

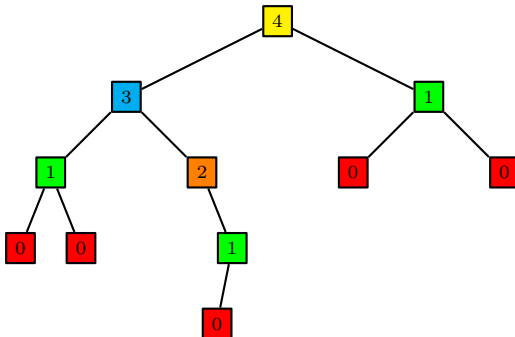
# CS624 - Analysis of Algorithms

## Heaps

September 17, 2019

# Heaps and Heapsort – Introduction to Heaps

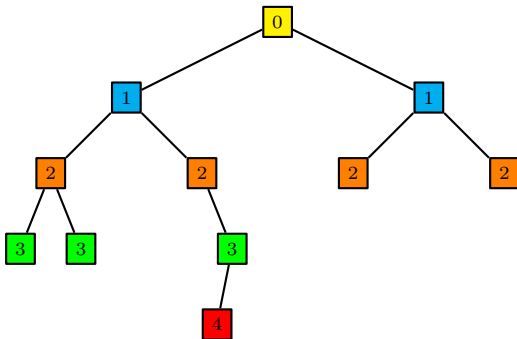
Define the height of a node in a tree as the number of edges on the longest path from that node down to a leaf



The height of the tree,  $H$ , is the height of its root.

# Heaps and Heapsort – Introduction to Heaps

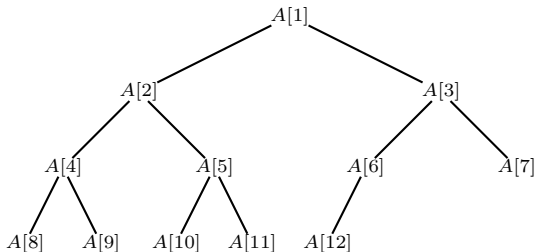
The *level* of the root is 0, the children of the root are at level 1. In general, the children of a node of level  $k$  are at level  $k + 1$ .



# Heaps and Pre-Heaps

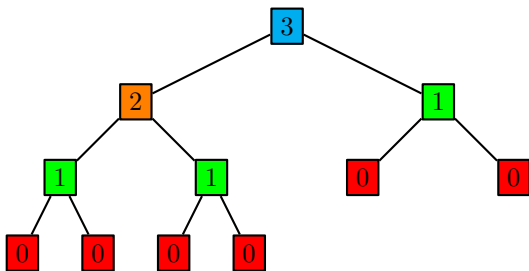
- In a binary tree, there are at most  $2^k$  nodes at level  $k$ .
- If the highest level is completely filled in, that level contains  $2^H$  nodes, and the tree contains  $1 + 2 + 4 + \dots + 2^H = 2^{H+1} - 1$  nodes.
- A *heap* is a special kind of a binary tree (do not confuse with the CS term related to memory allocation!).
- Let us define a *pre – heap* as follows:
  - All leaves are on at most two adjacent levels.
  - Except maybe the lowest level, all the levels are completely filled. The leaves on the lowest level are filled in, without gaps, from the left.

# Pre-Heap – Example



- Notice that it can be represented as a simple array.
- The children of the node holding  $A[n]$  are the nodes holding  $A[2n]$  and  $A[2n + 1]$ , and the parent of the the node holding  $A[n]$  is  $A[\lfloor n/2 \rfloor]$ .

# Pre-Heap – Another Example



- The nodes are tagged by their height.
- All the levels less than 3 are completely filled in, and there are a total of  $2^3 - 1$  nodes at those levels.

# Pre-Heap Properties

- If we have a pre-heap with  $n$  nodes, denote its height by  $H$ .
- As seen above, we must have  $2^H \leq n \leq 2^{H+1} - 1 < 2^{H+1}$ .  
Equivalently,  $H = \lfloor \log_2 n \rfloor$

## Lemma

*In a pre-heap with  $n$  elements, there are  $\lceil \frac{n}{2} \rceil$  leaves.*

## Proof.

- Some leaves are at level  $H$ , and some are at level  $H - 1$ .
- Since the number of nodes at level  $H - 1$  or less is  $2^H - 1$ , the number of leaves at level  $H$  is  $n - (2^H - 1)$ .
- The parent of node  $n$  is node  $\lfloor \frac{n}{2} \rfloor$ , and that node is the last node of height 1.



