

தேசிய வெளிக்கள நிலையம் தொண்டைமானாறு முதலாம் தவணைப் பரீட்சை - 2023

National Field Work Centre, Thondaimanaru. 1st Term Examination - 2023

Grade - 12 (2024)	ph	ysics	M	Larking Scheme
T=3.1415		E = me ² Nysics Liese 1		
01) 4	06) 5	11) 1	16) 3	21) 4
02) 3	07) 4	12) 3	17) 1	22) 1
03) 2	08) 4	13) 1	18) 5	23) 5
04) 5	09) 2	14) 4	19) 2	24) 3
05) 2	10) 1	15) 5	20) 5	25) 5
		0.1		

PART -ILA.

01/

- as To maintain vertical equillibrium in a horizontal plane (
- b) Located in the vertex of an equilateral triangle 2

1/ By adjusting the screw just to touch the image - 2

n,



1, adjust the screw to louch the curved surface -2

11/ 1/ 0.03 mm — (1) 2.70 mm — (2)

2/ 3.00 mm - (1)

14/

- 1/ Vernier calliper 0 internal jaw
- 2/ Press the spherometer on a white sheet and ______ ?

 measure the distance between the legs using the internal jaws.

$$R = \frac{5}{30 \times 30} + \frac{3}{2} = 50 + 1.5 - 0$$

$$= 51.5 \text{ mm} - 0.$$

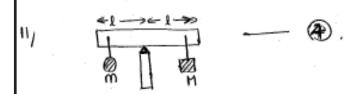
d, measuring the radius or large sphere - 2

20

		
02/		
9/		
, ', Å	Vertical adjustment knob	to adjust vertically
В	Focusing knob	to focus the object on the cross wire.
C	levelling screw	to adjust the plane
30 E	horizonial fine adjustment knob	to adjust horizontally
Gı	stage	10 keep the objects to be observed
b/ adjust	the egepiece until the cros	s while is cleanly seen — ②
· C1	screw F is not tightly	fixed ②.
d, 1, 0.01	mm — ①	
111 38	s·65 mm — ②.	
e, Yes -		
10 (obtain circular image of the	end through microscope.
F, (30)		
	W.	
9, No -	only the diameter of the	end is measured— ①
	ning the diameter of the uning the diameter of the	soap bubble, re thin rubber tube
	•	
		20

03/ a, to determine the centre of gravity point to avoid the mass of the metre ruler in the measurement

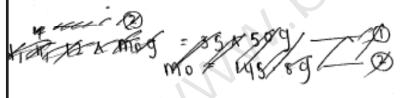
length measurements are approximately equal — (2) P1 11 509

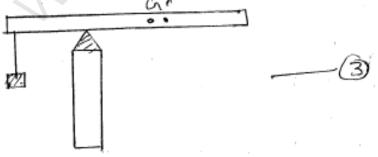


ml = HL -> mEML

Fractional error of length measurement To reduce the percentage

to avoid other forces contributing in the moment of metre ruler





Rii Rz - Reaction given by the floor

fi - by rotating the engine wheel

F2 - by rolling the wheel

To - resistive force given by air & Drag force

w - gravilational force.

2, A, energy used to rotate the wheel = 20 x4x107 = 8 × 10 g/1 -0.

Power used to rolate the wheel in zoms ! = 5x103 115

in time duration for 18 =
$$\frac{8 \times 10^6}{5 \times 10^3} = \frac{8000}{5}$$

= 1600 sec ___ 0 distance travelled in 1600 sec = 1600 x 2.0.

