

# Discrete Fourier Transform



Jean-Baptiste Joseph **Fourier**  
1768~1830

Wonyong Sung

## Fourier Transform

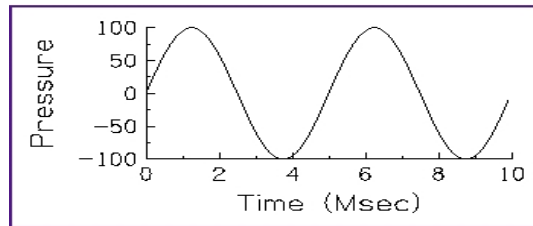
- Property of transforms:
  - They convert a function from one domain to another with no loss of information
- Fourier Transform: converts a function from the time (or spatial) domain to the frequency domain

$$F(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt$$

# Time Domain and Frequency Domain

- Time Domain:

- Tells us how properties (air pressure in a sound function, for example) change over time:

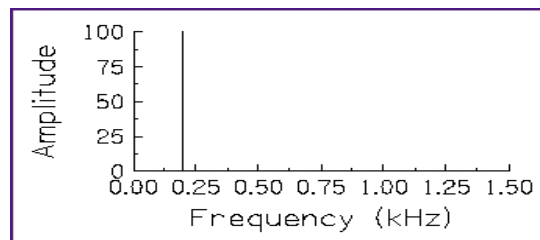


- Amplitude = 100
- Frequency = number of cycles in one second = 200 Hz

# Time Domain and Frequency Domain

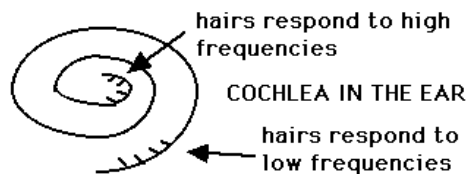
- Frequency domain:

- Tells us how properties (amplitudes) change over frequencies:



## Time Domain and Frequency Domain

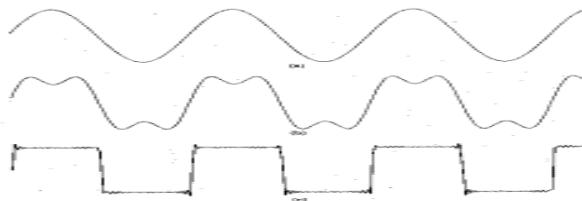
- Example:
  - Human ears do not hear wave-like oscillations, but constant tone



- Often it is easier to work in the frequency domain

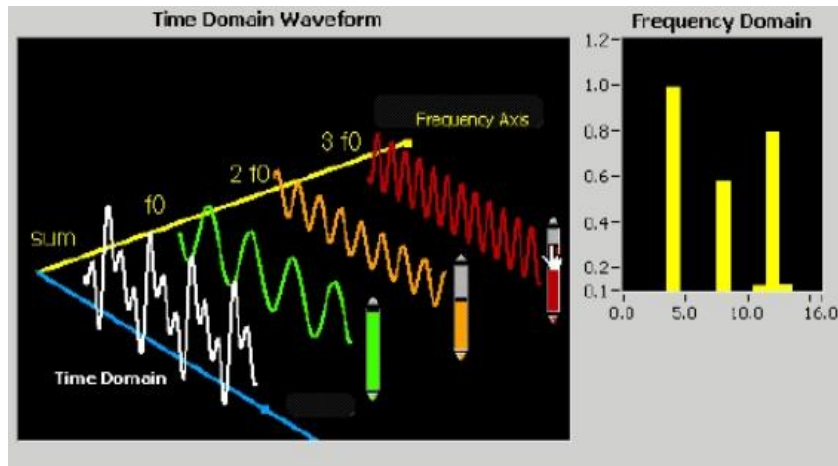
## Time Domain and Frequency Domain

- In 1807, Jean Baptiste Joseph Fourier showed that any periodic signal could be represented by a series of sinusoidal functions



