

# Control experiment Thu May 28 03:15 PM

## Notes

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This is a bunch of notes!!

## Stats

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**Experiment time: 10.0 seconds**

**Overshoot by axis:**

X : 0.0

Y : 0.0

Z : 0.0

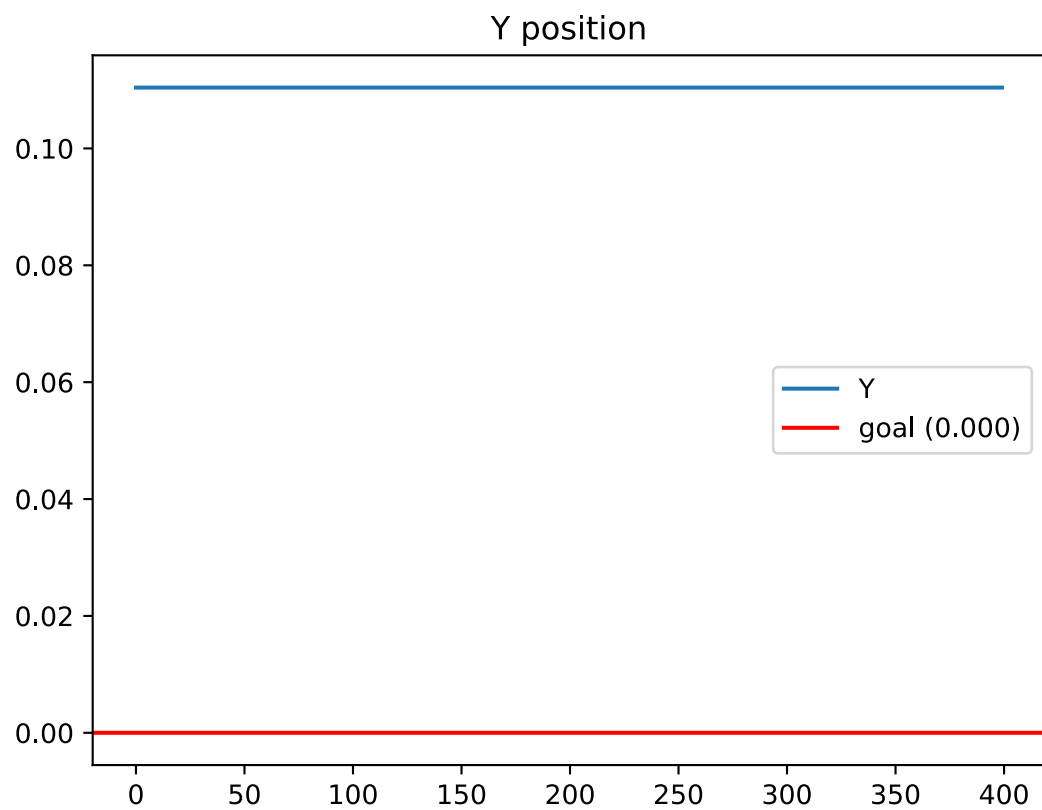
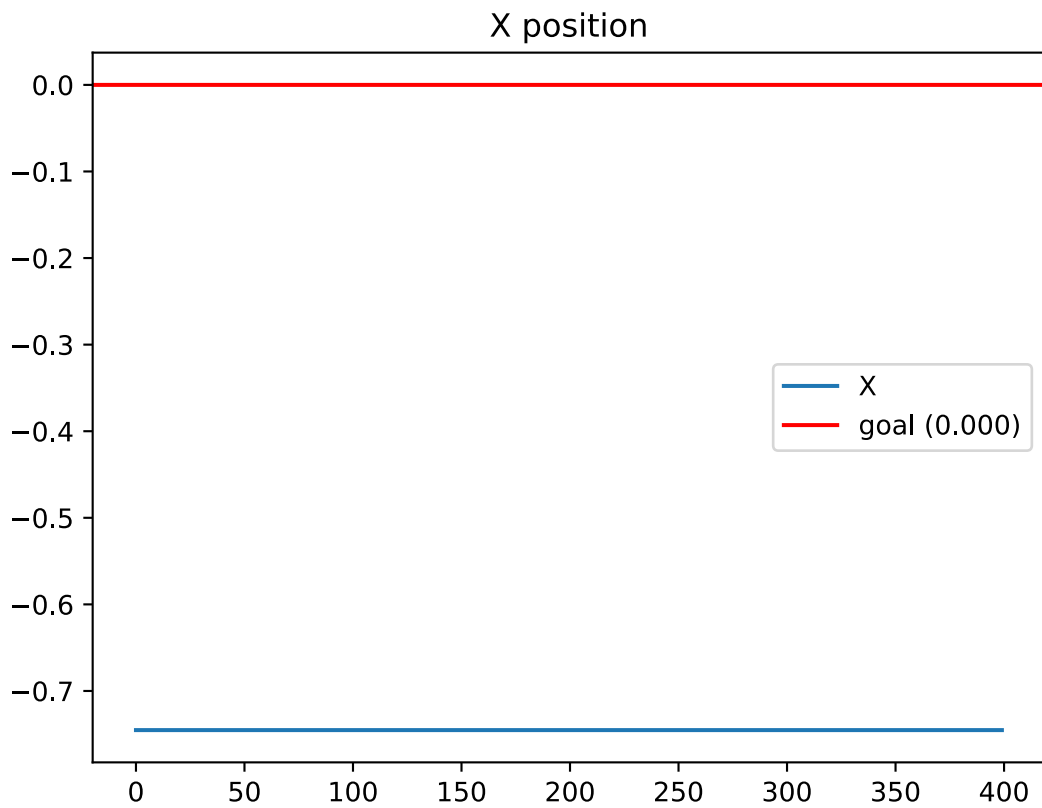
Roll : 0.0

