Recurrent Neural Networks

1. IMDB Review Classification Battlefield - Contestants : Feedforward, CNN, RNN, LSTM

In this task, we are going to do sentiment classification on a movie review dataset. We are going to build a feedforward net, a convolutional neural net, a recurrent net and combine one or more of them to understand performance of each of them. A sentence can be thought of as a sequence of words which have semantic connections across time. By semantic connection, we mean that the words that occur earlier in the sentence influence the sentence's structure and meaning in the latter part of the sentence. There are also semantic connections backwards in a sentence, in an ideal case (in which we use RNNs from both directions and combine their outputs). But for the purpose of this tutorial, we are going to restrict ourselves to only uni-directional RNNs.

```
In [1]: import numpy as np
# fix random seed for reproducibility
np.random.seed(1)

In [2]: # We want to have a finite vocabulary to make sure that our word
matrices are not arbitrarily small
vocabulary_size = 10000
```

#We also want to have a finite length of reviews and not have to
process really long sentences.
max_review_length = 500

TOKENIZATION

For practical data science applications, we need to convert text into tokens since the machine understands only numbers and not really English words like humans can. As a simple example of tokenization, we can see a small example.

Assume we have 5 sentences. This is how we tokenize them into numbers once we create a dictionary.

- 1. i have books [1, 4, 7]
- 2. interesting books are useful [10,2,9,8]
- 3. i have computers [1,4,6]
- 4. computers are interesting and useful [6,9,11,10,8]
- 5. books and computers are both valuable. [2,10,2,9,13,12]
- 6. Bye Bye [7,7]

Create tokens for vocabulary based on frequency of occurrence. Hence, we assign the following tokens

I-1, books-2, computers-3, have-4, are-5, computers-6,bye-7, useful-8, are-9, and-10,interesting-11, valuable-12, both-13

Thankfully, in our dataset it is internally handled and each sentence is represented in such tokenized form.

