Lecture 04

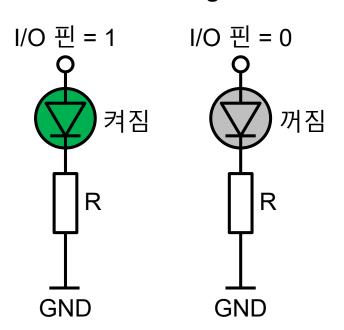
FND 제어

LED 제어

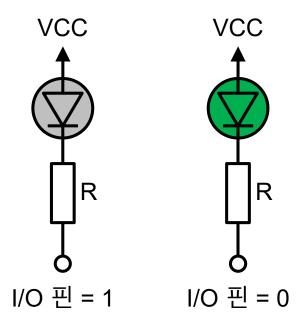


■ LED 제어 방법

Active high

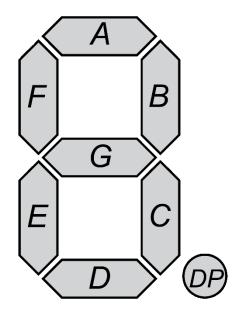


Active low

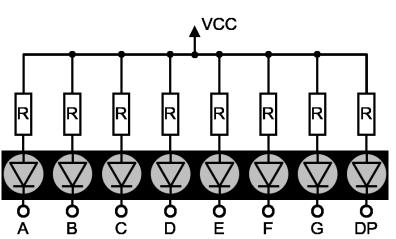




■ FND (또는 7-segment LED)



Active high 또는 common cathode (CC)



R R R R R R R

Active low 또는 common anode (CA)



■ FND 제어 방법

숫 자		16							
자	DP	G	F	Е	D	С	В	Α	진수
0	0	0	1	1	1	1	1	1	0x3f
1	0	0	0	0	0	1	1	0	0x06
2	0	1	0	1	1	0	1	1	0x5b
3	0	1	0	0	1	1	1	1	0x4f
4	0	1	1	0	0	1	1	0	0x66
5	0	1	1	0	1	1	0	1	0x6d
6	0	1	1	1	1	1	0	1	0x7d
7	0	0	1	0	0	1	1	1	0x27
8	0	1	1	1	1	1	1	1	0x7f
9	0	1	1	0	0	1	1	1	0x67

숫 자		16							
자	DP	G	F	ш	D	O	В	A	진수
а	0	1	1	1	0	1	1	1	0x77
b	0	1	1	1	1	1	0	0	0x7c
С	0	1	0	1	1	0	0	0	0x58
d	0	1	0	1	1	1	1	0	0x5e
е	0	1	1	1	1	0	0	1	0x79
f	0	1	1	1	0	0	0	1	0x71



■ FND 제어 방법

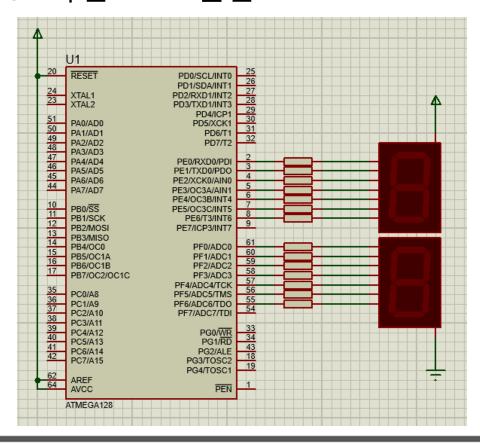
숫 자		16							
	DP	G	F	Е	D	C	В	A	진수
0	1	1	0	0	0	0	0	0	0xc0
1	1	1	1	1	1	0	0	1	0xf9
2	1	0	1	0	0	1	0	0	0xa4
3	1	0	1	1	0	0	0	0	0xb0
4	1	0	0	1	1	0	0	1	0x99
5	1	0	0	1	0	0	1	0	0x92
6	1	0	0	0	0	0	1	0	0x82
7	1	1	0	1	1	0	0	0	0xd8
8	1	0	0	0	0	0	0	0	0x80
9	1	0	0	1	1	0	0	0	0x98

숫 자		16							
	DP	G	F	Е	D	C	В	Α	진수
а	1	0	0	0	1	0	0	0	0x88
b	1	0	0	0	0	0	1	1	0x83
С	1	0	1	0	0	1	1	1	0xa7
d	1	0	1	0	0	0	0	1	0xa1
е	1	0	0	0	0	1	1	0	0x86
f	1	0	0	0	1	1	1	0	0x8e





