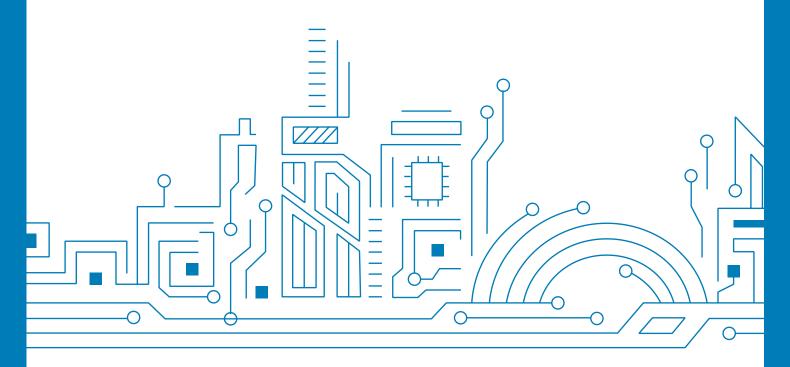


# GNSS Positioning Module TAU1105

Datasheet V1.4





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# **About the Document**

#### ■ Basic info

Document applies to	TAU1105
Document type	Datasheet
Revision and date	V1.4/2021-07
Product status	Mass production

## ■ Product status description

In development Objective specification. Revision may be released in later status.						
Engineering sample	Product specifications tested on early. Revision may be released in later status.					
Preliminary	Product specifications come from small production. Revision may be released in					
Premimary	later status.					
Mass production	Final product specification to mass market.					



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#### 1 SYSTEM OVERVIEW

#### 1.1 Overview

TAU1105 is a GNSS positioning module, which is based on the state of art CYNOSURE III architecture. It supports GPS, BeiDou, Galileo, GLONASS, and QZSS.

TAU1105 integrates efficient power management architecture, while providing high sensitivity and low power GNSS solutions which make it suitable for navigation applications on automotive and consumer electronics, and fleet management.

#### 1.2 Features

- · Concurrent reception of GPS, BDS, GLONASS, Galileo, and QZSS
- · High sensitivity design and low power management
- Smart jammer detection and suppression
- Highly integrated labelling module, the best cost-effective GNSS solution

Table 1 TAU1105

	GNSS			Features			Interface			Accuracy		Grade		е							
Product	Band (S/D/T)	GPS	BDS	GLONASS	Galileo	IRNSS	Built-in LNA	Programmable (flash)	Data logging	D-GNSS	Oscillator	UART	12C	USB	SPI	Meter	Sub-meter	Centimeter	Standard	Professional	Automotive
TAU1105-1010A00	S	•	•	•	•		•	•	•	•	Т	•	0			•			•		

T= TCXO

o=Supported upon request with special firmware

#### 1.3 Module Photo



Figure 1 TAU1105 module photo



# 1.4 Block Diagram

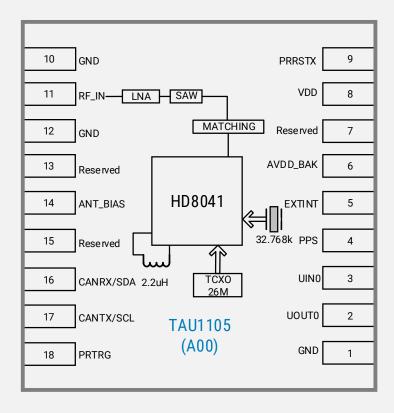


Figure 2 Block diagram

# 1.5 Specifications

**Table 2 Specifications** 

Parameter		Specification					
GNSS tracking channels	40						
	GPS/QZSS: L1C/A						
CNICC recention	BDS: B1I	BDS: B1I					
GNSS reception	GLONASS: L10F						
	Galileo: E1	Galileo: E1					
Update rate	Maximum 10Hz						
Position accuracy [1]	GNSS	2.5m CEP					
Valagity 9 Time accuracy	GNSS	0.1m/s CEP					
Velocity & Time accuracy	1PPS	20ns					
Time to First Fix (TTFF)	Hot start	1 sec					
Time to First Fix (TTFF)	Cold start	28 secs					
	Cold start	-148dBm					
Consitivity	Hot start	-155dBm					
Sensitivity	Reacquisition	-158dBm					
	Tracking & navigation	-162dBm					
Operating limit	Velocity	515 m/s					