Load data

In [3]: from keras.datasets import imdb
from keras.preprocessing import sequence

```
Using TensorFlow backend.
/home/daryna/.local/lib/python3.7/site-packages/tensorflow/python
/framework/dtypes.py:516: FutureWarning: Passing (type, 1) or 'lt
ype' as a synonym of type is deprecated; in a future version of n
umpy, it will be understood as (type, (1,)) / (1,)type'.
  _np_qint8 = np.dtype([("qint8", np.int8, 1)])
/home/daryna/.local/lib/python3.7/site-packages/tensorflow/python
/framework/dtypes.py:517: FutureWarning: Passing (type, 1) or 'lt
ype' as a synonym of type is deprecated; in a future version of n
umpy, it will be understood as (type, (1,)) / (1,)type'.
  _np_quint8 = np.dtype([("quint8", np.uint8, 1)])
/home/daryna/.local/lib/python3.7/site-packages/tensorflow/python
/framework/dtypes.py:518: FutureWarning: Passing (type, 1) or '1t
ype' as a synonym of type is deprecated; in a future version of n
umpy, it will be understood as (type, (1,)) / (1,)type'.
  _np_qint16 = np.dtype([("qint16", np.int16, 1)])
/home/daryna/.local/lib/python3.7/site-packages/tensorflow/python
/framework/dtypes.py:519: FutureWarning: Passing (type, 1) or 'lt
ype' as a synonym of type is deprecated; in a future version of n
umpy, it will be understood as (type, (1,)) / (1,)type'.
  _np_quint16 = np.dtype([("quint16", np.uint16, 1)])
/home/daryna/.local/lib/python3.7/site-packages/tensorflow/python
/framework/dtypes.py:520: FutureWarning: Passing (type, 1) or 'lt
ype' as a synonym of type is deprecated; in a future version of n
umpy, it will be understood as (type, (1,)) / (1,)type'.
  np qint32 = np.dtype([("qint32", np.int32, 1)])
/home/daryna/.local/lib/python3.7/site-packages/tensorflow/python
/framework/dtypes.py:525: FutureWarning: Passing (type, 1) or '1t
ype' as a synonym of type is deprecated; in a future version of n
umpy, it will be understood as (type, (1,)) / (1,)type'.
 np resource = np.dtype([("resource", np.ubyte, 1)])
/home/daryna/anaconda3/envs/ml ukma/lib/python3.7/site-packages/t
ensorboard/compat/tensorflow_stub/dtypes.py:541: FutureWarning: P
assing (type, 1) or 'ltype' as a synonym of type is deprecated; i
n a future version of numpy, it will be understood as (type,
(1,)) / '(1,)type'.
  np gint8 = np.dtype([("gint8", np.int8, 1)])
/home/daryna/anaconda3/envs/ml_ukma/lib/python3.7/site-packages/t
ensorboard/compat/tensorflow_stub/dtypes.py:542: FutureWarning: P
assing (type, 1) or 'ltype' as a synonym of type is deprecated; i
n a future version of numpy, it will be understood as (type,
(1,)) / '(1,)type'.
  _np_quint8 = np.dtype([("quint8", np.uint8, 1)])
/home/daryna/anaconda3/envs/ml ukma/lib/python3.7/site-packages/t
ensorboard/compat/tensorflow_stub/dtypes.py:543: FutureWarning: P
assing (type, 1) or 'ltype' as a synonym of type is deprecated; i
n a future version of numpy, it will be understood as (type,
(1,)) / '(1,)type'.
  _np_qint16 = np.dtype([("qint16", np.int16, 1)])
/home/daryna/anaconda3/envs/ml ukma/lib/python3.7/site-packages/t
ensorboard/compat/tensorflow stub/dtypes.py:544: FutureWarning: P
assing (type, 1) or 'ltype' as a synonym of type is deprecated; i
n a future version of numpy, it will be understood as (type,
(1,)) / '(1,)type'.
  _np_quint16 = np.dtype([("quint16", np.uint16, 1)])
/home/daryna/anaconda3/envs/ml_ukma/lib/python3.7/site-packages/t
ensorboard/compat/tensorflow stub/dtypes.py:545: FutureWarning: P
assing (type, 1) or 'ltype' as a synonym of type is deprecated; i
n a future version of numpy, it will be understood as (type,
```

```
(1,)) / '(1,)type'.
    _np_qint32 = np.dtype([("qint32", np.int32, 1)])
/home/daryna/anaconda3/envs/ml_ukma/lib/python3.7/site-packages/t
ensorboard/compat/tensorflow_stub/dtypes.py:550: FutureWarning: P
assing (type, 1) or 'ltype' as a synonym of type is deprecated; i
n a future version of numpy, it will be understood as (type,
(1,)) / '(1,)type'.
```

/home/daryna/anaconda3/envs/ml_ukma/lib/python3.7/site-packages/k eras/datasets/imdb.py:101: VisibleDeprecationWarning: Creating an ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant to do this, you must specify 'dtype=obje ct' when creating the ndarray

```
x_train, y_train = np.array(xs[:idx]), np.array(labels[:idx])
```

Number of reviews 25000 Length of first and fifth review before padding 218 147 First review [1, 14, 22, 16, 43, 530, 973, 1622, 1385, 65, 458, 4 468, 66, 3941, 4, 173, 36, 256, 5, 25, 100, 43, 838, 112, 50, 67 0, 2, 9, 35, 480, 284, 5, 150, 4, 172, 112, 167, 2, 336, 385, 39, 4, 172, 4536, 1111, 17, 546, 38, 13, 447, 4, 192, 50, 16, 6, 147, 2025, 19, 14, 22, 4, 1920, 4613, 469, 4, 22, 71, 87, 12, 16, 43, 530, 38, 76, 15, 13, 1247, 4, 22, 17, 515, 17, 12, 16, 626, 18, 2, 5, 62, 386, 12, 8, 316, 8, 106, 5, 4, 2223, 5244, 16, 480, 66, 3785, 33, 4, 130, 12, 16, 38, 619, 5, 25, 124, 51, 36, 135, 48, 2 5, 1415, 33, 6, 22, 12, 215, 28, 77, 52, 5, 14, 407, 16, 82, 2, 8, 4, 107, 117, 5952, 15, 256, 4, 2, 7, 3766, 5, 723, 36, 71, 43, 530, 476, 26, 400, 317, 46, 7, 4, 2, 1029, 13, 104, 88, 4, 381, 1 5, 297, 98, 32, 2071, 56, 26, 141, 6, 194, 7486, 18, 4, 226, 22, 21, 134, 476, 26, 480, 5, 144, 30, 5535, 18, 51, 36, 28, 224, 92, 25, 104, 4, 226, 65, 16, 38, 1334, 88, 12, 16, 283, 5, 16, 4472, 113, 103, 32, 15, 16, 5345, 19, 178, 32] First label 1

