#### **Dynamic Programming and Applications**

Investment

Lecture 9

Andreas Schaab

#### **Outline**

#### Part 1: Theory

- 1. Demand for capital
- 2. User cost of capital
- 3. Adjustment costs
- 4. Tobin's Q

#### Part 2: Empirical regularities

- 1. Tobin's Q in the data
- 2. Investment sensitivity to cash flows
- 3. Zwick and Mahon (2017)

#### **Overview**

- · Investment is important for macroeconomics
- · Investment increases the stock of capital, therefore key determinant of growth
- Investment is volatile, matters a lot for business cycle fluctuations

## 1. Demand for capital

Consider a firm that operates a production function

$$y_t = F(z_t, k_t, x_t)$$

where  $z_t$  is exogenous productivity and  $x_t$  other inputs

- Suppose firm can rent capital *frictionlessly* at rate  $r_t^k$
- Firm problem therefore given by

$$\max_{k} F(z_t, k_t, x_t^*) - r_t^k k_t$$

where  $x_t^*$  denotes optimal choice of other inputs

Optimal capital demand then determined by:

$$F_{k,t} \equiv \partial_k F(\cdot) = r_t^k$$

# 2. User cost of capital

- · Capital usually not rented but owned by firms
- What is the appropriate notion of "rental rate"?
   wser cost literature
- Consider the deterministic firm (sequence) problem:

$$V(k_0) = \max_{\{i_t\}_{t \ge 0}} \int_0^\infty e^{-\int_0^t r_s ds} \Big( f_t(k_t) - p_t i_t \Big) dt$$

where  $f_t(k_t) = F(z_t, k_t, x_t^*)$ , facing the capital accumulation technology

$$\dot{k}_t = i_t - \delta k_t$$

Interpretation? (PE, small firm, take prices as given, SDF, ...)

- How do we solve this problem? (i) optimal control theory (ii) dynamic programming
- Hamiltonian is:  $\mathcal{H}_t(k_t, i_t, \lambda_t) = f_t(k_t) p_t i_t + \lambda_t (i_t \delta k_t)$
- What are control and state? Cookbook solution:

$$0 = \partial_i \mathcal{H}_t = -p_t + \lambda_t$$
$$r_t \lambda_t - \dot{\lambda}_t = \partial_k \mathcal{H}_t = f_{k,t} - \delta \lambda_t$$

- · Practice: derive the transversality condition at home using calculus of variations
- Combining and using the capital demand condition  $r_t^k = f_{k,t}$ :

user cost 
$$= r_t^k = \left(r_t + \delta - \frac{\dot{p}_t}{p_t}\right) p_t$$

Next: dynamic programming. Convince yourself you can derive HJB:

$$r_t V_t(k) = \partial_t V_t(k) + \max_i \left\{ f_t(k) - p_t i + (i - \delta k) \partial_k V_t(k) \right\}$$

- Why is this HJB not stationary, i.e., why  $\partial_t V_t(k)$ ?
- FOC:  $p_t = \partial_k V_t(k) \implies$  price of investment = marginal value of capital

$$r_t V_t(k) = \partial_t V_t(k) + \max_i \left\{ f_t(k) - p_t i + (i - \delta k) \partial_k V_t(k) \right\}$$

Envelope condition:

$$r_t \partial_k V_t(k) = \partial_{kt} V_t(k) + \partial_k f_t(k) - \delta \partial_k V_t(k) + (i(k) - \delta k) \partial_{kk} V_t(k)$$

• Next, differentiate FOC  $p_t = \partial_k V_t(k)$  with respect to time:

$$\dot{p}_t = \frac{d}{dt}p_t = \frac{d}{dt}\partial_k V_t(k) = \partial_{kt} V_t(k) \frac{dt}{dt} + \partial_{kk} V_t(k) \frac{dk}{dt}$$

Finally, put all together:

$$r_t \partial_k V_t(k) = \partial_k f_t(k) - \delta \partial_k V_t(k) + \dot{p}_t$$

$$\implies \text{user cost } = r_t^k = \partial_k f_t(k) = \left(r_t + \delta - \frac{\dot{p}_t}{p_t}\right) p_t$$

