Arduino based obstacle avoidance robot

Report Name	Progress Report
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1   Project Summary

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2   Current Progress

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3   Planning

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Annotated Bibliography

[1] H. M. Dee and D. C. Hogg, "Navigational strategies in behaviour modelling," *Artificial Intelligence*, vol. 173(2), pp. 329–342, 2009.

    This is my annotation. I should add in a description here.

[2] S. Duckworth, "A picture of a kitten at Hellifield Peel," http://www.geograph.org.uk/ photo/640959, 2007, copyright Sylvia Duckworth and licensed for reuse under a Creative Commons Attribution-Share Alike 2.0 Generic Licence. Accessed August 2011.

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[3] M. Neal, J. Feyereisl, R. Rascunà, and X. Wang, "Don't touch me, I'm fine: Robot autonomy using an artificial innate immune system," in *Proceedings of the 5th International Conference on Artificial Immune Systems*.   Springer, 2006, pp. 349–361.

    This paper...

[4] W. Press *et al.*, *Numerical recipes in C*.   Cambridge University Press Cambridge, 1992, pp. 349–361, 0123456789.

    This is my annotation. I can add in comments that are in **bold** and *italics and then other content*.

[5] Various, "Fail blog," http://www.failblog.org/, Aug. 2011, accessed August 2011.

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