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DISCRETE STRUCTURE FOR COMPUTER SCIENCE

Large assignment

Finding the shortest path

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1 Traveling Salesman Problem

The Traveling Salesman Problem (TSP) is a classic optimization problem where a person must find the shortest possible route that visits each of N cities exactly once and returns to the starting city. The goal is to minimize the total travel cost.

In this exercise, I implemented two different approaches to solve TSP depending on the input size:

- **Bitmask Dynamic Programming:** Used for small instances ($N \leq 20$), where we apply DP with bitmasking to explore all subsets of cities efficiently.
- **Genetic Algorithm:** Used for larger instances (e.g., $N = 25$), where we evolve a population of candidate solutions using selection, crossover, and mutation to find a near-optimal tour.

1.1 Bitmask Dynamic Programming Approach

Goal: Find the shortest Hamiltonian cycle that visits all V cities and returns to the starting point.

State Representation:

Let:

- $mask$ be a bitmask representing the set of visited vertices.
- u be the current vertex.

What is bitmask? Bitmask is a binary number used for representing something. For e.g: we have five bulbs, which are numbered from 1 to 5, to show that the bulbs at position 1 and 4 are on, we can write a bitmask: 10010.

Some operations with bitmask:

- **Set the i^{th} bit:**

$$b | (1 \ll i)$$

This sets the bit at position i (0-indexed from the right) to 1.

Example: Let $b = 0b10011$ (19 in decimal), set bit 3:

$$0b10011 | (1 \ll 3) = 0b11011$$

- **Clear the i^{th} bit:**

$$b \& \sim (1 \ll i)$$

This clears (sets to 0) the bit at position i .

Example: Let $b = 0b10111$, clear bit 4:

$$0b10111 \& \sim (1 \ll 4) = 0b00111$$

- **Toggle the i^{th} bit:**

$$b \oplus (1 \ll i)$$

This flips the bit at position i .

Example: Let $b = 0b10001$, toggle bit 2:

$$0b10001 \oplus (1 \ll 2) = 0b10101$$

- **Check if the i^{th} bit is set:**

$$b \& (1 \ll i)$$

If the result is non-zero, the i^{th} bit is set to 1.

Example: Let $b = 0b10010$, check bit 3:

$$0b10010 \& (1 \ll 3) = 0$$



- **Left Shift:**

$$1 \ll i$$

Shifts 1 to the left by i positions, setting the i^{th} bit from the right.

- **Right Shift:**

$$b \gg i$$

Shifts the bits of b to the right by i positions, effectively dividing by 2^i .

Bitmask takes a vital role of storing keep track of which cities have been visited without explicitly storing the actual set. Suppose we have n cities (vertices) labeled from 0 to $n-1$. We represent the set of visited cities using a binary mask of length n , where each bit corresponds to a city.

If the i -th bit is 1: the city has been visited.

If the i -th bit is 0: the city has not been visited.

We define:

$dp[mask][u]$ = Minimum cost to reach vertex u after visiting all cities in $mask$

Transition:

For each unvisited vertex v :

$$dp[mask \cup \{v\}][v] = \min(dp[mask \cup \{v\}][v], dp[mask][u] + cost[u][v])$$

Initialization:

$$dp[1 \ll start][start] = 0$$

Final Cost:

Once all cities are visited:

$$\min_{i \in [0, V-1]} (dp[(1 \ll V) - 1][i] + cost[i][start])$$

Time Complexity:

$$O(V^2 \cdot 2^V)$$

This approach is efficient for small values of V (up to 20).

1.2 Genetic Algorithm Approach

Goal: Find an approximate solution to TSP for larger V using a population-based evolutionary strategy.

Chromosome Representation: Each individual is a permutation of $\{0, 1, \dots, V - 1\}$ representing a travel route.

Algorithm Steps:

1. **Initialization:**

- The first individual is generated using the Nearest Neighbor heuristic.
- The rest are randomly generated permutations.

2. **Fitness Function:**

$$fitness(ind) = \text{Total travel cost of the path}$$

3. **Selection:** Tournament selection between two randomly chosen individuals.

4. **Crossover (Order Crossover - OX):**

- Select two cut points l and r .
- Copy segment $[l, r]$ from parent 1 to child.
- Fill the remaining values from parent 2 in order, avoiding duplicates.

5. **Mutation:** With a small probability, swap two cities in the tour.

6. **Elitism:** Carry the best individual to the next generation.

7. **Evolution:** Repeat the selection, crossover, mutation, and fitness update for a fixed number of generations.

Time Complexity:

$$O(POP_SIZE \cdot GENERATIONS \cdot V)$$

This method scales better for larger values of V (e.g., 25 cities).