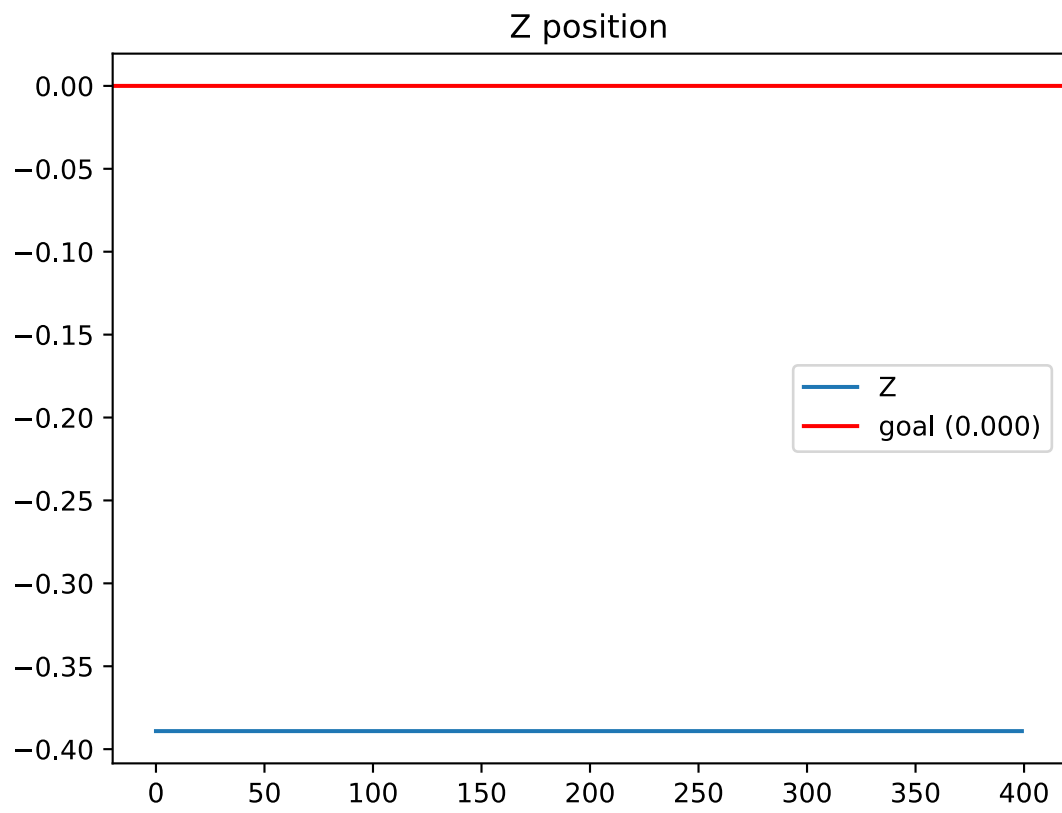
Pitch : 0.0