Parameter	Specification					
	Altitude	18,000 m				
Safety supervision	Antenna short circuit prote	ection				
Serial interface	UART	1				
Senai interrace	I2C <sup>[2]</sup>	1				
	NMEA 0183 Protocol Ver. 4	4.00/4.10				
Protocol	RTCM 3.0/3.2/2.3/2.4x <sup>[3]</sup>	RTCM 3.0/3.2/2.3/2.4x <sup>[3]</sup>				
	Cynosure GNSS Receiver Protocol					
	Main voltage	2.0 ~ 3.6V				
Operating condition	Digital I/O voltage	1.8 ~ 3.6V				
	Backup voltage	1.8 ~ 3.6V				
	GPS+QZSS	25mA@3.3V				
Power consumption	GNSS	35mA@3.3V				
	Standby	12uA				
Operating temperature	-40 °C ~ +85 °C					
Storage temperature	-40 °C ~ +85 °C					
Package	10.1mm x 9.7mm x 2.5mm 18-pin stamp hole					
Certification	RoHS & REACH					

<sup>\* [1]</sup> Open sky, demonstrated with a good external LNA

<sup>\* [2]</sup> Supported upon request with special FW

<sup>\* [3]</sup> RTCM 2.3/2.4x are supported upon request with special FW.



# 2 PIN DESCRIPTION

# 2.1 Pin Assignment

10 GND  11 RF_IN  12 GND  13 Reserved  14 ANT_BIAS TAU1105 Top View  15 Reserved  16 CANRX/SDA  17 CANTX/SCL  18 PRTRG	PRRSTX  VDD  Reserved  AVD D_BAK  EXTINT  PPS  UIN0  UOUT0  GND	9 8 7 6 5 4 3 2
--	---	--------------------------------------

<sup>\*</sup> Pin 1 aligns to the circular hole on module cover.

Figure 3 Pin assignment (top view)



# 2.2 Detailed Pin Descriptions

Table 3 Detailed pin descriptions

Function	Symbol	No.	I/O	Description
	VDD	8	Power	Main supply input.
Power	GND	1,10,12	VSS	Ground
	AVDD_BAK	6	Power	Backup supply input.
RF_IN		11	I	RF signal input. Use a controlled impedance of $50\Omega$ for the routing from RF_IN pin to the antenna or the antenna connector.
Antenna				RF section output voltage. Used to power the
	ANT_BIAS	14	0	external active antenna. The current is limited
				below 35mA.
UART	UOUT0	2	0	UART0 serial data output.
OAITI	UIN0	3	I	UART0 serial data input.
		16	I/O	I <sup>2</sup> C data transmission or CAN data input. Leave it floating if not used.
I <sup>2</sup> C/CAN <sup>[1]</sup>	CANTX/SCL	17	1/0	I <sup>2</sup> C clock, or CAN data output. Leave it floating if not used.
	PRTRG	18	I	Mode selection, or the trigger input in deep sleep mode to wake up the system
		9	I	External reset, low active
System	PPS	4	0	Setting for time pulse output(PPS)
	EXTINT	5	I	GPIO, Default (EXTINT): a trigger pin to external interrupt, leave it floating if not used.
Reserved	Reserved	7,13,15		Reserved, leave it floating if not used

<sup>\* [1]</sup> Supported upon request with special FW.



# 3 ELECTRICAL CHARACTERISTICS

# 3.1 Absolute Maximum Rating

**Table 4 Absolute rating** 

Symbol	Parameter	Min.	Max.	Unit
VDD	Power input for the main power domain	-0.5	3.63	V
AVDD_BAK	Power input for the backup power domain	-0.5	3.63	V
T <sub>storage</sub>	Storage temperature	-40	85	°C
T <sub>solder</sub>	Solder reflow temperature		260	°C

## 3.2 IO Characteristics

#### 3.2.1 PRRSTX and PRTRG

#### **Table 5 PRRSTX and PRTRG**

Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
I <sub>IZ</sub>	Input leakage current				+/-1	uA
V <sub>IH</sub>	Input high voltage		AVDD_BAK*0. 7		AVDD_BAK	V
V <sub>IL</sub>	Input low voltage		0		AVDD_BAK*0.3	V
Ci	Input capacitance				10	pF
R <sub>PU</sub>	Pull-up resistance		18		84	ΚΩ

