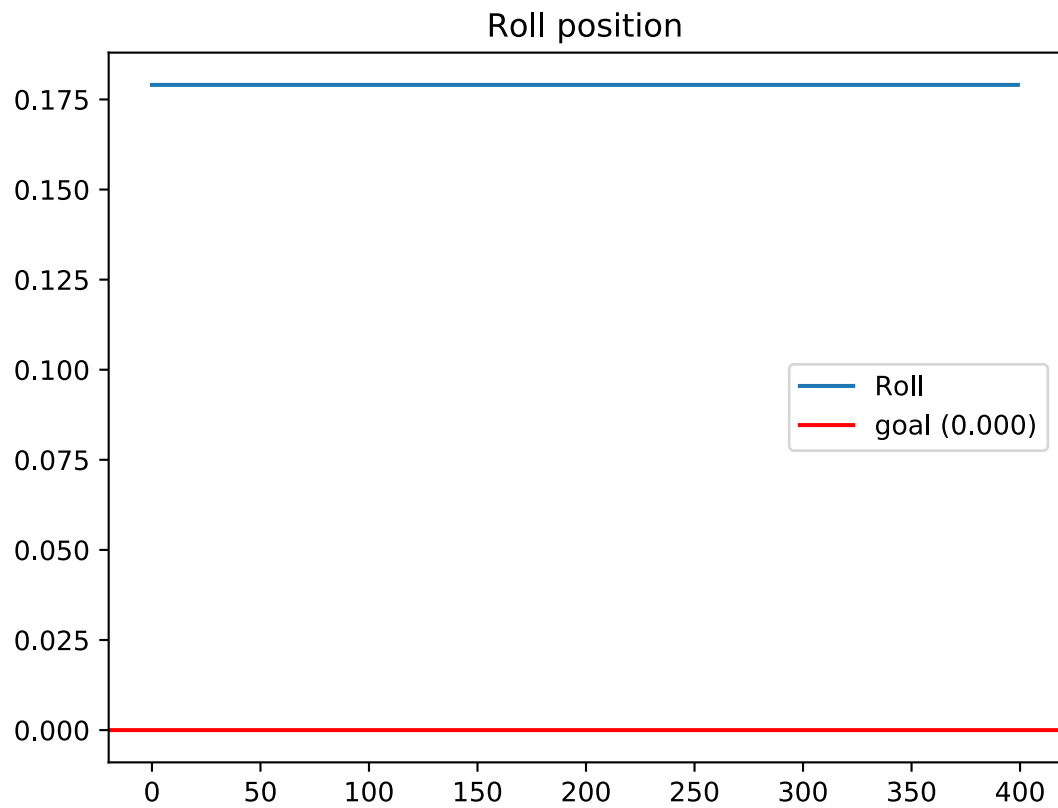
Pitch : 0.0

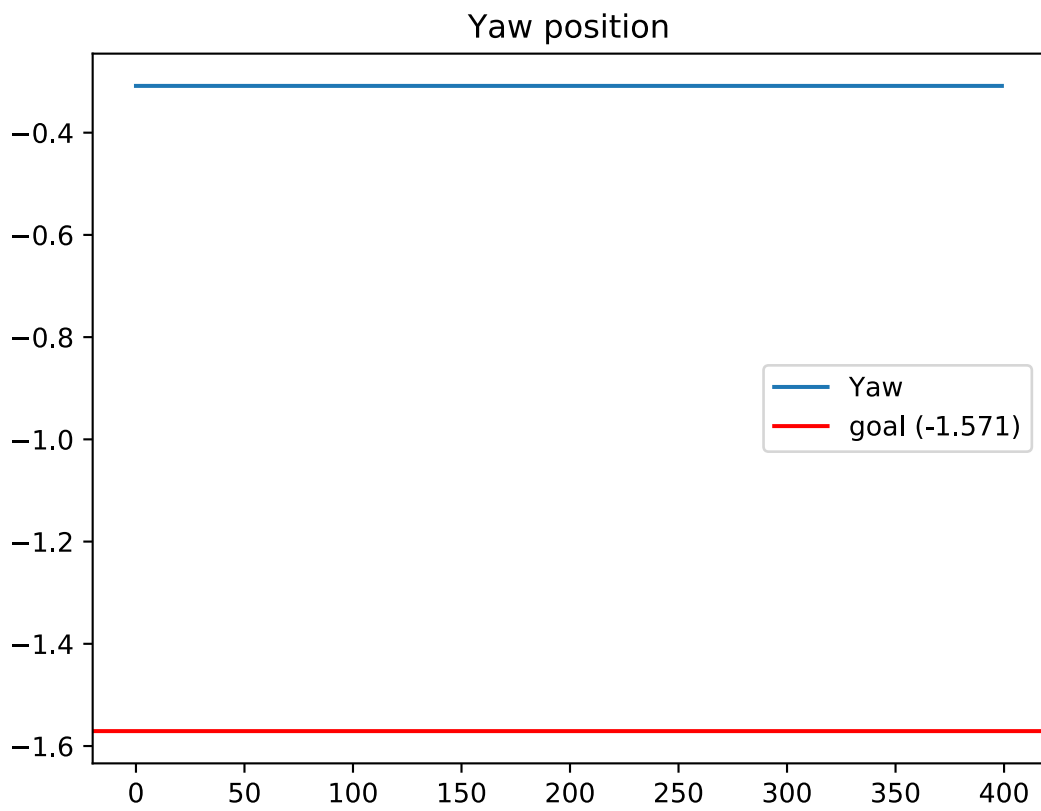
Yaw : 0.0

