

In [4]:

```
!pip install folium
```

Collecting folium
 Downloading folium-0.12.1.post1-py2.py3-none-any.whl (95 kB)
 Requirement already satisfied: numpy in c:\users\e.daboner\anaconda3\lib\site-packages (from folium) (1.20.1)
 Requirement already satisfied: jinja2>=2.9 in c:\users\e.daboner\anaconda3\lib\site-packages (from folium) (2.11.3)
 Requirement already satisfied: requests in c:\users\e.daboner\anaconda3\lib\site-packages (from folium) (2.25.1)
 Collecting branca>=0.3.0
 Downloading branca-0.5.0-py3-none-any.whl (24 kB)
 Requirement already satisfied: MarkupSafe>=0.23 in c:\users\e.daboner\anaconda3\lib\site-packages (from jinja2>=2.9->folium) (1.1.1)
 Requirement already satisfied: certifi>=2017.4.17 in c:\users\e.daboner\anaconda3\lib\site-packages (from requests->folium) (2020.12.5)
 Requirement already satisfied: urllib3<1.27,>=1.21.1 in c:\users\e.daboner\anaconda3\lib\site-packages (from requests->folium) (1.26.4)
 Requirement already satisfied: idna<3,>=2.5 in c:\users\e.daboner\anaconda3\lib\site-packages (from requests->folium) (2.10)
 Requirement already satisfied: chardet<5,>=3.0.2 in c:\users\e.daboner\anaconda3\lib\site-packages (from requests->folium) (4.0.0)
 Installing collected packages: branca, folium
 Successfully installed branca-0.5.0 folium-0.12.1.post1

In [24]:

```
!pip install polyline
```

Collecting polyline
 Downloading polyline-1.4.0-py2.py3-none-any.whl (4.4 kB)
 Requirement already satisfied: six>=1.8.0 in c:\users\e.daboner\anaconda3\lib\site-packages (from polyline) (1.15.0)
 Installing collected packages: polyline
 Successfully installed polyline-1.4.0

In [25]:

```
import pandas as pd
import matplotlib.pyplot as plt
import seaborn as sns
import numpy as np
import folium
import requests
import polyline
dataFrame=pd.read_csv('c:/datasets/RAS2.csv')
```

In [2]:

```
dataFrame.head()
```

Out[2]:

	Time	UTC Time	Lap	GPS_Update	GPS_Delay	Latitude	Longitude	Altitude (m)	Altitude (ft)	Speed (Km/h)	Heading	Accuracy (m)	Accel X	Accel Y	Accel Z	Brake (calculated)	Barometric Pressure (kPa)	Pressure Altitude (m)
0	0.000	1659024166	0	1	0	9.051417	7.491423	485.6	1593	0.3	-1.0	5.3	0.56	-1.05	1.04	1	95.55	492.2
1	0.006	1659024166	0	0	0	9.051417	7.491423	485.6	1593	0.3	-1.0	5.3	0.53	-1.05	1.04	1	95.55	492.2
2	0.053	1659024166	0	0	0	9.051417	7.491423	485.6	1593	0.3	-1.0	5.3	0.56	-1.04	1.10	1	95.55	492.2
3	0.104	1659024166	0	0	0	9.051417	7.491423	485.6	1593	0.3	-1.0	5.3	0.56	-1.04	1.10	1	95.55	492.2
4	0.154	1659024166	0	0	0	9.051417	7.491423	485.6	1593	0.3	-1.0	5.3	0.59	-1.04	1.14	1	95.55	492.2

In [3]:

```
dataFrame.info()
```

```
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 18246 entries, 0 to 18245
Data columns (total 18 columns):
 #   Column           Non-Null Count  Dtype  
--- 
 0   Time             18246 non-null   float64
 1   UTC Time         18246 non-null   int64  
 2   Lap              18246 non-null   int64  
 3   GPS_Update       18246 non-null   int64  
 4   GPS_Delay        18246 non-null   int64
```

```

5   Latitude          18246 non-null float64
6   Longitude         18246 non-null float64
7   Altitude (m)     18246 non-null float64
8   Altitude (ft)    18246 non-null int64
9   Speed (Km/h)     18246 non-null float64
10  Heading          18246 non-null float64
11  Accuracy (m)    18246 non-null float64
12  Accel X          18246 non-null float64
13  Accel Y          18246 non-null float64
14  Accel Z          18246 non-null float64
15  Brake (calculated) 18246 non-null int64
16  Barometric Pressure (kPa) 18246 non-null float64
17  Pressure Altitude (m) 18246 non-null float64
dtypes: float64(12), int64(6)
memory usage: 2.5 MB

```

```
In [4]:
newDf=dataFrame.drop(index=dataFrame.index[0::2])
newDf
newDf2=newDf.reset_index()
newDf3=newDf2.drop(index=newDf2.index[0::2])
newDf4=newDf3.reset_index()
newDf5=newDf4.drop(index=newDf4.index[0::2])
newDf5.head()
```

	level_0	index	Time	UTC Time	Lap	GPS_Update	GPS_Delay	Latitude	Longitude	Altitude (m)	Altitude (ft)	Speed (Km/h)	Heading	Accuracy (m)	Accel X	Accel Y	Accel Z	Brake (calculated)	Barometric Pressure (kPa)	Pressure Altitude (m)
1	3	7	0.305	1659024166	0	0	0	9.051417	7.491423	485.6	1593	0.3	-1.0	5.3	0.59	-1.05	1.13	1	95.55	492.2
3	7	15	0.696	1659024167	0	0	0	9.051419	7.491430	485.5	1593	1.2	-1.0	5.2	0.59	-1.04	1.09	1	95.55	492.3
5	11	23	1.099	1659024167	0	0	0	9.051419	7.491430	485.5	1593	1.2	-1.0	5.2	0.55	-1.03	1.09	1	95.55	492.3
7	15	31	1.499	1659024167	0	0	0	9.051419	7.491430	485.5	1593	1.2	-1.0	5.2	0.56	-1.06	1.11	1	95.55	492.3
9	19	39	1.901	1659024168	0	0	0	9.051417	7.491431	485.4	1592	0.6	-1.0	5.1	0.56	-1.04	1.12	1	95.55	492.3

```
In [5]:
newDf5.shape
```

```
Out[5]: (2280, 20)
```

```
In [6]:
locations=newDf5[["Latitude", "Longitude"]]
print(locations)

locationslist=locations.values.tolist()

print(len(locationslist))

print()
print(locationslist)

print(locationslist[9])
```

	Latitude	Longitude
1	9.051417	7.491423
3	9.051419	7.491430
5	9.051419	7.491430
7	9.051419	7.491430
9	9.051417	7.491431
...
4551	9.069009	7.446148
4553	9.069009	7.446148
4555	9.068983	7.446154