#### **3.2.2** Others

#### Table 6 Others

Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
I <sub>IZ</sub>	Input leakage current				+/-1	uA
V <sub>IH</sub>	Input high voltage		VDD*0.7		VDD	V
V <sub>IL</sub>	Input low voltage		0		VDD*0.3	V
V <sub>OH</sub>	Output high voltage	I <sub>OH</sub> =11.9 mA, VDD=3.3V	2.64		-	V
V <sub>OL</sub>	Output low voltage	I <sub>OL</sub> =7.9 mA, VDD=3.3V			0.4	V
Ci	Input capacitance				11	pF
R <sub>PU</sub>	Pull-up resistance	-	35		84	ΚΩ



# 3.3 DC Characteristics

# **3.3.1** Operating Conditions

**Table 7 Operating conditions** 

Symbol	Parameter	Min.	Тур.	Max.	Unit
VDD	Power input for the main power domain	2.0	3.3	3.6	V
AVDD_BAK	Power input for the backup power domain	1.8	3.3	3.6	V
I <sub>ANT_BIAS</sub>	ANT_BIAS output current	-	-	35	mA
V <sub>ANT_BIAS</sub>	ANT_BIAS output voltage		VDD-0.2	-	V
ICC <sub>max</sub>	Maximum operating current @ VDD			200	mA
T <sub>env</sub>	Operating temperature	-40	-	85	°C

## 3.3.2 Power Consumption

**Table 8 Power consumption** 

Symbol	Parameter	Measure Pin	Тур.	Unit
I <sub>CCRX1</sub>	Average tracking current (GPS+QZSS)	VDD <sup>[1]</sup>	25	mA
I <sub>CCRX2</sub>	Average tracking current (GNSS)	VDD <sup>[1]</sup>	35	mA
I <sub>CCDBM</sub>	Standby mode	AVDD_BAK <sup>[2]</sup>	12	uA

<sup>\* [1]</sup> Condition: VDD=3.3V@Room Temperature; All Pins Open.

<sup>\* [2]</sup> Condition: AVDD\_BAK=3.3V@Room Temperature; All Pins Open.



#### 4 HARDWARE DESCRIPTION

#### 4.1 Connecting Power

TAU1105 positioning module has two power supply pins: VDD and AVDD\_BAK. The VDD pin provides the main supply voltage, and the AVDD\_BAK pin provides the backup supply voltage. In order to ensure the positioning performance, please control the ripple of the module power supply. It is recommended to use the LDO above 200mA.

If the power for VDD pin is off, the real-time clock (RTC) and battery backed RAM (BBR) are supplied through the AVDD\_BAK pin. Thus, orbit information and time can be maintained and will allow a Hot or Warm start. If no backup battery is connected, the module performs a cold start at every power up if not aiding data are sent to the module.

Note: If no backup supply is available, connect AVDD\_BAK pin to VDD or leave it floating.

#### 4.2 Power on/off Sequence

TAU1105 has two independent power domains (backup and main domain). In data backup mode, main power supply can be completely shut down for further power reduction for ultra-low power application.

#### 4.2.1 Initial system power on

When both backup and main supply power on from their off state, external reset (PRRSTX) must be active and hold more than 5ms after both backup supply and main supply reach the minimum operating voltage. Initial system power on sequence is illustrated in Figure 4.

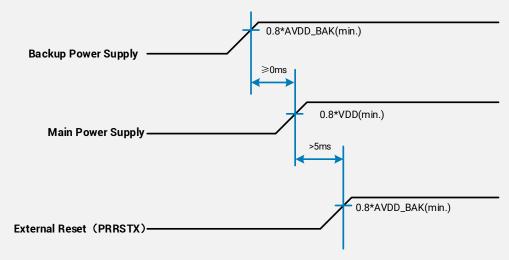


Figure 4 Initial system power on sequence

#### 4.2.2 Main power supply off/on in application

If application intends to shut down main power supply (VDD) while keep backup power supply (AVDD\_BAK) alive to save backup data, the following rules should be applied:



External reset (PRRSTX) must be active when main power supply is under power off. In this case, external reset must be hold active more than 5ms after main power supply resumes to minimum operating voltage. Main power on sequence in application is illustrated in Figure 5.

