

Open MP Clauses/Directive

Clauses / Directives Summary

• The table below summarizes which clauses are accepted by which OpenMP directives.

	Directive						
Clause	PARALLEL	DO/for	SECTIONS	SINGLE	PARALLEL DO/for	PARALLEL SECTIONS	
IF	•				•	•	
PRIVATE	•	•	•	•	•	•	
SHARED	•	•			•	•	
DEFAULT	•				•	•	
FIRSTPRIVATE	•	•	•	•	•	•	
LASTPRIVATE		•	•		•	•	
REDUCTION	•	•	•		•	•	
COPYIN	•				•	•	
COPYPRIVATE				•			
SCHEDULE		•			•		
ORDERED		•			•		
NOWAIT		•	0	•			



Open MP Clauses/Directive

- The following OpenMP directives do not accept clauses:
 - MASTER
 - CRITICAL
 - → BARRIER
 - ATOMIC
 - FLUSH
 - ORDERED
 - THREADPRIVATE



Directive Binding and Nesting Rules

Directive Binding:

- The DO/for, SECTIONS, SINGLE, MASTER and BARRIER directives bind to the dynamically enclosing PARALLEL, if one exists.
- The ORDERED directive binds to the dynamically enclosing DO/for.
- The ATOMIC directive enforces exclusive access with respect to ATOMIC directives in all threads, not just the current team.
- The CRITICAL directive enforces exclusive access with respect to CRITICAL directives in all threads, not just the current team.
- A directive can never bind to any directive outside the closest enclosing PARALLEL.



Run-time Library routines

- The OpenMP API includes an ever-growing number of run-time library routines.
- These routines are used for a variety of purposes as shown in the table below:

Routine	Purpose
OMP_SET_NUM_THREADS	Sets the number of threads that will be used in the next parallel region
OMP_GET_NUM_THREADS	Returns the number of threads that are currently in the team executing the parallel region from which it is called
OMP_GET_MAX_THREADS	Returns the maximum value that can be returned by a call to the OMP_GET_NUM_THREADS function
OMP_GET_THREAD_NUM	Returns the thread number of the thread, within the team, making this call.
OMP_GET_THREAD_LIMIT	Returns the maximum number of OpenMP threads available to a program
OMP_GET_NUM_PROCS	Returns the number of processors that are available to the program
OMP_IN_PARALLEL	Used to determine if the section of code which is executing is parallel or not
OMP_SET_DYNAMIC	Enables or disables dynamic adjustment (by the run time system) of the number of threads available for execution of parallel regions
OMP_GET_DYNAMIC	Used to determine if dynamic thread adjustment is enabled or not

Run-time Library routines

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OMP_IN_PARALLEL	Used to determine if the section of code which is executing is parallel or not
OMP_SET_DYNAMIC	Enables or disables dynamic adjustment (by the run time system) of the number of threads available for execution of parallel regions
OMP_GET_DYNAMIC	Used to determine if dynamic thread adjustment is enabled or not
OMP_SET_NESTED	Used to enable or disable nested parallelism
OMP_GET_NESTED	Used to determine if nested parallelism is enabled or not
OMP_SET_SCHEDULE	Sets the loop scheduling policy when "runtime" is used as the schedule kind in the OpenMP directive
OMP_GET_SCHEDULE	Returns the loop scheduling policy when "runtime" is used as the schedule kind in the OpenMP directive
OMP_SET_MAX_ACTIVE_LEVELS	Sets the maximum number of nested parallel regions
OMP_GET_MAX_ACTIVE_LEVELS	Returns the maximum number of nested parallel regions
OMP_GET_LEVEL	Returns the current level of nested parallel regions
OMP_GET_ANCESTOR_THREAD_NUM	Returns, for a given nested level of the current thread, the thread number of ancestor thread
OMP_GET_TEAM_SIZE	Returns, for a given nested level of the current thread, the size of the thread team
OMP_GET_ACTIVE_LEVEL	Returns the number of nested, active parallel regions enclosing the task that contains the call
OMP_IN_FINAL	Returns true if the routine is executed in the final task region; otherwise it returns false
OMP_INIT_LOCK	Initializes a lock associated with the lock variable
OMP_DESTROY_LOCK	Disassociates the given lock variable from any locks
OMP_SET_LOCK	Acquires ownership of a lock
OMP_UNSET_LOCK	Releases a lock
OMP_TEST_LOCK	Attempts to set a lock, but does not block if the lock is unavailable
OMP INIT NEST LOCK	Initializes a nested lock associated with the lock variable