In picture: the composition of the first two functions gives the bottom one

# Time Domain and Frequency Domain



		Hertz	cpspch	Half-Step	MIDI Note
c	5	523.25	9.00	3	72
b	4	493.88	8.11	2	71
a#	4	466.16	8.10	1	70
a	4	440.0	8.09	0	69
g#	4	415.3	8.08	-1	68
g	4	391.1	8.07	-2	67
f#	4	369.99	8.06	-3	66
f	4	349.23	8.05	-4	65
e	4	329.63	8.04	-5	64
d#	4	311.13	8.03	-6	63
d	4	293.66	8.02	-7	62
c#	4	277.18	8.01	-8	61
c	4	261.63	8.00	-9	60

# Fourier Transform

## EULER's FORMULA

- Because of the property:
 
$$e^{i\theta} = \cos \theta + i \sin \theta$$

$$e^{i\omega t} = \cos \omega t + i \sin \omega t$$
 where  $i = \sqrt{-1}$

- Fourier Transform takes us to the frequency domain:

$$F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt$$

the Fourier transform; strength of frequency  $\omega$  contained in  $f(t)$

scale factor for the Fourier Transform  $F(\omega)$ ; the original signal in the time domain; the "inverse Fourier transform".

sinusoidally varying "basis" function for the expansion

CTFT

CTFT :  $ContSignals \rightarrow ContSignals$ .

InvCTFT :  $ContSignals \leftarrow ContSignals$

$t \rightarrow x(t)$                        $\omega \rightarrow X(\omega)$

$$\forall \omega, \quad X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-i\omega t} dt$$

$$\forall t, \quad x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{i\omega t} d\omega$$

Discrete-time Fourier Transform (DTFT)

$$\begin{aligned}\text{DTFT} : \text{DiscSignals} &\rightarrow \text{ContPeriodic}_{2\pi} \\ \text{InvDTFT} : \text{ContPeriodic}_{2\pi} &\leftarrow \text{DiscSignals}\end{aligned}$$

$$n \rightarrow x(n) \qquad \omega \rightarrow X(\omega)$$

$$\forall \omega \in \text{Reals}, \quad X(\omega) = \sum_{-\infty}^{\infty} x(n)e^{-i\omega n}$$

Sequence domain: discrete and unlimited length  
Frequency domain: continuous

$$\forall n \in \text{Ints}, \quad x(n) = \frac{1}{2\pi} \int_0^{2\pi} X(\omega)e^{i\omega n} d\omega$$

## Discrete Fourier Transform

- In practice, we often deal with discrete functions (digital signals, for example)
- The input is of limited length (n)
- Discrete version of the Fourier Transform is much more useful in computer science:

$$f_j = \sum_{k=0}^{n-1} x_k e^{-\frac{2\pi i}{n}jk} \quad j = 0, \dots, n-1$$

- $O(n^2)$  time complexity

## Discrete Fourier Transform

In practice, we often deal with discrete functions

The input is of limited length ( $n$ )

Discrete version of the Fourier Transform is much more useful in computer science:

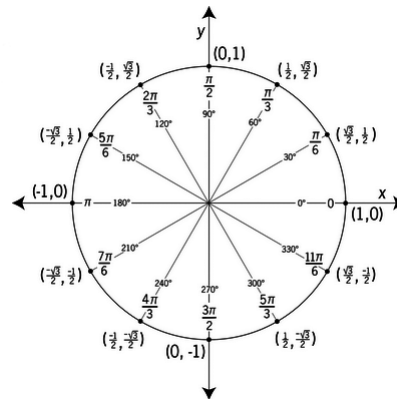
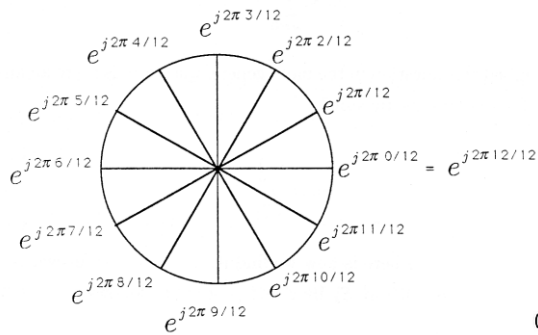
Let  $x[n]$  be an  $N$ -point signal, and  $W_N$  be the  $N^{\text{th}}$  root of unity. The  $N$ -point discrete Fourier Transform of  $x[n]$ , denoted  $X(k) = \text{DFT}\{x[n]\}$ , is defined as