## Proof (Cont.)

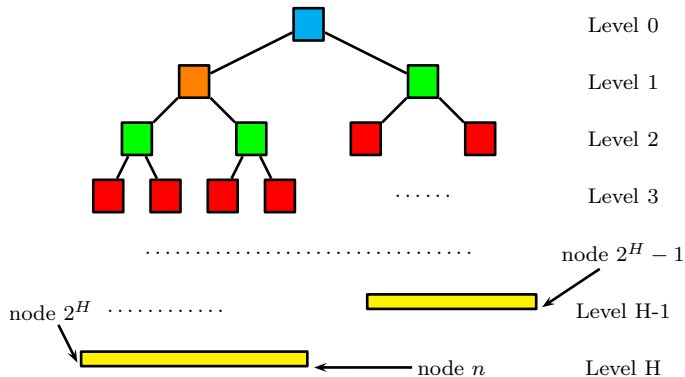
- So all the rest of the nodes at level  $H - 1$  are of height 0, i.e., are leaf nodes.
- Therefore the number of leaves at level  $H - 1$  is  $(2^H - 1) - \lfloor \frac{n}{2} \rfloor$ .
- Hence the total number of leaves is

$$n - (2^H - 1) + (2^H - 1) - \lfloor \frac{n}{2} \rfloor = n - \lfloor \frac{n}{2} \rfloor = \lceil \frac{n}{2} \rceil$$





# Pre-Heap Properties



# Pre-Heap Properties

## Corollary

*In a pre-heap with height  $H$ , there are at most  $2^H$  leaves.*

## Proof.

If  $n$  is the number of elements in the pre-heap, we know that  $2^H \leq n \leq 2^{H+1} - 1 < 2^{H+1}$ . Then by the Lemma, the number of leaves is

$$\left\lceil \frac{n}{2} \right\rceil \leq \frac{2^{H+1}}{2} = 2^H$$



# Pre-Heap Properties

## Theorem

*In a pre-heap with  $n$  elements, there are at most  $\frac{n}{2^h}$  nodes at height  $h$ .*

## Proof.

- We have just seen that there are at most  $2^H$  leaves in such a tree, and the leaves are just the nodes at height 0.
- If we take away the leaves, we have a smaller pre-heap with at most  $2^{H-1}$  leaves, and these leaves are exactly the nodes at height 1 in the original tree.
- Continuing, we see that there are at most  $2^{H-h}$  nodes at height  $h$  in the original tree, therefore  $2^{H-h} = \frac{2^H}{2^h} \leq \frac{n}{2^h}$

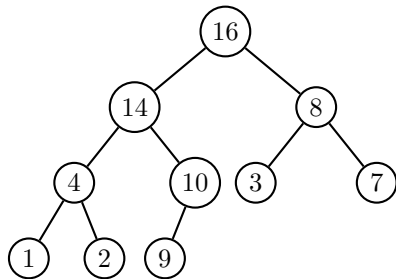
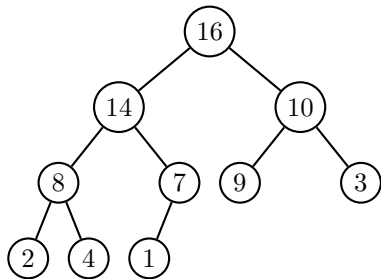


## Definition

- A *heap* is a binary tree with a key in each node.
- The keys must be comparable.
- Additionally, the heap must have the following properties:
  - All leaves are on at most two adjacent levels.
  - With the possible exception of the lowest level, all the levels are completely filled. The leaves on the lowest level are filled in, without gaps, from the left.
  - The key at each node is greater than or equal to the key in any descendant of that node.

- Note that another way of phrasing the third condition would be:
  - The key in the root is greater than or equal to that of its children, and its left and right subtrees are again heaps.
- Thus every heap is a pre-heap.
- Even though the shape of a heap containing  $n$  elements is uniquely determined (since it is a pre-heap), the arrangement of those  $n$  elements is not.

## Example – Two Heaps With the Same Set of Keys



# The Heapify Procedure

- The fundamental procedure to build a heap.
- We have a binary tree in the shape of a heap (but perhaps not actually a heap).
- We represent the tree as an array  $A[1..n]$ , where  $n$  is the size of the heap.
- We look at node  $i$  (holding the value  $A[i]$ ). We assume that:
  - The tree rooted at  $l = \text{Left}(i)$  is a heap.
  - The tree rooted at  $r = \text{Right}(i)$  is a heap.
- However, we do not assume that the tree rooted at  $i$  is a heap.
- Heapify works by letting the value  $A[i]$  “float down” to its proper position in the heap.