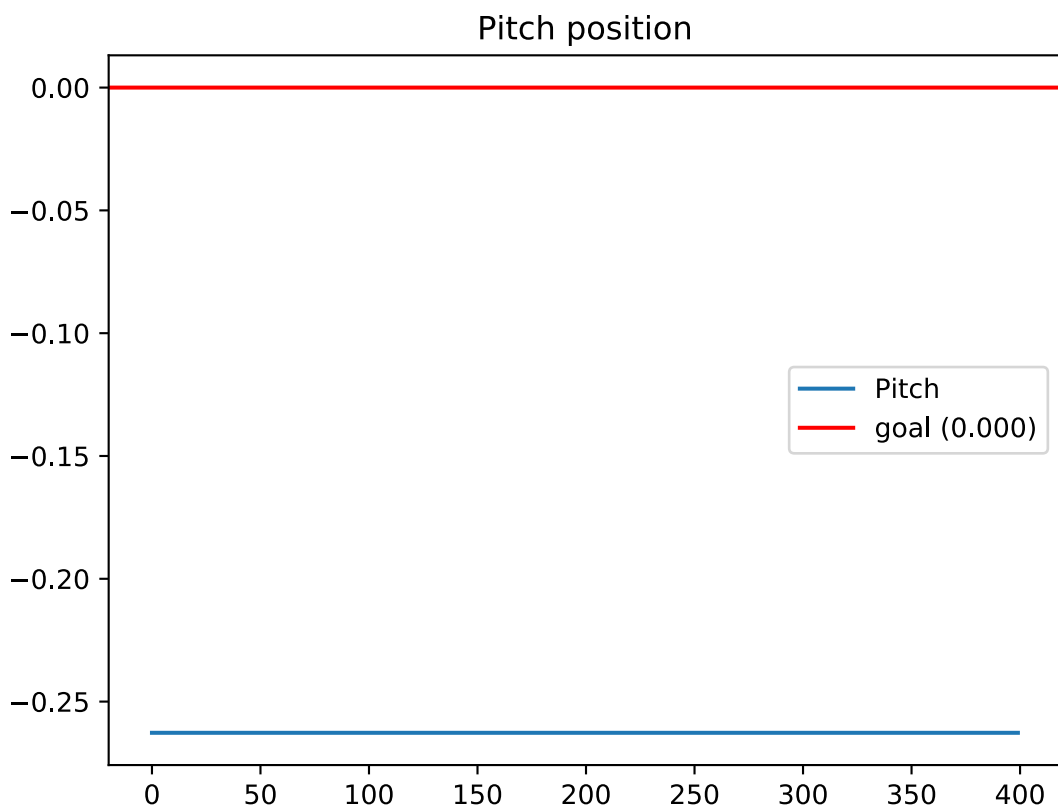
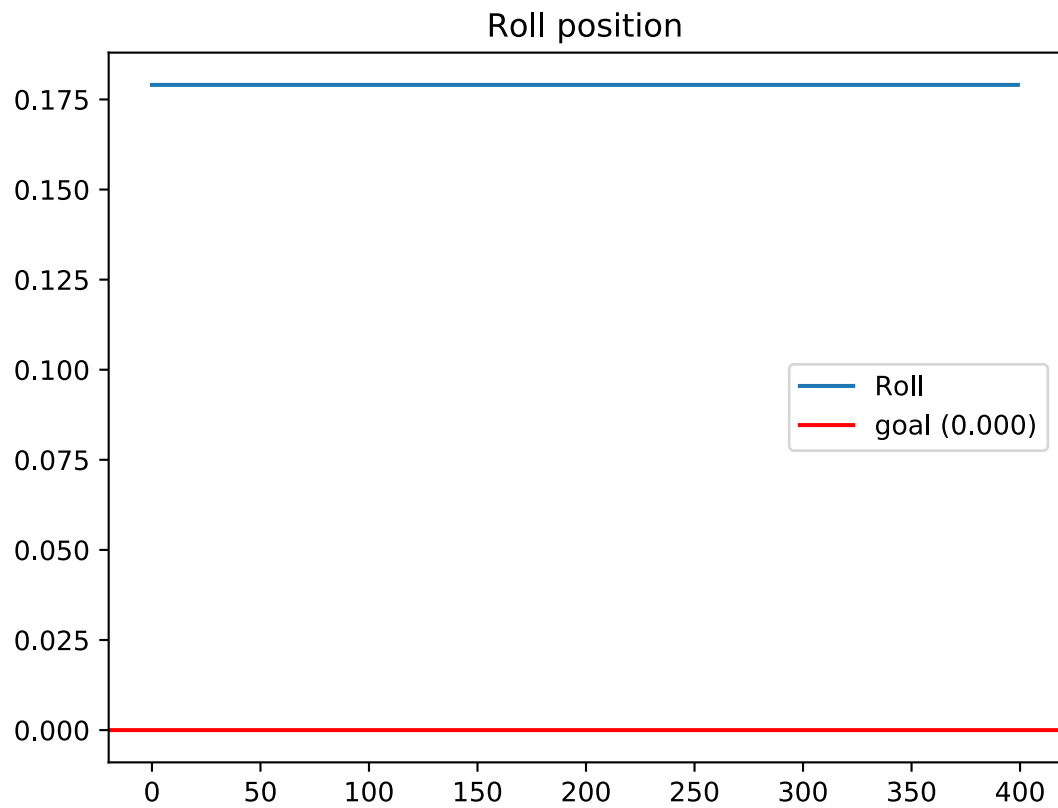
Yaw : 0.0