$$\begin{aligned} X(k) &= \sum_{n=0}^{N-1} x[n] W_N^{kn}, \quad 0 \leq k \leq N-1 \\ &= \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi kn}{N}} \end{aligned}$$

### $W_N^k$ $N^{\text{th}}$ Root of Unity

$$W_N = \exp\left(-\frac{j2\pi}{N}\right)$$

- |                      |                             |
|----------------------|-----------------------------|
| 1) $W_N^{N/4} = j$   | 5) $W_N^{k+N} = W_N^k$      |
| 2) $W_N^{N/2} = -1$  | 6) $W_N^{k+(N/2)} = -W_N^k$ |
| 3) $W_N^{3N/4} = -j$ | 7) $W_N^{2k} = W_{N/2}^k$   |
| 4) $W_N^N = 1$       | 8) $W_N^* = W_N^{-1}$       |



## Matrix Formulation

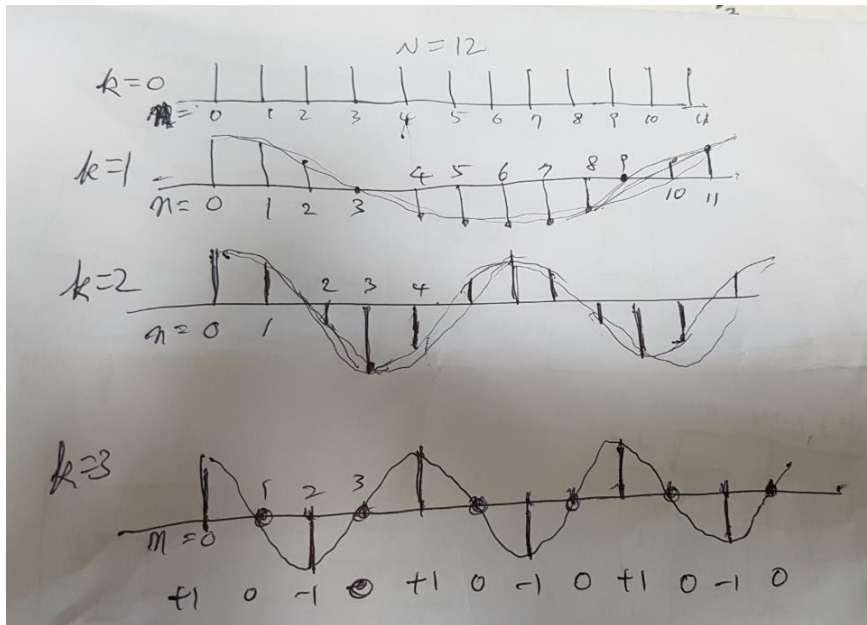
$$\begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ \vdots \\ X(N-1) \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & W_N^1 & W_N^2 & \cdots & W_N^{N-1} \\ 1 & W_N^2 & W_N^4 & \cdots & W_N^{2(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^{N-1} & W_N^{2(N-1)} & \cdots & W_N^{(N-1)(N-1)} \end{bmatrix} \begin{bmatrix} x[0] \\ x[1] \\ x[2] \\ \vdots \\ x[N-1] \end{bmatrix}$$

$$\underline{X} = W \underline{x}$$

주기가 N인 discrete (cosine, sine)  
sequence (한 sample에  $2\pi/N$  씩 진전)