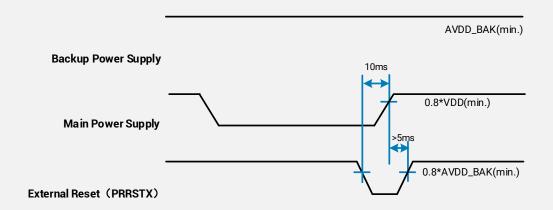


Figure 5 Main power on sequence

## 4.3 Antenna Design

There is built-in LNA and SAW in the GNSS module. It is recommended to use an active antenna with gain less than 36dB and the noise figure less than 1.5dB.

The module has built-in short circuit detection and open circuit detection function, which can detect the status of normal connection, and send out antenna status prompt message in NMEA data.

- Short circuit protection
  - » The module includes internal short circuit antenna detection. Once an overcurrent is detected at the ANT\_BIAS port, the module will restrict current output automatically to protect from damages.
- · Open circuit detection
  - The module can detect an open circuit in the antenna. Users can judge it from antenna status messages.

Table 9 ANT\_BIAS current range and antenna status

Antenna status	Status output	ANT_BIAS current range
Open circuit	OPEN	0< ANT_BIAS ≤ 1mA
Regular circuit or open circuit	OK or OPEN	1mA< ANT_BIAS ≤ 2mA
Regular circuit	OK	2mA< ANT_BIAS ≤ 40±5mA <sup>[1]</sup>
Short circuit	SHORT	40±5mA <sup>[1]</sup> < ANT_BIAS < 55mA

<sup>\* [1] ±5</sup>mA are differences between product batches.

#### TIPs:

- 1. Pulse width of the minimum detectable overshoot current should be more than 10uS.
- 2. NMEA message of antenna status output:
- OPEN: \$GNTXT,01,01,01,ANT\_OPEN\*40
- OK: \$GNTXT,01,01,01,**ANT\_OK**\*50
- SHORT: \$GNTXT,01,01,01,ANT\_SHORT\*06



#### 4.4 Reset and Mode Control

The operation mode of GNSS module is controlled by PRRSTX (nRESET) and PRTRG (BOOT) pin. While the module works in normal operation, leave PRRSTX and PRTRG pins floating if there is no upgrading or reset demands, or others.

- Keep PRTRG pin floating during system power-up or the external reset (PRRSTX from low to high), and the module will enter **User Normal Mode**.
- When the module powers up or PRRSTX from low to high, the module will execute an external
  reset. (If the power for AVDD\_BAK is always on, the external reset will not affect the ephemeris
  data in the backup domain)
- Drive PRTRG pin to low or connect PRTRG to GND directly (not by pull-down resistance) during
  system power-up or the external reset (PRRSTX from low to high), and the system enters
  BootROM Command Mode at PRTRG pin being released from low to floating state, and ready for
  firmware upgrading command.
- When connecting PRRSTX and PRTRG to any host IO, DO NOT use the pull-up or pull-down resistance.

#### 4.5 Default Serial Interfaces

Table 10 Default messages

Interface	Settings	
UART output	Data format: 1 start bit, 8 data bits, 1 stop bit, no checksum	
	Default baud rate: 115200bps.	
	Configured to transmit both NMEA and HD Binary protocols, but only the following	
	NMEA (and no HD Binary sentence) messages have been activated at start-up:	
	GGA, GSA, GSV, RMC, ZDA, TXT-ANT	
	115200 baud, 8 data bits, no parity bit, 1 stop bit, autobauding disabled	
LIADT input	Automatically accepts following protocols without need of explicit configuration:	
UART input	HD binary sentence, NMEA, RTCM	
	The GNSS receiver supports interleaved HD binary and NMEA messages.	
Timepulse	1 pulse per second, synchronized at rising edge, pulse length 100ms	
(1Hz Nav)	i puise per second, synchronized at rising edge, puise length rooms	

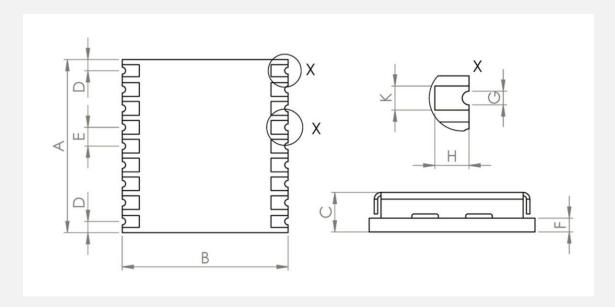
<sup>\*</sup> Refer to GNSS\_Protocol\_Specification for information about other settings.