4557	9.068983	7.446154
4559	9.068983	7.446154

[2280 rows x 2 columns]
2280

[9.0681027, 7.4815982], [9.0681027, 7.4815982], [9.0681027, 7.4815982], [9.0680718, 7.4813981], [9.0680718, 7.4813981], [9.0680449, 7.4812014], [9.0680449, 7.4812014], [9.0680449, 7.4812014], [9.0680222, 7.4810006], [9.0680222, 7.4810006], [9.0680222, 7.4810006], [9.0680045, 7.4807966], [9.0680045, 7.4807966], [9.0679942, 7.4805898], [9.0679942, 7.4805898], [9.0679884, 7.4803803], [9.0679884, 7.4803803], [9.0679873, 7.4801656], [9.0679873, 7.4801656], [9.0679927, 7.4799494], [9.0679927, 7.4799494], [9.0680097, 7.4797289], [9.0680097, 7.4797289], [9.0680303, 7.4795066], [9.0680303, 7.4795066], [9.0680542, 7.4792858], [9.0680542, 7.4792858], [9.0680542, 7.4792858], [9.0680542, 7.4792858], [9.0680861, 7.4790604], [9.0681195, 7.478834], [9.0681195, 7.478834], [9.0681528, 7.4786006], [9.0681528, 7.4786006], [9.0681883, 7.4783634], [9.0681883, 7.4783634], [9.0681883, 7.4783634], [9.0682299, 7.4781236], [9.0682299, 7.4781236], [9.0682765, 7.4778784], [9.0682765, 7.4778784], [9.0682765, 7.4778784], [9.0683214, 7.4776332], [9.0683214, 7.4776332], [9.0683669, 7.4773899], [9.0683669, 7.4773899], [9.0684122, 7.4771477], [9.0684122, 7.4771477], [9.0684551, 7.4769024], [9.0684551, 7.4769024], [9.0684551, 7.4769024], [9.0684986, 7.4766557], [9.0685435, 7.4764098], [9.0685435, 7.4764098], [9.0685435, 7.4764098], [9.0685435, 7.4764098], [9.0685872, 7.4761643], [9.0685872, 7.4761643], [9.0686301, 7.4759185], [9.0686301, 7.4759185], [9.0686301, 7.4759185], [9.0686301, 7.4759185], [9.0686301, 7.4759185], [9.0686754, 7.4756699], [9.0686754, 7.4756699], [9.0687204, 7.4754227], [9.0687204, 7.4754227], [9.0687204, 7.4754227], [9.0687663, 7.4751768], [9.0687663, 7.4751768], [9.068815, 7.474933], [9.068815, 7.474933], [9.0688549, 7.4746871], [9.0688549, 7.4746871], [9.0688549, 7.4746871], [9.0688965, 7.474442], [9.0688965, 7.474442], [9.0689414, 7.4741996], [9.0689414, 7.4741996], [9.0689836, 7.4739539], [9.0689836, 7.4739539], [9.0690284, 7.4737099], [9.0690284, 7.4737099], [9.0690284, 7.4737099], [9.0690758, 7.4734657], [9.0691236, 7.4732219], [9.0691236, 7.4732219], [9.0691236, 7.4732219], [9.0691236, 7.4732219], [9.069171, 7.4729759], [9.069171, 7.4729759], [9.069171, 7.4729759], [9.069171, 7.4729759], [9.0692148, 7.4727303], [9.0692148, 7.4727303], [9.0692601, 7.4724863], [9.0692601, 7.4724863], [9.0693026, 7.4722417], [9.0693026, 7.4722417], [9.0693026, 7.4722417], [9.0693026, 7.4722417], [9.0693417, 7.4719969], [9.0693417, 7.4719969], [9.0693417, 7.4719969], [9.0693417, 7.4719969], [9.0693747, 7.4717538], [9.0693747, 7.4717538], [9.0694106, 7.471514], [9.0694106, 7.471514], [9.0694461, 7.4712743], [9.0694461, 7.4712743], [9.0694461, 7.4712743], [9.0694461, 7.4712743], [9.0694878, 7.4710392], [9.0695288, 7.4708122], [9.0695288, 7.4708122], [9.0695288, 7.4708122], [9.0695288, 7.4708122], [9.0695661, 7.4705944], [9.0695661, 7.4705944], [9.0695999, 7.4703808], [9.0695999, 7.4703808], [9.0696386, 7.470174], [9.0696386, 7.470174], [9.0696747, 7.4699697], [9.0696747, 7.4699697], [9.0696747, 7.4699697], [9.0696747, 7.4699697], [9.0697445, 7.4695757], [9.0697445, 7.4695757], [9.0697805, 7.4693951], [9.0697805, 7.4693951], [9.0698122, 7.4692254], [9.0698122, 7.4692254], [9.0698122, 7.4692254], [9.0698453, 7.4690571], [9.0698453, 7.4690571], [9.0698771, 7.4688921], [9.0698771, 7.4688921], [9.0699117, 7.4687248], [9.0699117, 7.4687248], [9.069944, 7.4685529], [9.069944, 7.4685529], [9.0699742, 7.4683781], [9.0699742, 7.4683781], [9.0700096, 7.4681969], [9.0700096, 7.4681969], [9.0700096, 7.4681969], [9.0700096, 7.4681969], [9.0700417, 7.4680145], [9.0700417, 7.4680145], [9.0700747, 7.4678274], [9.0700747, 7.4678274], [9.0701134, 7.4676431], [9.0701134, 7.4676431], [9.0701134, 7.4676431], [9.0701547, 7.4674601], [9.0701547, 7.4674601], [9.0701547, 7.4674601], [9.070196, 7.4672774], [9.070196, 7.4672774], [9.0702504, 7.4670938], [9.0702504, 7.4670938], [9.0702504, 7.4670938], [9.070307, 7.4669093], [9.070307, 7.4669093], [9.0703691, 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7.4580604], [9.0771279, 7.4579465], [9.0771279, 7.4579465], [9.0772084, 7.4578318], [9.0772084, 7.4578318], [9.0772084, 7.4578318], [9.0772854, 7.4577255], [9.0772854, 7.4577255], [9.0773556, 7.4576307], [9.0773556, 7.4576307], [9.0774161, 7.4575429], [9.0774161, 7.4575429], [9.0774608, 7.4574608], [9.0774608, 7.4574608], [9.0774608, 7.4574608], [9.0775177, 7.4573804], [9.0775177, 7.4573804], [9.077564, 7.4573042], [9.077564, 7.4573042], [9.0776049, 7.4572379], [9.0776049, 7.4572379], [9.0776049, 7.4572379], [9.0776431, 7.4571773], [9.0776431, 7.4571773], [9.0776759, 7.4571218], [9.0776759, 7.4571218], [9.0777053, 7.4570702], [9.0777053, 7.4570702], [9.0777335, 7.457021], [9.0777335, 7.457021], [9.0777335, 7.457021], [9.077766, 7.4569642], [9.077766, 7.4569642], [9.0777992, 7.4569016], [9.0777992, 7.4569016], [9.0778344, 7.4568381], [9.0778344, 7.4568381], [9.0778344, 7.4568381], [9.0778344, 7.4568381], [9.077871, 7.4567716], [9.077871, 7.4567716], [9.0779076, 7.4567022], [9.0779076, 7.4567022], [9.0779446, 7.4566305], [9.0779446, 7.4566305], [9.0779446, 7.4566305


```
In [7]: location_details=newDf5[['UTC Time', 'Speed (Km/h)']]
```

```
locationdetailslist=location_details.values.tolist()
print(len(locationdetailslist))
print()
print(locationdetailslist)
print()
print(locationdetailslist[9])
```