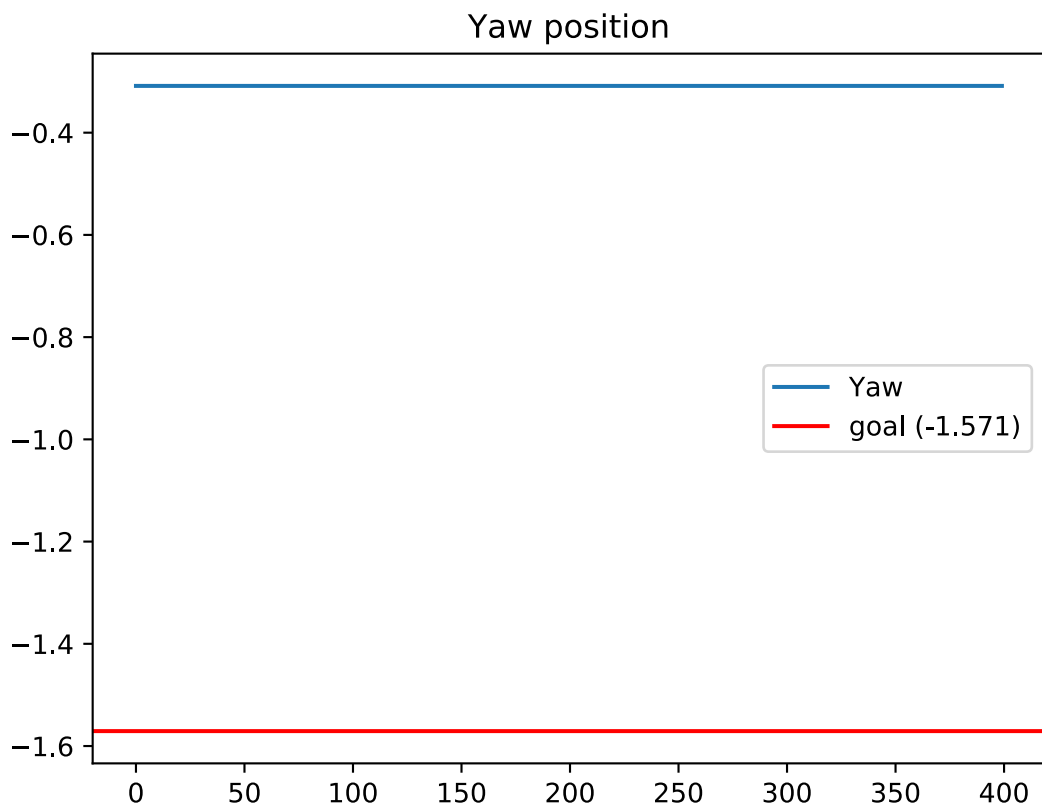
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## Position vs goal plots



