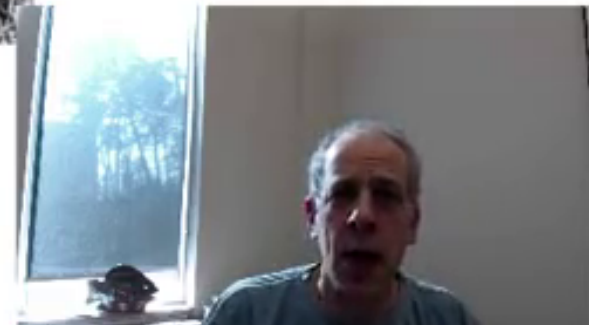


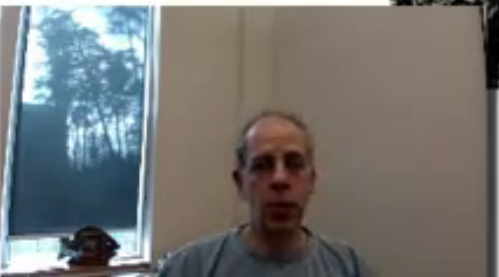
# Automatic Segmentation is Tough!



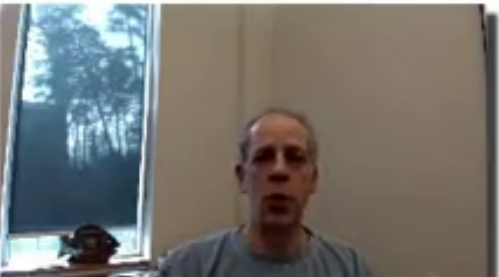
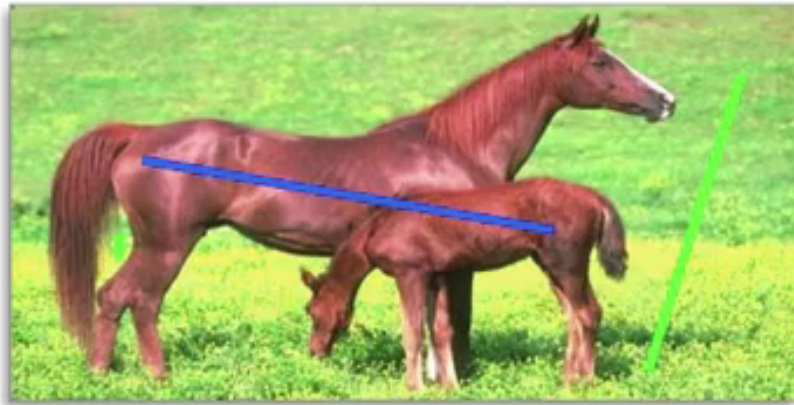
By Doolittle



# Automatic Segmentation is Tough!

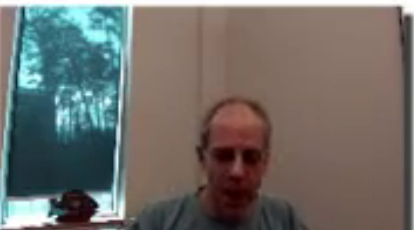
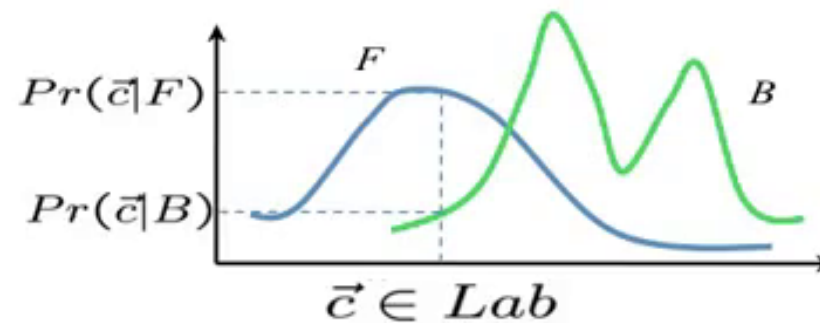


# Interactive image segmentation



# Step1 – Feature Distribution Estimation

- Estimate the color distribution on scribbles
- Each pixel is assigned a probability to belong to F or B:



$$\leftarrow P_F(x) = \frac{Pr(\vec{c}_x|F)}{Pr(\vec{c}_x|F) + Pr(\vec{c}_x|B)}$$