When the module is applied to the specific application, users can shut off the main power in order to further reduce the power consumption. To avoid the high level in serial interface influencing the normal operation, it is highly suggested to cut off the serial port when shut off the main power.

Otherwise, please set the serial port to input mode or high impedance state with pull-down resistor.



# **5 MECHANICAL SPECIFICATION**



**Figure 6 Dimensions** 

**Table 11 Dimensions** 

Symbol	Min. (mm) Typ.(mm)		Max. (mm)	
Α	9.9	10.1	10.3	
В	9.5	9.7	9.9	
С	2.3	2.5	2.7	
D	D 0.55		0.95	
Е	E 1.0		1.2	
F	0.6	0.8	-	
G	G 0.4 0.5		0.6	
Н	H 0.8 0.9		1.0	
K	0.7	0.8 0.9		



## **6 REFERENCE DESIGN**

# 6.1 Minimal design

This is a minimal design for a TAU1105 GNSS module. When connecting to an active antenna, make sure there is an 82nH(L1) inductance soldered as shown in the following figure. When it is connected to a passive antenna, there is no need for the 82nH inductance. The characteristic impedance from RF\_IN pin to the antenna connector should be  $50\Omega$ .

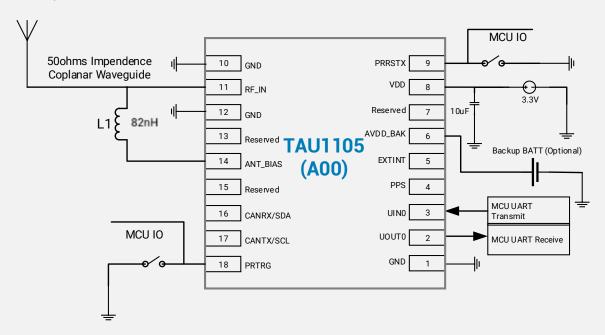
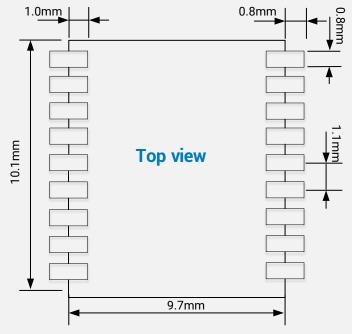


Figure 7 Minimal application diagram



# **6.2** PCB Footprint Reference



**Figure 8 PCB Footprint Reference** 

#### **6.3** Layout Notes

- (1) A decoupling capacitor should be placed close to VDD pin of the module, and the width of power routing should be more than 0.5mm.
- (2) The width of RF routing between RF port to antenna interface should be wider than 0.2mm. The characteristic impedance of RF routing between RF port to antenna interface should be controlled to  $50\Omega$ .
- (3) It is recommended that the routing from RF port to antenna interface refers to the second layer, and no routing are recommended on the layer.
- (4) Do not place the module close to any EMI source, like antenna, RF routing, DC/DC or power conductor, clock signal or other high-frequency switching signal, etc.



# 7 REFLOW SOLDERING

#### Table 12 Reflow profile features

Profile Feature	Pb-Free Assembly
Preheat/Soak	
Temperature Min (T <sub>smin</sub> )	150 °C
Temperature Max (T <sub>smax</sub> )	200 °C
Time (ts) from (Tsmin to Tsmax)	60-120s
Ramp-up rate (T∟to T <sub>p</sub> )	3 °C/second max.
Liquidous temperature (TL)	217 °C
Time (t <sub>L</sub> ) maintained above T <sub>L</sub>	60-150s
Peak package body temperature (Tp)	must not exceed the Classification temp T <sub>c</sub> <sup>[1]</sup>
Time (t <sub>p</sub> )* within 5 °C of the specified classification temperature (T <sub>c</sub> )	30* seconds [2]
Ramp-down rate (Tp to TL)	6 °C/second max.
Time 25 °C to peak temperature	8 minutes max.