Position vs goal plots



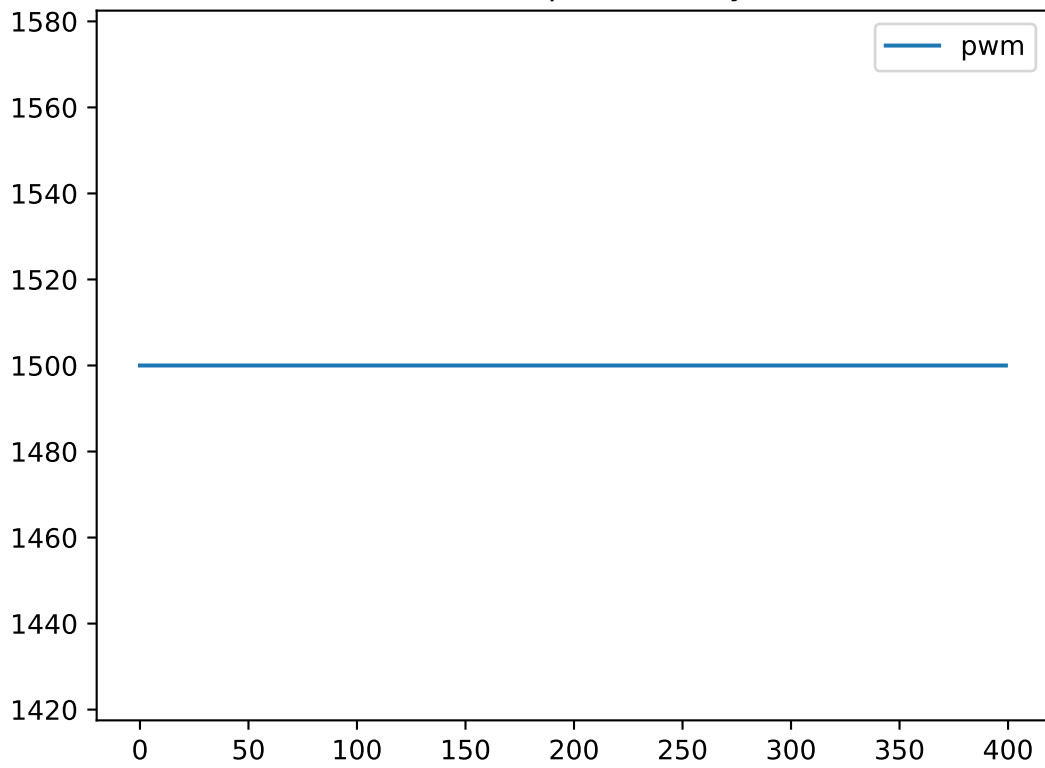




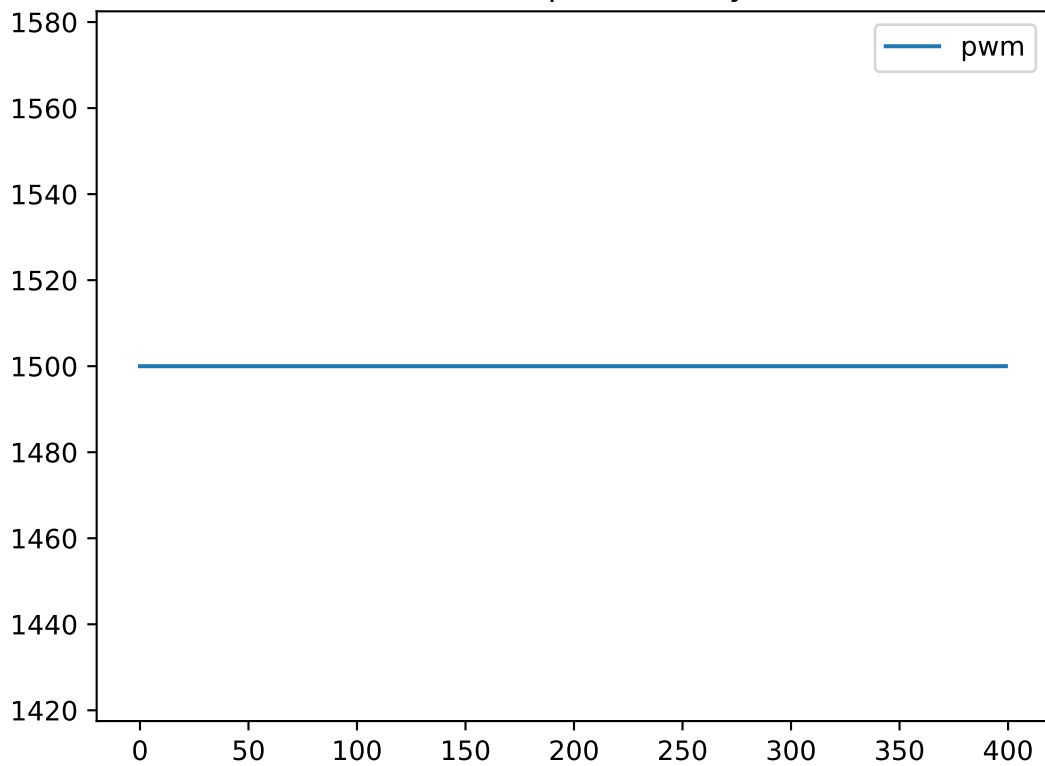