Environment Variables

- · OpenMP provides the following environment variables for controlling the execution of parallel code.
- All environment variable names are uppercase. The values assigned to them are not case sensitive.

OMP_SCHEDULE

Applies only to DO, PARALLEL DO (Fortran) and for, parallel for (C/C++) directives which have their schedule clause set to RUNTIME. how iterations of the loop are scheduled on processors. For example:

```
setenv OMP_SCHEDULE "guided, 4"
setenv OMP SCHEDULE "dynamic"
```

OMP_NUM_THREADS

Sets the maximum number of threads to use during execution. For example:

```
setenv OMP NUM THREADS 8
```

OMP_DYNAMIC

Enables or disables dynamic adjustment of the number of threads available for execution of parallel regions. Valid values are TRUE or FALSE.

```
setenv OMP_DYNAMIC TRUE
```





Environment Variables

OMP_PROC_BIND

Enables or disables threads binding to processors. Valid values are TRUE or FALSE. For example:

```
setenv OMP PROC BIND TRUE
```

OMP_NESTED

Enables or disables nested parallelism. Valid values are TRUE or FALSE. For example:

```
setenv OMP NESTED TRUE
```

OMP_STACKSIZE

Controls the size of the stack for created (non-Master) threads. Examples:

```
setenv OMP_STACKSIZE 2000500B
setenv OMP_STACKSIZE "3000 k "
setenv OMP_STACKSIZE 10M
setenv OMP_STACKSIZE " 10 M "
setenv OMP_STACKSIZE "20 m "
setenv OMP_STACKSIZE "1G"
setenv OMP_STACKSIZE 20000
```



Message-Passing Programming

Abstraction of Multi-Computers system.

 MPI (Message Passing Interface) is the standard programming interface, that defines a set of functions that allow a programmer to instruct their code to execute tasks in parallel.



Basics

Initialization

All MPI programs must begin with a call to

MPI::Init() //Initialize the MPI execution environment

And close with a call to

MPI::Finalize() // Terminates MPI execution environment



Basics

Size and rank

Get how many processes are running in a given communicator,

size= MPI::COMM_WORLD.Get_size();

and the rank of the calling process within that communicator.

myrank= MPI::COMM_WORLD.Get_rank();



Point-to-Point Communication

MPI::COMM_WORLD.Send(void*buf,

int count, —

MPI_Datatype datatype, ____

int dest,

int tag)

MPI_Send(&x, 1, MPI_DOUBLE, dest, mytag)

MPI::COMM_WORLD.Recv (void *buf,

int count,

MPI_Datatype datatype,

int source,

int tag)

MPI_Receive(&x, 1, MPI_DOUBLE, source, mytag)



Send & Receive process

Blocking	Non-Blocking
Send Recv	Isend Irecv

Blocking point-to-point operations will wait until a communication has completed on its local processor before continuing. (Subroutine will not return till copy is completed to/from system buffer)

Non-blocking point-to-point operations will initiate a communication without waiting for that communication to be completed. (Copy is just initiated to/from system buffer). You must handle waiting for correct data by yourself.