■ CC타입 및 CA타입 FND 실습







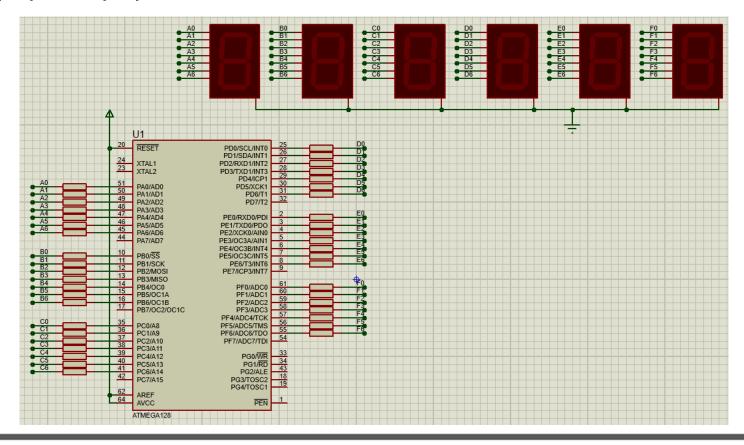
■ CC타입 및 CA타입 FND 실습

```
unsigned char CC[] = {0x3f, 0x06, 0x5b, 0x4f, 0x66, 0x6d, 0x7d, 0x27, 0x7f, 0x67, 0x77, 0x7c, 0x58, 0x5e, 0x79, 0x71, 0x80};
unsigned char CA[] = {0xc0, 0xf9, 0xa4, 0xb0, 0x99, 0x92, 0x82, 0xd8, 0x80, 0x98, 0x88, 0x83, 0xa7, 0xa1, 0x86, 0x8e, 0x7f};
int main(void) {
    DDRE = DDRF = 0xff;
    int i = 0;
    while(1) {
        PORTE = CA[i];
        PORTF = CC[i];
        i++;
        if (i>15) i=0;
        _delay_ms(300);
    }
}
```





■ 디지털 시계 실습







■ 디지털 시계 실습

```
void display(void);
void time_process(void);

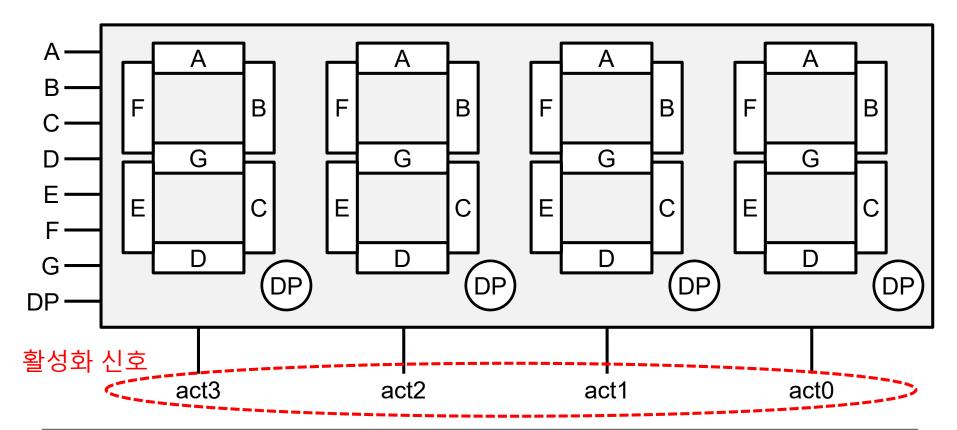
unsigned char CC[] = {0x3f, 0x06, 0x5b, 0x4f, 0x66, 0x6d, 0x7d,
0x27, 0x7f, 0x67, 0x77, 0x7c, 0x58, 0x5e, 0x79, 0x71, 0x80};
unsigned char CA[] = {0xc0, 0xf9, 0xa4, 0xb0, 0x99, 0x92, 0x82,
0xd8, 0x80, 0x98, 0x88, 0x83, 0xa7, 0xa1, 0x86, 0x8e, 0x7f};
unsigned char h, m, s;

int main(void) {
    DDRA = DDRB = DDRC = DDRD = DDRE = DDRF = 0xff;
    h = m = s = 0;
    while(1) {
        display();
        _delay_ms(1000);
        time_process();
    }
}
```

```
void display(void) {
   PORTA = CC[h/10];
   PORTB = CC[h%10];
   PORTC = CC[m/10];
   PORTD = CC[m%10];
   PORTE = CC[s/10];
   PORTF = CC[s%10];
void time process(void) {
   s++;
   if (s>59) {
      s = 0;
      m++;
      if (m>59) {
         m = 0;
         h++;
         if (h>12) h = 1;
```