- \* [1] T<sub>c</sub>=260°C.
- \* [2] The time above 255 °C must not exceed 30 seconds.

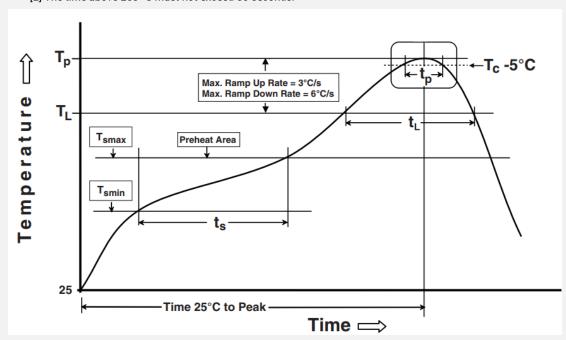


Figure 9 Reflow soldering profile (Refer to IPC/JEDEC J-STD-020E)



## 8 PRODUCT PACKAGING AND HANDLING

# 8.1 Packaging

#### 8.1.1 Packaging Notes

TAU1105 GNSS module is a Moisture Sensitive Device (MSD) and Electrostatic Sensitive Device (ESD). During the packing and shipping, it is strictly required to take appropriate MSD handling instructions and precautions. The table below shows the general packing hierarchy for the standard shipment.

**Table 13 Packing hierarchy** 



#### 8.1.2 Tape and Reel

The TAU1105 modules are delivered as hermetically sealed, reeled tapes in order to enable efficient production, production lot set-up and tear-down. The figure below shows the tape dimension.

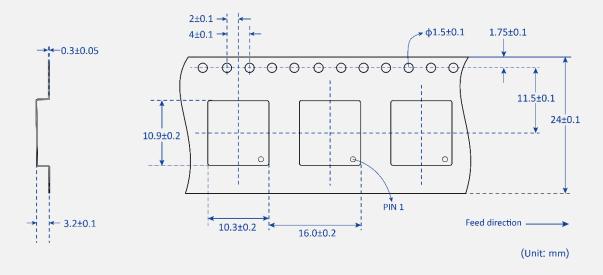


Figure 10 Tape dimensions



TAU1105 modules are deliverable in quantities of 1000pcs on a reel. The figure below shows the dimensions of reel for TAU1105.

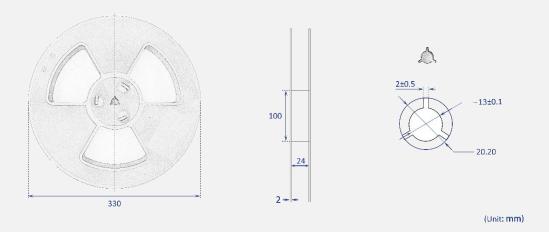
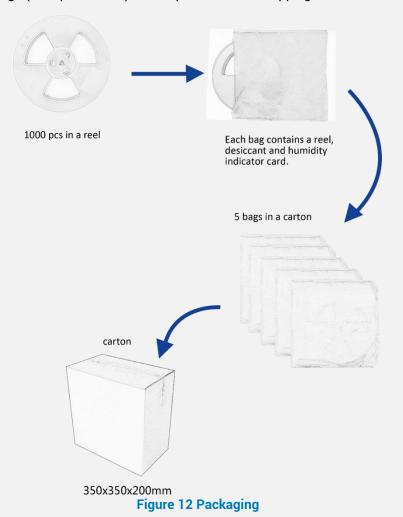


Figure 11 Reel dimensions

## 8.1.3 Shipment Packaging

The reels of TAU1105 modules are packed in the sealed bags and shipped by shipping cartons. Up to five sealed bags (5000pcs in total) can be packed in one shipping carton.





## 8.2 Storage

In order to prevent moisture intake and protect against electrostatic discharge, TAU1105 is packaged together with a humidity indicator card and desiccant to absorb humidity.