# The Heapify Procedure

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**Algorithm 1** Heapify( $A, i$ )

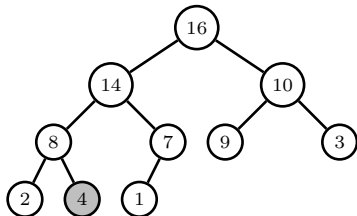
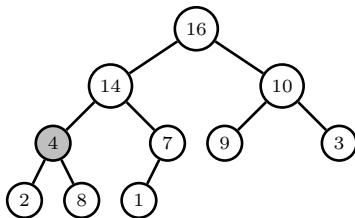
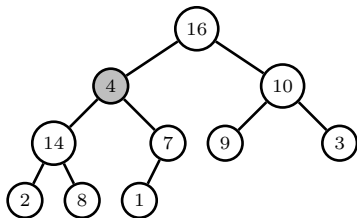
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```
1:  $l \leftarrow \text{Left}(i)$ 
2:  $r \leftarrow \text{Right}(i)$ 
3: if  $l \leq \text{Heapsize}[A]$  and  $A[l] > A[i]$  then
4:    $\text{largest} \leftarrow l$ 
5: else
6:    $\text{largest} \leftarrow i$ 
7: end if
8: if  $r \leq \text{heapsize}[A]$  and  $A[r] > A[\text{largest}]$  then
9:    $\text{largest} \leftarrow r$ 
10: end if
11: if  $\text{largest} \neq i$  then
12:    $\text{exchange} A[i] \leftrightarrow A[\text{largest}]$ 
13:   Heapify( $A, \text{largest}$ )
14: end if
```

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# Heapify – Example



# Running Time of Heapify

The time needed to run Heapify on a subtree of size  $n$  rooted at a given node  $i$  is

- time  $\Theta(1)$  to fix up the relationships among the elements  $A[i]$ ,  $A[\text{Left}(i)]$ , and  $A[\text{Right}(i)]$
- time to run Heapify on a subtree rooted at one of the children of node  $i$ .
- That subtree has size at most  $2n/3$  – the worst case occurs when the last row of the tree is exactly half full.

So the running time  $T(n)$  can be characterized by the recurrence

$$T(n) \leq T(2n/3) + \Theta(1)$$

This falls into case 2 of the “master theorem”, and so we must have  $T(n) = O(\log n)$

# Building a Heap

The heap is built from the bottom up, starting at the first non-leaf node.

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**Algorithm 2** BuildHeap( $A$ )

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```
1:  $heapsize[A] \leftarrow length[A]$ 
2: for  $i \leftarrow \lfloor length[A]/2 \rfloor$  to 1 do
3:    $Heapify(A, i)$ 
4: end for
```

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To prove that this is correct We use the following loop invariant:

## Lemma

*At the start of each iteration of the for loop, each node  $i + 1, i + 2, \dots, n$  is the root of a heap.*

# Proof of Correctness

## Proof.

- On the first iteration of the loop,  $i = \lfloor n/2 \rfloor$ . Each node  $\lfloor n/2 \rfloor + 1, \lfloor n/2 \rfloor + 2, \dots, n$  is a leaf and is thus the root of a trivial heap.
- Inductive step – going from  $i + 1$  to  $i$ , we assume that each element  $i + 1, i + 2, \dots, n$  is the root of a heap.
- Therefore each of the two children of node  $i$  (i.e., nodes  $2i$  and  $2i + 1$ ) is the root of a heap.
- Therefore the call to *Heapify*( $A, i$ ) makes  $i$  the root of a heap.
- Further, all nodes which are not descendants of  $i$  are untouched by the call to *Heapify*( $A, i$ ), (Do you see why?) and so we can conclude that each node  $i, i + 1, \dots, n$  is now the root of a heap.



# Running Time of BuildHeap

- The number of elements of the heap at height  $h$  is  $\leq \frac{n}{2^h}$ , and the cost of running Heapify on a node of height  $h$  is  $O(h)$ .
- The root of a heap of  $n$  elements has height  $\lfloor \log_2 n \rfloor$ .
- Therefore the worst-case cost of running BuildHeap on a heap of  $n$  elements is bounded by

$$\sum_{h=0}^{\lfloor \log_2 n \rfloor} \frac{n}{2^h} O(h) = O\left(n \sum_{h=0}^{\lfloor \log_2 n \rfloor} \frac{h}{2^h}\right) = O(n)$$

since the sum converges, so we don't care what the upper bound of the summation is.

