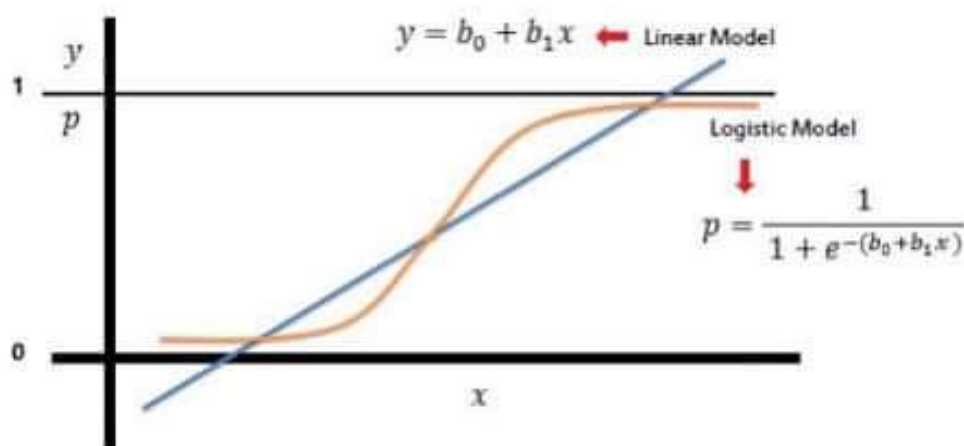


# logistic regression

Logistic Regression is a Supervised statistical technique to find the probability of dependent variable.

The Logistic Regression instead for fitting the best fit line, condenses the output of the linear function between 0 and 1.



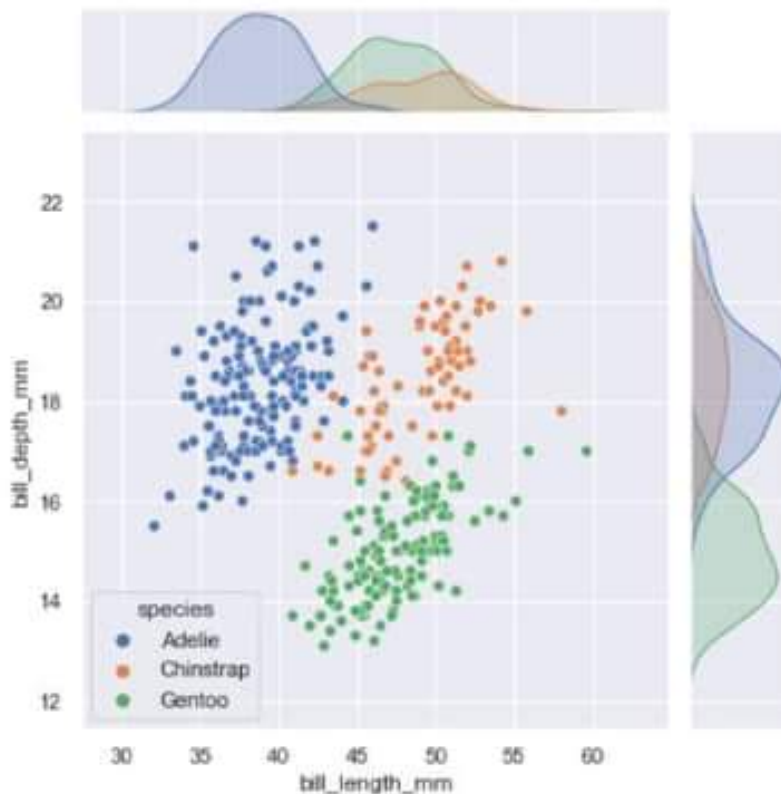
In the formula of the logistic model, when  $b_0 + b_1x = 0$ , then the  $p$  will be 0.5, similarly,  $b_0 + b_1x > 0$ , then the  $p$  will be going towards 1 and  $b_0 + b_1x < 0$ , then the  $p$  will be going towards 0.

# seaborn joint plot

```
import seaborn as sns
# Load Your Dataframe
penguins = sns.load_dataset("penguins")
# Visualize
sns.set_theme()
sns.jointplot(data=penguins, x="bill_length_mm", y="bill_depth_mm", hue="species")
```

executed in 381ms, finished 20:02:11 2022-05-10

<seaborn.axisgrid.JointGrid at 0x18b496fb130>



# bernoulli trial

In the theory of probability and statistics, a **Bernoulli trial** (or binomial trial) is a random experiment with exactly **two possible outcomes**, "success" and "failure", in which the probability of success is the **same** every time the experiment is conducted.

A random variable corresponding to a binomial experiment is denoted by  **$B(n,p)$** , and is said to have a binomial distribution. The probability of exactly  **$k$**  successes in the experiment  **$B(n,p)$**  is given by:

$$P(k) = \binom{n}{k} p^k q^{n-k}$$

where,

**$n$**  : number of experiments

**$k$**  : probability of success in  $k$  times

**$p$**  : probability of single success

**$q$**  : probability of single failure ( $1=1-p$ )

# poisson distribution

The Poisson distribution is a **discrete probability** distribution that expresses the probability of a given **number of events** occurring in a **fixed interval of time** or space if these events occur with a known constant mean rate and independently of the time since the last event.

A discrete random variable  $X$  is said to have a Poisson distribution, with parameter  $\lambda > 0$  if it has a probability mass function given by:

$$f(k; \lambda) = \Pr(X=k) = \frac{\lambda^k e^{-\lambda}}{k!}$$

where,

$k$  is the number of occurrences ( $k = 0, 1, 2, \dots$ )

$e$  is Euler's number ( $e = 2.71828\dots$ )

$!$  is the factorial function.

The positive real number  $\lambda$  is equal to the expected value of  $X$  and also to its variance.