# 8.3 Handling

#### **8.3.1** ESD Handling Precautions

TAU1105 module which contains highly sensitive electronic circuitry is an Electrostatic Sensitive Device (ESD). Observe precautions for handling! Failure to observe these precautions may result in severe damage to the GNSS module!

- Unless there is a galvanic coupling between the local GND (i.e. the workbench) and the PCB GND, then the first point of contact when handling the PCB must always be between the local GND and PCB GND
- Before mounting an antenna patch, connect ground of the device.
- When handling the RF pin, do not come into contact with any charged capacitors and be careful when contacting materials that can develop charges (e.g. patch antenna ~10 pF, coax cable ~50 80 pF/m, soldering iron...)
- To prevent electrostatic discharge through the RF input, do not touch any exposed antenna area.
   If there is any risk that such exposed antenna area is touched in non ESD protected work area, implement proper ESD protection measures in the design.
- When soldering RF connectors and patch antennas to the receiver's RF pin, make sure to use an ESD safe soldering iron (tip).



#### 8.3.2 ESD Protection Measures

The GNSS positioning module is sensitive to static electricity. Whenever handling the module, particular care must be exercised to reduce the risk of electrostatic charges. In addition to standard ESD safety practices, the following measures should be taken into account.

- Add ESD Diodes to the RF input part to prevent electrostatics discharge.
- Do not touch any exposed antenna area.
- Add ESD Diodes to the UART interface.

#### **8.3.3** Moisture Sensitivity Level

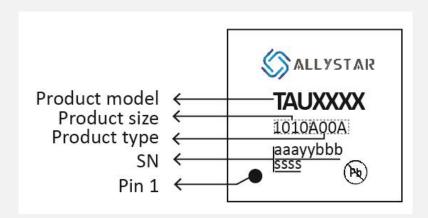
The Moisture Sensitivity Level (MSL) of the GNSS module is MSL4.



# 9 LABELING AND ORDERING INFORMATION

Labeling and ordering information help customers get more about Allystar products.

# 9.1 Labeling



**Table 14 Labeling content** 

Symbol	Explanation	Instance	
TAUXXXX	Product model TAU1105		
	1010 represents the product size.	1010A00	
1010A00A	A00 means the product type.		
TOTOAUUA	Second A refers to sales area code. Different code for	E (for Europe market)	
	different sales area.		
aaayybbbssss	Serial number.	351190010001	

# 9.2 Ordering info

**Table 15 Ordering codes** 

Ordering No.	Product
TAU1105-1010A00E	Concurrent GNSS LCC Module, TCXO, ROM, 10.1*9.7mm, 1000 pieces/reel,
TAUTTUS-TUTUAUUE	Europe market.
TAU1105-1010A00H	Concurrent GNSS LCC Module, TCXO, ROM, 10.1*9.7mm, 1000 pieces/reel,
1A01103-1010A00H	India market.
TAU1105-1010A00R	Concurrent GNSS LCC Module, TCXO, ROM, 10.1*9.7mm, 1000 pieces/reel,
1A01105-1010A00K	Russia market.



# 10 RELATED DOCUMENTS

- [1] Satrack User Manual
- [2] Allystar Common Commands
- [3] GNSS Protocol Specification

# 11 REVISION HISTORY

Revisio n	Date	Reviser	Status / Comments
V1.0	2019-08	Vita Wu	First released
V1.1	2019-09	Vita Wu	Logo and wording update
			Updates ANT_BIAS info;
			Adds PCB package info;
			Adds packaging info;
V1.2	2020-07	Vita Wu	Updates mechanical specification;
			Updates antenna gain to 36dB;
			Adds built-in chock in reference design;
			Simplifies Pin description;
			Updates MSL.
			Clarifies power on/off sequence.
			Updates AVDD_BAK connectivity description in Section 4.1.
		Vita Wu	Improves mechanical specification.
V1.3	2020-12		Improves wordings.
			Localization.
			Improves layout notes in Section 6.3.
			Deletes 1K resistor in the minimal design diagram.
			Updates description about short circuit protection.
	2021-07	021-07 Vita Wu	Adds labeling and ordering info.
			Details default settings.
V1.4			Adds related document list.
<b>V</b> 1.1	2021 07		Adds document info section.
			Removes C00 design
			Updates main voltage range to be 2.0V~3.6V.





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