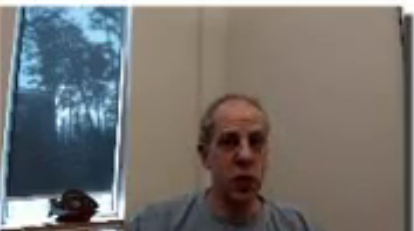
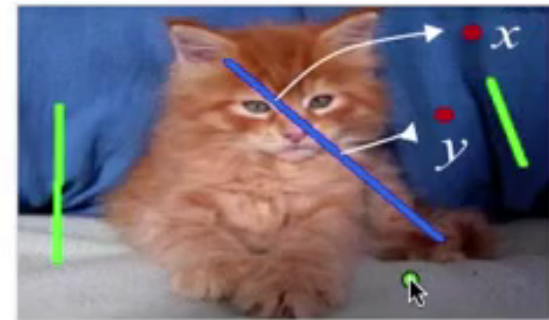
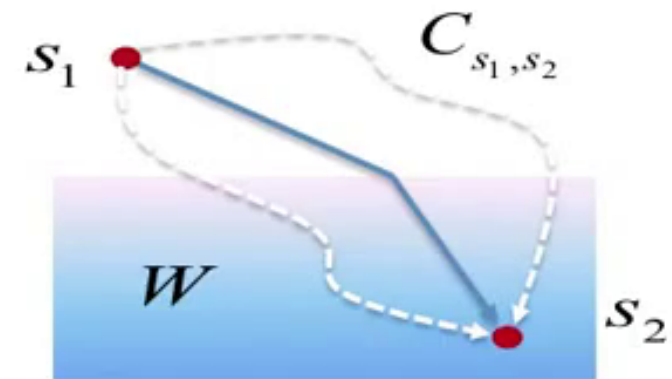


# Step2 – Weighted Distance Transform

## Weighted Geodesic Distance

$$d(s_1, s_2) := \min_{C_{s_1, s_2}} \int_{C_{s_1, s_2}} W ds$$

- Computed in linear time!



# Weighted Distance Transform (cont' d)

$$W := |\nabla P_F(x) \cdot \vec{C}'_{s_1, s_2}(x)|$$

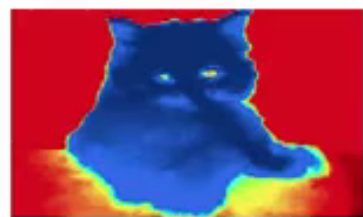
$$D_l(x) := \min_{s \in \Omega_l} d(s, x), \quad l \in \{F, B\}$$



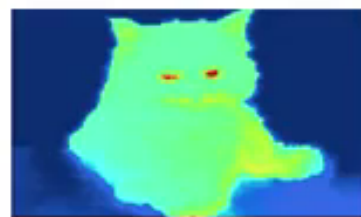
- Pixels are classified by comparing  $D_F(x)$  and  $D_B(x)$



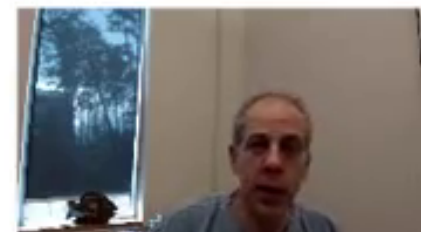
$P_F(x)$



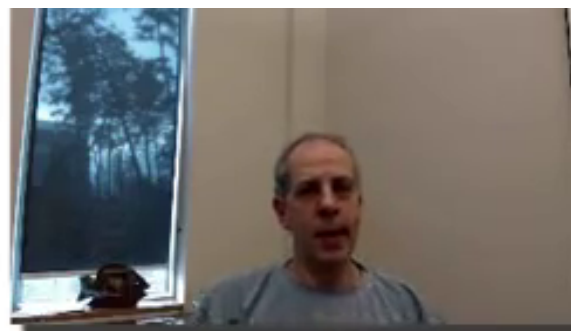
$D_F(x)$



$D_B(x)$



# Weighted Distance Transform



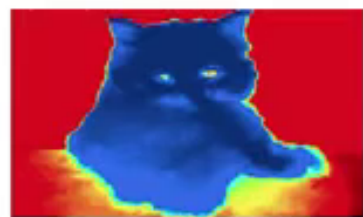
$$W := |\nabla P_F(x) \cdot \vec{C}'_{s_1, s_2}(x)|$$

$$D_l(x) := \min_{s \in \Omega_l} d(s, x), \quad l \in \{F, B\}$$

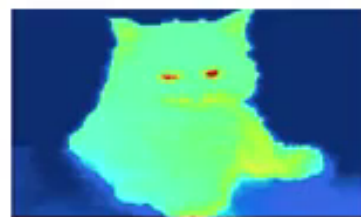
- Pixels are classified by comparing  $D_F(x)$  and  $D_B(x)$