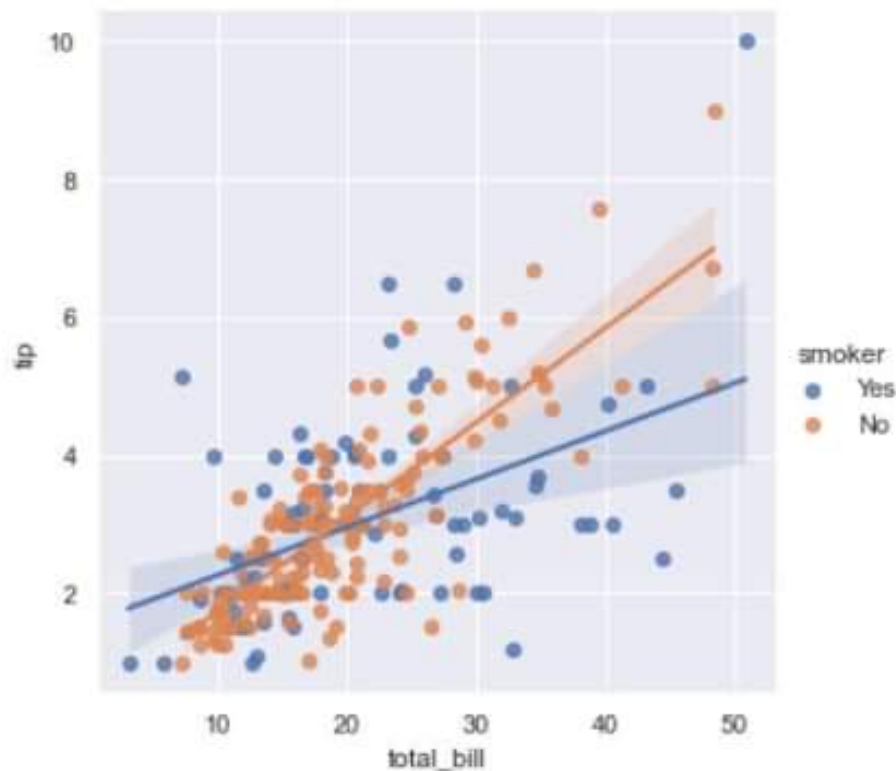
# seaborn

## scatter with regression

```
import seaborn as sns
# Load Your Dataframe
tips = sns.load_dataset("tips")
# Visualize
sns.set_theme()
sns.lmplot(x="total_bill", y="tip", hue="smoker", data=tips)
```

executed in 479ms, finished 17:15:38 2022-04-24

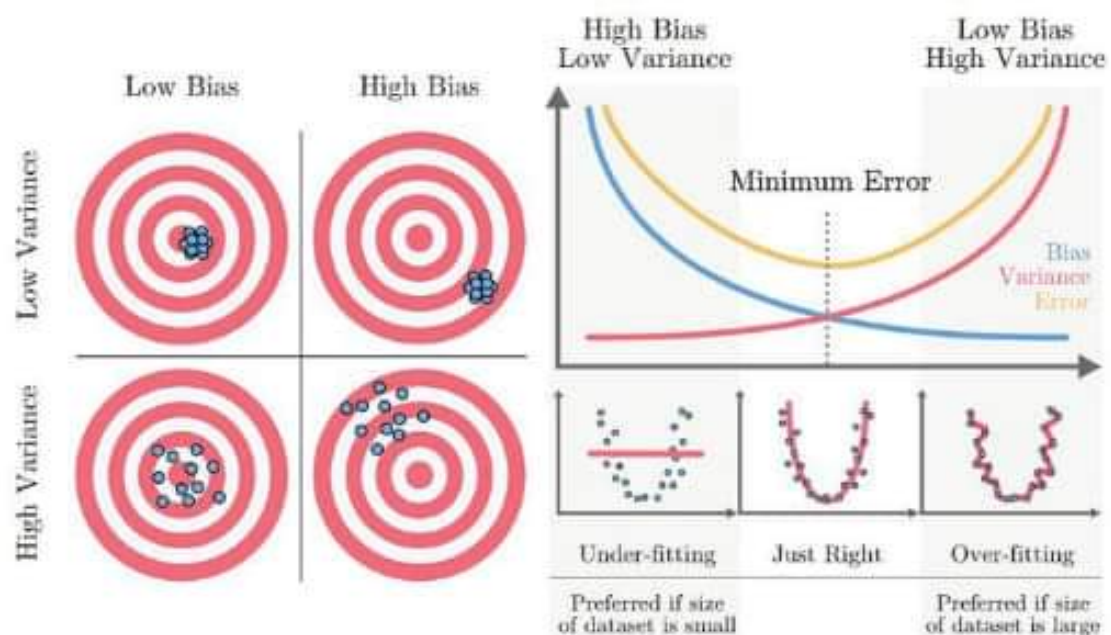
<seaborn.axisgrid.FacetGrid at 0x1f389ef2b80>





# bias-variance tradeoff

**Bias-variance** tradeoff is the property of a model that the **variance** of the parameter estimated across samples can be **reduced** by **increasing the bias** in the estimated parameters.



## Bias-variance Tradeoff

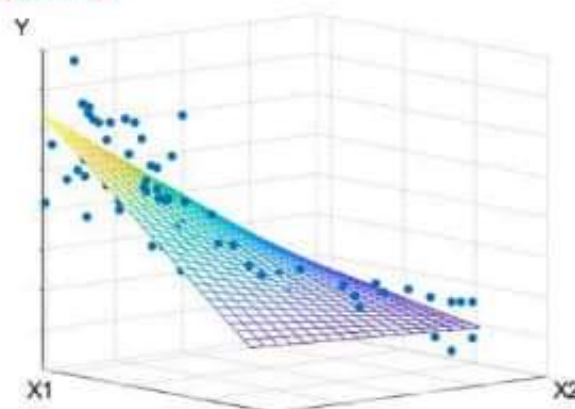
- **Increasing** bias (not always) **reduces** variance and vice-versa
- $\text{Error} = \text{bias}^2 + \text{variance} + \text{irreducible error}$
- The **best** model is where the **error** is reduced
- **Compromise** between bias and variance

# linear regression

A Linear Regression model representation is a linear equation :

$$y = \beta_0 + \beta_1 x_1 + \dots + \beta_i x_i$$

$\beta_0$  is usually called intercept or **bias** coefficient. The dimension of the hyperplane of the regression is its **complexity**.



Learning a LR means estimating the coefficients from the training data. Common methods include Gradient Descent or Ordinary Least Squares.

