

# Humbot S. Light follower: Connection instructions

② Upload the program to your UNO board. Check makit tutorials if you have any doubts

④ Connect both servos. Check cables and colors

③ Connect LDR sensors as shown

① Voltage slider switch should be in 5V

⑤ Finally, double check all connections and connect the batteries. If your Humbot does not start, try pressing reset button once

