

# Naïve Bayse

$$P(h|D) = \frac{P(D|h)P(h)}{P(D)}$$

A set of labels  $V = \{v_1, \dots, v_i\}$

Naïve Bayse Classifier becomes  
Set of Examps  $x = \{x_1, x_2 \dots x_n\}$   
represented by features  $\{f_1, f_2, \dots f_m\}$

$$v_{no} = \operatorname{argmax}_{v \in V} P(v_j) \prod P(f_i | v_j)$$