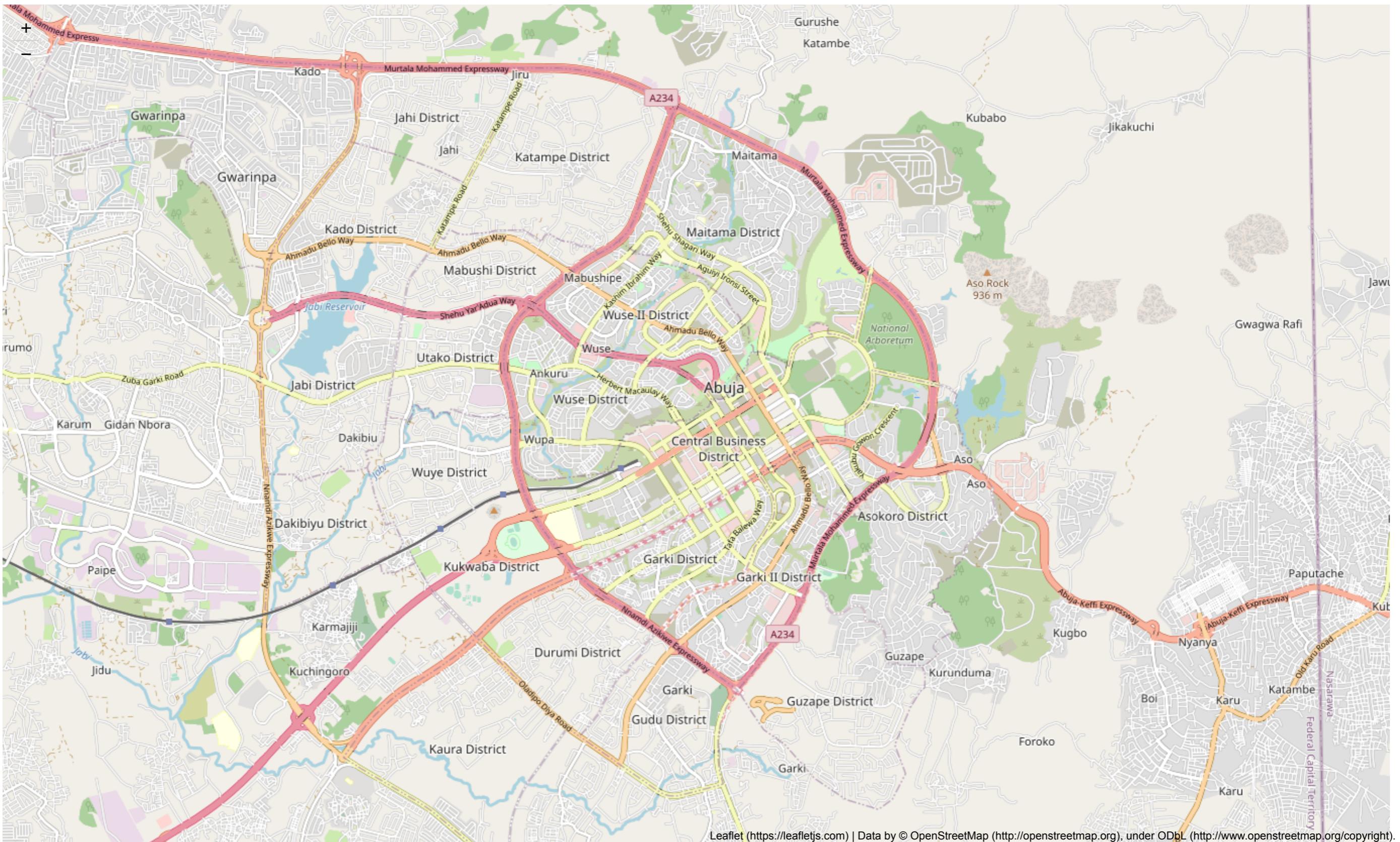
2280

[1659024170.0, 0.0]

In [8]:

```
map = folium.Map(location=[locations.Latitude.mean(), locations.Longitude.mean()], zoom_start=13)
map
```

Out[8]:

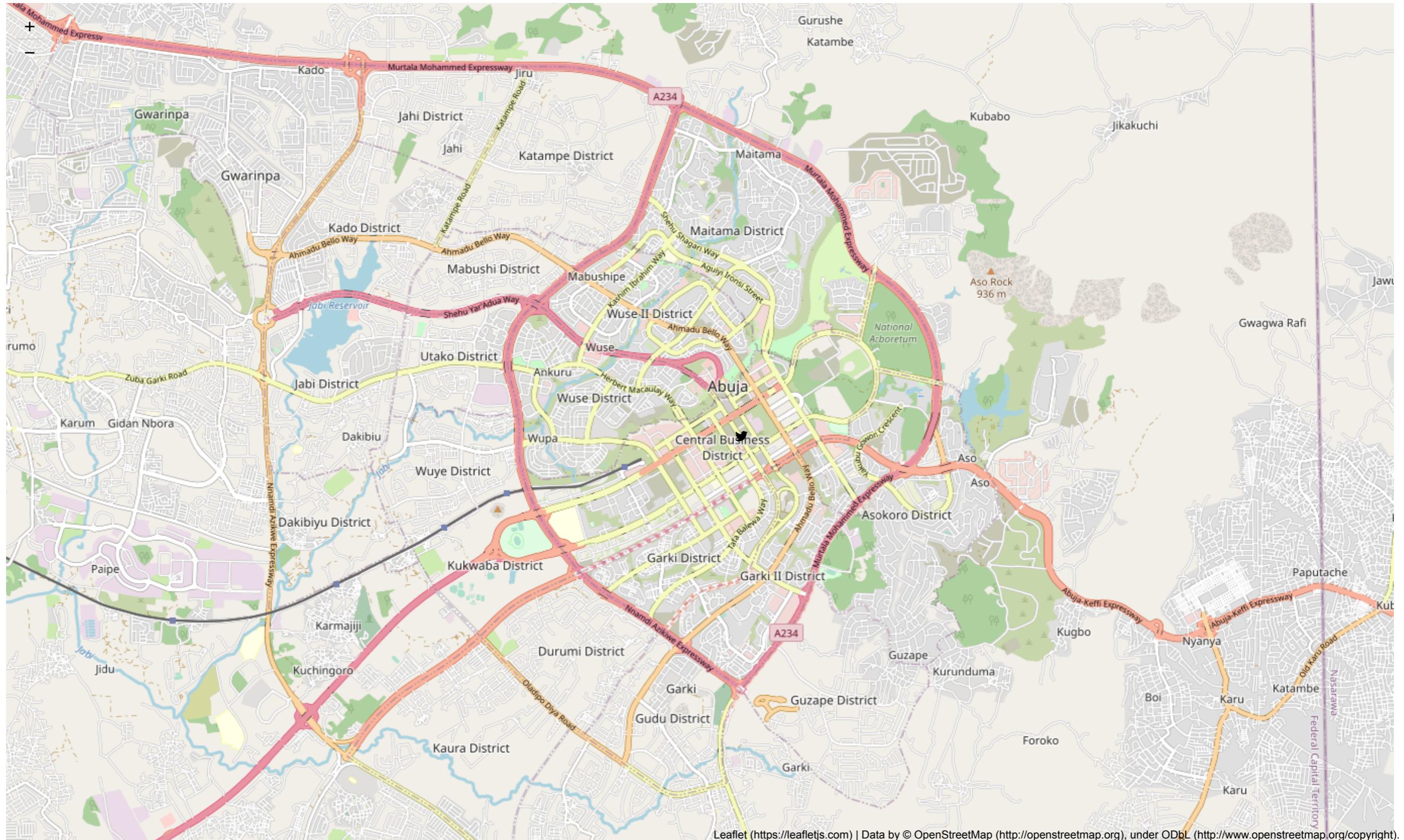


In [9]:

```
#starting point
folium.Marker(locationslist[1], popup=locationdetailslist[1], icon=folium.Icon(color="darkpurple", icon_color='white', icon="twitter", prefix='fa')).add_to(map)
folium.PolyLine(locations = [locationslist[1], locationslist[2]],
line_opacity = 0.2).add_to(map)
```

map

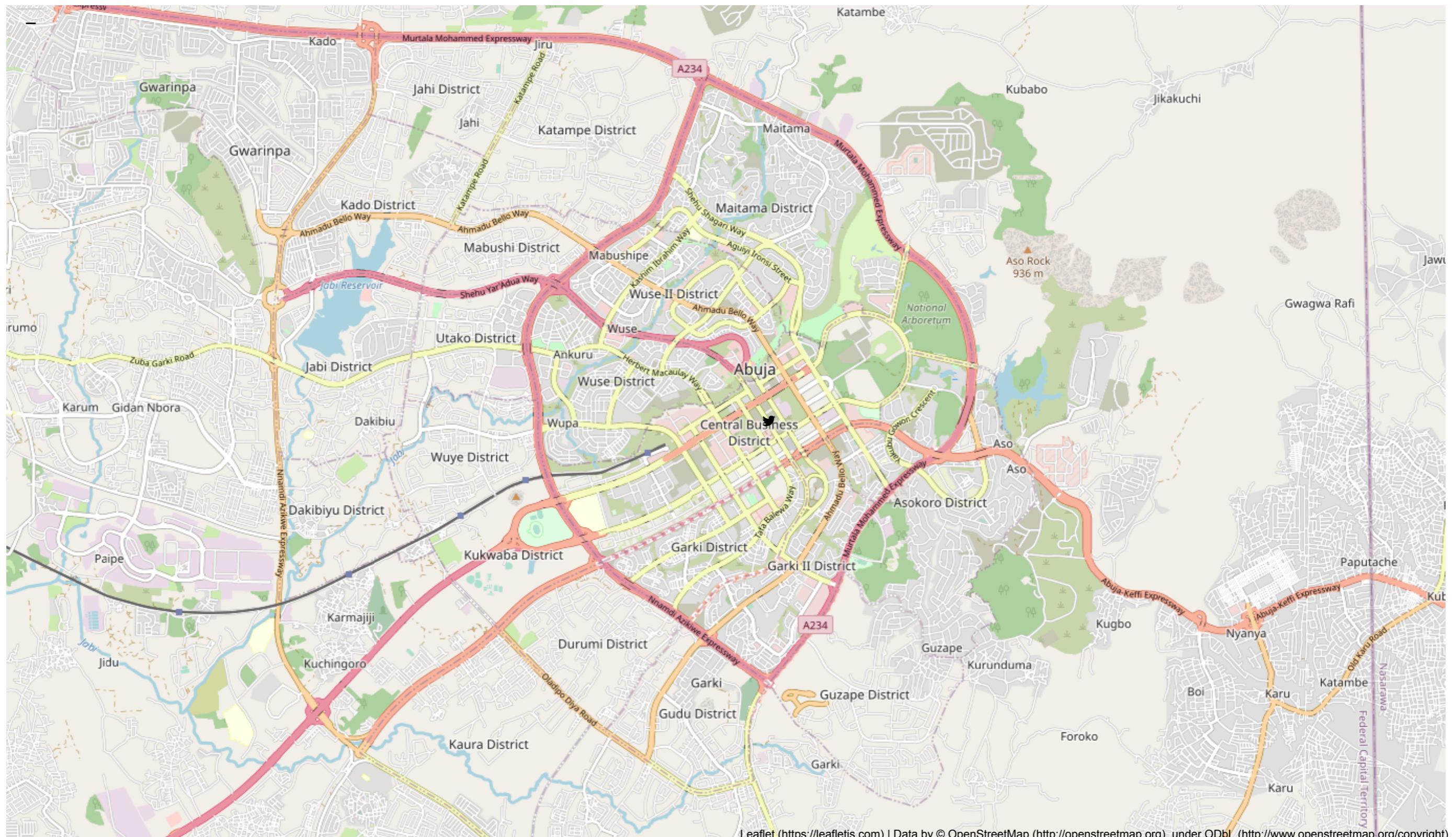
Out[9]:

Leaflet (<https://leafletjs.com>) | Data by © OpenStreetMap (<http://openstreetmap.org>), under ODbL (<http://www.openstreetmap.org/copyright>).

In [10]:

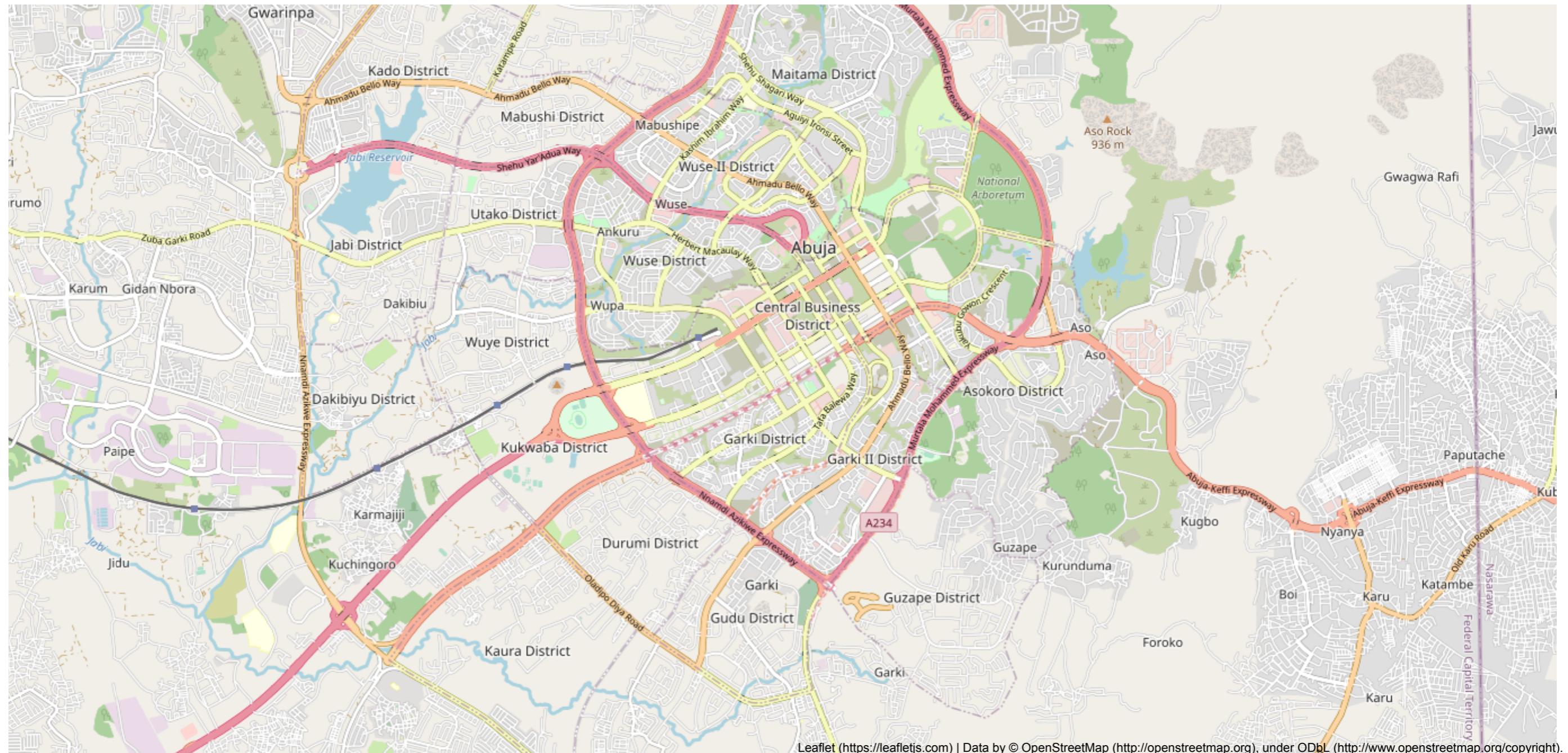
```
#middle point
folium.CircleMarker(locationslist[100], radius=1, popup=locationdetailslist[100]).add_to(map)
#folium.PolyLine(locations = [Locationslist[100], Locationslist[101]],
#                 line_opacity = 0.2).add_to(map)
map
```

Out[10]:



```
In [11]: map = folium.Map(location=[locations.Latitude.mean(), locations.Longitude.mean()], zoom_start=13)
map
```

```
Out[11]:
```



In [12]:

```
map = folium.Map(location=[locations.Latitude.mean(), locations.Longitude.mean()], zoom_start=13)

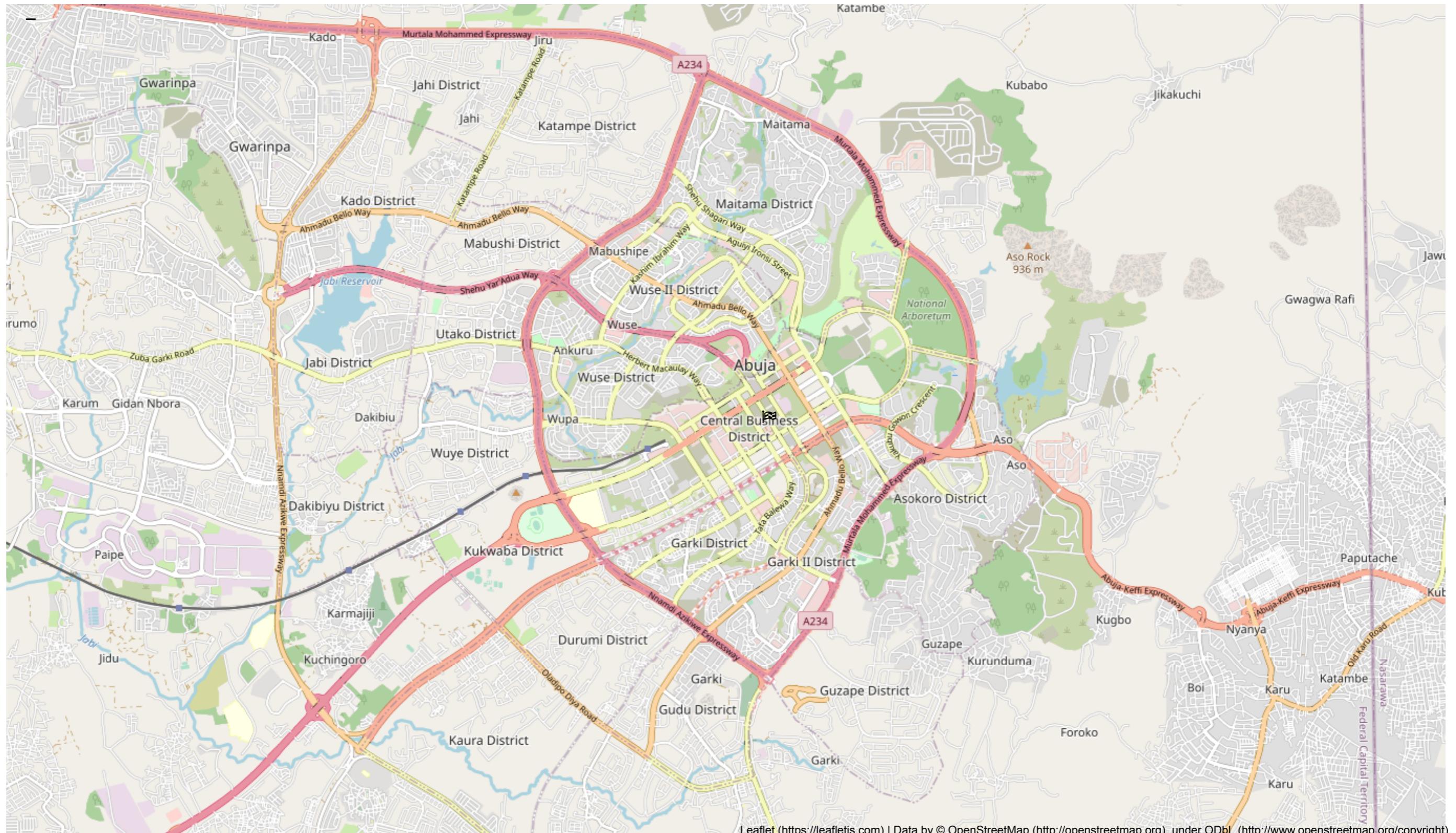
#starting point
folium.Marker(locationslist[1], popup=locationdetailslist[1],icon=folium.Icon(color="green", icon_color='white', icon="flag-checkered", prefix='fa')).add_to(map)
folium.PolyLine(locations = [locationslist[1], locationslist[2]],
    line_opacity = 0.2).add_to(map)

#middle points
for point in range(1, len(locationslist)-1):
    folium.CircleMarker(locationslist[point], radius=1, popup=locationdetailslist[point]).add_to(map)
    folium.PolyLine(locations = [locationslist[point], locationslist[point+1]],
        line_opacity = 0.2).add_to(map)

#Finish line
folium.Marker(locationslist[len(locationslist)-1], popup=locationdetailslist[len(locationslist)-1],icon=folium.Icon(color="red", icon_color='white', icon="flag-checkered", prefix='fa')).add_to(map)
folium.PolyLine(locations = [locationslist[len(locationslist)-2], locationslist[len(locationslist)-1]],
    line_opacity = 0.2).add_to(map)
map
```

