

Docker Swarm

Objectives

- Docker Swarm capabilities and terminology
- Demonstrate docker swarm

Docker Swarm

- Current versions of Docker include *swarm mode*
 - Support for natively managing a cluster of Docker Engines called a swarm.
- What is a swarm?
 - Multiple Docker hosts running in swarm mode
 - They can be ...
 - Managers (to manage membership and task delegation)
 - Workers (to run swarm services)
 - Or both.

Docker Swarm

- You create *services* on a swarm
 - Define optimal state – number of replicas, network and storage resources, ports exposed etc.
- Docker works to maintain that desired state
 - If a worker node becomes unavailable, Docker schedules that node's tasks on other nodes.
- A *task* is a running container which is part of a swarm service and managed by a swarm manager, as opposed to a standalone container.

Advantage and Features

- Modify a service's configuration without needing to (manually) restart the service
 - Including modifying networks and volumes it is connected to.
 - Docker updates the configuration and does the stopping and starting needed on the tasks.
- While Docker is running in swarm mode, you can still run standalone containers on any of the Docker hosts in the swarm.
 - But only swarm managers can manage a swarm.
- You can define and run Swarm Service stacks in the same way you use Docker Compose.

Key Concepts

- **Nodes** (or Docker Node)
 - Instance of the Docker Engine participating in the swarm.
 - Typically nodes are distributed across multiple physical and cloud machines.
- **Manager Node**
 - A service definition is submitted to a manager node, which dispatches work units (tasks) to **Worker Nodes**.

Key Concepts

- **Services and Tasks**

- A **Service** is the definition of the tasks that the swarm executes.
- It is the central structure of the swarm system & root of user interaction
- A **Task** carries a Docker container and the commands to run in that container.
- **Replicated Services**: manager distributes a specific number of tasks among the nodes.
- **Global Services**: manager runs one task for the service on every available node.

- **Load balancing**

- The swarm manager uses **Ingress Load Balancing** to make services available externally to the swarm.
- The swarm manager uses **internal load balancing** to distributed requests among nodes in the cluster.

Getting Started with Swarm

- You need at least 3 linux machines with docker installed.
- On the command line in the manager machine type

```
$ docker swarm init --advertise-addr 172.31.9.64
```

Your IP address in here

- This brings up a very long command you need to copy to join the swarm:

Getting started with a swarm

Swarm initialized: current node (oyaymj9ee49ivwa3siy55yv1y) is now a manager.

To add a worker to this swarm, run the following command:

```
docker swarm join --token SWMTKN-1-  
05p3cwhydsf13or53hr1kryawkuys0p4rpkdrgxi232iww4102-648g6iyo3xyze9x52o8yhb  
172.31.9.64:2377
```

To add a manager to this swarm, run 'docker swarm join-token manager' and follow the instructions.

Copy this!

Starting a swarm

- You can see the current state of the swarm using `$docker info`:

```
$ docker info
Containers: 11
  Running: 5
  Paused: 0
  Stopped: 6
Images: 22
... snip ...
Swarm: active
  NodeID: oyaymj9ee49ivwa3siy55yv1y
  Is Manager: true
  ClusterID: 1vxz99ibp9ltvg19aqs6t9u65
  Managers: 1
  Nodes: 1
```

Starting a swarm

- Run `$docker node ls` to view information about nodes:

```
$ docker node ls
```

ID	HOSTNAME	STATUS	AVAILABILITY	MANAGER STATUS	ENGINE VERSION
oyaymj9ee49ivwa3siy55yv1y *	<long name here>	Ready	Active	Leader	18.06.1-ce

- Now we are ready to add more nodes to our swarm...

Joining a swarm

- On the command line of your worker machine, enter the join command from the manager:

```
$docker swarm join --token SWMTKN-1-05p3cwhydsf13or53hr1kryawkuys0p4rpkdrgxi232iww4102-648g6iyo3xyze9x52o8ybszut172.31.9.64:2377
```

- If you don't have the join token, you can just type the following in the manager to retrieve it
 - `$docker swarm join-token worker`
- Use `$docker node ls` in the manager to see the worker nodes

Deploy a service

- On the command line of your manager machine, run this command

```
$docker service create --replicas 1 --name helloworld alpine ping docker.com
```

- The `$docker service create` command creates the service.
 - The `--name` flag names the service `helloworld`.
 - The `--replicas` flag specifies the desired state of 1 running instance.
 - The arguments `alpine ping docker.com` define the service as an Alpine Linux container that executes the command `ping docker.com`.
- Use `$docker service ls` to see the running service:

ID	NAME	MODE	REPLICAS	IMAGE	PORTS
viwvf7u8ceti	helloworld	replicated	1/1	alpine:latest	

Now what?

- Inspect the service on the manager:

```
$docker service inspect --pretty helloworld
```

- Scale the service in the swarm

```
$docker service scale helloworld=5
```

- To see the updated task list:

```
$docker service ps helloworld
```

- **\$docker ps** will show the containers running on each of the workers and the manager

Delete a service

- Deleting a service is simple:

```
$docker service rm helloworld
```

- Use `$docker service inspect helloworld` and `$docker ps` to verify that it has been removed.

What else can you do?

- You can apply rolling updates to your service.
- You can drain a single node (for example for maintenance) without stopping the service
 - Docker just pushes the tasks onto other nodes until you are ready to bring that node up again.

Final notes:

- The only command that was executed on the worker nodes was to join the swarm – no further information about services was required.
- There is some configuration needed to enable a swarm on a given set of machines
 - For example, in AWS you need to modify the security group to allow the swarm to communicate.
 - You need to have certain ports available.

Summary

- Docker Swarm capabilities and terminology
- Demonstrate docker swarm

Lab

Using play-with-docker create your own docker swarm:

[Labs/07-docker-swarm-lab.md](#)

Questions or Comments?

