Linear Transformations

- **DEFINITION** (Linear Transformation): A transformation (or mapping) T from a vector space V_1 to a vector space V_2 , $T: V_1 \to V_2$ is a linear transformation (or a linear operator, a linear map, etc.), if:
 - (i) $T(\vec{\mathbf{u}} + \vec{\mathbf{v}}) = T\vec{\mathbf{u}} + T\vec{\mathbf{v}}$ for all vectors $\vec{\mathbf{u}}, \vec{\mathbf{v}}$ in V_1 ; and
 - (ii) $T(c\vec{\mathbf{u}}) = cT\vec{\mathbf{u}}$ for all vectors $\vec{\mathbf{u}}$ in V_1 and all scalars c.
- **EQUIVALENT DEFINITION (Linear Transformation):** A transformation $T: V_1 \rightarrow V_2$ is a *linear transformation* if:

 $T(a\vec{\mathbf{u}} + b\vec{\mathbf{v}}) = aT\vec{\mathbf{u}} + bT\vec{\mathbf{v}}$ for all vectors $\vec{\mathbf{u}}, \vec{\mathbf{v}}$ in V_1 and all scalars a, b.

BASIC FACTS:

- If T is a linear transformation, then $T\mathbf{0}$ must be $\mathbf{0}$. (So if you find $T\mathbf{0} \neq \mathbf{0}$, that means your T is not a linear transformation.)
- Any linear transformation $T: \mathbb{R}^n \to \mathbb{R}^m$ can be given by a matrix A of type $m \times n$, $T(\vec{\mathbf{u}}) = A\vec{\mathbf{u}}$ for vectors $\vec{\mathbf{u}}$ in \mathbb{R}^n .

EXAMPLES: The following are linear transformations.

• $T: \mathbb{R}^5 \to \mathbb{R}^2$ defined by

$$T\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2x_2 - 5x_3 + 7x_4 + 6x_5 \\ -3x_1 + 4x_2 + 8x_3 - x_4 + x_5 \end{bmatrix},$$

or equivalently,

$$T\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 & 2 & -5 & 7 & 6 \\ -3 & 4 & 8 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix}.$$

- Scaling (expansion by factor 5): $T: \mathbb{R}^3 \to \mathbb{R}^3$ with matrix $\begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}$.
- Scaling (contraction by factor 1/3): $T: \mathbb{R}^2 \to \mathbb{R}^2$ with matrix $\begin{bmatrix} 1/3 & 0 \\ 0 & 1/3 \end{bmatrix}$.
- Scaling in certain direction: $T: \mathbb{R}^2 \to \mathbb{R}^2$ with matrix $\begin{bmatrix} 5 & 0 \\ 0 & 1 \end{bmatrix}$.
- Rotation in \mathbb{R}^2 about the origin by angle $\pi/3$ counterclockwise: $T: \mathbb{R}^2 \to \mathbb{R}^2$ with matrix $\begin{bmatrix} \cos(\pi/3) & -\sin(\pi/3) \\ \sin(\pi/3) & \cos(\pi/3) \end{bmatrix} = \begin{bmatrix} 1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & 1/2 \end{bmatrix}.$
- Reflection in \mathbb{R}^2 through the x_2 axis: matrix $\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$.
- Orthogonal projection in \mathbb{R}^3 onto the x_1x_3 -plane: matrix $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.
- Orthogonal projection in \mathbb{R}^3 onto the plane $x_1 2x_2 + 2x_3 = 0$: matrix $\frac{1}{9} \begin{bmatrix} 8 & 2 & -2 \\ 2 & 5 & 4 \\ -2 & 4 & -5 \end{bmatrix}$.
- A horizontal shear in \mathbb{R}^2 : matrix $\begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}$.
- $T: C[-\pi, \pi] \to \mathbb{R}$, defined by $Tf = \int_{-\pi}^{\pi} f(x) \sin(3x) dx$.
- $T: C^1[0,1] \to \mathbb{R}$, defined by Tf = f'(1) + 3f(1).
- $T: C^2[0,3] \to C[0,3]$, defined by $Tf(x) = -x^2 f''(x) 3x f'(x) + e^x f(x)$.

EXAMPLES: The following are NOT linear transformations.

• $T: \mathbb{R}^5 \to \mathbb{R}^2$ defined by

$$T\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2x_2 - 5x_3 + 7x_4 + 6x_5 + 777 \\ -3x_1 + 4x_2 + 8x_3 - x_4 + x_5 \end{bmatrix}.$$

- $T: \mathbb{R} \to \mathbb{R}, T(x) = \frac{x^2}{x^2}$.
- $T: \mathbb{R}^3 \to \mathbb{R}^2$, $T \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 + 2\sin(x_2) 4x_3 \\ x_2 + 2x_3 \end{bmatrix}$.
- $T: \mathbb{R}^2 \to \mathbb{R}$ defined by

$$T\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{cases} 2x_1 - 3x_2 & \text{if } x_1 \ge 0, \\ 4x_1 - 3x_2 & \text{if } x_1 < 0. \end{cases}$$

(Check whether or not $T\begin{bmatrix} -3 \\ 0 \end{bmatrix} = -3T\begin{bmatrix} 1 \\ 0 \end{bmatrix}$. If not satisfied, this T is not linear.)

- $T: C^2[0,1] \to C[0,1], Tf = f'' + 1 f.$
- $\bullet \ T: C^2[0,1] \to C[0,1], \ Tf = f'' + f {\color{red} e^f}.$

EXERCISES

Are the following mappings linear transformations?

1.
$$T: \mathbb{R} \to \mathbb{R}, T(x) = 3x$$
.

$$2. T: \mathbb{R} \to \mathbb{R}, T(x) = 3x - 2.$$

3.
$$T: \mathbb{R} \to \mathbb{R}, T(x) = x^3$$
.

4.
$$T: \mathbb{R} \to \mathbb{R}, T(x) = (x+3)^2 - x^2 - 9.$$

5.
$$T: \mathbb{R}^2 \to \mathbb{R}^3, T \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
.

6.
$$T: \mathbb{R}^2 \to \mathbb{R}^3$$
, $T \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$.

7.
$$T: \mathbb{R}^2 \to \mathbb{R}^3$$
, $T\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \sin(x_1 + x_2) \\ 0 \\ 0 \end{bmatrix}$.

8.
$$T: \mathbb{R}^3 \to \mathbb{R}^3$$
, $T \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 + x_3 \\ x_2 + 5x_3 \\ x_1 \end{bmatrix}$.

9.
$$T: C[0,1] \to C[0,1], Tf(x) = \int_0^1 f(y) \sin(x-y) dy.$$

10.
$$T: C[0,1] \to \mathbb{R}, Tf = \int_0^1 f^2(y) dy$$
.

11.
$$T: C^1[0,1] \to \mathbb{R}, Tf = f'(0)f(0).$$

12.
$$T: C^1[0,1] \to \mathbb{R}, Tf = f'(0) - f(0).$$

13.
$$T: C^4[0,1] \to C[0,1], Tf(x) = -\frac{d^4f}{dx^4}(x) + \frac{d^2f}{dx^2}(x) + f(x).$$

14.
$$T: C^4[0,1] \to C[0,1], Tf(x) = -\frac{d^4f}{dx^4}(x) + \frac{d^2f}{dx^2}(x) + (1+x^2)f(x).$$

15.
$$T: C^4[0,1] \to C[0,1], Tf(x) = -\frac{d^4f}{dx^4}(x) + \frac{d^2f}{dx^2}(x) + 1 + f(x)^2.$$