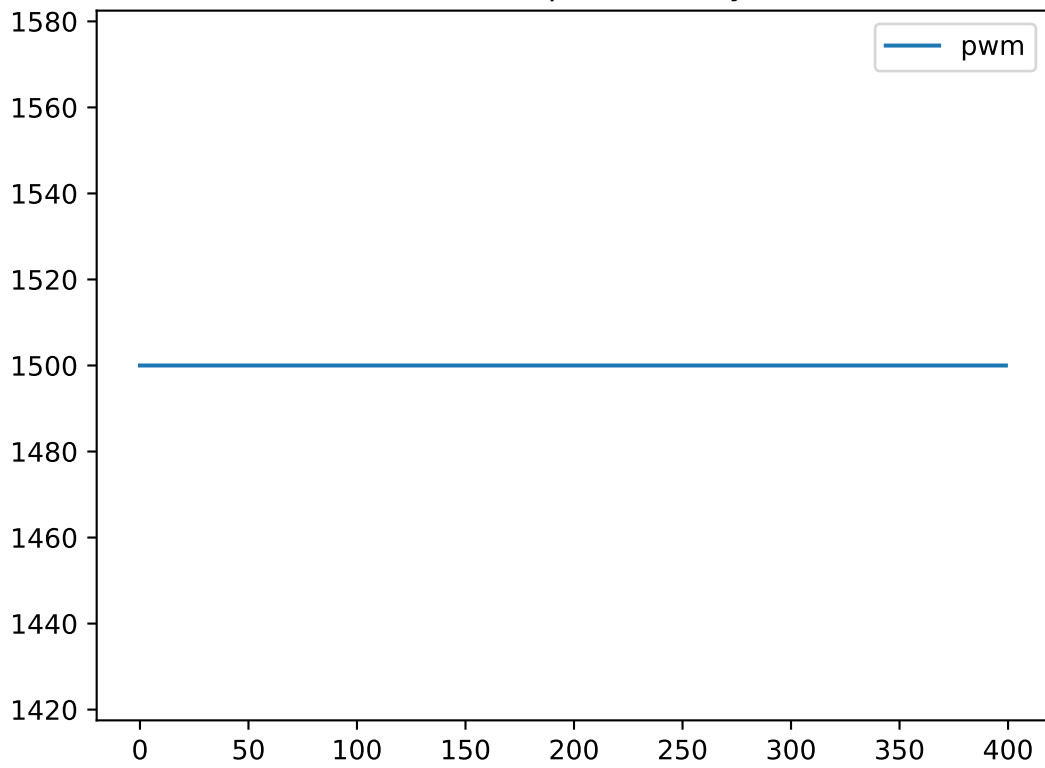




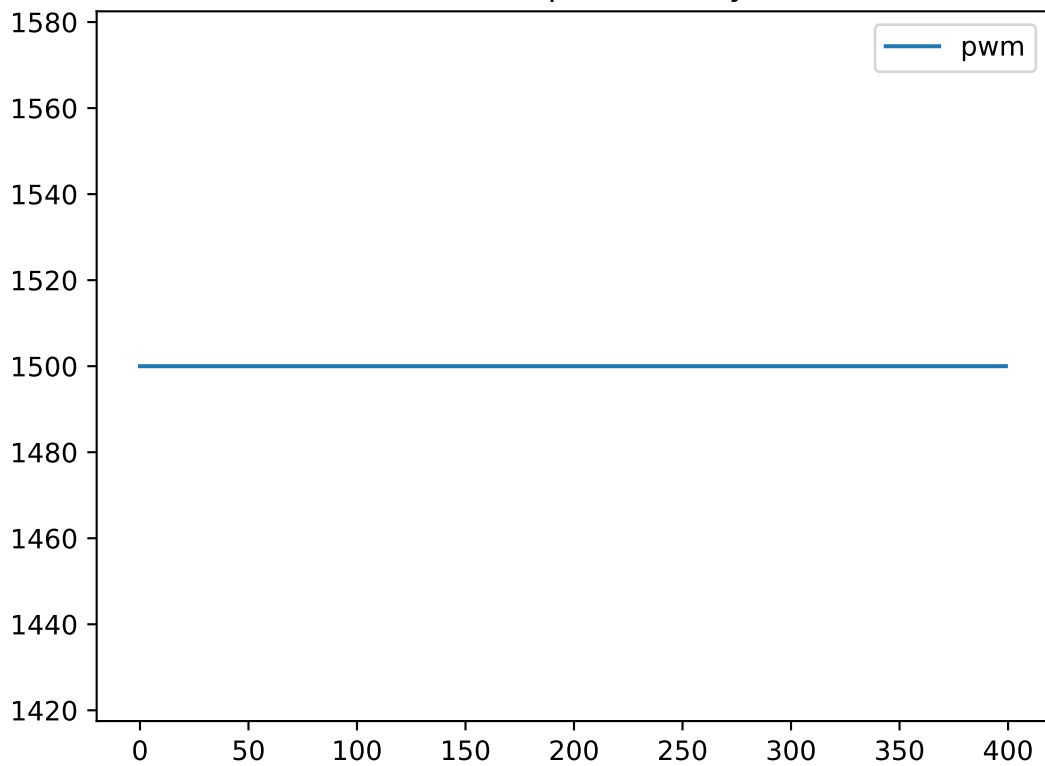


## Motor speed plots

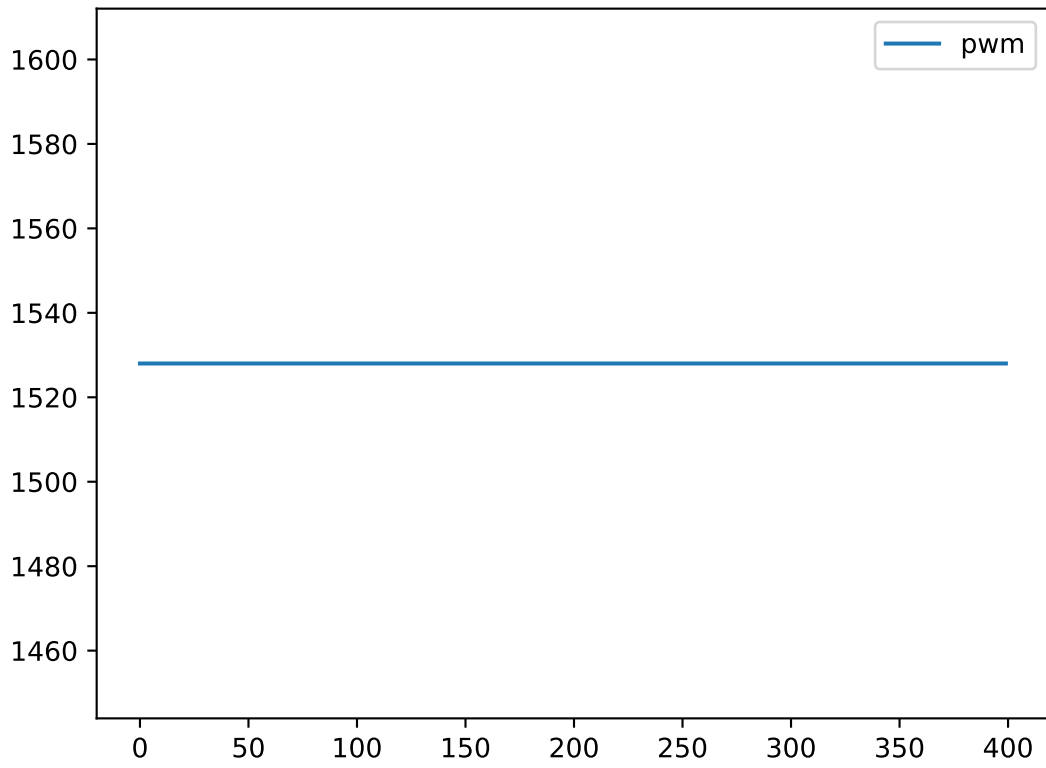