Out[12]:





In [13]:

```
help(folium.Icon)
```

Help on class Icon in module folium.map:

```
class Icon(branca.element.MacroElement)
    | Icon(color='blue', icon_color='white', icon='info-sign', angle=0, prefix='glyphicon', **kwargs)
```

Creates an Icon object that will be rendered using Leaflet.awesome-markers.

Parameters

color : str, default 'blue'

The color of the marker. You can use:

```
['red', 'blue', 'green', 'purple', 'orange', 'darkred',
 'lightred', 'beige', 'darkblue', 'darkgreen', 'cadetblue',
 'darkpurple', 'white', 'pink', 'lightblue', 'lightgreen',
 'gray', 'black', 'lightgray']

icon_color : str, default 'white'
    The color of the drawing on the marker. You can use colors above,
    or an html color code.
icon : str, default 'info-sign'
    The name of the marker sign.
    See Font-Awesome website to choose yours.
    Warning : depending on the icon you choose you may need to adapt
    the `prefix` as well.
angle : int, default 0
    The icon will be rotated by this amount of degrees.
prefix : str, default 'glyphicon'
    The prefix states the source of the icon. 'fa' for font-awesome or
    'glyphicon' for bootstrap 3.

https://github.com/lvoogdt/Leaflet.awesome-markers

Method resolution order:
Icon
branca.element.MacroElement
branca.element.Element
builtins.object

Methods defined here:

__init__(self, color='blue', icon_color='white', icon='info-sign', angle=0, prefix='glyphicon', **kwargs)
    Initialize self. See help(type(self)) for accurate signature.

-----
Data and other attributes defined here:

color_options = {'beige', 'black', 'blue', 'cadetblue', 'darkblue', 'd...'

-----
Methods inherited from branca.element.MacroElement:

render(self, **kwargs)
    Renders the HTML representation of the element.

-----
Methods inherited from branca.element.Element:

add_child(self, child, name=None, index=None)
    Add a child.

add_children(self, child, name=None, index=None)
    Add a child.

add_to(self, parent, name=None, index=None)
    Add element to a parent.

get_bounds(self)
    Computes the bounds of the object and all it's children
    in the form [[lat_min, lon_min], [lat_max, lon_max]].

get_name(self)
    Returns a string representation of the object.
    This string has to be unique and to be a python and
    javascript-compatible
    variable name.

get_root(self)
    Returns the root of the elements tree.
```

```

save(self, outfile, close_file=True, **kwargs)
    Saves an Element into a file.

    Parameters
    -----
    outfile : str or file object
        The file (or filename) where you want to output the html.
    close_file : bool, default True
        Whether the file has to be closed after write.

to_dict(self, depth=-1, ordered=True, **kwargs)
    Returns a dict representation of the object.

to_json(self, depth=-1, **kwargs)
    Returns a JSON representation of the object.

-----
Data descriptors inherited from branca.element.Element:

__dict__
    dictionary for instance variables (if defined)

__weakref__
    list of weak references to the object (if defined)

```

In []:

In [14]:

`help(folium.CircleMarker)`

Help on class CircleMarker in module folium.vector_layers:

```

class CircleMarker(folium.map.Marker)
    CircleMarker(location=None, radius=10, popup=None, tooltip=None, **kwargs)

    A circle of a fixed size with radius specified in pixels.

    See :func:`folium.vector_layers.path_options` for the `Path` options.

Parameters
-----
location: tuple[float, float]
    Latitude and Longitude pair (Northing, Easting)
popup: string or folium.Popup, default None
    Input text or visualization for object displayed when clicking.
tooltip: str or folium.Tooltip, default None
    Display a text when hovering over the object.
radius: float, default 10
    Radius of the circle marker, in pixels.
**kwargs
    Other valid (possibly inherited) options. See:
    https://leafletjs.com/reference-1.6.0.html#circlemarker

```

Method resolution order:

```

CircleMarker
folium.map.Marker
branca.element.MacroElement
branca.element.Element
builtins.object

```

Methods defined here:

```

__init__(self, location=None, radius=10, popup=None, tooltip=None, **kwargs)
    Initialize self. See help(type(self)) for accurate signature.

```

Methods inherited from folium.map.Marker:

```
render(self)
    Renders the HTML representation of the element.

-----
Methods inherited from branca.element.Element:

add_child(self, child, name=None, index=None)
    Add a child.

add_children(self, child, name=None, index=None)
    Add a child.

add_to(self, parent, name=None, index=None)
    Add element to a parent.

get_bounds(self)
    Computes the bounds of the object and all it's children
    in the form [[lat_min, lon_min], [lat_max, lon_max]].

get_name(self)
    Returns a string representation of the object.
    This string has to be unique and to be a python and
    javascript-compatible
    variable name.

get_root(self)
    Returns the root of the elements tree.

save(self, outfile, close_file=True, **kwargs)
    Saves an Element into a file.

    Parameters
    -----
    outfile : str or file object
        The file (or filename) where you want to output the html.
    close_file : bool, default True
        Whether the file has to be closed after write.

to_dict(self, depth=-1, ordered=True, **kwargs)
    Returns a dict representation of the object.

to_json(self, depth=-1, **kwargs)
    Returns a JSON representation of the object.

-----
Data descriptors inherited from branca.element.Element:

__dict__
    dictionary for instance variables (if defined)

__weakref__
    list of weak references to the object (if defined)
```

In [15]:

```
#OSRM
```

In [16]:

```
print(len(locationslist))
print(locationslist[0])
print(locationslist[2279])
```

```
2280
[9.0514168, 7.4914232]
[9.068983, 7.4461538]
```

In []:

```
http://router.project-osrm.org/route/v1/driving/13.388860,52.517037;13.397634,52.529407;13.428555,52.523219?overview=false
```