### Interpreting user cost model

- User cost of capital
  - increases with  $r_t$
  - increases with depreciation rate  $\delta$
  - decreases with capital gains rate  $\dot{p}_t/p_t$
- Hall and Jorgenson (1967): user cost model helpful to evaluate tax policies
- But not very helpful for investment dynamics:
  - Model determines capital stock, change in  $r_t^k$  requires 'jumps'
  - Decisions about capital stock become static, not forward-looking

- What might slow down the adjustment of the capital stock?
- Internal adjustment costs:
  - Direct costs faced by firms
  - More costly construction and training of workers
  - Disruption of current production
- External adjustment costs:
  - Financing needs ⇒ large upfront investment costs
  - Capital goods distinct from consumption goods, distinct capital producing sector, firm may not be "small"

# 3. A model of firm investment with adjustment costs

Let's start with simple quadratic (smooth + convex) adjustment cost:

$$C(i_t)$$
, where  $C(0) = 0, C'(0) = 0, C''(i_t) > 0$ 

Firms problem now:

$$V(k_0) = \max_{\{i_t\}_{t \ge 0}} \int_0^\infty e^{-\int_0^t r_s ds} \left( f_t(k_t) - i_t - C(i_t) \right) dt$$

facing the capital accumulation technology

$$\dot{k}_t = i_t - \delta k_t$$

HJB is given by (make sure this makes sense to you):

$$r_t V_t(k) = \partial_t V_t(k) + \max_i \left\{ f_t(k) - i - C(i) + (i - \delta k) \partial_k V_t(k) \right\}$$

Implies FOC:

$$1 + C'(i_t(k)) = \partial_k V_t(k) \implies i_t(k) = (C')^{-1} (\partial_k V_t(k) - 1)$$

• Envelope condition (dropping *t* subscripts and abbreviating derivatives):

$$rV_k = V_{tk} + f_k + (i - \delta k)V_{kk} - \delta V_k$$

· Rewriting:

$$(r - \delta)V_k = f_k + V_{tk} + (i - \delta k)V_{kk}$$

• Now again differentiate:  $\dot{V}_k = V_{kt} + V_{kk}\dot{k} = V_{tk} + (i - \delta k)V_{kk}$ , so

$$(r-\delta)V_k = f_k + \dot{V}_k$$

· We now introduce new notation:

Tobin's (marginal) 
$$Q = q = V_k$$

• Firm's decision problem summarized by system of equations:

$$(r - \delta)q = f_k + \dot{q}$$
$$\dot{k} = i - \delta k$$
$$C'(i) = q - 1$$

Denote the function:

$$i = (C')^{-1}(q-1)$$
  $\Longrightarrow$   $i = \Phi(q-1)$ 

• Given initial capital  $k_0$ , sequences  $\{q_t, k_t\}_{t\geq 0}$  solve the firm problem if they satisfy

$$\dot{q}_t = (r_t - \delta)q_t - f_{k,t}$$
$$\dot{k}_t = \Phi(q_t - 1) - \delta k_t$$

- System of 2 ODEs. q equation is forward-looking while k equation is backward-looking.
   Why?
- We can solve *q* equation forward to obtain:

$$q_t = \int_t^\infty e^{-\int_t^s (r_\ell - \delta) d\ell} f_{k,s} ds$$

- Analyze via phase diagram, suppose  $r_t = r$  and  $\delta = 0$
- Steady state: q = 1 and  $r = f_k$
- $q_t$  is a jump variable (like consumption)
- Capital  $k_t$  is a predetermined state variable, must always follow continuous path (infinite investment would be too costly)

#### 4. Tobin's Q

- What is the significance of  $q_t = \partial_k V_t(k)$ ?
- $q_t$  is the (shadow) value of one additional unit of installed capital
- Connection between sequence problem and dynamic programming:  $q_t$  turns out to be the Lagrange multiplier on relaxing capital / investment constraint
- In this model,  $q_t$  is a sufficient statistic for firm investment
- Firms invest whenever shadow value of installed capital is larger than value of consumption good:  $q_t>1$
- Without adjustment costs, firms invest until  $q_t = 1$
- With, firms invest until excess value equal to adjustment cost on margin