Motor 1 speed history



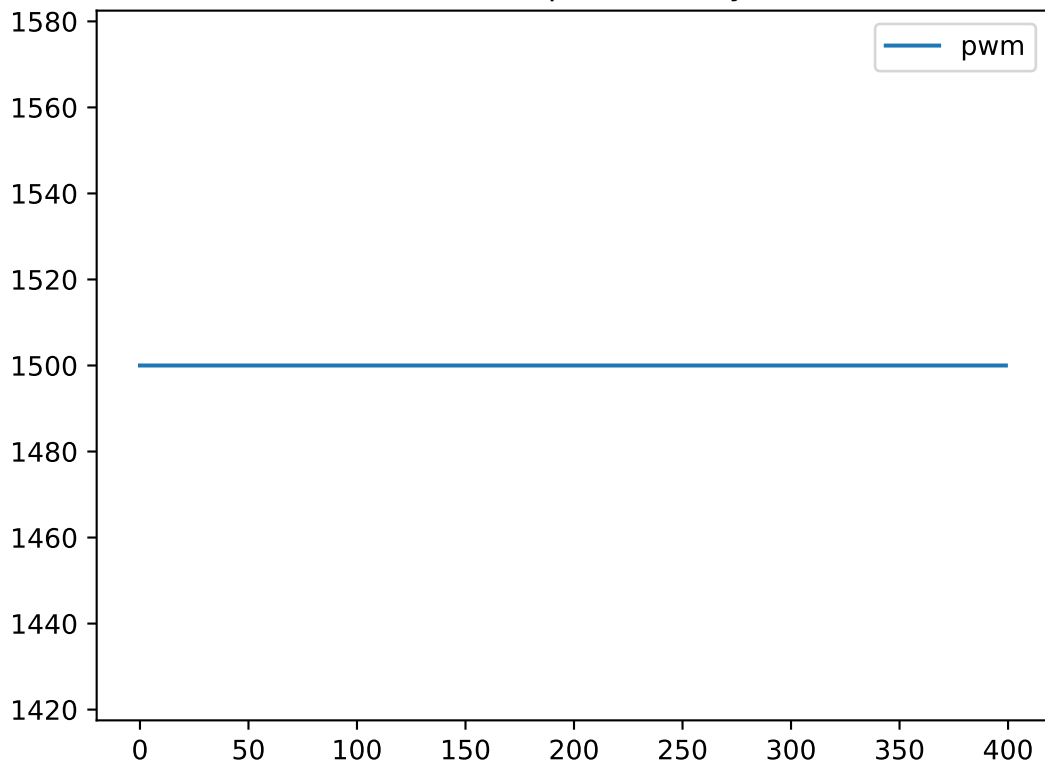
Motor 2 speed history



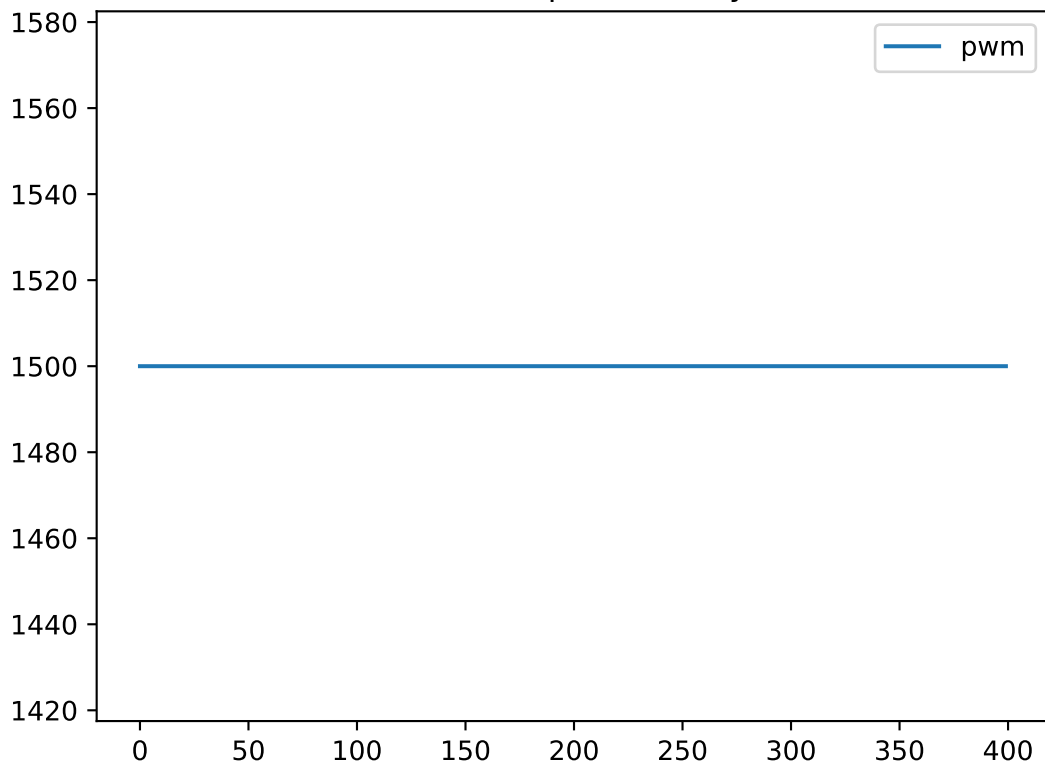
Motor 3 speed history