## Variations

Lasso Regression : where OLS is modified to minimize the **sum** of the coefficients (**L1 regularization**)

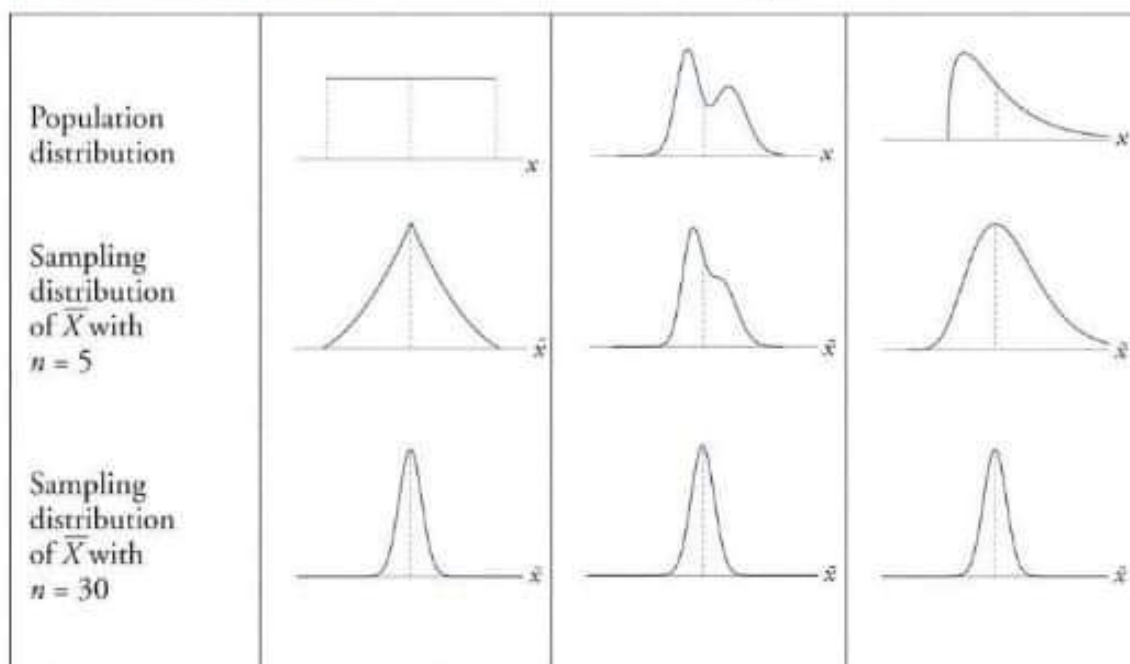
Ridge Regression : where OLS is modified to minimize the **squared sum** of the coefficients (**L2 regularization**)

# central limit theorem

For **large** sample sizes, the sampling distribution of **means** will approximate to **normal distribution** even if the population distribution is not normal.

**Mean** of the sample means is computed as  $\mu_{\bar{X}} = \mu$

And the **standard deviation** of sample means  $\sigma_{\bar{X}} = \frac{\sigma}{\sqrt{n}}$



Above picture, shows 3 different **population** distributions which are **not normal**. **Sampling** distribution of **means** gets a little closer to normal distribution when we take  $n = 5$  and almost normal distribution when  $n = 30$



# the law of large number

**The law of large numbers** is a theorem that describes the result of performing the same experiment a large number of times. According to the law, the **average** of the results obtained from a large number of trials should be **close** to the **expected value**.

as  $n \rightarrow \infty$ , the sample mean  $\langle x \rangle$  equals the population **mean**  $\mu$  of each variable.

$$\begin{aligned}\langle X \rangle &= \left\langle \frac{X_1 + \dots + X_n}{n} \right\rangle \\ &= \frac{1}{n} (\langle X_1 \rangle + \dots + \langle X_n \rangle) \\ &= \frac{n \mu}{n} \\ &= \mu.\end{aligned}$$

**Example** : Law of large numbers in **Insurance**

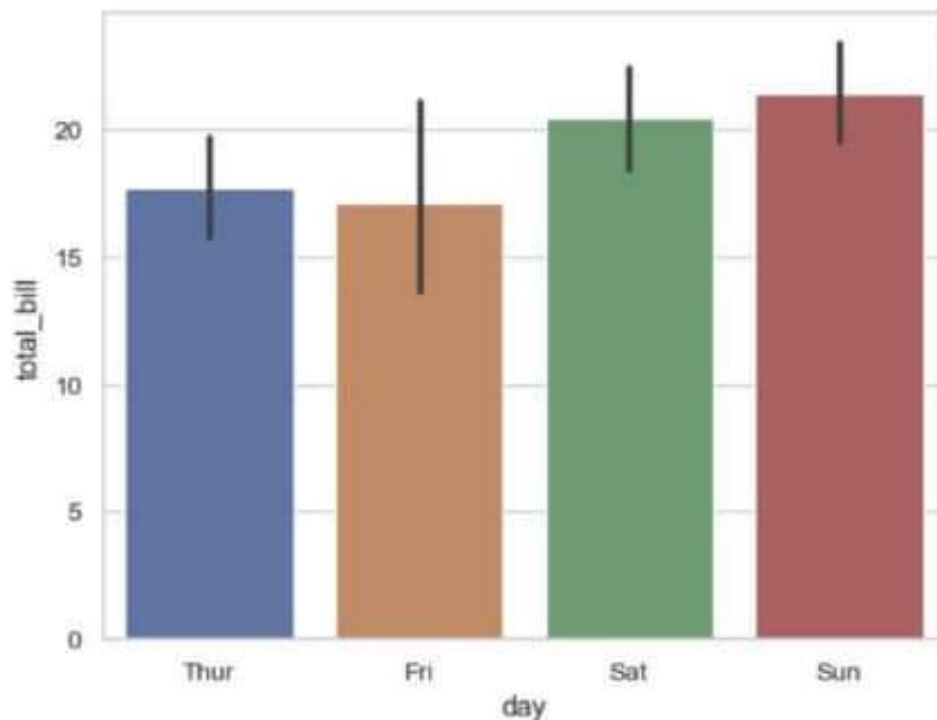
Imagine **500** people **paying** a **premium** for his property to the Insurance. Even though they pay you for the property damage that was caused by fire to **10%** of the subscriber i.e. **50** people they have the premium of **450 people still**. And that's how they calculate their risk management and the Law of Large Numbers comes in the role.

