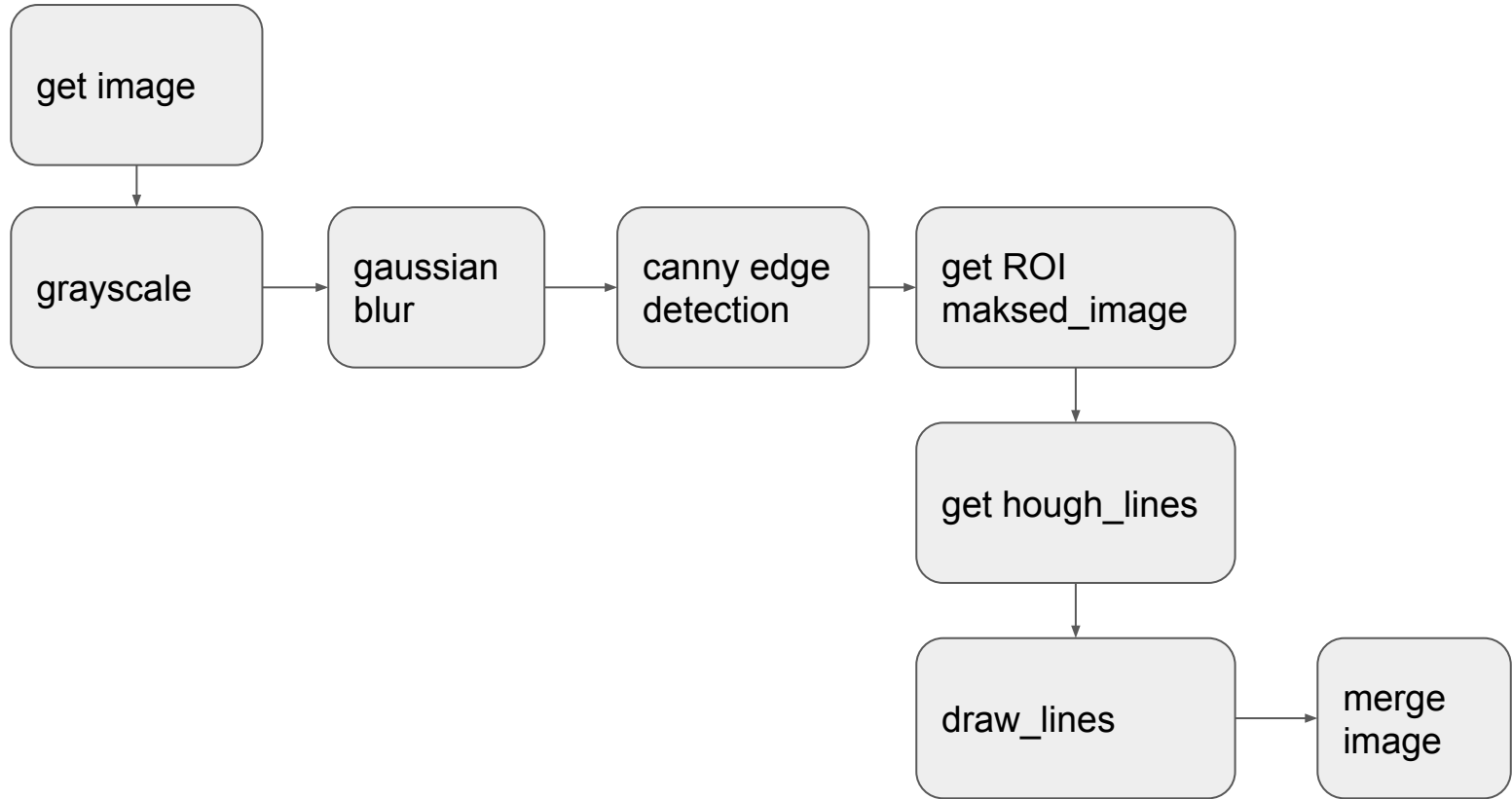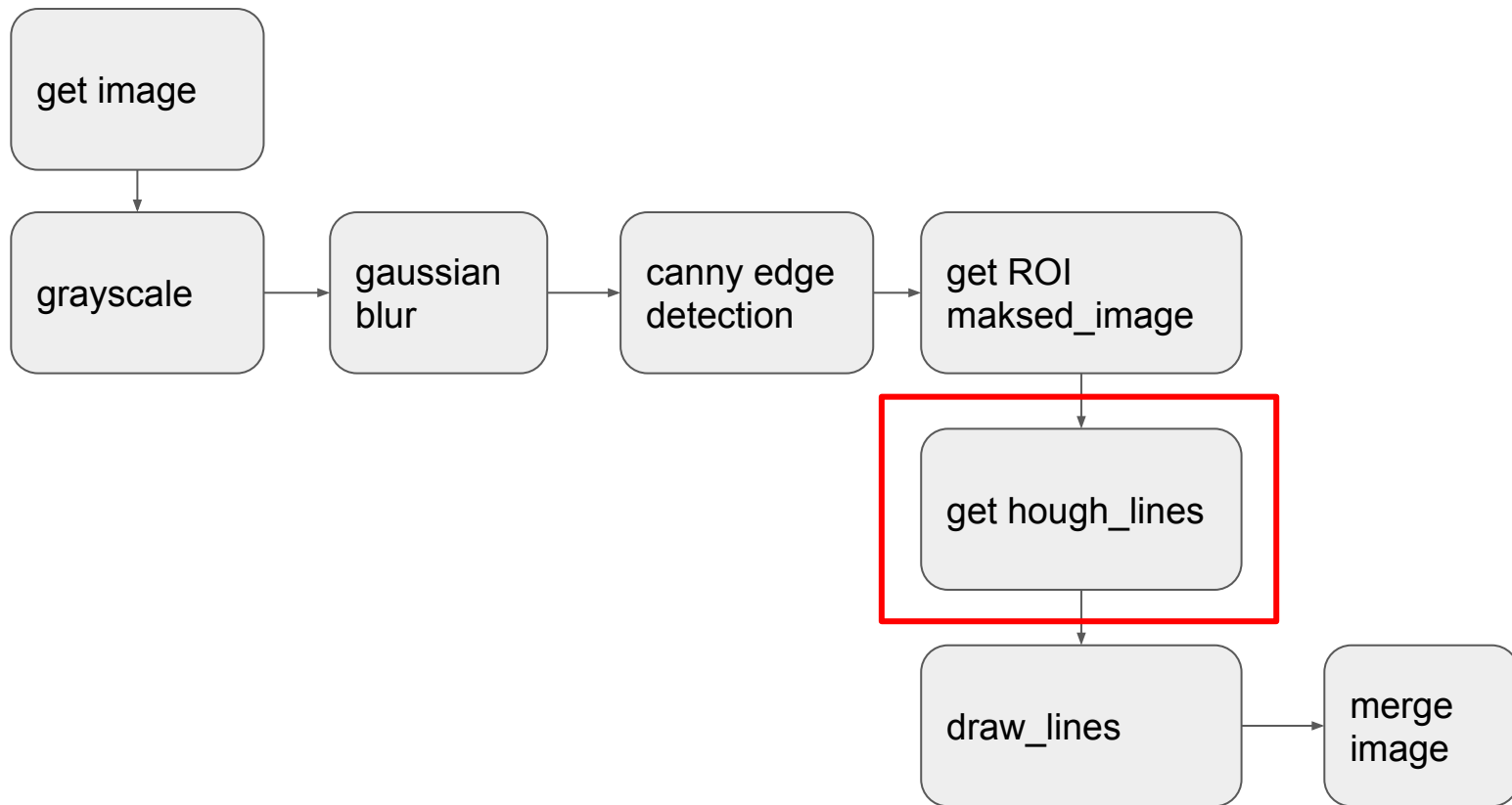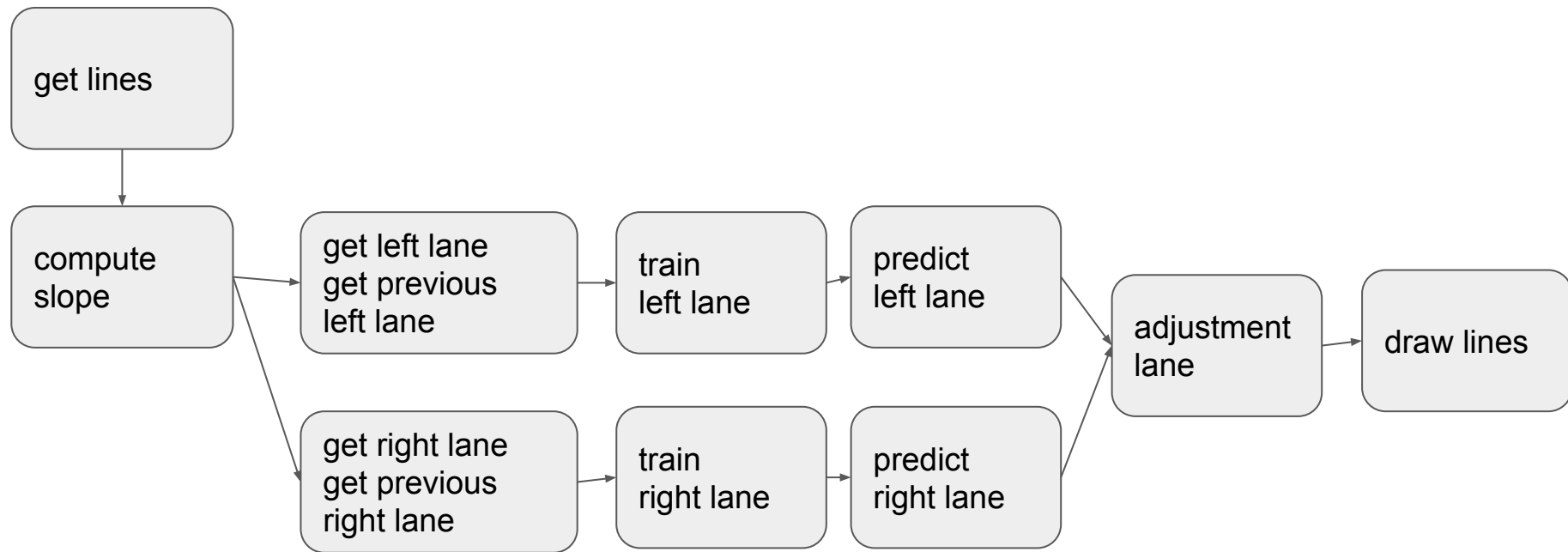# Reflection: Total pipeline

Reflection: dive into get hough_line

Reflection: get hough_line

Potential shortcomings my pipeline

My pipeline uses the previous data if it does not get the appropriate linear value.

Therefore, detection can be difficult if the steering angle changes suddenly.

Suggest Possible improvement my pipeline

The pipeline I use now depends too much on the Hough linear transformation.

It would be better to consider other pipelines for more robust and secure lane detection.