주기가 N/2인 discrete (cosine,  
sine) sequence





## Matrix Formulation

$$\begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ \vdots \\ X(N-1) \end{bmatrix} = \frac{1}{N} \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & W_N^{-1} & W_N^{-2} & \dots & W_N^{-(N-1)} \\ 1 & W_N^{-2} & W_N^{-4} & \dots & W_N^{-2(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^{-(N-1)} & W_N^{-2(N-1)} & \dots & W_N^{-(N-1)(N-1)} \end{bmatrix} \begin{bmatrix} x[0] \\ x[1] \\ x[2] \\ \vdots \\ x[N-1] \end{bmatrix}$$

$$\underline{x} = \frac{1}{N} W^* \underline{X}$$

## Inverse Discrete Fourier Transform

Let  $X(k)$  be an  $N$ -point DFT sequence, and  $W_N$  be the  $N^{\text{th}}$  root of unity. The  $N$ -point inverse discrete Fourier Transform of  $X(k)$ , denoted  $x[n] = \text{IDFT}\{X(k)\}$ , is defined as

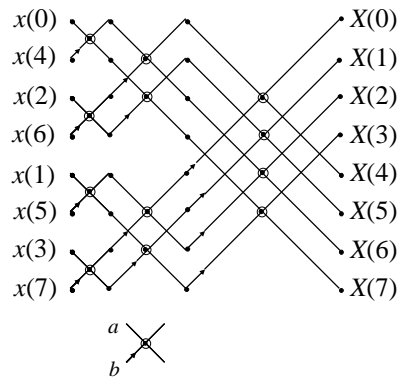
$$\begin{aligned} x[n] &= \frac{1}{N} \sum_{k=0}^{N-1} X(k) W_N^{-kn}, \quad 0 \leq n \leq N-1 \\ &= \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{j \frac{2\pi kn}{N}} \end{aligned}$$

## Faster DFT computation?

- Take advantage of the symmetry and periodicity of the complex exponential (let  $W_N = e^{-j2\pi/N}$ )
  - symmetry:  $W_N^{k[N-n]} = W_N^{-kn} = (W_N^{kn})^*$
  - periodicity:  $W_N^{kn} = W_N^{k[n+N]} = W_N^{(k+N)n}$
- Note that two length  $N/2$  DFTs take less computation than one length  $N$  DFT:  $2(N/2)^2 < N^2$
- Algorithms that exploit computational savings are collectively called *Fast Fourier Transforms*

## 8-point FFT

### • 8-point Signal Flow Diagram



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## FFT times

### • Time (1 multiplication per microsec)

	$N$	Direct DFT	FFT
$2^6$	64	.02 sec	.002 sec
$2^9$	512	1	.02 sec
$2^{12}$	4096	67	.2
$2^{15}$	32768	1 hr 11 mins	2
$2^{18}$	262144	3 days 4 hrs	19

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## DFT Computation Using MATLAB

- fft(x)      - Computes the  $N$ -point DFT of a vector  $x$  of length  $N$
- fft(x, M) - Computes the  $M$ -point DFT of a vector  $x$  of length  $N$   
               If  $N < M$ ,  $x$  is zero-padded at the end to make it into  
               a vector of length  $M$   
               If  $N > M$ ,  $x$  is truncated to the first  $M$  samples
- ifft(X)     - Computes the  $N$ -point IDFT of a vector  $X$  of length  $N$
- ifft(X, M) - Computes the  $M$ -point IDFT of a vector  $X$  of length  $N$   
               If  $N < M$ ,  $X$  is zero-padded at the end to make it into  
               a vector of length  $M$   
               If  $N > M$ ,  $X$  is truncated to the first  $M$  samples