Motor speed plots

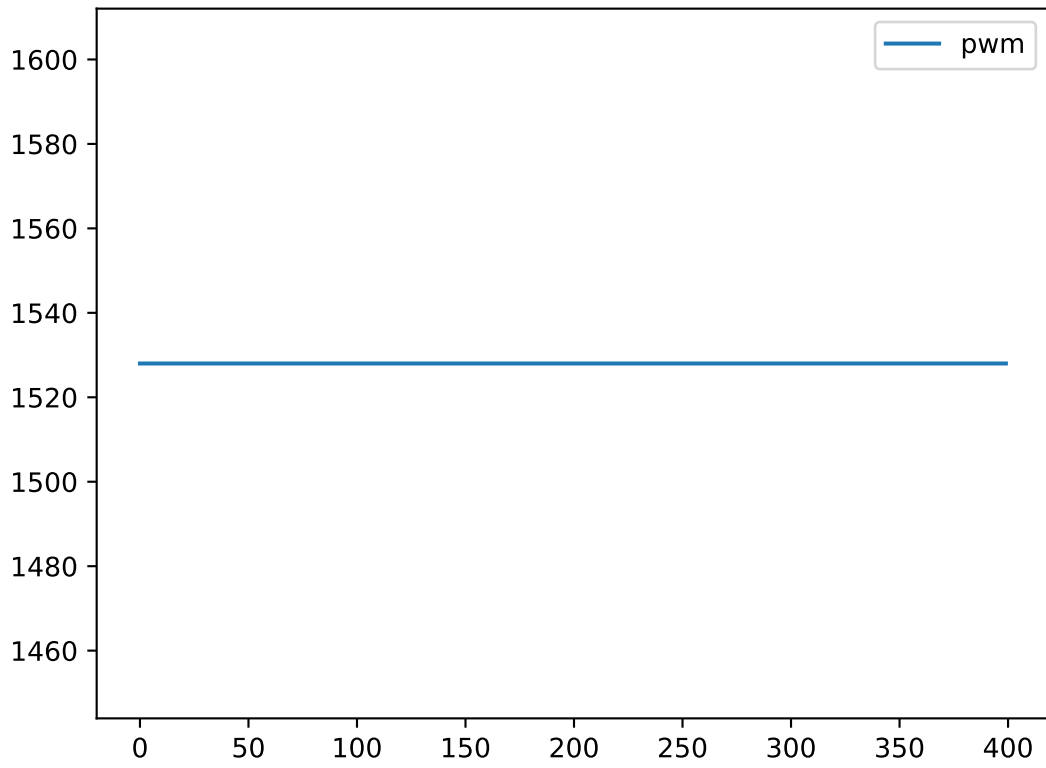
Motor 1 speed history