Send Array

```
int MyID , Size , Sender , Receiver ;
MPI::Init( Argc , Argv);
MyID = MPI::COMM_WORLD.Get_rank();
Size = MPI::COMM WORLD.Get size();
if(MyID == 0)
    int Data[10] = {1,2,3,4,5,6,7,8,9,10};
\longrightarrow Receiver = 1;
 ■ MPI::COMM WORLD.Send( &Data , 10 , MPI::INT ,Receiver, 0);
else
    int Data[10];
    Sender = 0;
   MPI::COMM WORLD.Recv( &Data , 10 , MPI::INT ,Sender, 0);
    for(int i =0;i<10;i++)
        cout<<Data[i]<<endl;</pre>
MPI::Finalize();
return 0;
```



Collective Communication

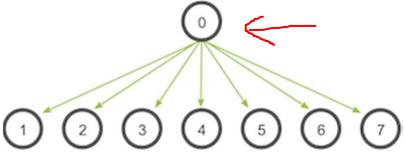
- Collective communication involves all processes in the scope of the communicator.
- All processes are by default, members in the communicator MPI_COMM_WORLD.



Collective Communication - Broadcast

MPI::Comm::Bcast (void* buffer, int count, const MPI::Datatype& datatype, int root

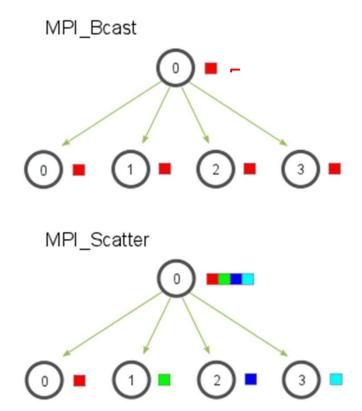
- INOUT buffer starting address of buffer (choice)
- IN count number of entries in buffer (non-negative integer)
- IN datatype data type of buffer (handle)
- IN root rank of broadcast root (integer)





Collective Communication - Scatter

- MPI_Scatter is a collective routine that is very similar to MPI_Bcast
- MPI_Scatter involves a designated root process sending data to all processes in a communicator.





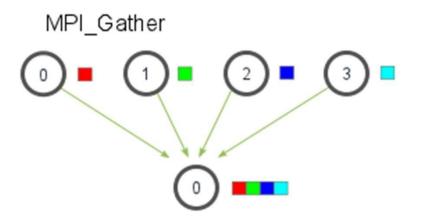
Collective Communication - Scatter

MPI::Comm::Scatter(void* send_data, int send_count, MPI_Datatype send_datatype, void* recv_data, __ int recv_count, MPI_Datatype recv_datatype, int root)



Collective Communication - Gather

 MPI_Gather is the inverse of MPI_Scatter. Instead of spreading elements from one process to many processes, MPI_Gather takes elements from many processes and gathers them to one single process.





Collective Communication - Gather

MPI::Comm::Gather(void* send_data, int send_count, MPI_Datatype send_datatype, void* recv_data, int recv_count, MPI_Datatype recv_datatype, int root)



Collective Communication - Reduction

 Reduction Perform an operation over data on all processes and store the result in one process

MPI::Comm::Reduce(

void* sendbuf,
void* recvbuf,
int count,
const MPI::Datatype& datatype,
const MPI::Op& op,
int root) —

- IN-- sendbuf address of send buffer (choice)
- OUT-- recvbuf address of receive buffer (choice, significant only at root)
- IN-- **count** number of elements in send buffer (non-negative integer)
- IN-- datatype data type of elements of send buffer (handle)
- IN-- op reduce operation (handle)
- IN-- root rank of root process (integer)



Collective Communication - Reduction

MPI::Comm::Reduce operators

MPI::MAX

MPI::MIN

MPI::SUM

MPI::PROD

MPI::MAXLOC

MPI::MINLOC

MPI::LAND

MPI_BAND

MPI::LOR

MPI::BOR

MPI::LXOR

MPI::BXOR



MPI_Wtime

Returns an elapsed time on the calling processor

double MPI_Wtime(void)

Return value: Time in seconds since an arbitrary time in the past.