## DFT Interpretation

DFT sample  $X(k)$  specifies the magnitude and phase angle of the  $k^{\text{th}}$  spectral component of  $x[n]$ .

$$\text{Magnitude spectrum} = \frac{1}{N} |X(k)|$$

$$\text{Phase spectrum} = \angle X(k)$$

The amount of power that  $x[n]$  contains at a normalized frequency,  $f_k$ , can be determined from the **power density spectrum** defined as

$$P_N(k) = \frac{|X(k)|^2}{N^2}, \quad 0 \leq k \leq N-1$$

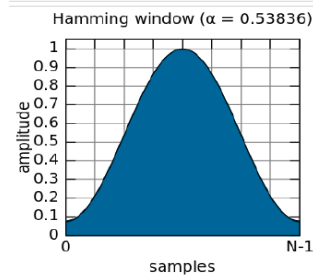
Complex number 의 magnitude 는 real term 과 imaginary term을 각각 제곱하여 더 한후 square root를 씌운다

# Windowing

- $x[n]$ 의 길이가  $N$ 보다 길 때, 이를  $N$ 으로 맞추어야 한다.

- Hamming window 가 유명

$$\begin{aligned} w_0(n) &\stackrel{\text{def}}{=} w\left(n + \frac{N-1}{2}\right) \\ &= 0.54 + 0.46 \cos\left(\frac{2\pi n}{N-1}\right) \end{aligned}$$

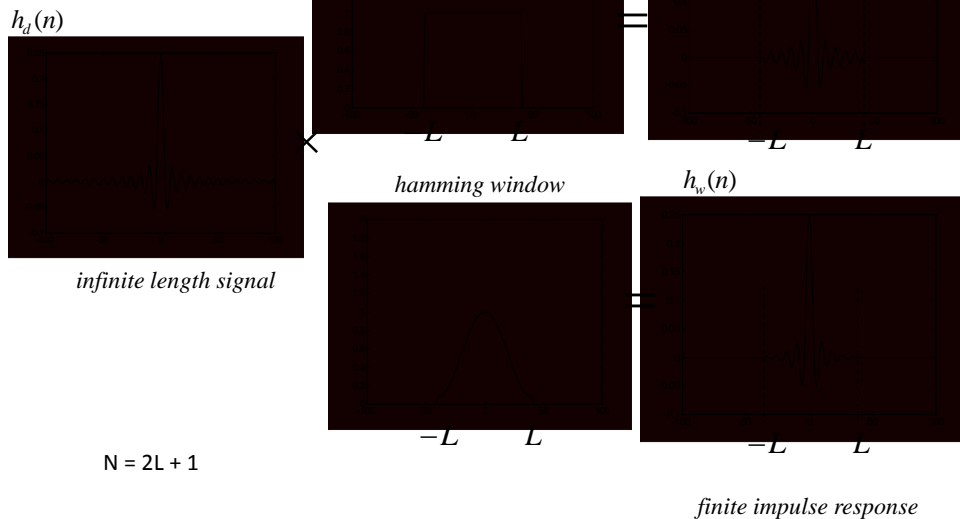


- Rectangular window의 경우 주파수 영역에서의 찌그러짐이 있다.