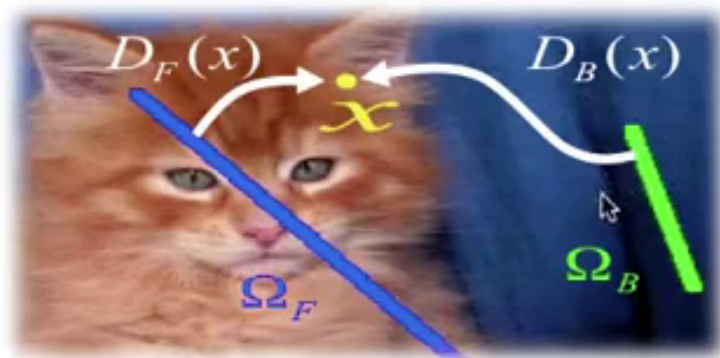
$P_F(x)$



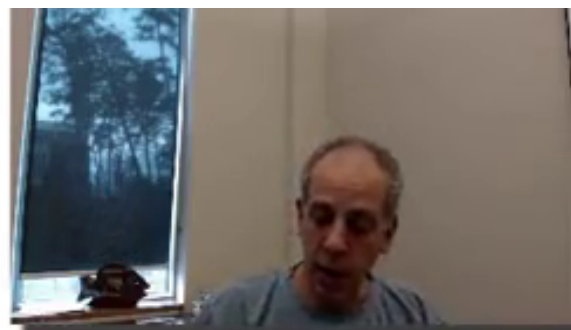
$D_F(x)$



$D_B(x)$



# Weighted Distance Transform



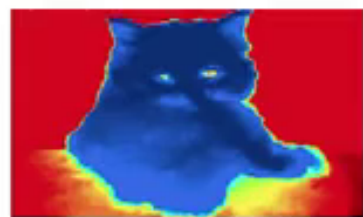
$$W := |\nabla P_F(x) \cdot \vec{C}'_{s_1, s_2}(x)|$$

$$D_l(x) := \min_{s \in \Omega_l} d(s, x), \quad l \in \{F, B\}$$

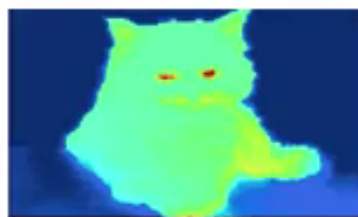
- Pixels are classified by comparing  $D_F(x)$  and  $D_B(x)$