Speedup

Speedup:

$$S_p = \overline{\frac{T_s}{T_p}}$$

Parallel efficiency

$$E_p = \frac{S_p}{p} = \frac{T_s}{pT_p}$$

- -p = # of processors
- Ts = execution time of the sequential algorithm
- Tp = execution time of the parallel algorithm with p processors
- Sp= P (linear speedup: ideal)



What is Hybridization?

- the use of inherently different models of programming in a complementary manner, in order to achieve some benefit not possible otherwise;
- a way to use different models of parallelization in a way that takes advantage of the good points of each;
- also known as "mixed mode" programming





When Does Hybridization Make Sense?

- when one wants to scale a shared memory OpenMP application for use on multiple SMP nodes in a cluster;
- when one wants to reduce an MPI application's sensitivity to becoming communication bound;
- when one is designing a parallel program from the very beginning to maximize utilization of a distributed memory machine consisting of individual SMP nodes;





Hybridization Using MPI and OpenMP

- facilitates cooperative shared memory (OpenMP) programming across clustered SMP nodes;
- MPI facilitates communication among SMP nodes, including the efficient packing and sending of complex data structures;
- OpenMP manages the workload on each SMP node;
- MPI and OpenMP are used in tandem to manage the overall concurrency of the application;



MPI vs. OpenMP

™ Pure MPI Pro:

- wHigh scalability
- wHigh portability

™ Pure MPI Con:

- wHard to develop and debug.
- **w**Explicit communications
- [™]Coarse granularity
- The Hard to ensure load balancing

Pure OpenMP Pro:

Easy to deploy (often)

Low latency

Implicit communications

Coarse and fine granularity

Dynamic Load balancing

Pure OpenMP Con:

Only on shared memory machines

Intranode scalability

Possible long waits for unlocking data

Undefined thread ordering

Example: Calculating π

Numerical integration

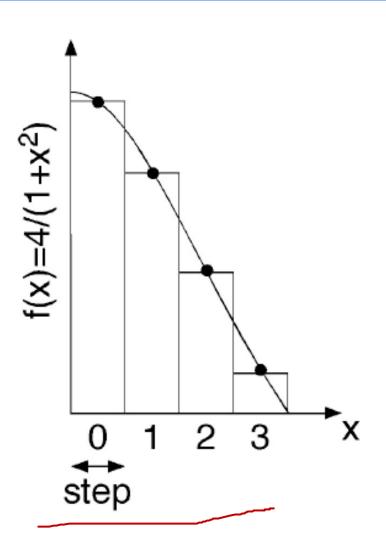
$$\int_0^1 \frac{4}{1+x^2} \, dx = \pi$$

• Discretization:

```
\Delta = 1/N: step = 1/NBIN
x_i = (i+0.5)\Delta \ (i=0,...,N-1)
```

$$\sum_{i=0}^{N-1} \frac{4}{1+x_i^2} \Delta \cong \pi$$

```
#include <stdio.h>
#define NBIN 100000
void main() {
   int i; double step,x,sum=0.0,pi;
   step = 1.0/NBIN;
   for (i=0; i<NBIN; i++) {
      x = (i+0.5)*step;
      sum += 4.0/(1.0+x*x);}
   pi = sum*step;
   printf("PI = %f\n",pi);
}</pre>
```



pi – MPI version

```
#include <stdio.h>
#include <stdlib.h>
#include <mpi.h>
                    /* MPI header file */
#define NUM_STEPS 100000000
<mark>i</mark>nt main(int argc, char *argv[]) {
  int nprocs;
  int myid;
  double start_time, end_time;
  int i;
  double x, pi;
  double sum = 0.0;
  double step = 1.0/(double) NUM_STEPS;
  /* initialize for MPI */
 MPI_Init(&argc, &argv); /* starts MPI */
  /* get number of processes */
   MPI_Comm_size(MPI_COMM_WORLD, &nprocs);
  /* get this process's number (ranges from 0 to nprocs - 1) */
       Comm_rank(MPI_COMM_WORLD, &myid);
```