# seaborn simple barchart

Draw a set of vertical bar plots grouped by a categorical variable:

```
>>> import seaborn as sns
>>> sns.set_theme(style="whitegrid")
>>> tips = sns.load_dataset("tips")
>>> ax = sns.barplot(x="day", y="total_bill", data=tips)
```

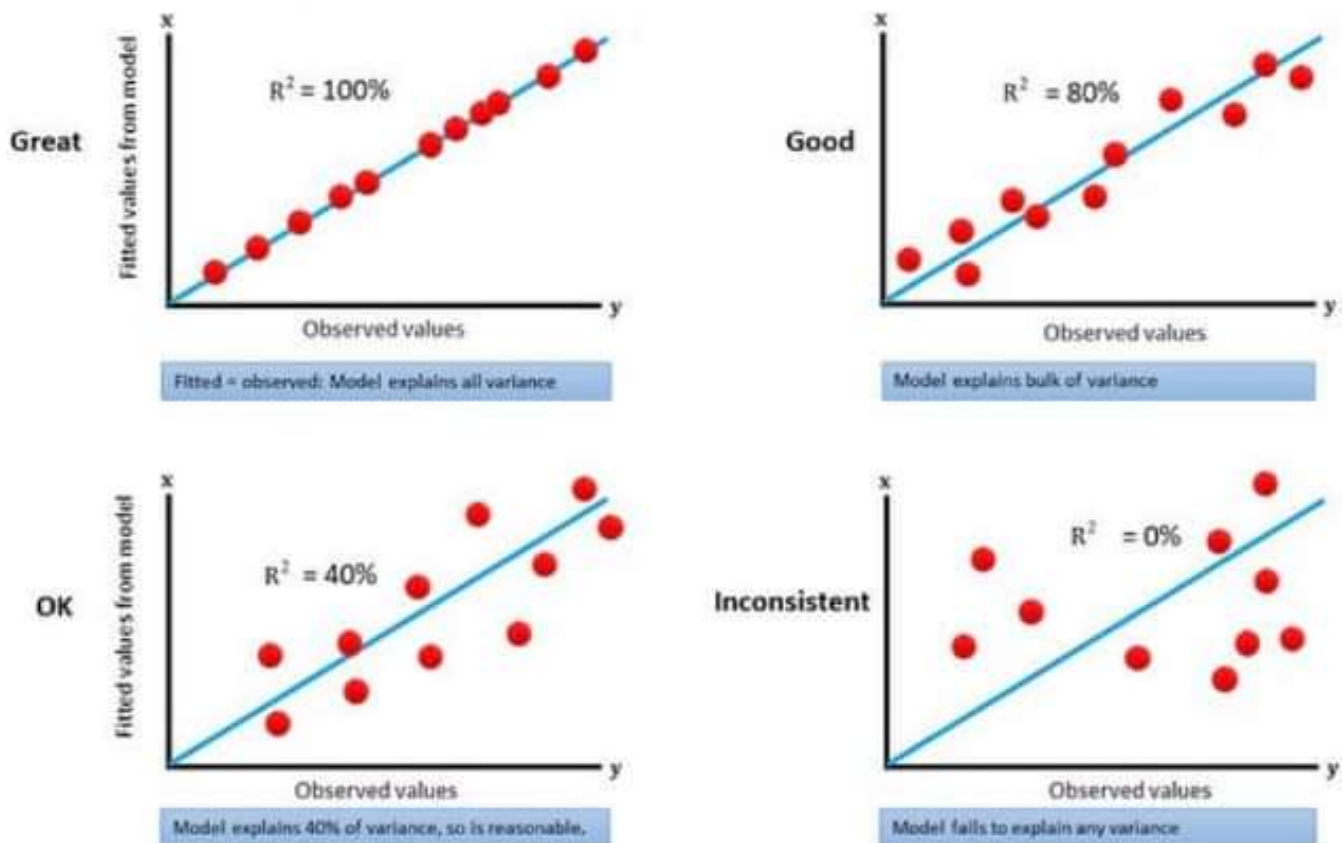
*your dataframe* →



# R-Square

R-square( $R^2$ ) is also known as the **coefficient of determination**, It is the **proportion** of variation in **Y explained by** the independent variables **X**. It is the measure of goodness of fit of the model.

Comparison of R-Squared for Different Linear Models (Same Data Set)



If  $R^2$  is 0.8 it means **80% of the variation** in the output can be explained by the **input variable**.

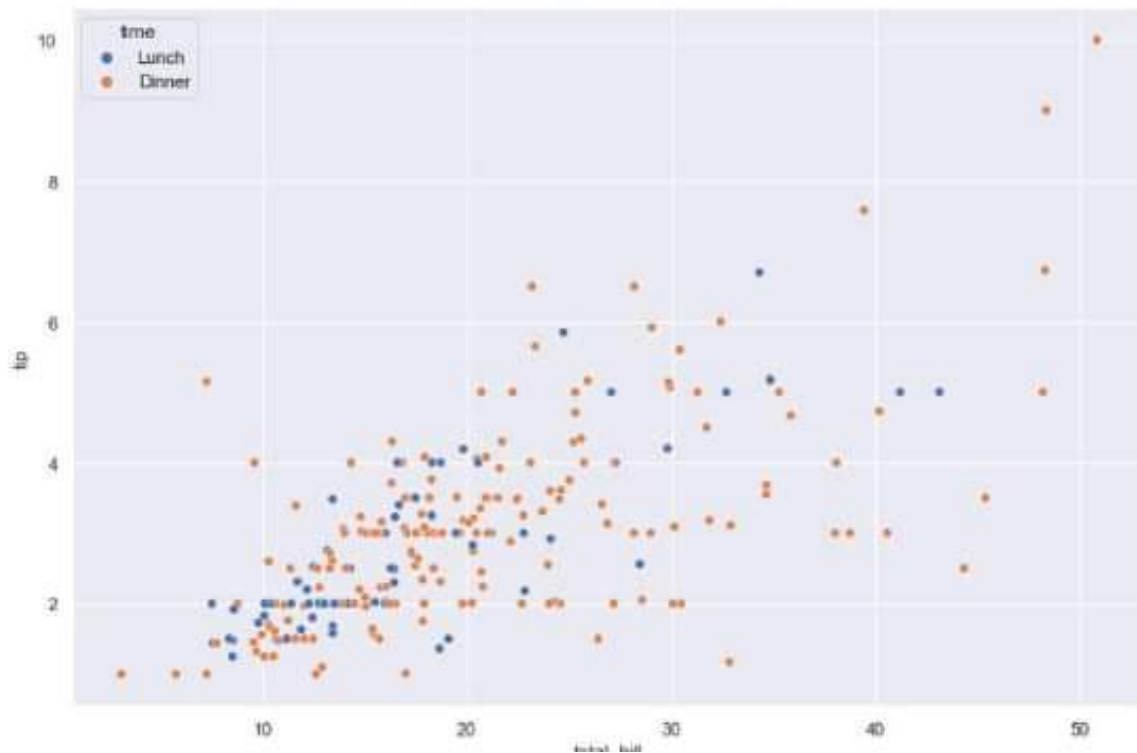
# seaborn basic scatterplot

```
import seaborn as sns

# Load Your Dataframe
tips = sns.load_dataset("tips")

# Plot Scatter with Hue

# Set Theme
sns.set_theme()
# Set figure size
sns.set(rc={'figure.figsize':(12,8)})
# Visualize
sns.scatterplot(data=tips, x="total_bill", y="tip", hue="time")
```