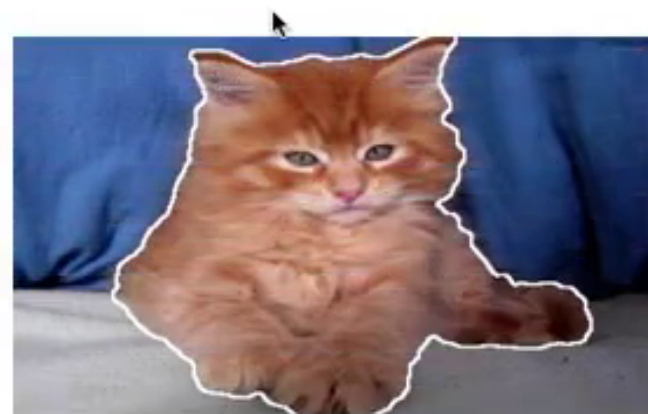
$P_F(x)$



$D_F(x)$



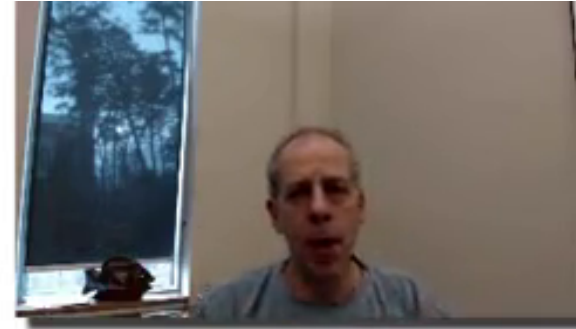
$D_B(x)$



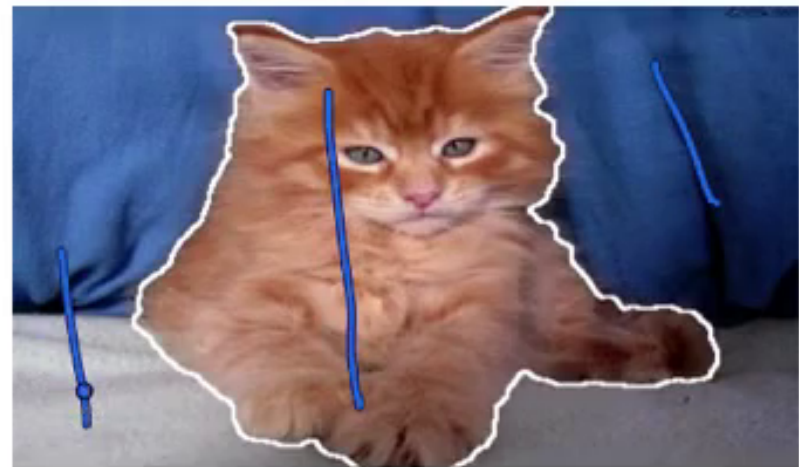
*binary segmentation*



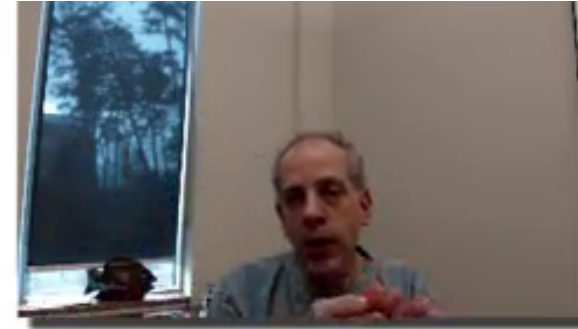
## Step3 – Refine



- Automatically create a narrow band and new scribbles.
  - Band boundaries serve as “new scribbles”

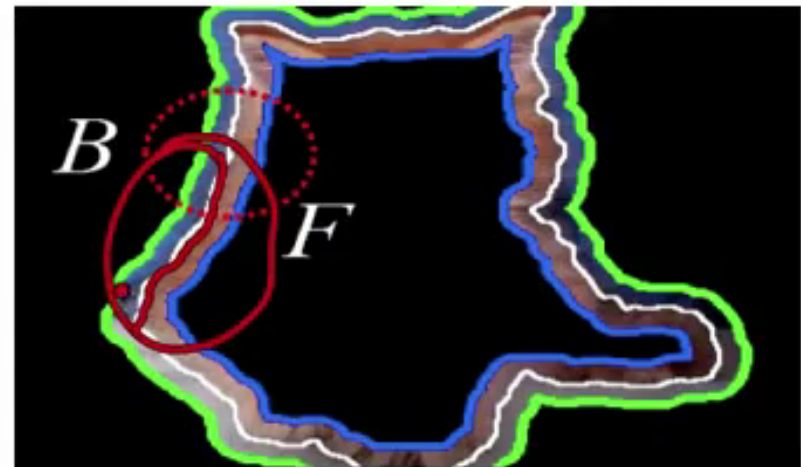


## Step3 – Refine

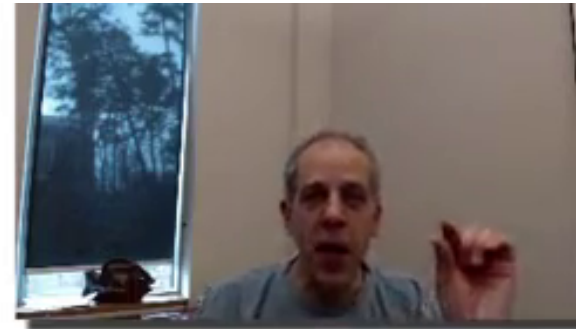


- Automatically create a narrow band and new scribbles.
  - Band boundaries serve as “new scribbles”