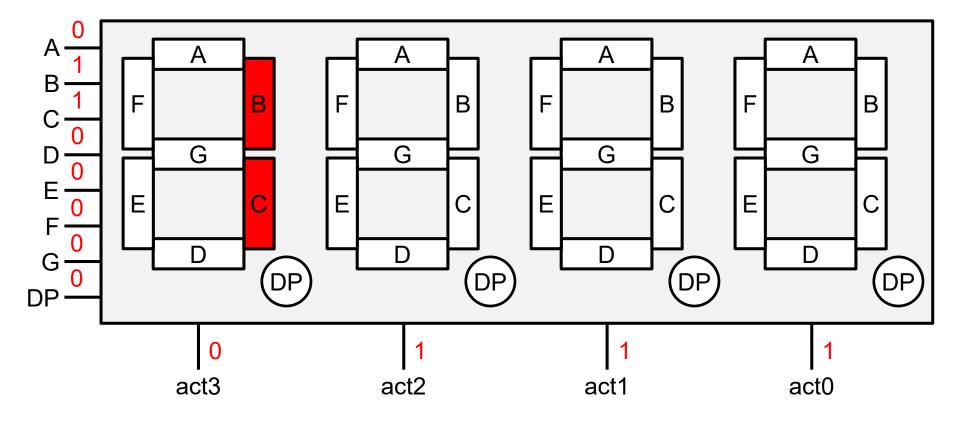


■ FND 제어 시 핀 개수를 줄이는 방법(CC타입 사용)



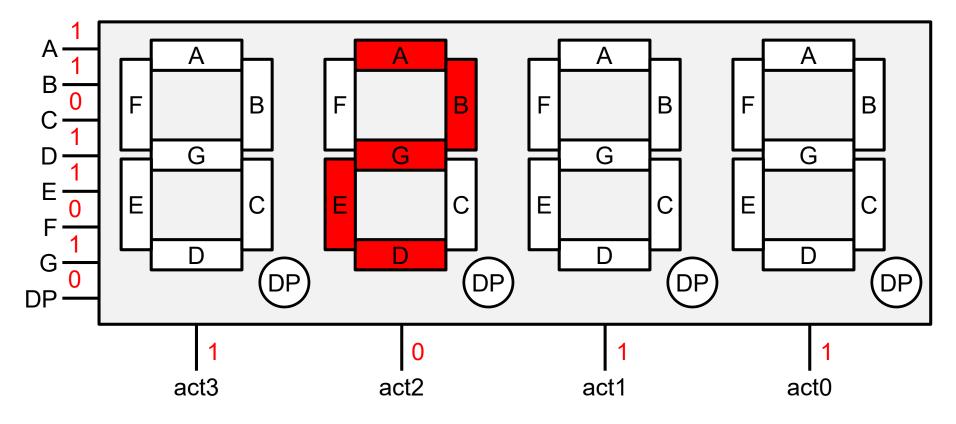


■ FND 제어 시 핀 개수를 줄이는 방법(CC타입 사용)



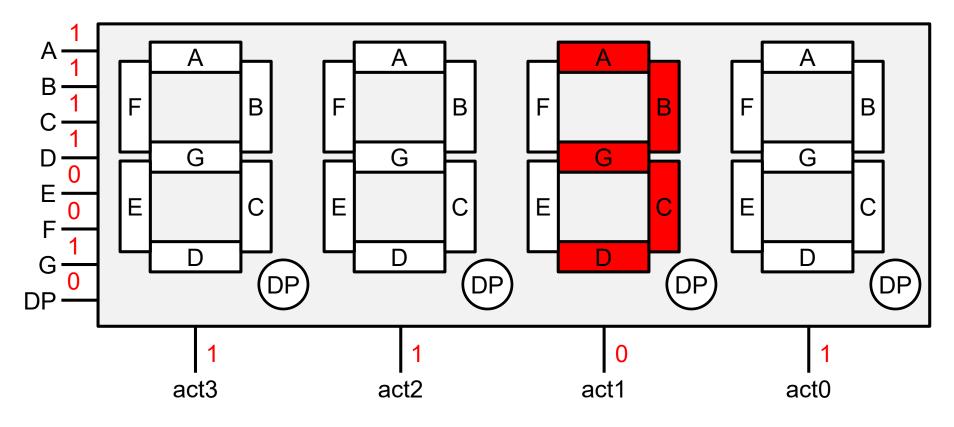


■ FND 제어 시 핀 개수를 줄이는 방법(CC타입 사용)