In [19]:

```
url = "http://router.project-osrm.org/route/v1/driving/9.0514168,7.4914232;9.068983,7.4461538"
r = requests.get(url)
res = r.json()
res
```

```
Out[19]: {'code': 'Ok',
'routes': [{''geometry': 's~ul@u{gv@dPnBhU|FtZxKf^|EwCuR|@gAvEEeD}IeG_H{FoYpAmBfUeGrVq@hSdA`q@uk@fMkElGmFpJxC`d@|FnKrC',
'legs': [{''steps': [],
'summary': '',
'weight': 1082,
'duration': 1082,
'distance': 7416}],
'weight_name': 'routability',
'weight': 1082,
'duration': 1082,
'distance': 7416}],
'waypoints': [{''hint': '45nfgtAz5oNJAAAAdQAAAFkJAACiAgAAkhZKQn7SoEI9pM5E88_oQ0kAAAB1AAAAWQkAAKICAACZGgAA8jGKAMBLcgAZHYoAX09yAA0A3wsm41_Y',
'distance': 597.956307,
'name': '',
'location': [9.056754, 7.490496]},
{'hint': 'D5zfhU05oMAAAAAaQAAAJ8DAAD8BQAAAAAAAGygkEIDQyBE3EGERAAAAABpAAAAAnwMAAPwFAACZGgAA3mmKAGmacQC3YYoAip5xAAIA_wEm41_Y',
'distance': 258.347153,
'name': '',
'location': [9.07107, 7.445097]}]]}
```

In []:

```
...
The trip has distance of 7416 meters and a travel time of 1082 seconds
```

```
...
```

In [36]:

```
polyline.decode('s~ul@u{gv@dPnBhU|FtZxKf^|EwCuR|@gAvEEeD}IeG_H{FoYpAmBfUeGrVq@hSdA`q@uk@fMkElGmFpJxC`d@|FnKrC', precision=5, geojson=True)
```

Out[36]:

```
[(9.05675, 7.4905),
(9.05619, 7.48775),
(9.05492, 7.48418),
(9.05287, 7.47975),
(9.05176, 7.47475),
(9.05491, 7.47551),
(9.05527, 7.4752),
(9.0553, 7.47412),
(9.05705, 7.47495),
(9.05849, 7.47626),
(9.06273, 7.47752),
(9.06328, 7.47711),
(9.06459, 7.47355),
(9.06484, 7.46977),
(9.06449, 7.46652),
(9.07164, 7.45851),
(9.07266, 7.45623),
(9.07385, 7.45488),
(9.07308, 7.45303),
(9.07181, 7.4471),
(9.07107, 7.4451)]
```

In [45]:

```
def get_route(pickup_lat, pickup_lon, dropoff_lat, dropoff_lon):
    loc = "{};{};{};{}".format(pickup_lat, pickup_lon, dropoff_lat, dropoff_lon)
    url = "http://router.project-osrm.org/route/v1/driving/"
    r = requests.get(url + loc)
    if r.status_code != 200:
        return {}
```

```

res = r.json()
routes = polyline.decode(res['routes'][0]['geometry'], precision=5, geojson=True)
start_point = [res['waypoints'][0]['location'][0], res['waypoints'][0]['location'][1]]
end_point = [res['waypoints'][1]['location'][0], res['waypoints'][1]['location'][1]]

distance = res['routes'][0]['distance']

out = {'route':routes,
       'start_point':start_point,
       'end_point':end_point,
       'distance':distance
      }

return out

```

In [46]:

```

pickup_lat, pickup_lon, dropoff_lat, dropoff_lon = 9.0514168,7.4914232,9.068983,7.4461538
test_route = get_route(pickup_lat, pickup_lon, dropoff_lat, dropoff_lon)
test_route

```

Out[46]:

```

{'route': [(9.05675, 7.4905),
           (9.05619, 7.48775),
           (9.05492, 7.48418),
           (9.05287, 7.47975),
           (9.05176, 7.47475),
           (9.05491, 7.47551),
           (9.05527, 7.4752),
           (9.0553, 7.47412),
           (9.05705, 7.47495),
           (9.05849, 7.47626),
           (9.06273, 7.47752),
           (9.06328, 7.47711),
           (9.06459, 7.47355),
           (9.06484, 7.46977),
           (9.06449, 7.46652),
           (9.07164, 7.45851),
           (9.07266, 7.45623),
           (9.07385, 7.45488),
           (9.07308, 7.45303),
           (9.07181, 7.4471),
           (9.07107, 7.4451)],
 'start_point': [9.056754, 7.490496],
 'end_point': [9.07107, 7.445097],
 'distance': 7416}

```

In [65]:

```

def get_map(route):

    m = folium.Map(location=[(route['start_point'][0] + route['end_point'][0])/2,
                             (route['start_point'][1] + route['end_point'][1])/2],
                   zoom_start=13)

    folium.PolyLine(
        route['route'],
        weight=8,
        color='black',
        opacity=0.6
    ).add_to(m)

    folium.Marker(
        location=route['start_point'],
        icon=folium.Icon(color="green", icon_color='white', icon="flag-checkered", prefix='fa')
    ).add_to(m)

    folium.Marker(