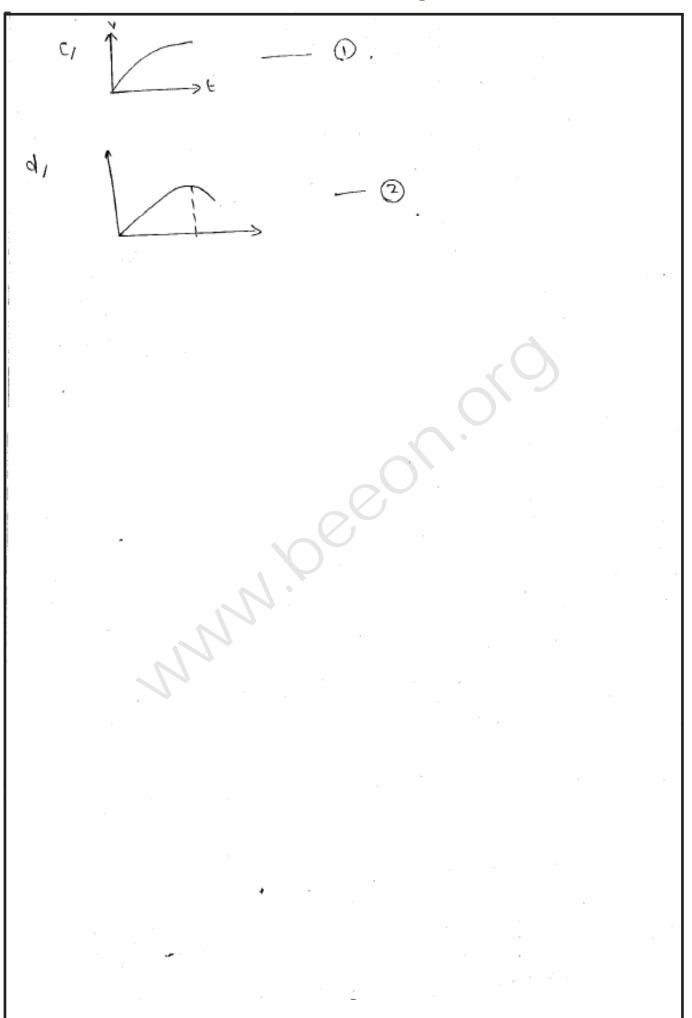
= 32000 M

fuel efficiency = 32 km/2 ___ O

B, Increase the Mictional Porce of Mont wheel - 2 decreasing the air resistive force / Thedraw the Areas

$$V_1 = KAPV^2$$

 $160 = KA2AI 2A20^2 - 0$.
 $K = 0.17 - 0$



osy Acceleration - gradient of the graph.

Displacement area of the graph.

a, ii) Rate of change of velocity

$$a_1 \text{ ii) Rate of change of } velocity$$

$$a_1 \text{ ii) Rate of change of } velocity$$

$$a_1 \text{ iii) } a = -\frac{V-D}{3}$$

$$-10 = -\frac{V}{3}$$

$$V = 30 \text{ ms}^{-1} - 0^{-1}$$
(III) At 4th sec

$$Velocity \text{ of } \text{ car } A = 40 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } B = 30 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } B = 30 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } B = 30 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } B = 30 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } B = 30 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } B = 30 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } B = 30 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } B = 30 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } B = 30 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } B = 30 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } A = 40 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } A = 40 \text{ ms}^{-1} \text{ (VAE)}$$

$$Velocity \text{ of } \text{ car } A = 40 \text{ ms}^{-1} \text{ (VAE)}$$

$$VAE$$

(vi) Distance travelled at 12 sec = 400m
.:
$$400 \text{ m} = \frac{1}{2} \times \left[(t-12) + (t-15) \right] \times 30$$
 ——①

$$2t - 2 = \frac{400 \times 2}{30} = \frac{80}{3}.$$

$$2t = \frac{80}{3} + 2 = \frac{80 \times 81}{3}$$

$$2t = \frac{80 \times 81}{3}$$

$$t = \frac{80 \times 81}{3}$$

$$t = \frac{80 \times 81}{3}$$

Car B.

Distance travelled = $-270 + \frac{1}{2} \times (14.83 + 9.83) \times 25 - 0$.

= -270 + 308.25= 38.25m (Right) -0.