Motor 4 speed history

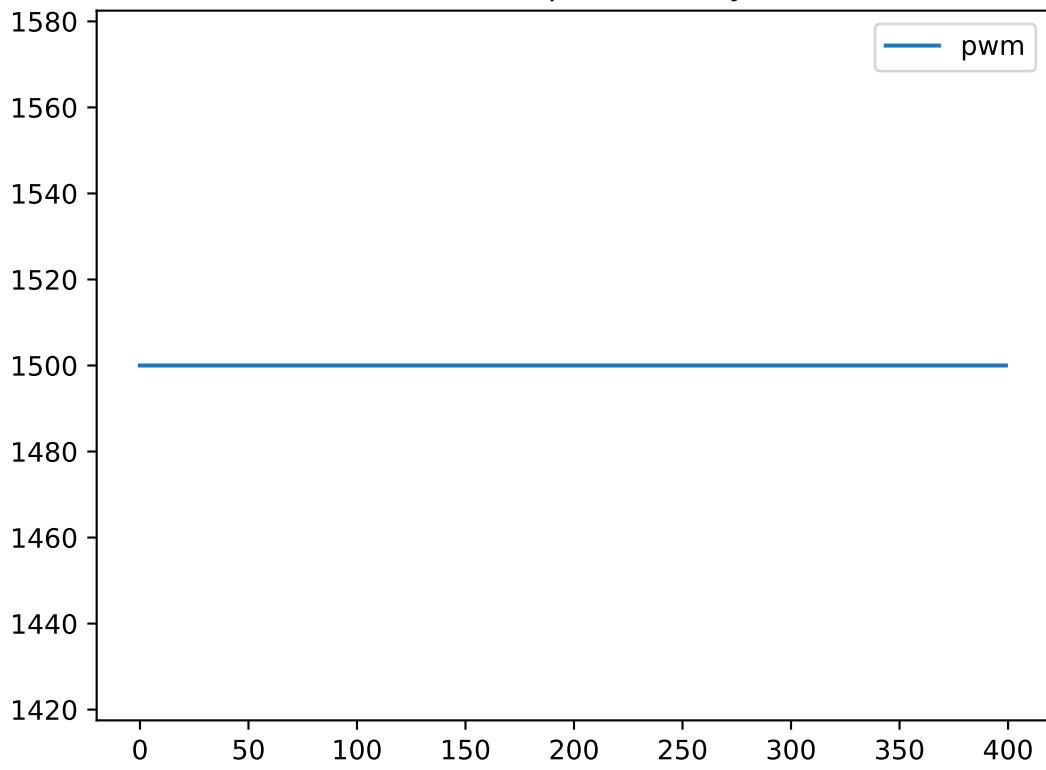


Motor 5 speed history

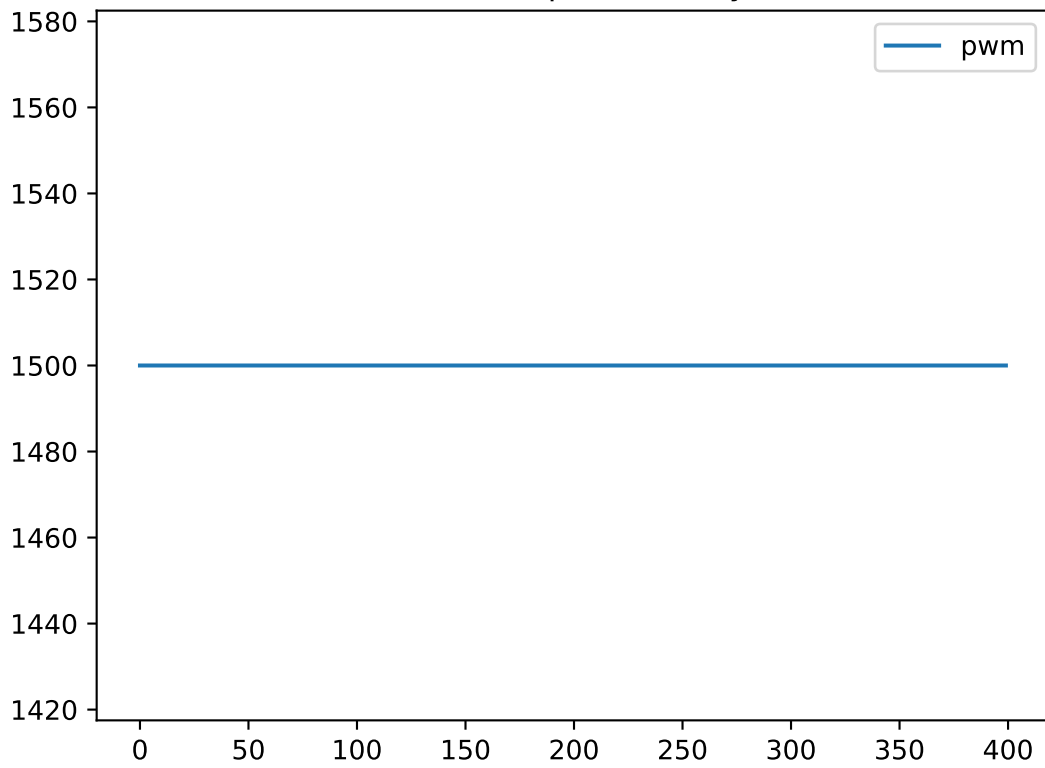