# Heap Properties

- Heaps give us partial information about the order of elements in a set.
- We can tell immediately what the largest element is.
- They are really cheap to build and can be stored in a simple array.
- This makes them very useful for various applications.

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**Algorithm 3** Heapsort( $A$ )

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```
1: BuildHeap( $A$ )
2: for  $i \leftarrow \text{length}[A]$  to 2 do
3:   exchange  $A[1] \leftrightarrow A[i]$ 
4:    $\text{heapsize}[A] \leftarrow \text{heapsize}[A] - 1$ 
5:   Heapify( $A, 1$ )
6: end for
```

---

The call to *BuildHeap* takes time  $O(n)$ . Each of the  $n - 1$  calls to *Heapify* takes time  $O(\log n)$ . Hence the total running time is (in the worst case)  $O(n \log n)$ .

# Priority Queues

## Definition

A *priority queue* is a data structure that maintains a set  $S$  of elements, each with an associated value called a *key*. (As usual, the keys must be comparable.) The priority queue supports the following operations:

*Insert*( $S, x$ ) inserts the element  $x$  into the set  $S$ .

*Maximum*( $S$ ) returns the element of  $S$  with the largest key.

*ExtractMax*( $S$ ) removes and returns the element of  $S$  with the largest key.

*IncreaseKey*( $S, x, k$ ) increases the value of element  $x$ 's key to the new value  $k$ , which is assumed to be at least as large as  $x$ 's current key value.

A priority queue can be implemented using a heap.



# Priority Queue Operations

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**Algorithm 4** HeapMaximum( $A$ )

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1: **return**  $A[1]$

---

Obviously, the run time is  $O(1)$ .

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**Algorithm 5** HeapExtractMax( $A$ )

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1: **if**  $\text{heapsize}[A] < 1$  **then**  
2:     *ERROR – heap underflow*  
3: **end if**  
4:  $\text{maxx} \leftarrow A[1]$   
5:  $A[1] \leftarrow A[\text{heapsize}[A]]$   
6:  $\text{heapsize}[A] \leftarrow \text{heapsize}[A] - 1$   
7:  $\text{Heapify}(A, 1)$   
8: **return**  $\text{maxx}$

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Here the running time is dominated by the call to Heapify, so it is  $O(\log n)$ .

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**Algorithm 6** HeapIncreaseKey( $A, i, \text{key}$ )

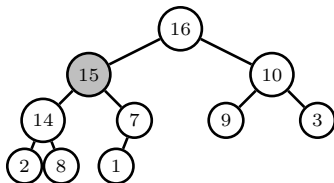
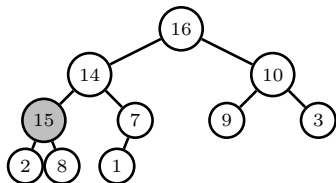
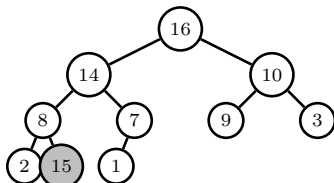
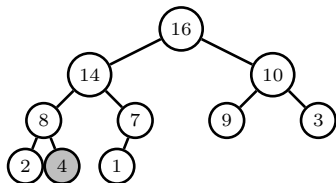
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```
1: if  $\text{key} < A[i]$  then
2:   ERROR – new key is smaller than current key
3: end if
4:  $A[i] \leftarrow \text{key}$ 
5: while  $i > 1$  and  $A[\text{Parent}(i)] < A[i]$  do
6:    $\text{exchange} A[i] \leftrightarrow A[\text{Parent}(i)]$ 
7:    $i \leftarrow \text{Parent}(i)$ 
8: end while
```

---

We just increase the key of  $A[i]$ , and then let that node “float up” to its proper position.

# HeapIncreaseKey – Example



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**Algorithm 7** HeapInsert( $A$ ,  $key$ )

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- 1:  $heapsize[A] \leftarrow heapsize[A] + 1$
  - 2:  $A[heapsize[A]] \leftarrow -\infty$
  - 3:  $HeapIncreaseKey(A, heapsize[A], key)$
- 

The running time here is again  $O(\log_2 n)$ .

Thus, a heap supports any priority queue operation on a set of size  $n$  in  $O(\log n)$  time.