```
tao@tao:~$ rostopic hz /can_2_ros_gps
subscribed to [/can_2_ros_gps]
average rate: 100.115
        min: 0.008s max: 0.012s std dev: 0.00076s window: 96
average rate: 100.054
        min: 0.008s max: 0.012s std dev: 0.00075s window: 196
average rate: 100.039
        min: 0.008s max: 0.012s std dev: 0.00077s window: 297
average rate: 100.028
        min: 0.008s max: 0.012s std dev: 0.00078s window: 397
average rate: 100.022
        min: 0.008s max: 0.012s std dev: 0.00078s window: 497
average rate: 99.998
        min: 0.008s max: 0.012s std dev: 0.00077s window: 597
average rate: 100.016
        min: 0.008s max: 0.012s std dev: 0.00077s window: 697
average rate: 100.017
        min: 0.008s max: 0.012s std dev: 0.00076s window: 797
```