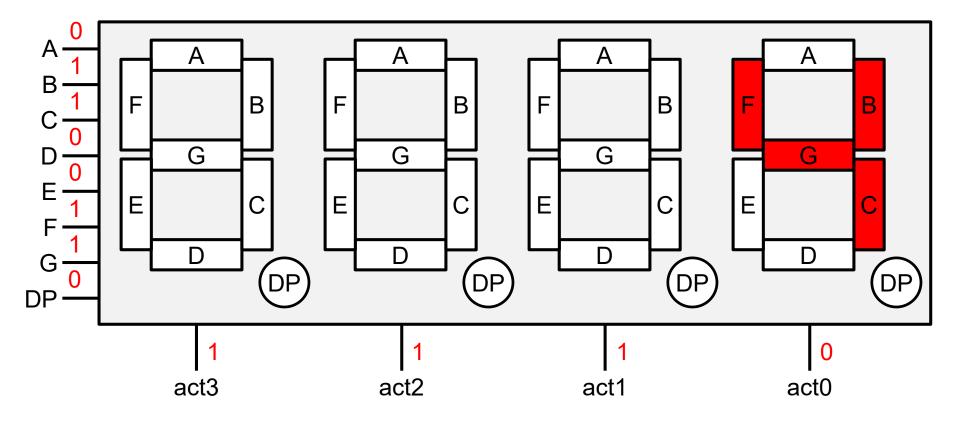


■ FND 제어 시 핀 개수를 줄이는 방법(CC타입 사용)



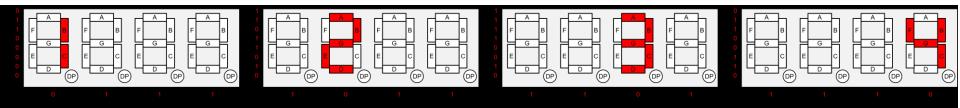


■ FND 제어 시 핀 개수를 줄이는 방법(CC타입 사용)





■ 활성화 신호 빠르게 변환시킴 → 동시에 켜진 것처럼 보임

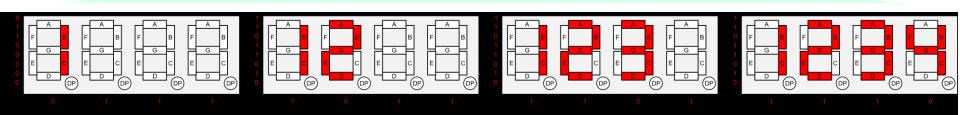


현실



활성화 신호 바꾸는 속도 ≥ 50Hz

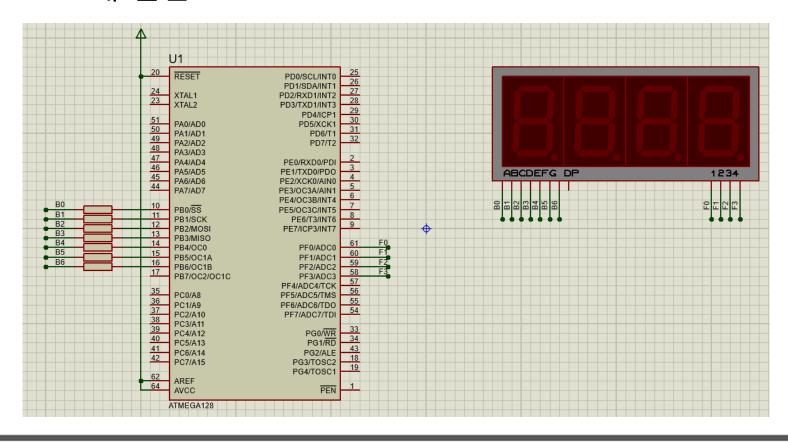
Persistence of Vision (POV)







■ FND 4개 실습







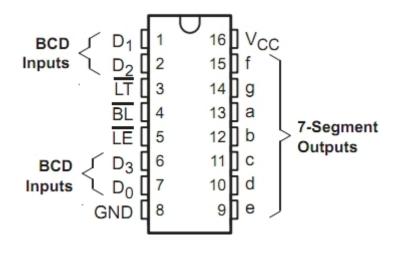
■ FND 4개 실습

```
unsigned char CC[] = \{0x3f, 0x06, 0x5b, 0x4f, 0x66, 0x6d, 0x7d, 0x27, 0x7f, 0x67, 0x77, 0x7c, 0x58, 0x5e, 0x6d, 0x6d, 0x7d, 0x7d, 0x67, 0x67, 0x7d, 0x7d, 0x7d, 0x6d, 0x6d, 0x6d, 0x6d, 0x6d, 0x6d, 0x7d, 0x7d, 0x6d, 
0x79, 0x71, 0x80;
unsigned char act[4] = \{0x0e, 0x0d, 0x0b, 0x07\};
int main(void) {
              DDRB = DDRF = 0xff;
              int i, j=0, r=0;
              while(1) {
                            for (i=0; i<4; i++) {
                                          PORTF = act[i];
                                          if (i==0) PORTB = CC[j/1000];
                                         if (i==1) PORTB = CC[(j%1000)/100];
                                          if (i==2) PORTB = CC[(j%100)/10];
                                          if (i==3) PORTB = CC[j%10];
                                         _delay ms(1);
                            r++;
                            if (r==20) { // update j every 20*20 = 400ms
                                          r=0;
                                          j++;
                            if (j>9999) j=0;
                            delay ms(16); // total delay time is 1*4 + 16 = 20ms
```