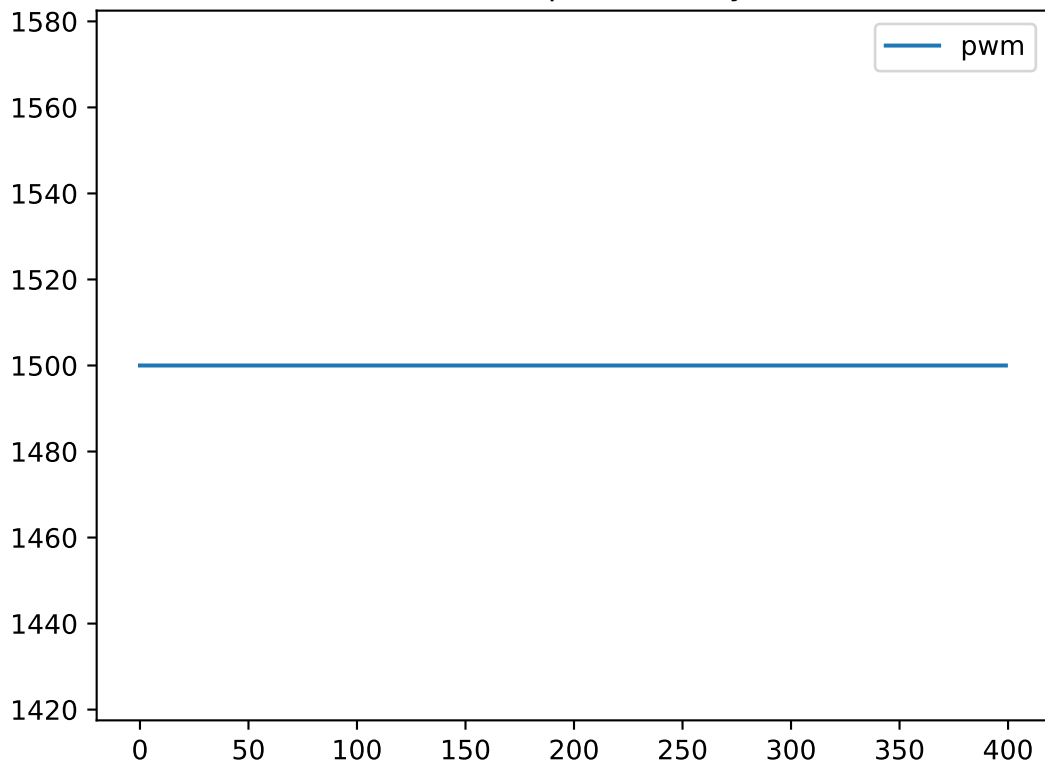
Motor 2 speed history



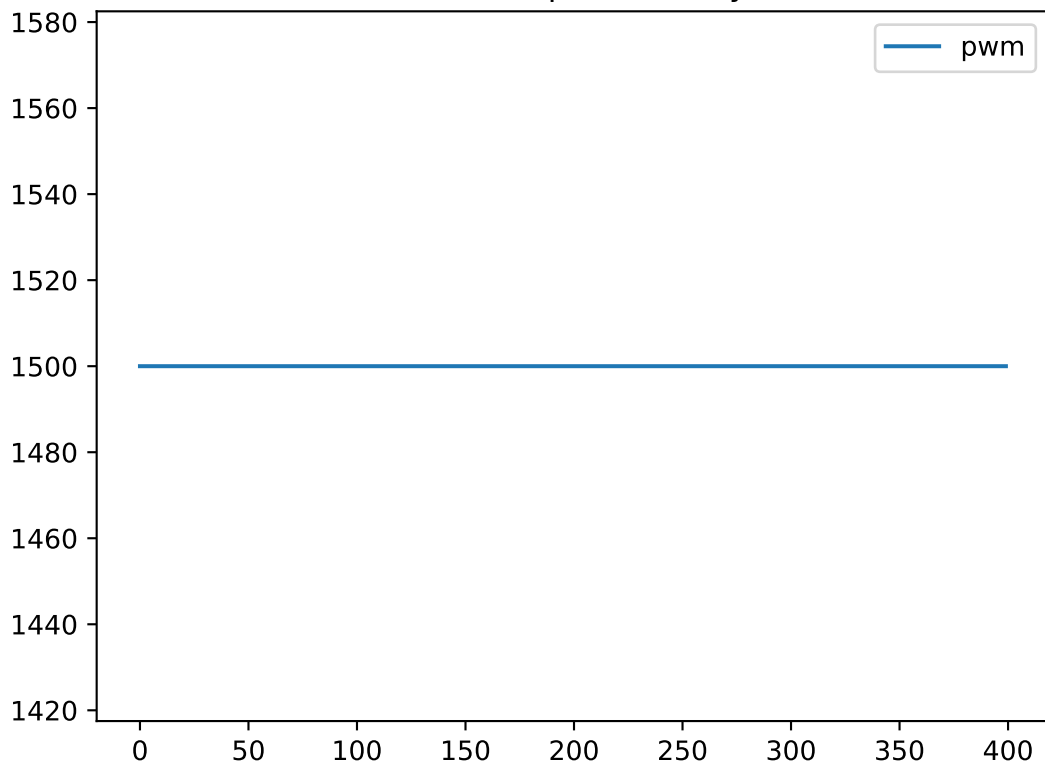
Motor 3 speed history