```

```

location=route['end_point'],
icon=folium.Icon(color="red", icon_color='white', icon="flag-checkered", prefix='fa')
).add_to(m)

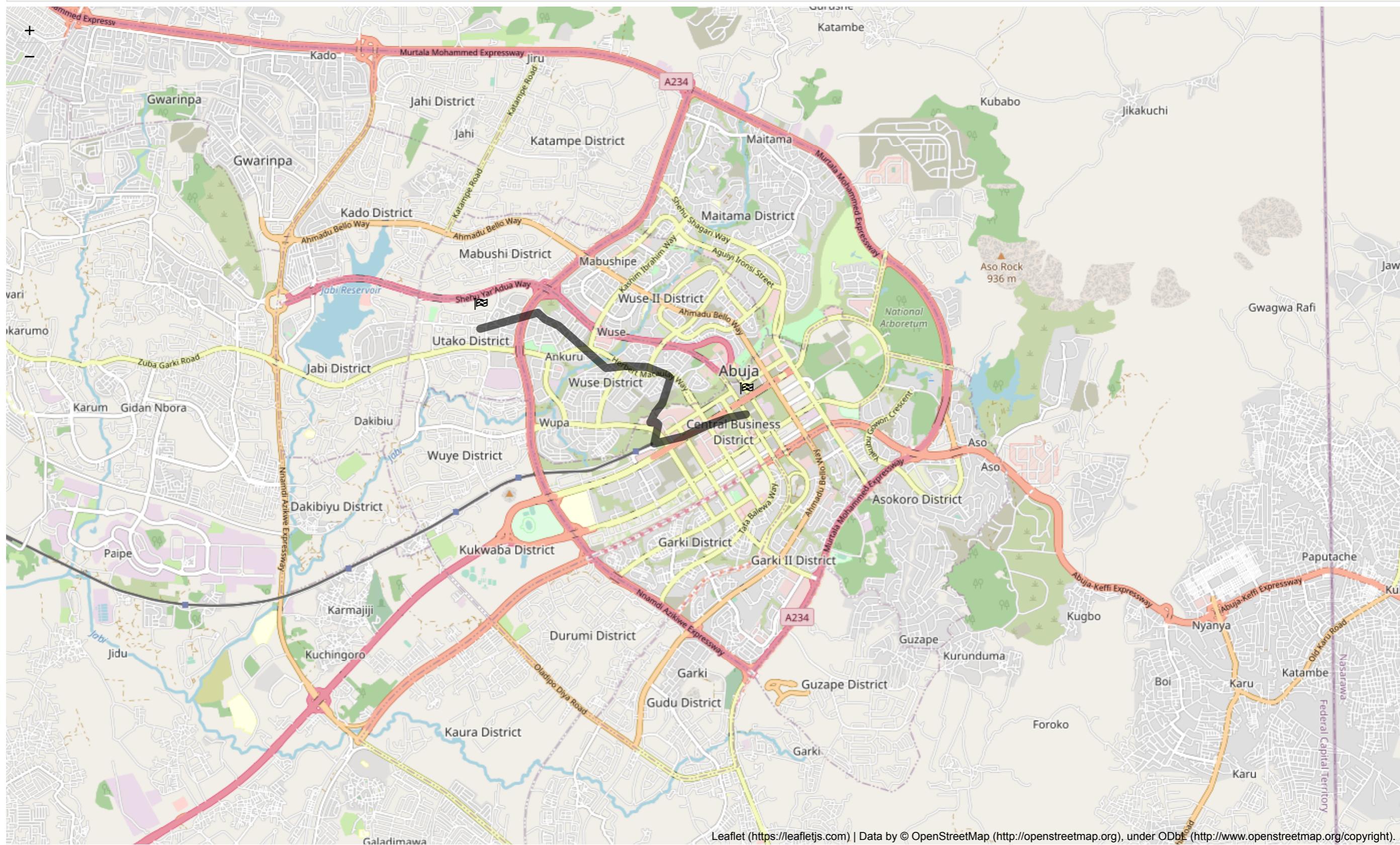
return m

```

In [66]:

```
# Route rendered using OSRM
get_map(test_route)
```

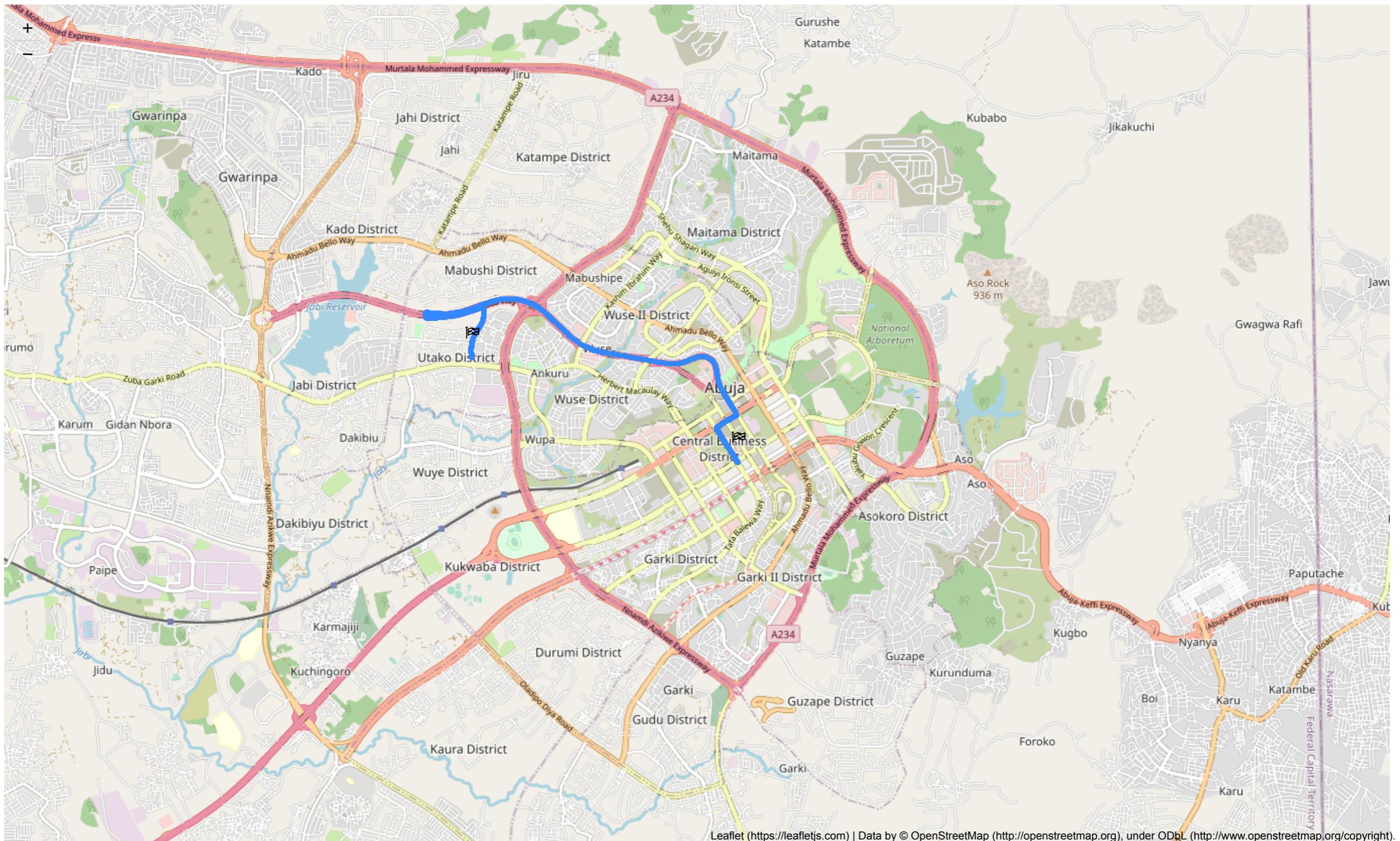
Out[66]:



In [32]:

```
# Route rendered by plotting all the coordinates using folium
map
```

Out[32]:



Leaflet (<https://leafletjs.com>) | Data by © OpenStreetMap (<http://openstreetmap.org>), under ODbL (<http://www.openstreetmap.org/copyright>).

In [33]:

```
help(polyline.decode)
```

Help on function decode in module polyline:

```
decode(expression, precision=5, geojson=False)
```

Decode a polyline string into a set of coordinates.

:param expression: Polyline string, e.g. 'u{~vFvyys@fs]'.

```
:param precision: Precision of the encoded coordinates. Google Maps uses 5, OpenStreetMap uses 6.  
    The default value is 5.  
:param geojson: Set output of tuples to (lon, lat), as per https://tools.ietf.org/html/rfc7946#section-3.1.1  
:return: List of coordinate tuples in (lat, lon) order, unless geojson is set to True.
```

In []:

In []: