

Yiddish word of the day

Yiddish expression of the day

Matrix Multiplication

1st - Matrix Addition

Let A, B be $m \times n$ matrices.

$$A = (a_{ij})_{\substack{i=1, n \\ j=1, m}} = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix}, \quad B = (b_{ij})$$

Then $A + B = () = \left(\begin{array}{c} \\ \\ \\ \end{array} \right)_{m \times n}$

note: If we think of vector $\vec{v} = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$ in \mathbb{R}^n

we can think of this as $n \times 1$ matrix

So this addition we defined for matrices just generalizes the addition we defined for vectors.

ex) $\begin{pmatrix} 1 & 2 & 3 \\ 2 & 7 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 1 & 2 \\ 6 & 8 & 1 \end{pmatrix} = \begin{pmatrix} \quad & \quad & \quad \\ \quad & \quad & \quad \end{pmatrix}$

There's another reason to define matrix add this way

Recall: $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ $\xrightarrow{\text{we get}}$

Now, let $T, S: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be two linear transf.
we get a new transformation

$(\underline{\quad}) : \mathbb{R}^n \rightarrow \mathbb{R}^m$ defined by

$$(\underline{\quad})(\underline{\vec{v}}) = \underline{\quad}$$

$$\begin{array}{ccc} T & \xrightarrow{\quad} & \underline{\quad} \\ S & \xrightarrow{\quad} & \underline{\quad} \end{array} \quad (T+S) \xrightarrow{\quad} \underline{\quad}$$

Then the way we've defined matrix addition makes

$$\text{ex) } T: \mathbb{R}^2 \rightarrow \mathbb{R}^3 \quad \text{by} \quad T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \\ y \end{pmatrix}$$

$$S: \mathbb{R}^2 \rightarrow \mathbb{R}^3 \quad \text{by} \quad S\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ x \\ y \end{pmatrix}$$

$$\text{Then } (T+S)\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \quad \\ \quad \end{pmatrix} + \begin{pmatrix} \quad \\ \quad \end{pmatrix} = \begin{pmatrix} \quad \\ \quad \end{pmatrix}$$

Find A_{T+S} , A_S, A_T check $A_{T+S} = A_S + A_T$

$$A_T = \begin{pmatrix} & \\ & \end{pmatrix}, \quad A_S = \begin{pmatrix} & \\ & \end{pmatrix}$$

$$\underbrace{A_{T+S}}_{=} = \begin{pmatrix} & \\ & \end{pmatrix} =$$

ex) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^5$ $T \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_0 \\ x_2 \\ x_0 \\ x_3 \end{pmatrix}$

$S: \mathbb{R}^3 \rightarrow \mathbb{R}^5$ $S \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_1 \\ 2x_2 \\ 0 \\ x_3 \end{pmatrix}$

$$(T+S) : \mathbb{R}^+ \rightarrow \mathbb{R}^+, (T+S)(\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}) \stackrel{\text{def}}{=} \left(\begin{array}{c} \cdot \\ \cdot \\ \cdot \end{array} \right) + \left(\begin{array}{c} \cdot \\ \cdot \\ \cdot \end{array} \right)$$

$$(T, S)(\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}) = \left(\begin{array}{c} \cdot \\ \cdot \\ \cdot \end{array} \right)$$

$$A_T = \left(\begin{array}{c} \cdot \\ \cdot \\ \cdot \end{array} \right)$$

$$A_S = \left(\begin{array}{c} \cdot \\ \cdot \\ \cdot \end{array} \right)$$

$$A_T + A_S = \left(\begin{array}{c} \cdot \\ \cdot \\ \cdot \end{array} \right)$$

$$Ans = \left(\begin{array}{c} \\ \\ \end{array} \right) = - +$$

Recall - Functions (composition)

$f: A \rightarrow B$, $g: B \rightarrow C$ we get a new function

$g \circ f: \underline{\quad} \rightarrow \underline{\quad}$ defined by $(g \circ f)(a) = \underline{\quad}$



ex) $f: \mathbb{R} \rightarrow \mathbb{R}$ by $f(x) = x^2$

$g: \mathbb{R} \rightarrow \mathbb{R}$ by $g(x) = x - 2$

Then $g \circ f: \mathbb{R} \rightarrow \mathbb{R}$, $(g \circ f)(x) =$

i) $f: \mathbb{R} \rightarrow \mathbb{R}^2$ by $f(x) = \begin{pmatrix} 2x \\ x^2 \end{pmatrix}$

$g: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ by $g\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \\ 0 \end{pmatrix}$

$g \circ f: \mathbb{R} \rightarrow \mathbb{R}^3$

$(g \circ f)(x) =$

Note: In example 2 up^t do

In example 1, we can do as well.

but $f \circ g f$



Now : Suppose $\mathbb{R}^n \xrightarrow{T} \mathbb{R}^m \xrightarrow{S} \mathbb{R}^q$

that $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$, $S: \mathbb{R}^m \rightarrow \mathbb{R}^q$ are linear transf.

Then the function $S \circ T: \mathbb{R}^n \rightarrow \mathbb{R}^q$ is still a linear transformation (you can check this)

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m \rightsquigarrow \text{---} (\text{--- matrix})$$

$$S: \mathbb{R}^m \rightarrow \mathbb{R}^q \rightsquigarrow \text{---} (\text{--- matrix})$$

$$S \circ T: \mathbb{R}^n \rightarrow \mathbb{R}^q \rightsquigarrow \text{---} (\text{--- matrix})$$

Q: How are these 3 related?

• Recall that given $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ we have the corresponding matrix A_T and the property that $T(\vec{v}) = \underline{\hspace{2cm}}$

• So the matrix associated to $S \circ T$ should satisfy a similar property as above

• That is, we want $(S \circ T)(\vec{v}) = \underline{\hspace{2cm}}$

We will define matrix mult in such a way, that this relationship holds

Let A $m \times n$ matrix B $n \times q$ matrix

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$S: \mathbb{R}^q \rightarrow \mathbb{R}^n$$

AB will be a $m \times q$ matrix whose $(i,j)^{\text{th}}$ component
will be
- "multiply" row i of matrix A to "column j " of matrix B

Examples

$$A = \begin{pmatrix} 1 & 0 \\ -1 & 2 \end{pmatrix}$$

$$B = \begin{pmatrix} 2 & 3 \\ 1 & 0 \end{pmatrix}$$

$\Rightarrow AB$ should be a — matrix

(1,1) :

(1,2) :

(2,1) :

(2,2) :

$$\Rightarrow AB = \left(\quad \right)$$

$$B = \begin{pmatrix} 2 & 3 \\ -1 & 0 \end{pmatrix}_{2 \times 2}, A = \begin{pmatrix} 1 & 0 \\ 1 & 2 \end{pmatrix}_{2 \times 2}$$

(1,1) :



(1,2) :



$$\Rightarrow BA = \begin{pmatrix} \text{ } & \text{ } \\ \text{ } & \text{ } \end{pmatrix}$$

(2,1) :



(2,2) :



Check: That this def of mult gives us what we want

ex) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $\underline{T\left(\begin{pmatrix} x \\ y \end{pmatrix}\right)} = \begin{pmatrix} x+y \\ y \end{pmatrix}$

$S: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $\underline{S\left(\begin{pmatrix} x \\ y \end{pmatrix}\right)} = \begin{pmatrix} y \\ x \end{pmatrix}$

Then $T \circ S: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $(T \circ S)\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) =$

that is $\underline{(T \circ S)\left(\begin{pmatrix} x \\ y \end{pmatrix}\right)} = \begin{pmatrix} \quad \\ \quad \end{pmatrix}$

$T \rightsquigarrow A_T = \begin{pmatrix} \quad & \quad \\ \quad & \quad \end{pmatrix}$

$S \rightsquigarrow A_S = \begin{pmatrix} \quad & \quad \\ \quad & \quad \end{pmatrix}$

ToS $\rightarrow A_{TOS} = ()$

Claim is : $A_{TOS} =$

Reverse way

$$(S \circ T) : \mathbb{R}^2 \rightarrow \mathbb{R}^2 \text{ by } (S \circ T) \begin{pmatrix} x \\ y \end{pmatrix} =$$

$$S \circ T \rightarrow A_{S \circ T} = \left(\quad \right)$$

Now check that $A_{S \circ T} =$

Ways matrix mult is different than "regular" multiplication

1) we've seen it's not commutative, ie $\underline{AB} \neq \underline{BA}$

for many reasons!

ex) $A = \begin{pmatrix} 1 & 1 & 2 \\ 3 & 0 & 1 \end{pmatrix}_{2 \times 3}$

$$B = \begin{pmatrix} -1 & 6 \\ -2 & 0 \\ -3 & 0 \end{pmatrix}_{3 \times 2}$$

$$AB = \left(\quad \right) = \left(\quad \right)_{2 \times 2}$$

$$BA = \left(\quad \right) = \left(\quad \right)_{3 \times 3}$$

ex2: $A = \begin{pmatrix} 1 & 1 & 2 \\ 3 & 0 & 1 \end{pmatrix}_{2 \times 3}$ $B = \begin{pmatrix} 1 & 6 & 0 \\ 2 & 0 & 0 \\ 3 & 0 & 1 \end{pmatrix}_{3 \times 3}$

Note: cannot do , not defined!

 = $\left(\quad \right) = \left(\quad \right)_{2 \times 3}$

2) It's possible for 2 non-zero matrices to

(shows that matrices aren't a so called integral)
domain

ex) $A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ $B = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

$$AB = \left(\quad \right)$$

3) Can't "cancel" out matrices.

ex) $A = \begin{pmatrix} 2 & -3 \\ -4 & 6 \end{pmatrix}$, $B = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ $C = \begin{pmatrix} 4 & -2 \\ 3 & -1 \end{pmatrix}$

$$AB = \left(\quad \right) \Rightarrow$$

$$AC = \left(\quad \right)$$