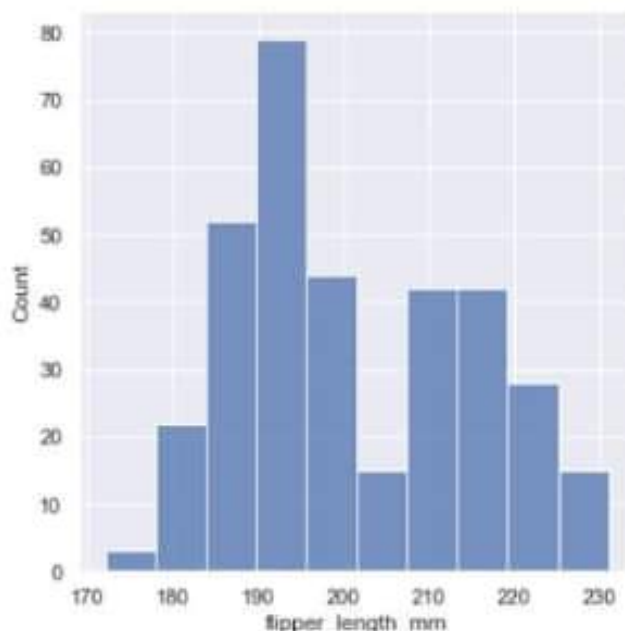
# seaborn

## basic histogram

```
import seaborn as sns
# Load Your Dataframe
penguins = sns.load_dataset("penguins")
# Visualize
sns.set_theme()
sns.displot(penguins, x="flipper_length_mm")
```

executed in 200ms, finished 17:41:58 2022-04-24

<seaborn.axisgrid.FacetGrid at 0x1bd3632d250>





# bayes theorem

In **probability theory** and **statistics**, Bayes' theorem named after Thomas Bayes, describes the **probability** of an event, based on **prior knowledge** of conditions that might be related to the event. (Wikipedia)

$$P(A \mid B) = \frac{P(B \mid A) \cdot P(A)}{P(B)}$$

where

$A, B$  = events

$P(A|B)$  = probability of A given B is true

$P(B|A)$  = probability of B given A is true

$P(A), P(B)$  = the independent probabilities of A and B

# mean squared error

Mean Squared Error / MSE is one of the most common **regression loss functions**. Mean Squared Error also known as **L2 loss**, we calculate the error by **squaring the difference** between the **predicted** value and **actual** value and **averaging** it across the dataset.

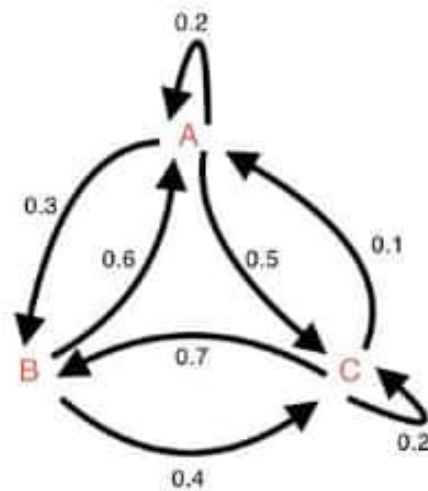
$$\text{MSE} = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

MSE is also known as **Quadratic loss** as the penalty is not proportional to the error but to the **square of the error**. Squaring the error gives higher **weight** to the **outliers**, which results in a smooth gradient for small errors.

A **good** model will have MSE value **closer to zero**.

# markov chain model

A **Markov chain** is a stochastic model created by Andrey Markov, which outlines the **probability** associated with a **sequence of events occurring** based on the state in the **previous event**.



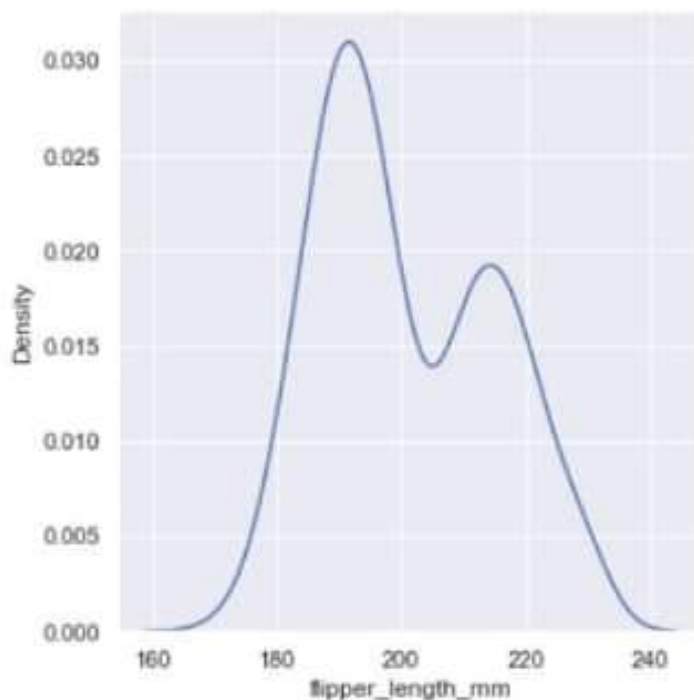
A very common **application** of Markov chains in data science is **text prediction**. It's an **area of NLP** which is commonly used in the tech industry by companies like Google, LinkedIn and Instagram. When you're writing emails, google predicts and **suggests you words/phrases** to autocomplete your email, when you receive messages on Instagram or LinkedIn, the app suggests some potential replies.