$\rho_F$



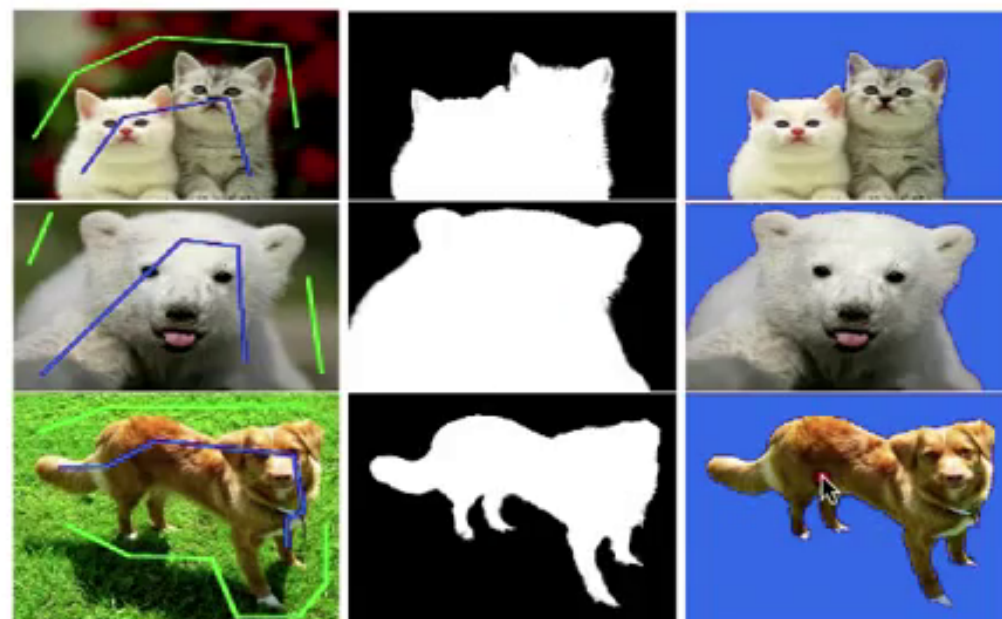
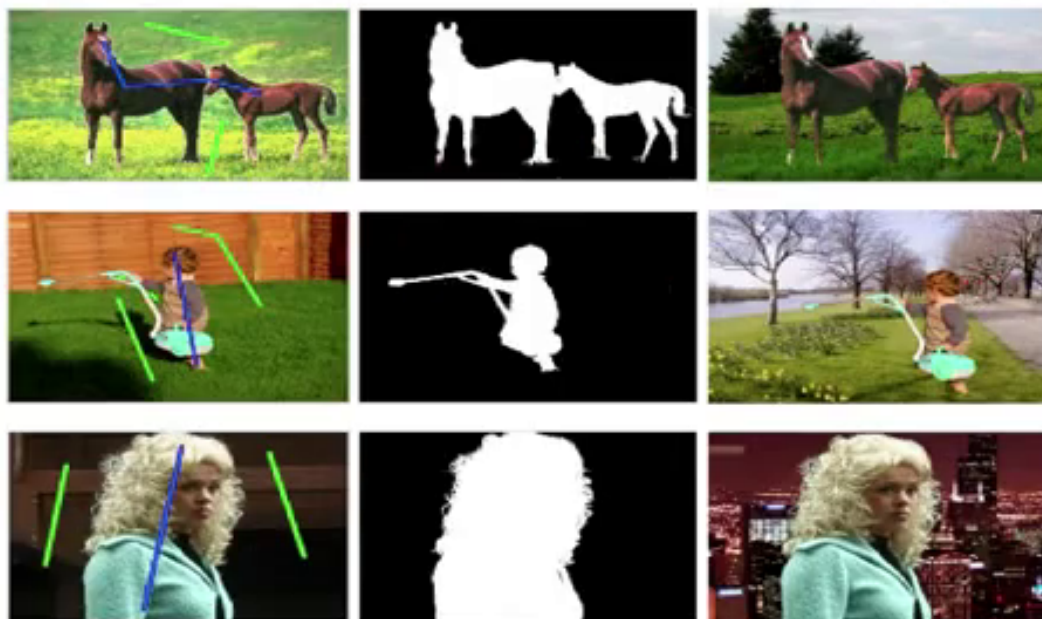
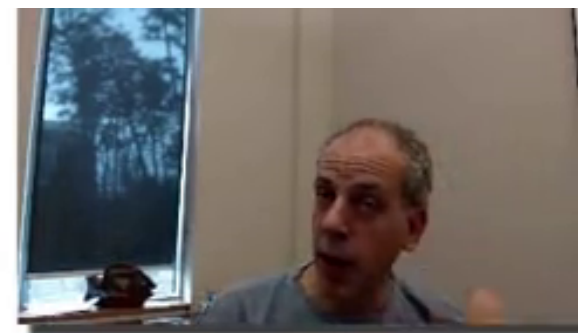
## Step3 – Refine



- Automatically create a narrow band and new scribbles.
  - Band boundaries serve as “new scribbles”



# Examples





# Scribble Robustness