**Problem:** we want to determine a causal Finite Impulse Response (FIR) approximation of the ideal filter.

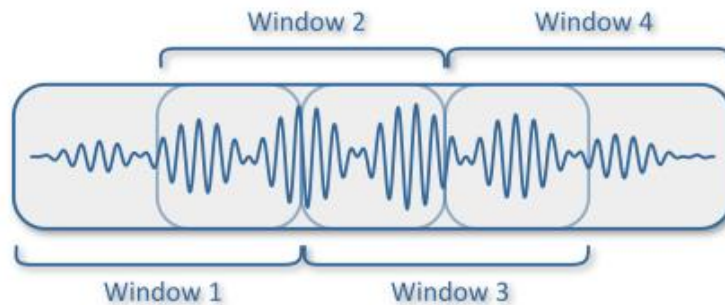
We do this by

a) Windowing



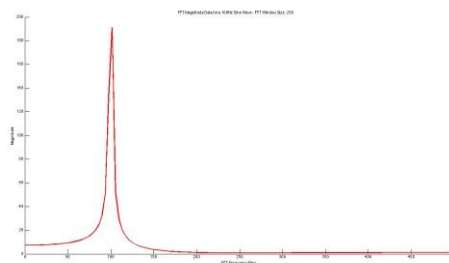
## Real-time signal processing

- Sampling -> sliding window -> DFT for each window -> Plot



## DFT의 bin number 와 실제 주파수

- 어떤 signal  $x(t)$ 를 10KHz로 sample 하였다. 그리고 sampling 된 신호  $x[0] \sim x[1023]$ 을 이용하여 1024 point FFT를 실행하였다.
- 아래 보이는 바와 같이  $x[100]$ 에 peak이 발생하였다.
- 몇 Hz에 해당?



## DFT의 bin number 와 실제 주파수

- $X[k = 0, 1, 2, \dots, N-1]$ 이 얻어지는데, 가상적으로  $k = N/2$ 이 sampling 주파수에 해당
- 즉 DFT domain에서  $k=1$ 이 변할 때 continuous time domain의 주파수는  $f_s/N$  또는  $\text{rad/sec}$ 로  $2\pi \cdot f_s/N$  만큼씩 변한다.
- 앞의 문제에 대한 답은  $100 \cdot 10\text{KHz}/1024 \approx \text{약 } 1\text{KHz}$
- Sampling 하기 전에 신호가 lowpass filter  $f_s/2$ 를 거치며,  $k=N/2 \sim N-1$ 은  $k=0 \sim N/2-1$ 과 symmetric하다 (real input signal의 경우)

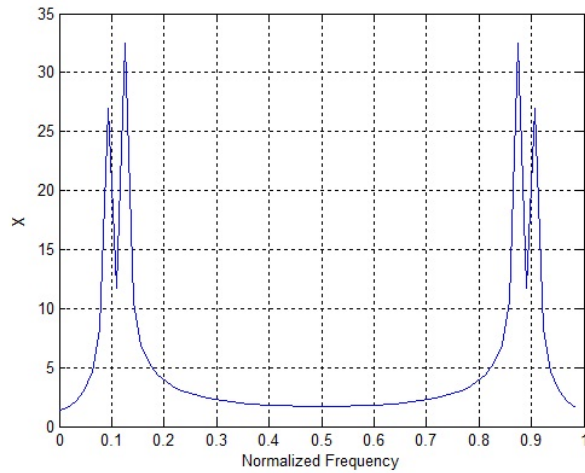
## Matrix Formulation

$$\begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ \vdots \\ X(N-1) \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & W_N^1 & W_N^2 & \dots & W_N^{N-1} \\ 1 & W_N^2 & W_N^4 & \dots & W_N^{2(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^{N-1} & W_N^{2(N-1)} & \dots & W_N^{(N-1)(N-1)} \end{bmatrix} \begin{bmatrix} x[0] \\ x[1] \\ x[2] \\ \vdots \\ x[N-1] \end{bmatrix}$$