# seaborn density plot (KDE)

```
import seaborn as sns
# Load Your Dataframe
penguins = sns.load_dataset("penguins")
# Visualize
sns.set_theme()
sns.displot(penguins, x="flipper_length_mm", kind="kde")
```

executed in 174ms, finished 17:11:20 2022-04-24

<seaborn.axisgrid.FacetGrid at 0x20b1ff64490>

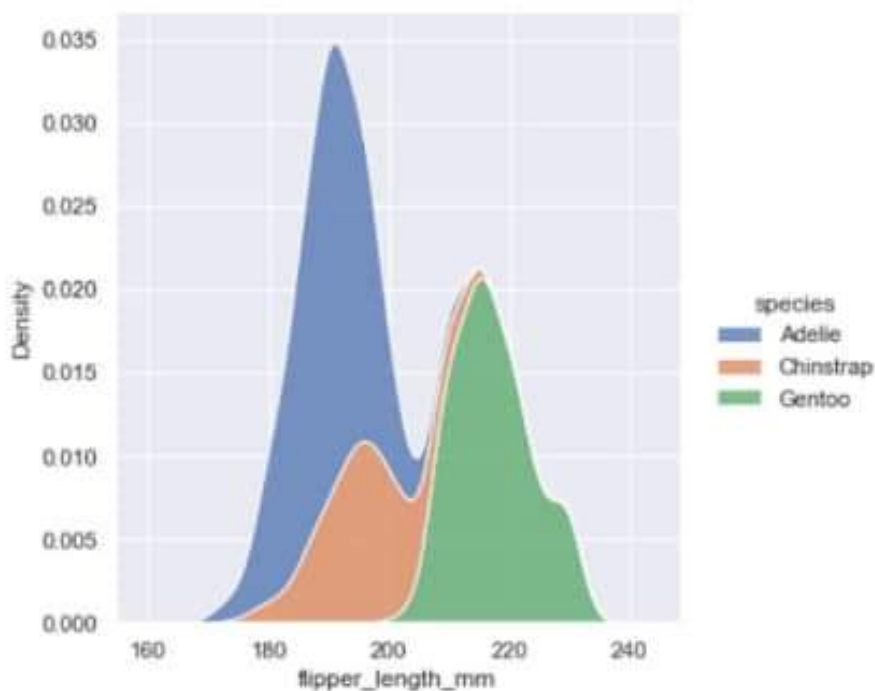


# seaborn KDE plot with hue

```
import seaborn as sns
# Load Your Dataframe
penguins = sns.load_dataset("penguins")
# Visualize
sns.set_theme()
sns.displot(penguins, x="flipper_length_mm", hue="species", kind="kde", multiple="stack")
```