- In the data, average Q easier to measure than marginal Q
- Our theory: marginal Q is sufficient statistic for investment
- Tobin (1969) argued that firms should invest if

$$Q = \frac{\text{Market value of firm capital}}{\text{Book value of capital}} > 1$$

 Hayashi (1982): Average Q = marginal Q when markets competitive and production function + adjustment cost homogeneous of degree 1

#### 5. Tobin's Q and investment in the data

- Q-theory suggests Q (NPV of marginal projects available to the firm) is sufficient statistic
- Under additional conditions, average Q (market relative to book value) encodes the NPV of these marginal projects
- Other variables such as contemporaneous cash flows should not matter. We can test this
- Suppose we estimate regression:

$$\frac{I_{it}}{K_{it}} = \alpha + \beta Q_{it} + \epsilon_{it}$$

• Summers (1981, Brookings) estimates this by OLS and finds  $\beta=0.031(0.005)$ . Very low, implies high adjustment cost!

• Suppose we estimate regression:

$$\frac{I_{it}}{K_{it}} = \alpha + \beta Q_{it} + \epsilon_{it}$$

- Problem:
  - Where did the  $\epsilon_{it}$  come from?
  - Q-theory says that there should be no  $\epsilon_{it}$
  - To estimate this equation, we need to know about  $\epsilon_{it}$ . Is it orthogonal to  $Q_{it}$ ?!
- View 1: measurement error in  $Q_{it}$ :
  - Stocks are volatile and may not reflect fundamental value
  - Assumptions under which marginal = average Q may not hold
  - Measurement error would result in attenuation bias
- View 2: model is wrong and other factors affect investment
  - If other factors that raise desired investment also raise interest rates, they may lower  $Q_{it}$  and downward bias  $\beta$
  - Bias could go either way

# **Beyond Q**

- Suppose we are interested in whether internal funds (cash flows) affect investment.
   Why?
- · Simple approach:

$$\frac{I_{it}}{K_{it}} = \alpha + \beta_1 Q_{it} + \beta_2 \frac{CF_{it}}{K_{it}} + \epsilon_{it}$$

- Problem:
  - Cash flow likely correlated with future profitability
  - If  $Q_{it}$  is mismeasured, cash flow would proxy for Q even if financial markets are perfect

### Fazzari-Hubbard-Petersen (1988)

- Use diff-in-diff strategy to circumvent cash flow profitability correlation problem
- Different groups of firms: e.g. high- vs. low-dividend-firms
- Low dividends proxy for greater financial constraints
- Is investment more sensitive to cash flows for low-dividend?
- Identifying assumption: cash flow profitability correlation the same on average for two groups
- Result: Cash flow sensitivity much higher for low dividend firms. Marginal propensity to invest out of cash flows very high.

#### Do cash flows matter for investment?

- Ideal: find a shock to cash flows that is orthogonal to investment opportunities (Q)
- Well-known examples:
  - Lamont (1997): investment of non-oil subsidiaries of oil companies falls when oil prices fall
  - Rouh (2006): investment of firms with underfunded pension plans due to drops in asset prices. Compare firms with and without mandatory contributions. Those with mandatory contributions see investment fall more.

## Temporary investment tax incentives: bonus depreciation

- Suppose the government introduces a policy that changes the marginal benefit or cost of investment. This is arguably exogenous to the firm.
- Firms pay taxes on income net of business expenses
- Can fully expense wages, advertising, etc. immediately
- But investment gets expensed over time according to tax depreciation schedules
- Bonus depreciation accelerates this depreciation schedule

## Zwick-Mahon (2017)

- Bonus depreciation changes occur in recessions: may be correlated with other determinants of investment
- Zwick-Mahon use diff-in-diff strategy:
  - Bonus more valuable in industries with longer lived investments
  - Compare effects of bonus across industries with differing investment duration
- Find large effects. More liquidity constrained firms have larger effects
- Effect only exists for firms with immediate tax benefit