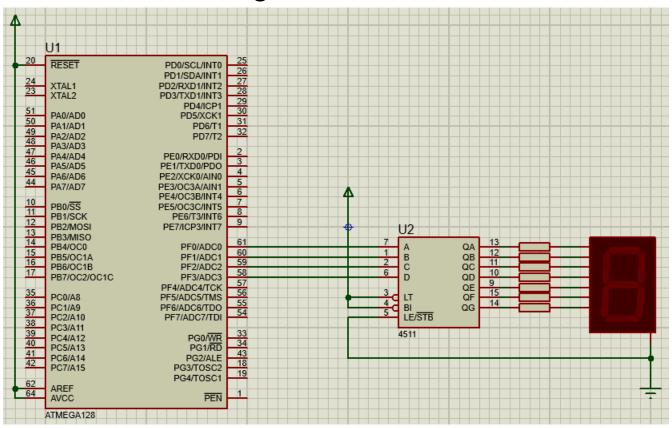
CD4511: BCD-to-7-Segment Decoder

숫 자		16							
자	DP	G	F	ш	D	C	В	A	진수
0	0	0	1	1	1	1	1	1	0x3f
1	0	0	0	0	0	1	1	0	0x06
2	0	1	0	1	1	0	1	1	0x5b
3	0	1	0	0	1	1	1	1	0x4f
4	0	1	1	0	0	1	1	0	0x66
5	0	1	1	0	1	1	0	1	0x6d
6	0	1	1	1	1	1	0	1	0x7d
7	0	0	1	0	0	1	1	1	0x27
8	0	1	1	1	1	1	1	1	0x7f
9	0	1	1	0	0	1	1	1	0x67









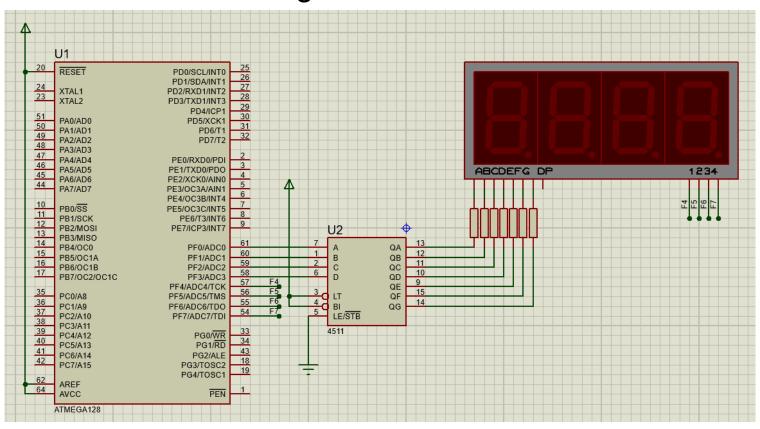




```
int main(void) {
   int i = 0;
   DDRF = 0xff;
   while(1) {
      PORTF = i;
      _delay_ms(500);
      i++;
      if (i>9) i = 0;
   }
}
```











```
unsigned char act[4] = \{0xe0, 0xd0, 0xb0, 0x70\};
int main(void) {
   DDRF = 0xff;
   int i, j=0, r=0;
   while(1) {
      for (i=0; i<4; i++) {
         if (i==0) PORTF = (j/1000) [act[i];
         if (i==1) PORTF = ((j%1000)/100) [act[i];
         if (i==2) PORTF = ((j%100)/10) [act[i];
         if (i==3) PORTF = (j%10) [act[i];
         delay ms(1);
      }
      r++;
      if (r==20) { // update j every 20*20 = 400ms
         r=0;
         1++;
      if (7>9999) 7=0;
      delay ms(16); // total delay time is 1*4 + 16 = 20ms
```