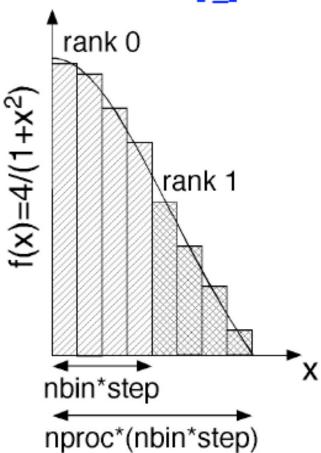
```
/* do computation */
  for (i=myid; i < NUM_STEPS; i += nprocs) { /* changed */
    x = (i+0.5)*step;
    sum = sum + 4.0/(1.0+x*x);
                                       /* changed */
  sum = step * sum;
  MPI_Reduce(&sum, &pi, 1, MPI_DOUBLE, MPI_SUM, 0, MPI_COMM_WORLD);/* added */
/* print results */
  if (myid == 0) {
     printf("parallel program results with %d processes:\n", nprocs);
     printf("pi = %g (%17.15f)\n",pi, pi);
  <mark>/* cle</mark>an up for MPI */
  MPI_Finalize();
  return 0;
```

OpenMP, reduction clause

```
#include <stdio.h>
#include <omp.h>
#define NBIN 100000
int main(int argc, char *argv[]) {
  int I, nthreads;
  double x, pi;
  double sum = 0.0;
  double step = 1.0/(double) NUM_STEPS;
  /* do computation -- using all available threads */
  #pragma omp parallel
    #pragma omp for private(x) reduction(+:sum) schedule(runtime)
    for (i=0; i < NUM_STEPS; ++i) {
       x = (i+0.5)*step;
       sum = sum + 4.0/(1.0+x*x);
    #pragma omp master
       pi = step * sum;
  printf("PI = %f\n",pi);
```

MPI+OpenMP Calculation of π

- Each MPI process integrates over a range of width 1/nproc, as a discrete sum of nbin bins each of width step
- Within each MPI process, nthreads OpenMP threads perform part of the sum as in omp_pi.c



MPI_OpenMP version

```
#include <stdio.h>
#include <stdlib.h>
#include <mpi.h> /* MPI header file */
#include <omp.h>
                           /* OpenMP header file */
#define NUM_STEPS 100000000
#define MAX_THREADS 4
int main(int argc, char *argv[]) {
  int nprocs, myid;
  int tid, nthreads, nbin;
  double start time, end time;
  double pi, Psum=0.0, sum[MAX_THREADS]={0.0};
  double step = 1.0/(double) NUM_STEPS;
  /* initialize for MPI */
 MPI_Init(&argc, &argv); /* starts MPI */
  /* get number of processes */
  MPI_Comm_size(MPI_COMM_WORLD, &nprocs);
  /* get this process's number (ranges from 0 to nprocs - 1) */
  MPI_Comm_rank(MPI_COMM_WORLD, &myid);
 nbin= NUM_STEPS/nprocs;
```

```
#pragma omp parallel private(tid)
    int i;
    double x;
    nthreads=omp_get_num_threads();
    tid=omp_get_thread_num();
    for (i=nbin*myid+tid; i < nbin*(myid+1); i+= nthreads) { /* changed*/
       x = (i+0.5)*step;
       sum[tid] += 4.0/(1.0+x*x);
for(tid=0; tid<nthreads; tid++) /*sum by each mpi process*/
    Psum += sum[tid]*step;
MPI_Reduce(&Psum, &pi, 1, MPI_DOUBLE, MPI_SUM, 0, MPI_COMM_WORLD);/* added*/
  if (myid == 0) {
    printf("parallel program results with %d processes:\n", nprocs);
    printf("pi = %g (%17.15f)\n",pi, pi);
       halize();
  return 0;
```

Assignment

30x30 matrix multiplication

- -OpenMP only
- -MPI only

Hyprid OpenMp+MPI

-Analysis Study (in time)