$$\underline{X} = W \underline{x}$$

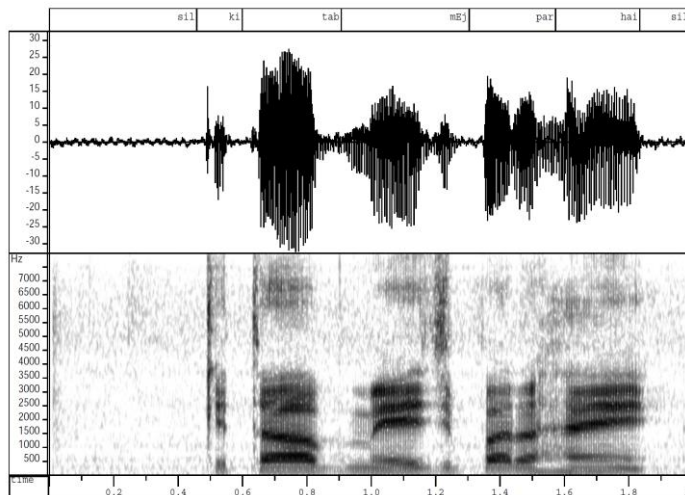
주기가  $N$ 인 discrete (cosine, sine) sequence (한 sample에  $2\pi/N$  씩 진전)

주기가  $N/2$ 인 discrete (cosine, sine) sequence



## Spectrogram

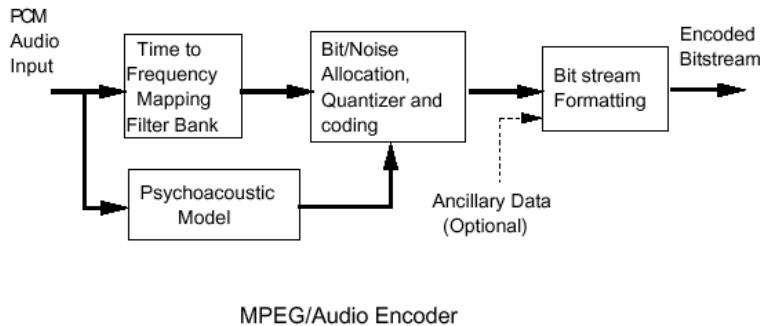
sample된 입력신호 -> sliding window -> FFT





## MP3 audio encoding

Sampling 된 audio 신호를 주파수 domain으로 바꾸어서 (filter bank – FFT 이용) 각 주파수별로 귀의 민감도와 masking 특성을 따진다. 사람의 귀는 높은 주파수에서 세밀하게 못 듣고 또 높은 세기의 주파수 성분 옆은 잘 안들린다 (masking 효과). 이를 이용하여 잘 못 듣는 부분은 영성하게 양자화한다. 16bit 48KHz (768Kbp) -> 128Kbps, 64Kbps 로 줄인다.



## Applications

- In image processing:
  - Instead of time domain: *spatial domain* (normal image space)
  - *frequency domain*: space in which each image value at image position F represents the amount that the intensity values in image I vary over a specific distance related to F

## Extending DFT to 2D (cont'd)

- **Special case:**  $f(x,y)$  is  $N \times N$ .

- Forward DFT 
$$F(u, v) = \frac{1}{N} \sum_{x=0}^{N-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi(\frac{ux+vy}{N})},$$
  

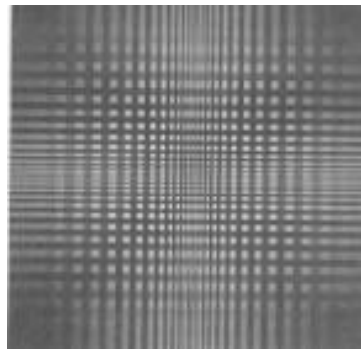
$$u, v = 0, 1, 2, \dots, N-1$$

- Inverse DFT 
$$f(x, y) = \frac{1}{N} \sum_{u=0}^{N-1} \sum_{v=0}^{N-1} F(u, v) e^{j2\pi(\frac{ux+vy}{N})},$$
  

$$x, y = 0, 1, 2, \dots, N-1$$

## Applications: Frequency Domain In Images

- *Spatial frequency* of an image refers to the rate at which the pixel intensities change
- In picture on right:
  - High frequencies:
    - Near center
  - Low frequencies:
    - Corners



## Other Applications of the DFT

- Signal analysis
- Sound filtering
- Data compression
- Partial differential equations
- Multiplication of large integers