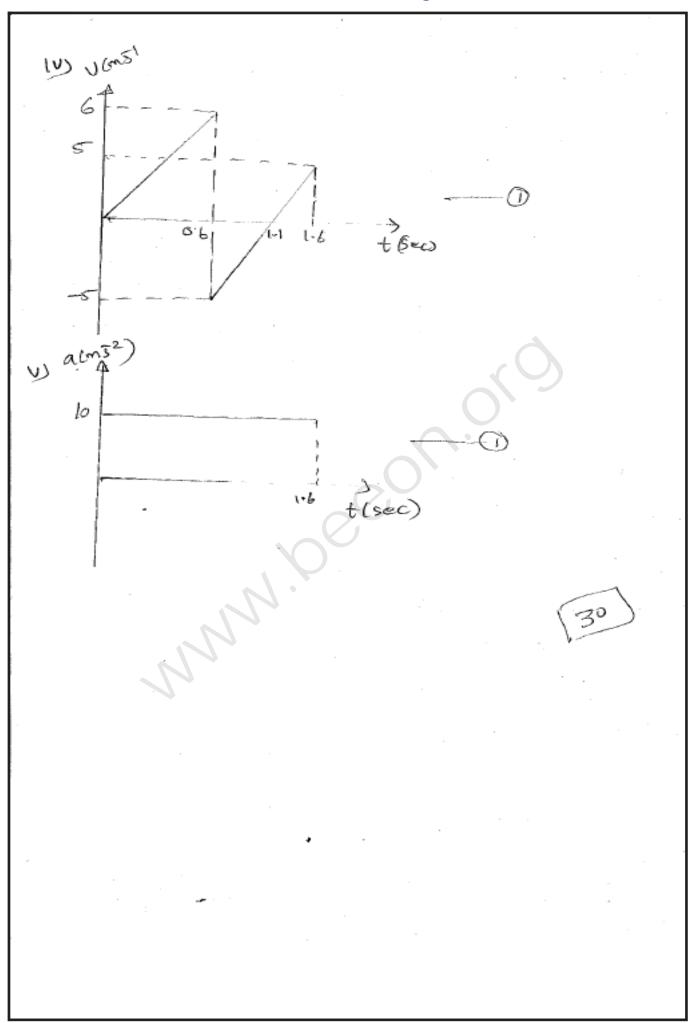
| Sm | Applying |
$$V^2 = U^2 + 2as$$
 | $V_1^2 = 0 + 2 \times 10 \times 1^{18}$ | $V_1^2 = 36$ | $V_1^2 = 36$ | $V_1 = 6 \text{ ms}^2$ | $V_1 = 6 \text{ ms}^2$ | $V_2 = 0 + 2 \times 10 \times 1^{18}$ | $V_1 = 6 \text{ ms}^2$ | $V_2 = 0 + 2 \times 10 \times 1^{18}$ | $V_2 = 0 + 2 \times 10 \times 1^{18}$ | $V_3 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_4 = 0 + 2 \times 10 \times 1^{18}$ | $V_5 = 0 + 2 \times 10 \times 1^{18}$ | $V_6 = 0 + 2 \times 10 \times 1^{18}$ | $V_7 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 1^{18}$ | $V_8 = 0 + 2 \times 10 \times 10 \times 10^{18}$ | $V_8 = 0 + 2 \times 10 \times 10^{18}$ | $V_8 = 0 + 2 \times 10 \times 10^{18}$ | $V_8 = 0 + 2 \times 10 \times 10^{18}$ | $V_8 = 0 + 2 \times 10 \times 10^{18}$ | $V_8 = 0 + 2 \times 10 \times 10^{18}$ | $V_8 = 0 + 2 \times 10 \times 10^{18}$ | $V_8 = 0 + 2 \times 10 \times 10^{18}$ | $V_8 = 0 + 2 \times 10^{18}$ | $V_8 = 0 + 2$

(III)
$$1 \text{ Szut} + \frac{1}{2} \text{at}^2$$

 $0 = 5 \times t - \frac{1}{2} \times 10t^2 - \text{ }$
 $5 t = 5t^2$
 $t = 15ec - \text{ }$

Time taken for $A \rightarrow B$ Applying $V_1 = U + at$ $6 = 10 \times t$ t = 0.6 sec.

Total time taken for and collision = 1 sec +0.6 sec = 1.6 sec -0



www.beeon.org

ob/al

till two forces acting on a point can be represented in "magnitude and direction by two adjacent sides of a parallelogram, then the resultant of the two forces will be represented in magnitude and direction by the diagonal of the parallelogram possing through that angular point:

—②

(11)yThe net external force on the system must be zero. — \bigcirc 2/The net torque on the system must be zero. — \bigcirc

(111) Stable

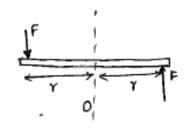


Unstable

Neutral



b/ (i)



Couple of forces = Fxd -0

Net moment about the axis 0 is

= Fxr + Fxr (anticlockwise) — ①

= 2Fr

= Fx2r ; d=2r

.. Net moment = couple of forces .

(III)
$$R = R \max \text{ when } \theta = \emptyset + \cos \theta = 1$$

$$R^{2}_{\max} = P^{2} + q^{2} + 2P\Phi$$

$$R^{2}_{\max} = (P + \Phi)^{2}$$

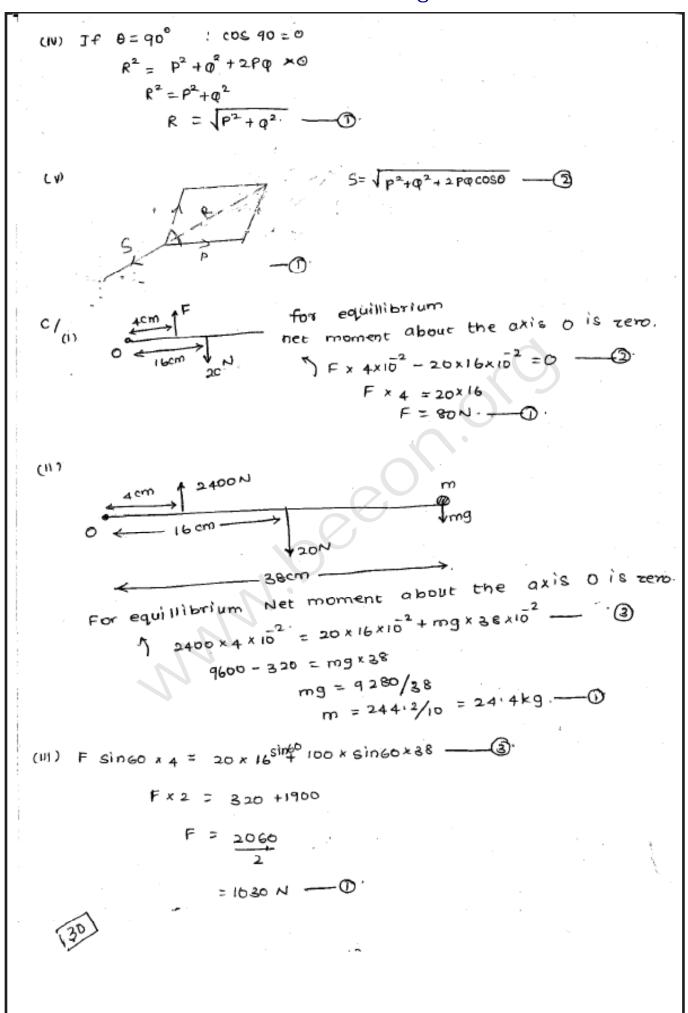
$$R_{\max} = P + \Phi$$

R = Rmin when
$$B = 180$$
; $\cos B = -1$ — ①

$$R_{min}^{2} = P_{r}^{2} + Q^{2} - 2PQ$$

$$R_{min}^{2} = (P - Q)^{2}$$

$$R_{min}^{2} = P - Q$$



of an isolated system remains the same in the absence of an external force. — 2

(1) using conservation of momentum.

Initial momentum = final momentum. $60\times0:1+0 = 1:5\times V$ $V = \frac{6}{1:5} = 4ms^{-1}$

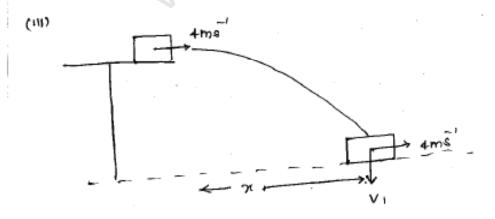
(11) Initial Energy E, =
$$\frac{1}{2} \times 0.1 \times 60^{2} = \frac{60 \times 60 \times 0.1}{2}$$

= 1805 - 0

Final Energy E2 = 1/2 × 1.5 × 42 = 123 - 0.

Percentage of energy loss = loss of energy x 1007.

No, Energy is lost in other forms such as sound, heat - 1.



For Block
Applying
$$\sqrt{s} = ut + \frac{1}{2}qt^2$$

$$0.8 = 0 + \frac{1}{2}t \cdot 10xt^2 - 0$$

$$t^2 = 0.16$$

$$t = 0.4 \sec - 0$$
Applying $\rightarrow s = ut + \frac{1}{2}at^2$

$$\pi = 4 \times \frac{4}{10} + 0 - 0$$

$$= 1.6 \text{ m} \cdot -0$$

Applying
$$\sqrt{v} = u + at$$

$$\sqrt{v} = 0 + 10 \times 0.4$$

$$\sqrt{v} = 4ms^{-1} - 0$$

$$\sqrt{u} = 4ms^{-1} + 1$$

$$\sqrt{u} = \sqrt{4^{2} + 4^{2}} = \sqrt{32} = 4\sqrt{2}ms^{-1} = 6.5ms^{-1} - 0$$

$$\sqrt{u} = 4s^{-1} + 1$$

$$0 = 4s^{-1} - 0$$

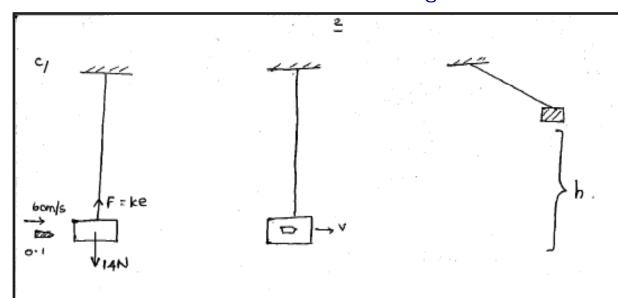
(11) loss of K.E = Friction force x distance
=
$$6 \times 1.5 - 0$$

= $9J - 0$

(III) Assume the final velocity is V.

Final K.E = Initial K.E-loss of K.E

$$V_2 mv^2 = V_2 mu^2 - q$$
 $V_2 \times 1.5 \times v^2 = V_2 \times 1.5 \times v^2 - q$
 $V_3 \times 1.5 \times v^2 = V_3 \times 1.5 \times v^2 - q$
 $V_4 \times 1.5 \times v^2 = V_3 \times 1.5 \times v^2 - q$
 $V_5 \times 1.5 \times v^2 = q$
 $V_5 \times 1.5 \times v^2 = q$



(40 Using conservation of Energy,

Initial Energy = Final Energy.