executed in 289ms, finished 17:49:08 2022-04-24

<seaborn.axisgrid.FacetGrid at 0x1bd3630eee0>

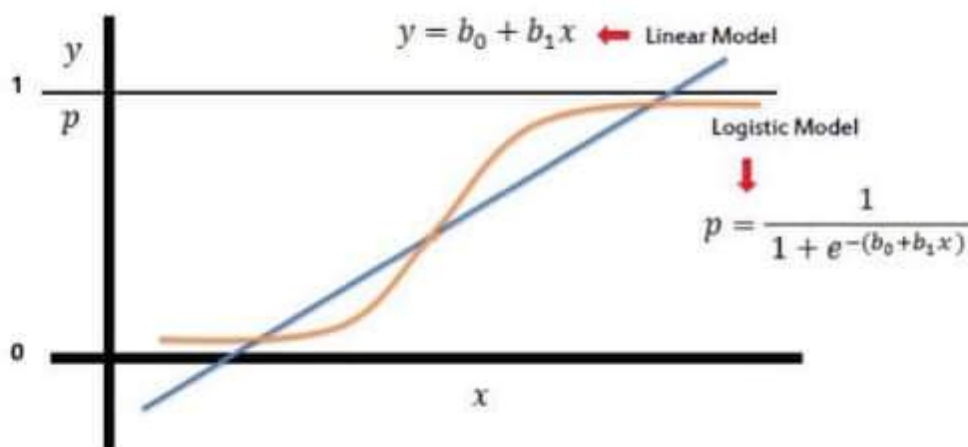




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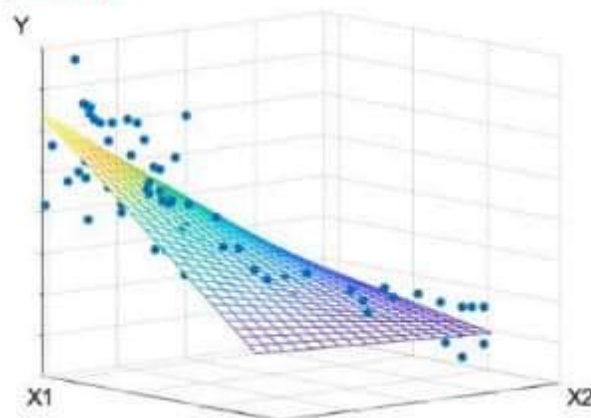
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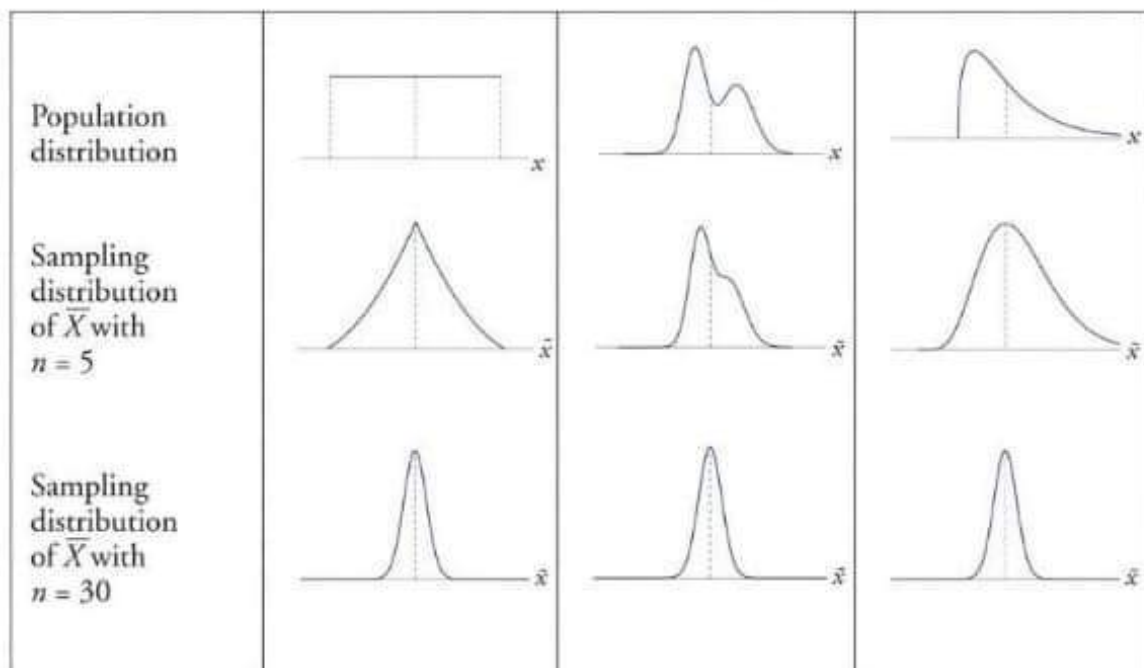
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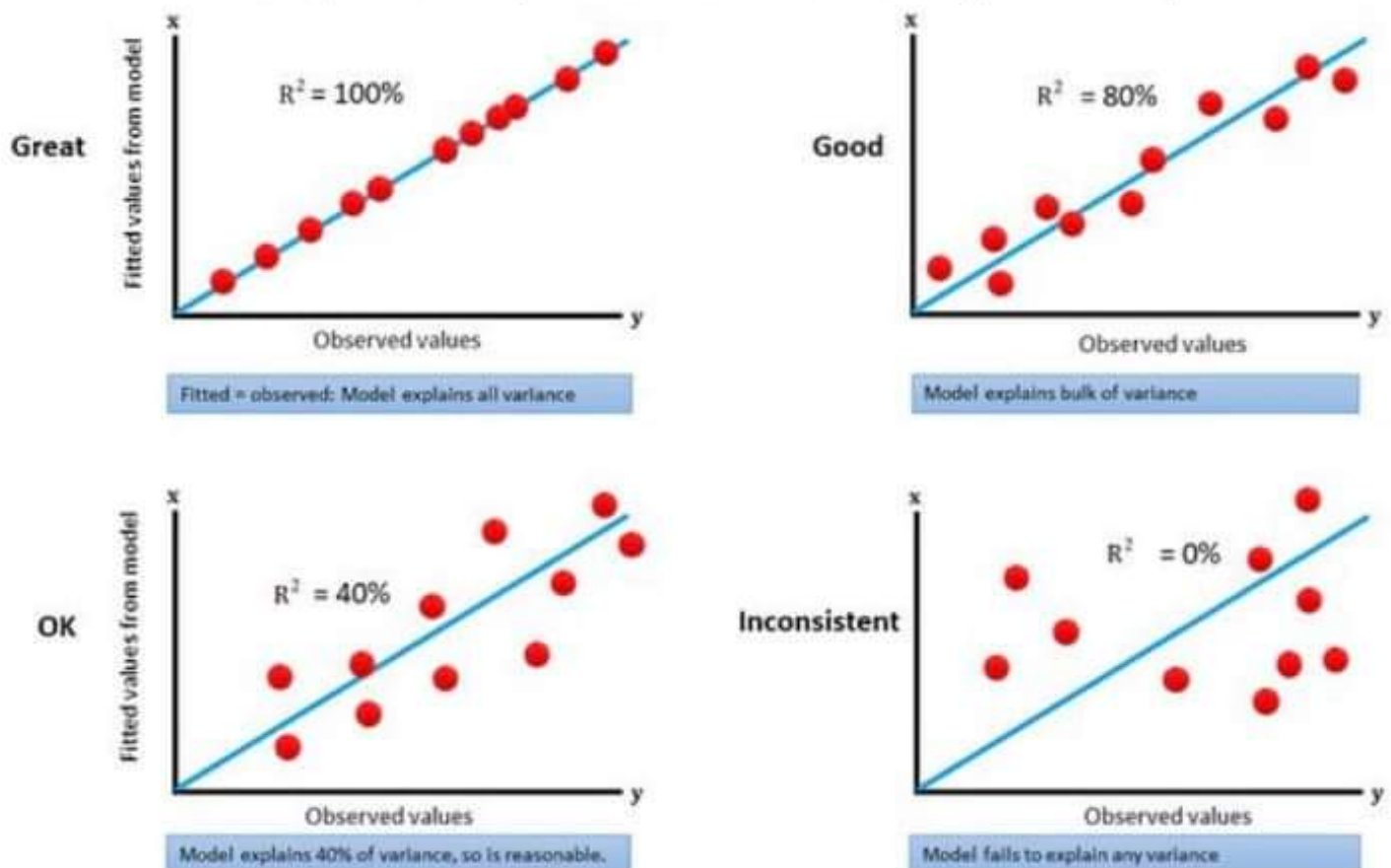