/home/daryna/anaconda3/envs/ml_ukma/lib/python3.7/site-packages/k eras/datasets/imdb.py:102: VisibleDeprecationWarning: Creating an ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant to do this, you must specify 'dtype=obje ct' when creating the ndarray

```
x test, y test = np.array(xs[idx:]), np.array(labels[idx:])
```

Preprocess data

Pad sequences in order to ensure that all inputs have same sentence length and dimensions.

```
In [5]: X_train = sequence.pad_sequences(X_train, maxlen=max_review_lengt
h)
    X_test = sequence.pad_sequences(X_test, maxlen=max_review_length)
    print('Length of first and fifth review after padding', len(X_train[0]) ,len(X_train[4]))
    Length of first and fifth review after padding 500 500

In [6]: X_train.shape
Out[6]: (25000, 500)
```

Models

```
In [7]: import torch
from torch import nn
from torch.utils.data import Dataset, DataLoader
import matplotlib.pyplot as plt
from sklearn.metrics import accuracy_score
from tqdm.notebook import tqdm
from sklearn.model_selection import train_test_split
In [8]: DEVICE = torch.device("cuda" if torch.cuda.is_available() else "c
pu")
if DEVICE.type == 'cuda':
    torch.set_default_tensor_type('torch.cuda.FloatTensor')
# DEVICE = torch.device("cpu")
print(DEVICE.type)

cuda
```

MODEL 1(a): FEEDFORWARD NETWORKS WITHOUT EMBEDDINGS

Let us build a single layer feedforward net with 250 nodes. Each input would be a 500-dim vector of tokens since we padded all our sequences to size 500.

EXERCISE: Calculate the number of parameters involved in this network and implement a feedforward net to do classification without looking at cells below.

```
In [9]: D_in = X_train.shape[1]
H = 250
D_out = 1

# X, y = torch.from_numpy(X_train).to(DEVICE), torch.from_numpy(y
    _train).float().to(DEVICE)
In [10]: epochs = 20
verbose = 1
learning_rate = 1e-2
batch_size=64
optimizer = torch.optim.Adam
criteria = nn.BCELoss(reduction='mean')
```

```
In [11]: def fit epoch(inputs, labels, model, criteria, optimizer):
             model.train()
             permutation = torch.randperm(inputs.size()[0])
             losses, accs = [], []
             for i in range(0,inputs.size()[0], batch_size):
                 indices = permutation[i:i+batch size]
                 batch x, batch y = inputs[indices], labels[indices]
                 output = model(batch x)[:,0]
                 optimizer.zero grad()
                 loss = criteria(output, batch y.float())
                 loss.backward()
                 optimizer.step()
                 preds = output > 0.5
                 correct = (preds == batch y).sum()
                 acc = correct / float(batch y.shape[0])
                 losses.append(loss.item())
                 accs.append(acc.item())
             losses, accs = np.array(losses), np.array(accs)
             return np.mean(losses), np.mean(accs)
         def eval_epoch(inputs, labels, model, criteria):
             model.eval()
             ids = [i for i in range(inputs.size()[0])]
             losses, accs = [], []
             for i in range(0,inputs.size()[0], batch size):
                 indices = ids[i:i+batch size]
                 batch x, batch y = inputs[indices], labels[indices]
                 with torch.set grad enabled(False):
                     output = model(batch x)[:,0]
                     loss = criteria(output, batch_y.float())
                     preds = output > 0.5
                     correct = (preds == batch y).sum()
                     acc = correct / float(batch y.shape[0])
                 losses.append(loss.item())
                 accs.append(acc.item())
             losses, accs = np.array(losses), np.array(accs)
             return np.mean(losses), np.mean(accs)
         def train(X, y, X_val, y_val,
                   model, epochs, verbose, learning rate, criteria, optimi
         zer, batch size=64):
             inputs, labels = torch.from_numpy(X).to(DEVICE), torch.from_n
         umpy(y).to(DEVICE)
             inputs val, labels val = torch.from numpy(X val).to(DEVICE),
         torch.from numpy(y val).to(DEVICE)
             optimizer = optimizer(model.parameters(), lr=learning rate)
```

```
log template = "\n[{ep:03d}/{epochs:03d}] train loss: {t los
         s:0.4f} \
             val loss {v loss:0.4f} train acc {t acc:0.4f} val acc {v acc:
         0.4f}"
             history = []
             for epoch in range(epochs):
                 train loss, train acc = fit epoch(inputs, labels, model,
         criteria, optimizer)
                 val loss, val acc = eval epoch(inputs val, labels val, mo
         del, criteria)
                 history.append([train loss, train acc, val loss, val ac
         c])
                 if (epoch==0) or (epoch%verbose==0) or (epoch==epochs-1):
                     print(log template.format(ep=epoch+1, epochs=epochs,
         t loss=train loss,
                                                     v loss=val loss, t acc
         =train acc, v acc=val acc))
             return history
In [12]: class SimpleNet(nn.Module):
             def __init__(self):
                 super(). init ()
                 self.fc1 = nn.Linear(D_in, H)
                 self.out = nn.Linear(H, D out)
                 self.out_act = nn.Sigmoid()
             def forward(self, input ):
                 a1 = self.fc1(input_.float())
                 a2 = self.out(a1)
                 y = self.out_act(a2)
                 return y
In [13]: simple model = SimpleNet().to(DEVICE)
```

```
In [14]: simple history = train(X train, y train, X test, y test, simple m
         odel.
               epochs=15, verbose=1, learning rate=1e-3, criteria=criteri
         a, optimizer=optimizer)
         [001/015] train_loss: 13.9541
                                            val loss 13.8124 train acc 0.49
         60 \text{ val acc } 0.5001
         [002/015] train loss: 13.8169
                                            val loss 13.8244 train acc 0.50
         00 val acc 0.4999
         [003/015] train loss: 13.8123
                                            val loss 13.8175 train acc 0.50
         01 val_acc 0.5000
         [004/015] train loss: 13.8131
                                            val loss 13.8175 train acc 0.50
         01 val acc 0.5000
         [005/015] train loss: 13.8151
                                            val loss 13.8175 train acc 0.50
         00 val acc 0.5000
         [006/015] train loss: 13.8171
                                            val loss 13.8175 train acc 0.49
         99 val acc 0.5000
         [007/015] train loss: 13.8151
                                            val loss 13.8175 train acc 0.50
         00 val acc 0.5000
         [008/015] train loss: 13.8157
                                            val loss 13.8175 train acc 0.50
         00 val acc 0.5000
         [009/015] train loss: 13.8164
                                            val loss 13.8175 train acc 0.50
         00 val acc 0.5000
         [010/015] train loss: 13.8144
                                            val loss 13.8175 train acc 0.50
         00 val acc 0.5000
         [011/015] train loss: 13.8144
                                            val loss 13.8175 train acc 0.50
         00 val acc 0.5000
         [012/015] train_loss: 13.8137
                                            val loss 13.8175 train acc 0.50
         01 val acc 0.5000
         [013/015] train loss: 13.8190
                                            val loss 13.8175 train acc 0.49
         99 val acc 0.5000
         [014/015] train loss: 13.8157
                                            val loss 13.8175 train acc 0.50
         00 val acc 0.5000
         [015/015] train loss: 13.8137
                                            val loss 13.8175 train acc 0.50
```

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01 val acc 0.5000

Discussion: Why was the performance bad? What was wrong with tokenization?

MODEL 1(b): FEEDFORWARD NETWORKS WITH EMBEDDINGS

What is an embedding layer?

An embedding is a linear projection from one vector space to another. We usually use embeddings to project the one-hot encodings of words on to a lower-dimensional continuous space so that the input surface is dense and possibly smooth. According to the model, an embedding layer is just a transformation from \$\mathbb{R}^{\inp}\$ to \$\mathbb{R}^{\inp}\$

Do embedding to dim 100 (in keras, tf, PyTorch: with Embedding layer) and after flattening add a dense layer with 250 units. Fit the model.

```
In [15]: vocabulary_size
Out[15]: 10000
In [16]: learning_rate = 1e-3
In [17]: | H emb = 100
         class EmbeddingNet(nn.Module):
             def init (self):
                 super().__init__()
                 self.emb = nn.Embedding(vocabulary size, H emb)
                 self.dp1 = torch.nn.Dropout(0.5)
                 self.fc1 = nn.Linear(H_emb * D_in, H)
                 self.dp2 = torch.nn.Dropout(0.5)
                 self.out = nn.Linear(H, D out)
                 self.out_act = nn.Sigmoid()
             def forward(self, input_):
                 emb = self.emb(input_.long()).view((input_.size(0), -1))
                 dp1 = self.dp1(emb)
                 a1 = self.fc1(dp1)
                 dp2 = self.dp2(a1)
                 a2 = self.out(dp2)
                 y = self.out_act(a2)
                 return y
```

```
In [18]:
         emb model = EmbeddingNet().to(DEVICE)
         emb_history = train(X_train, y_train, X_test, y_test, emb_model,
               epochs=50, verbose=5, learning rate=1e-3, criteria=criteri
         a, optimizer=optimizer)
         [001/050] train_loss: 7.4095
                                           val loss 0.8028 train acc 0.5088
         val acc 0.5114
         [006/050] train loss: 0.3679
                                           val loss 0.4482 train acc 0.8364
         val acc 0.7992
         [011/050] train loss: 0.2108
                                           val loss 0.4478 train acc 0.9165
         val acc 0.8354
         [016/050] train loss: 0.1500
                                           val loss 0.6077 train acc 0.9457
         val acc 0.8419
         [021/050] train loss: 0.1260
                                           val loss 0.6249 train acc 0.9592
         val acc 0.8430
         [026/050] train loss: 0.1059
                                           val loss 0.8599 train acc 0.9688
         val acc 0.8516
         [031/050] train loss: 0.0935
                                           val loss 1.1010 train acc 0.9743
         val acc 0.8517
         [036/050] train loss: 0.0971
                                           val loss 1.1076 train acc 0.9771
         val_acc 0.8550
                                           val loss 1.5285 train_acc 0.9829
         [041/050] train loss: 0.0828
         val acc 0.8564
         [046/050] train loss: 0.0667
                                           val loss 1.6448 train acc 0.9870
         val acc 0.8596
         [050/050] train loss: 0.1006
                                           val loss 1.9589 train acc 0.9846
         val acc 0.8570
```

MODEL 2: CONVOLUTIONAL NEURAL NETWORKS

Text can be thought of as 1-dimensional sequence and we can apply 1-D Convolutions over a set of words. Let us walk through convolutions on text data with this blog.

http://debajyotidatta.github.io/nlp/deep/learning/word-embeddings/2016/11/27/Understanding-Convolutions-In-Text/ (http://debajyotidatta.github.io/nlp/deep/learning/word-embeddings/2016/11/27/Understanding-Convolutions-In-Text/)

Fit a 1D convolution with 200 filters, kernel size 3 followed by a feedforward layer of 250 nodes and ReLU, sigmoid activations as appropriate.

```
In [19]: D_in
Out[19]: 500
```

```
In [20]: H conv = 200
         H=250
         C in = 1
         k \text{ size} = 3
         class ConvNet(nn.Module):
             def __init__(self):
                  super().__init__()
                  self.c1 =nn.Conv1d(C_in, H_conv, kernel_size=k_size, padd
         ina=1)
                    self.p1 = nn.AvgPool1d(H conv)
                  self.fc1 = nn.Linear(H conv*D in, H)
                  self.fc2 = nn.Linear(H, D_out)
                  self.out = nn.ReLU()
                 self.out act = nn.Sigmoid()
             def forward(self, input ):
                  conv = self.cl(input_.float().view(input_.size(0), 1, inp
         ut .size(1))) # (N, C in, L)
                 a1 = self.fcl(conv.view(input .size(0), -1))
                 a2 = self.fc2(a1)
                 a3 = self.out(a2)
                 y = self.out act(a3)
                  return y
In [21]: | conv model = ConvNet().to(DEVICE)
         conv_history = train(X_train, y_train, X_test, y_test, conv_mode
               epochs=15, verbose=5, learning rate=1e-3, criteria=criteri
         a, optimizer=optimizer)
         [001/015] train loss: 0.7083
                                           val loss 0.6931 train acc 0.4999
         val acc 0.4999
         [006/015] train_loss: 0.6931
                                           val loss 0.6931 train acc 0.5001
         val acc 0.4999
         [011/015] train_loss: 0.6931
                                           val loss 0.6931 train acc 0.4999
```

val loss 0.6931 train acc 0.5001

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val acc 0.4999

val acc 0.4999

[015/015] train loss: 0.6931

MODEL 3: SIMPLE RNN

Two of the best blogs that help understand the workings of a RNN and LSTM are

- 1. http://karpathy.github.io/2015/05/21/rnn-effectiveness/ (<a href="ht
- 2. http://colah.github.io/posts/2015-08-Understanding-LSTMs/ (http://colah.github.io/posts/2015-08-Understanding-LSTMs/)

Mathematically speaking, a simple RNN does the following. It constructs a set of hidden states using the state variable from the previous timestep and the input at current time. Mathematically, a simpleRNN can be defined by the following relation.

```
h_t = \sum(W([h_{t-1},x_{t}])+b)
```

If we extend this recurrence relation to the length of sequences we have in hand, we have our RNN network constructed.

Do simple RNN (keras, rf: SimpleRNN layer, pytorch: RNN layer) with 100 units with the input from embedding layer. How are the results different from the previous model?

```
In [22]: H emb = 100
          class RNNNet(nn.Module):
              def init (self):
                  super().__init__()
self.emb = nn.Embedding(vocabulary_size, H_emb)
                  self.rnn = nn.RNN(H emb, H)
                  self.dp1 = nn.Dropout(0.5)
                  self.fc1 = nn.Linear(D in * H, H)
                  self.dp2 = nn.Dropout(0.5)
                  self.out = nn.Linear(H, D out)
                  self.out act = nn.Sigmoid()
              def forward(self, input ):
                  emb = self.emb(input .long())
                  rnn, hid = self.rnn(emb)
                  rnn = self.dp1(rnn)
                  al = self.fcl(rnn.view((input .size(0), -1)))
                  a1 = self.dp2(a1)
                  a2 = self.out(a1)
                  y = self.out act(a2)
                  return y
```

```
In [241:
         rnn model = RNNNet().to(DEVICE)
         rnn_history = train(X_train, y_train, X_test, y_test, rnn_model,
               epochs=20, verbose=5, learning rate=1e-4, criteria=criteri
         a, optimizer=optimizer)
         [001/020] train loss: 0.7962
                                           val loss 0.6883 train acc 0.5377
         val acc 0.5865
         [006/020] train loss: 0.3621
                                           val loss 0.6388 train acc 0.8364
         val acc 0.6993
         [011/020] train loss: 0.2443
                                           val loss 0.6584 train acc 0.8953
         val acc 0.7383
         [016/020] train loss: 0.1821
                                           val loss 0.7017 train acc 0.9236
         val acc 0.7557
                                           val loss 0.7315 train acc 0.9400
         [020/020] train loss: 0.1467
         val_acc 0.7673
```

RNNs and vanishing/exploding gradients

Let us use sigmoid activations as example. Derivative of a sigmoid can be written as $\sigma'(x) = \sigma'(x) \cdot \sigma'(x) \cdot \sigma'(x)$.

Remember RNN is a "really deep" feedforward network (when unrolled in time). Hence, backpropagation happens from h_t all the way to h_1 . Also realize that sigmoid gradients are multiplicatively dependent on the value of sigmoid. Hence, if the non-activated output of any layer h_1 is < 0, then $\$ tends to 0, effectively "vanishing" gradient. Any layer that the current layer backprops to $H_{1:L-1}$ do not learn anything useful out of the gradients.

LSTMs and GRU

LSTM and GRU are two sophisticated implementations of RNN which essentially are built on what we call as gates. A gate is a probability number between 0 and 1. For instance, LSTM is built on these state updates

```
Note: L is just a linear transformation L(x) = W^*x + b.
```

 $C_t = f_t * C_{t-1}+i_t*hat{C}_t$ (Using the forget gate, the neural network can learn to control how much information it has to retain or forget)$

$$h_t = o_t * \tanh(c_t)$$

MODEL 4: LSTM

In the next step, we will implement a LSTM model to do classification. Use the same architecture as before. Try experimenting with increasing the number of nodes, stacking multiple layers, applyong dropouts etc. Check the number of parameters that this model entails.

```
In [53]: H emb = 100
         class LSTMNet(nn.Module):
             def __init___(self):
                 super(). init ()
                  self.emb = nn.Embedding(vocabulary_size, H_emb)
                  self.lstm = nn.LSTM(H emb, H)
                 self.dp1 = nn.Dropout(0.5)
                  self.fc1 = nn.Linear(D_in * H, H)
                  self.dp2 = nn.Dropout(0.5)
                 self.out = nn.Linear(H, D out)
                 self.out_act = nn.Sigmoid()
             def forward(self, input_):
                 emb = self.emb(input .long())
         #
                    print(emb.size())
                 lstm, hid = self.lstm(emb)
                 lstm = self.dp1(lstm)
                 a1 = self.fc1(lstm.view((input_.size(0), -1)))
                 a1 = self.dp2(a1)
                 a2 = self.out(a1)
                 y = self.out act(a2)
                 return y
```

```
In [54]: lstm model = LSTMNet().to(DEVICE)
         lstm history = train(X train, y train, X test, y test, lstm mode
         l,
               epochs=20, verbose=5, learning rate=1e-4, criteria=criteri
         a, optimizer=optimizer)
         [001/020] train loss: 0.7023 val loss 0.6595 train acc 0.5483
         val acc 0.6061
         KeyboardInterrupt
                                                    Traceback (most recent
         call last)
         <ipython-input-54-77bd1d4fa8d2> in <module>
               1 lstm model = LSTMNet().to(DEVICE)
               2 lstm history = train(X train, y train, X test, y test, ls
         tm model,
         ---> 3
                       epochs=20, verbose=5, learning rate=1e-4, criteria=
         criteria, optimizer=optimizer)
         <ipython-input-11-de9bc5ac7d9e> in train(X, y, X val, y val, mode
         l, epochs, verbose, learning rate, criteria, optimizer, batch siz
         e)
              59
                     history = []
                     for epoch in range(epochs):
              60
         ---> 61
                         train_loss, train_acc = fit_epoch(inputs, labels,
         model, criteria, optimizer)
                         val_loss, val_acc = eval_epoch(inputs_val, labels
         val, model, criteria)
         <ipython-input-11-de9bc5ac7d9e> in fit epoch(inputs, labels, mode
         l, criteria, optimizer)
              12
                         optimizer.zero grad()
              13
                         loss = criteria(output, batch y.float())
         ---> 14
                         loss.backward()
              15
                         optimizer.step()
              16
         ~/anaconda3/envs/ml ukma/lib/python3.7/site-packages/torch/tenso
         r.py in backward(self, gradient, retain_graph, create_graph)
             193
                                 products. Defaults to ``False``.
             194
         --> 195
                         torch.autograd.backward(self, gradient, retain gr
         aph, create_graph)
             196
             197
                     def register hook(self, hook):
         ~/anaconda3/envs/ml ukma/lib/python3.7/site-packages/torch/autogr
         ad/__init__.py in backward(tensors, grad_tensors, retain_graph, c
         reate_graph, grad_variables)
                     Variable. execution engine.run backward(
              97
              98
                         tensors, grad tensors, retain graph, create grap
         h,
                         allow unreachable=True) # allow unreachable flag
         ---> 99
             100
             101
```

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KeyboardInterrupt:

MODEL 5: CNN + LSTM

CNNs are good at learning spatial features and sentences can be thought of as 1-D spatial vectors (dimension being connotated by the sequence ordering among the words in the sentence.). We apply a LSTM over the features learned by the CNN (after a maxpooling layer). This leverages the power of CNNs and LSTMs combined. We expect the CNN to be able to pick out invariant features across the 1-D spatial structure(i.e. sentence) that characterize good and bad sentiment. This learned spatial features may then be learned as sequences by an LSTM layer followed by a feedforward for classification.

```
In [132]: H conv = 200
          H = 250
          k \text{ size} = 3
          p_size = 5
          class ConvLSTMNet(nn.Module):
              def init (self):
                   super().__init__()
                   self.c1 = nn.Conv1d(C in, H conv, k size, padding=k size
          //2)
                   self.p1 = nn.MaxPoolld(p size)
                   self.lstm = nn.LSTM(D in, H)
                   self.fc1 = nn.Linear((H_conv // p_size) * H, D_out)
                   self.out = nn.ReLU()
                   self.out act = nn.Sigmoid()
              def forward(self, input ):
                   c1 = self.c1(input .float().view(input .size(0), 1, input
          _.size(1)))
                   c1 = self.pl(c1.view(input .size(0), D in, H conv))
                  al, hid = self.lstm(c1.transpose(1, 2).transpose(0, 1))
                  a2 = self.fcl(a1.transpose(1,0).reshape((input_.size(0),
          -1)))
                   a3 = self.out(a2)
                   y = self.out_act(a3)
                   return y
```

```
In [133]: convlstm model = ConvLSTMNet().to(DEVICE)
          convlstm_history = train(X_train, y_train, X_test, y_test, convls
          tm model,
                epochs=20, verbose=5, learning rate=1e-3, criteria=criteri
          a, optimizer=optimizer)
          [001/020] train loss: 0.6932
                                            val loss 0.6931 train acc 0.5000
          val acc 0.4999
          [006/020] train loss: 0.6931
                                            val loss 0.6931 train acc 0.4999
          val acc 0.4999
          [011/020] train loss: 0.6931
                                            val loss 0.6931 train acc 0.5000
          val acc 0.4999
          [016/020] train loss: 0.6931
                                            val loss 0.6931 train acc 0.5000
          val_acc 0.4999
          [020/020] train loss: 0.6931
                                            val loss 0.6931 train acc 0.5001
          val acc 0.4999
```

CONCLUSION

We saw the power of sequence models and how they are useful in text classification. They give a solid performance, low memory footprint (thanks to shared parameters) and are able to understand and leverage the temporally connected information contained in the inputs. There is still an open debate about the performance vs memory benefits of CNNs vs RNNs in the research community.