MATH 20250

PSet 4

February 5, 2025

Problem 9.17.

Solution. a) The range of f is certainly all of $\mathbb{R}^2 n(0,0)$. It can be no more than \mathbb{R}^2 , so suffices to show that it is at least $\mathbb{R}^2 n(0,0)$. Any ratio between $f_1 \& f_2$ can be achieved, since it is the range of tan. Since e^x goes to infinity, the size of the points with any ratio is not limited. The only trouble is that $e^x > 0$, $\forall x$. Since $\frac{0}{0}$ is not a ratio, and the scalar can never be 0, (0.0) is far out.

b) In particular, the Jacobian Matrix of the function is $\begin{pmatrix} e^x \cos y & -e^x \sin y \\ e^x \sin y & e^x \cos y \end{pmatrix}$ $e^x \text{ is never 0. Computing determinant gives } \det(D(f(x))) = ((e^x \cos y)(e^x \cos y) - (-e^x \sin y)(e^x \sin y)) = e^{2x}$ by pythagoreon identity. So done.

c)But look, in general, $g_2(b) = a_2 = \tan^{-1}(\frac{f_2(a)}{f_1(a)}) = \tan^{-1}\frac{b_2}{b_1}$. Pick the obvious value (since certaily the functuion is not one to one, due to periodicity of \sin/\cos), or indeed chose any of them: just the same one for the whole neighborhood. Solving for $g_1(b)$ is $g_1(b) = a_1 = \ln(\frac{f_1(a)}{\cos(g_2(b))}) = \ln(\frac{b_1}{\cos(g_2(b))})$ (or flipped, but with \sin).

Evaluating the Jacobian Matrix at a:

$$\begin{pmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$$

I want to differentiate g using the explicit writing out of it which I did above. I can't though.

d) Parallel to the x axis, and constant y, they look like linear functions, through (0,0). Parallel to y axis, constant y, they look like circles of various diameters.

Problem 9.18.

 $4x^2y^2 = u^2 + v^2 \ge 0$, which is of course known to be as such, for any u and any v. Substituting that into the first equation gives the value of y for the x. So the range is all of \mathbb{R}^2

b) In particular the Jacobian Matrix is

$$\begin{pmatrix} 2x & -2y \\ 2y & 2x \end{pmatrix}$$

Jacobian is $\det(dF(x,y)) = 4x^2 + 4y^2$ The square of a real number results in non-negative numbers, so Jacobian is 0 iff x&y = 0. We know that roots of 4th order polynomials come in pairs of two, hence by the same manner that a single root is guaranteed, two are also (see above). So not one-one. c) Solving the previous hidden quadratic explicitly:

$$x^{2} = \frac{u \pm \sqrt{u^{2} + v^{2}}}{2} \implies x = \sqrt{\frac{u \pm \sqrt{u^{2} + v^{2}}}{2}}$$

To receive y, first use the u part of the jingle-jangle, which like spurrs, doth guide mine ramble. Since

$$x^{2} = \frac{u \pm \sqrt{u^{2} + v^{2}}}{2}$$
, & $y^{2} = x^{2} - u = \frac{-u \pm \sqrt{u^{2} + v^{2}}}{2}$.

So,

$$x = \pm \sqrt{\frac{u + \sqrt{u^2 + v^2}}{2}}; \ y = \pm \sqrt{\frac{-u + \sqrt{u^2 + v^2}}{2}}$$

To ensure positivity, since we are taking square roots, \pm is forgotten about, replaced by its more handsome brother. Also, from the defintion of v, and it follows that we pick a combination of the postives and the negative roots s.t the number of roots taken negative is even if v not negative, and odd if it is.

The given values imply that |x|=|y|, so $x=y=\pm\sqrt{\frac{\pi}{3}}$ In the one case, the Jacobian Matrix is:

$$\begin{pmatrix} \left(\frac{1}{2}\frac{u+\sqrt{u^2+v^2}}{2}\right)^{\frac{-1}{2}}\left((1+\frac{2u}{2\sqrt{u^2}+v^2})\right) & \left(\frac{1}{2}\frac{u+\sqrt{u^2+v^2}}{2}\right)^{\frac{-1}{2}}\left((\frac{2v}{2\sqrt{u^2}+v^2})\right) \\ \left(\frac{1}{2}\frac{-u+\sqrt{u^2+v^2}}{2}\right)^{\frac{-1}{2}}\left((-1+\frac{2u}{2\sqrt{u^2}+v^2})\right) & \left(\frac{1}{2}\frac{-u+\sqrt{u^2+v^2}}{2}\right)^{\frac{-1}{2}}\left((\frac{2v}{2\sqrt{u^2}+v^2})\right) \end{pmatrix}$$

Either that, or (-1) times that (since there must even amount of negative signs between x and y, so 0 or 2, so 1 or -1 scalar)

d) They look like graphs of $\frac{1}{x}$ (y constant) or $\frac{1}{y}$ (x constant) stretched in v direction by $\frac{1}{2}$ and shifted depending on where exactly the thing is parallel.

Problem 9.19.

Solution. It is visually clear that R1 = R2 + R3, excluding the R(u) component. I.e, taking $R1 \to R1 - R2 - R3$:

$$3x + y - 3z + u^2 = 0$$
$$x - y + 2z + u = 0$$

$$2x + 2y - 3z + 2u = 0$$

$$u^{2}-3u=0$$

$$x-y+2z+u=0$$

$$2x+2y-3z+2u=0$$

So we can clearly solve for which u lead to a valid system, (indeed, u=0 or u=3), and then we are spoilt for variables in the remaining two equations. But, conversely, the x,y,z parts of R2 & R3 together specify exactly R1, hence the only thing we can get (this has been done many times in the linear algebra class; if 1 equation 'agrees' with 2 others, it is irrelevant). So, WHEN the system is consistent, it means that exactly R1 = R2 + R3. So we have really a system of 2 3 variable equations, so from lin alg they can indeed all be solved for any of those variables. The solution then will be 2 families in each of the 3 cases (where we are solving for given x ory orz), one for each possible solution of u. General u on the other hand does not have a solution, so there.