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# R-Square

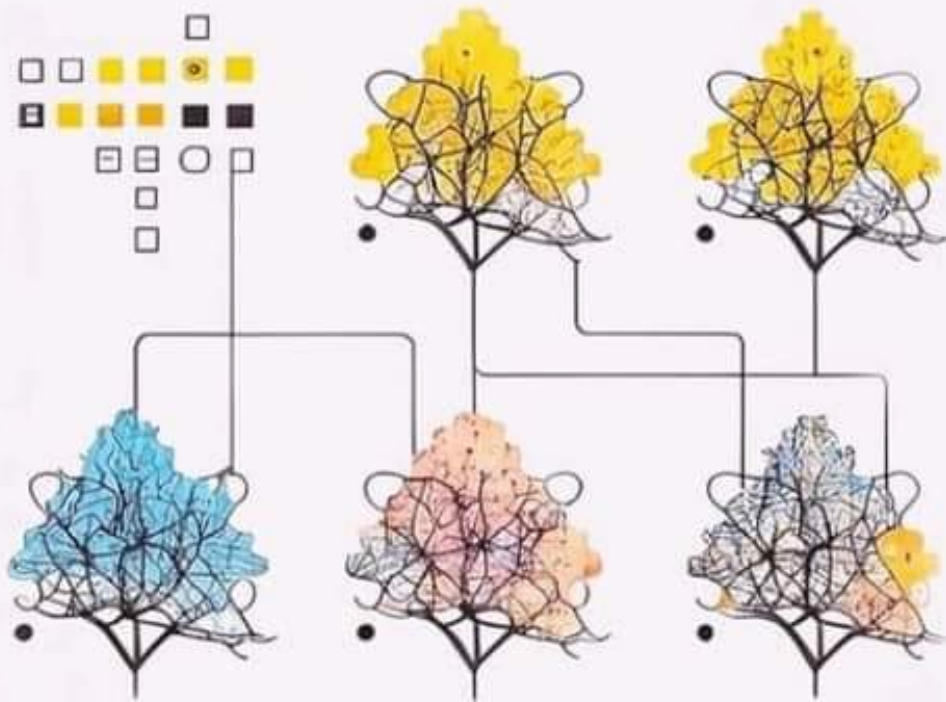
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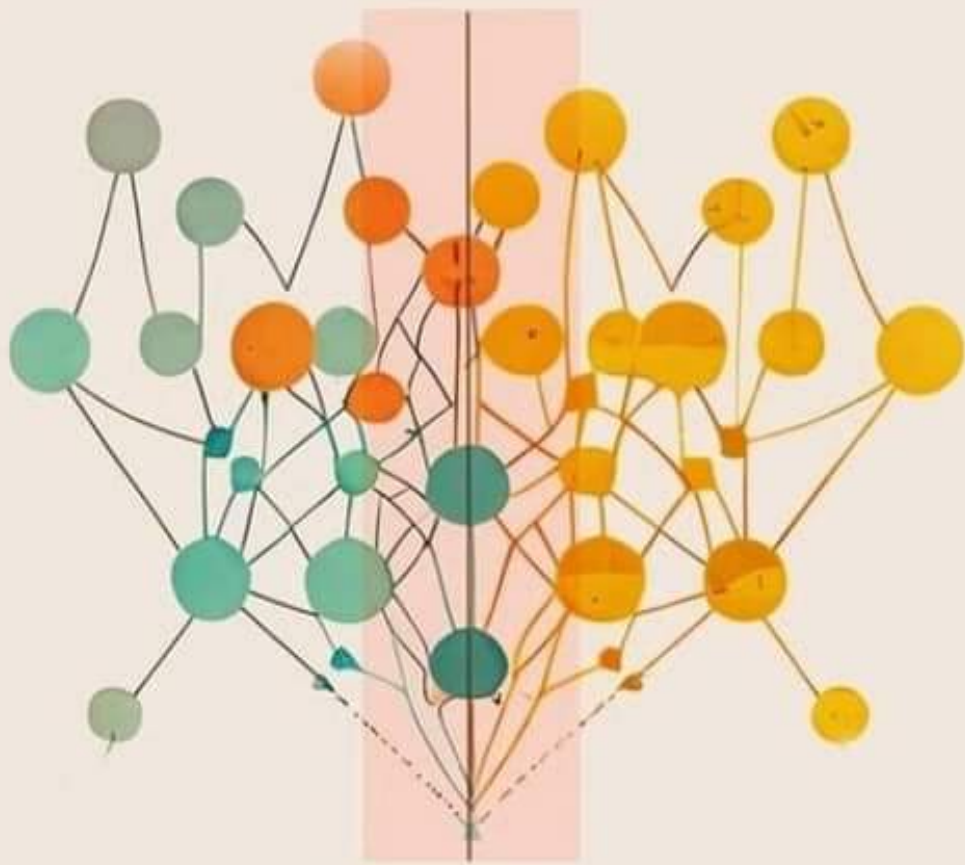




# Random Forest

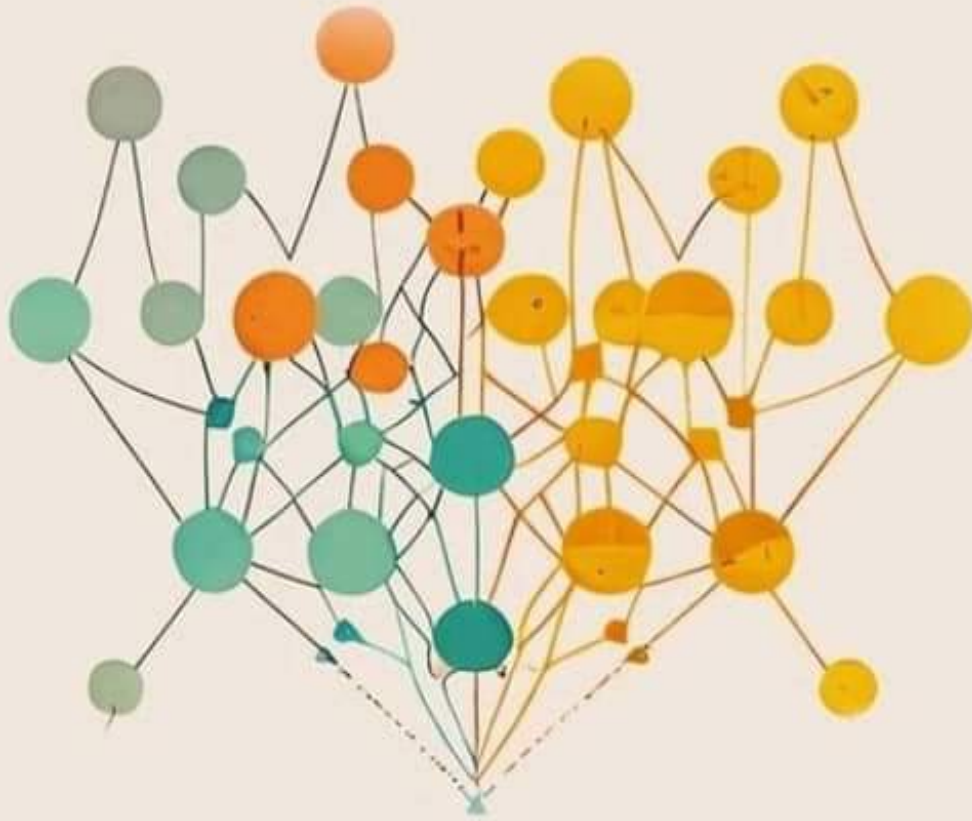
A random forest is a type of ensemble learning algorithm that trains multiple decision trees on random subsets of the data and then combines their predictions to make a final prediction. This can improve the performance of the model compared to using a single decision tree.





# Support Vector Machines

Support vector machines (SVMs) are a type of machine learning algorithm that is used for classification and regression tasks, and finds the hyperplane that maximally separates the classes in the data.



# Nearest Neighbour

Nearest neighbor is a type of machine learning algorithm that makes predictions for a sample by finding the most similar samples in the training data and using their labels to make a prediction.