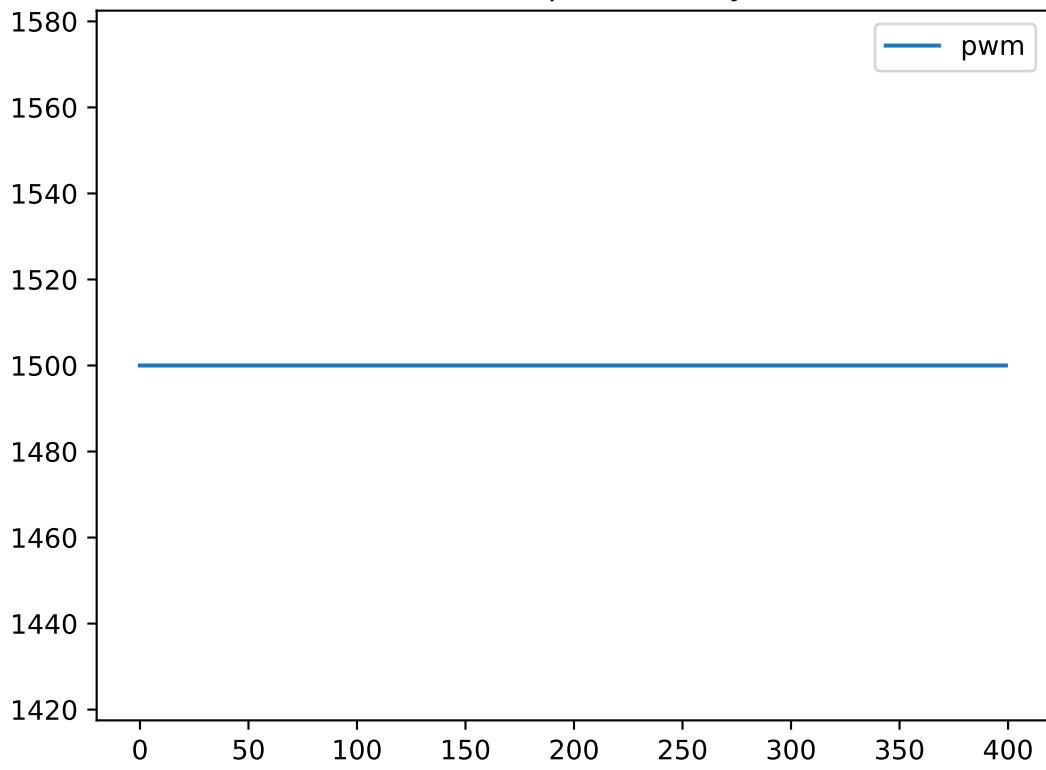
Motor 4 speed history



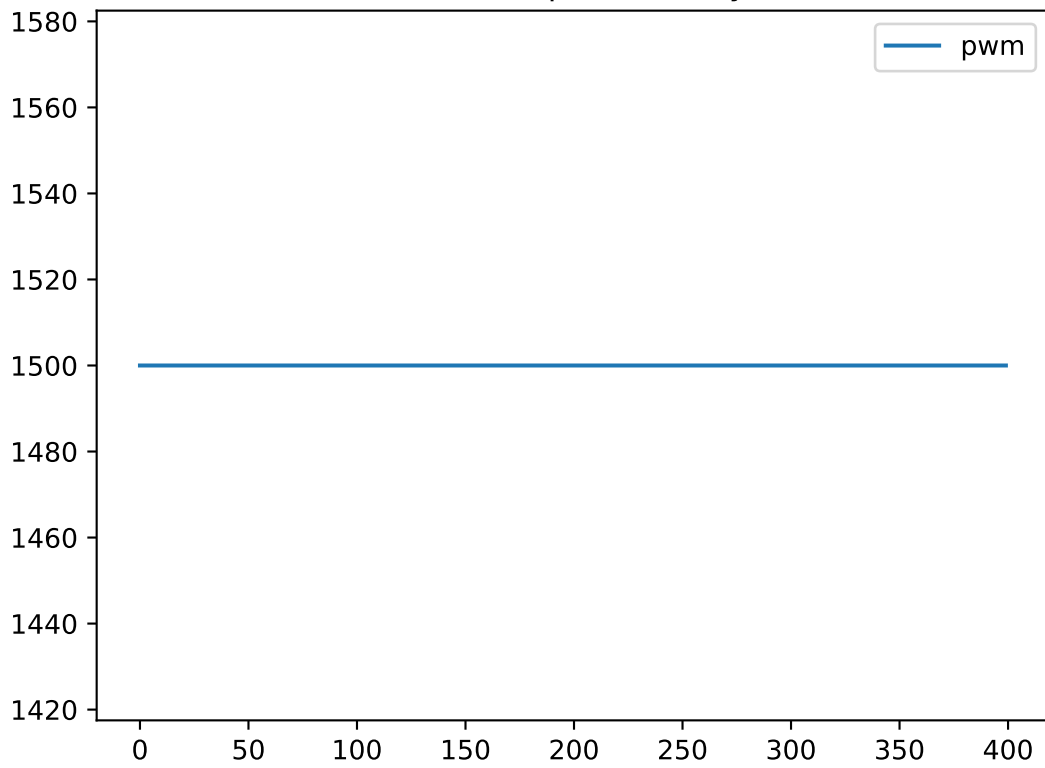
Motor 5 speed history



Motor 6 speed history



Motor 7 speed history



Motor 8 speed history