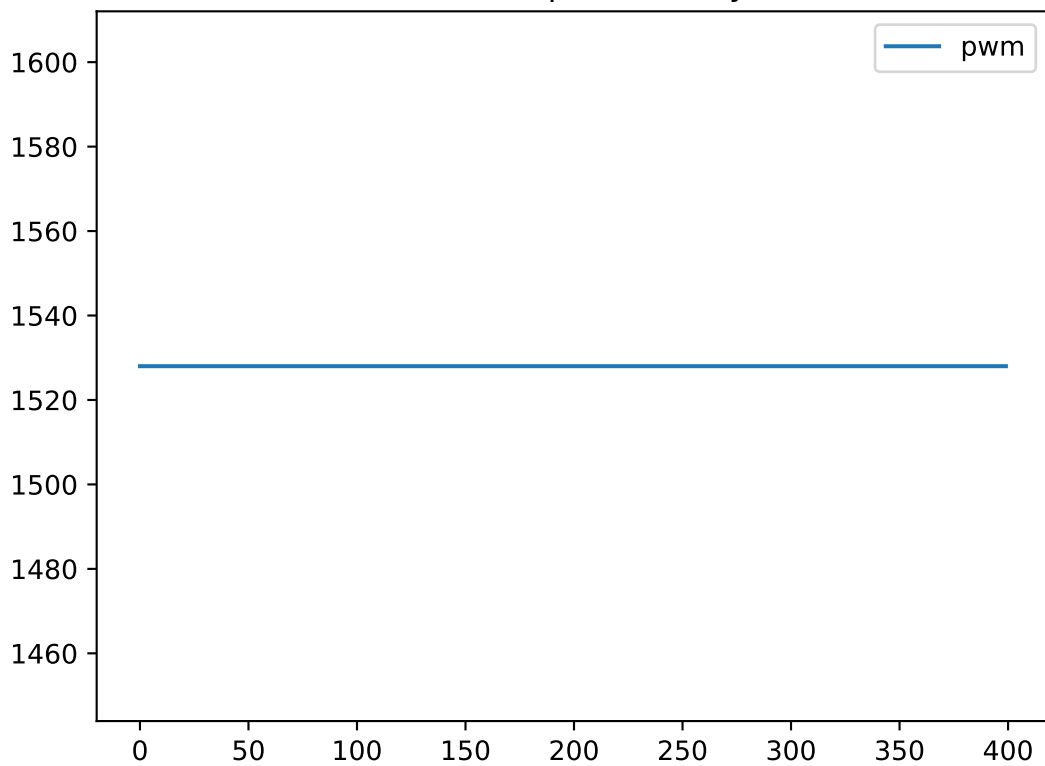
Motor 6 speed history



Motor 7 speed history



Motor 8 speed history



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