

# Using OpenMMLab to Accelerate Your Research

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1. Run on customized dataset: nlmages Dataset
2. MIM: **MIM** Installs Open**MMLab** projects
3. Develop a new algorithm: Swin Transformer

MIM Examples



Key steps:

1. Preprocess the dataset
2. Implement a new dataset class
3. Modify config file to use it
4. Train and test a model

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File structure:

Tiny and decoupled from MMSegmentation

```
project
├── configs
│   ├── _base_
│   │   ├── datasets
│   │   │   └── nuimages.py
│   │   ├── default_runtime.py
│   │   ├── models
│   │   │   ├── pspnet_r50-d8.py
│   │   └── schedules
│   │       └── schedule_80k.py
│   └── pspnet
│       └── pspnet_r18-d8_512x1024_80k_nuim.py
├── nuim_converter.py
└── nuim_dataset.py
```

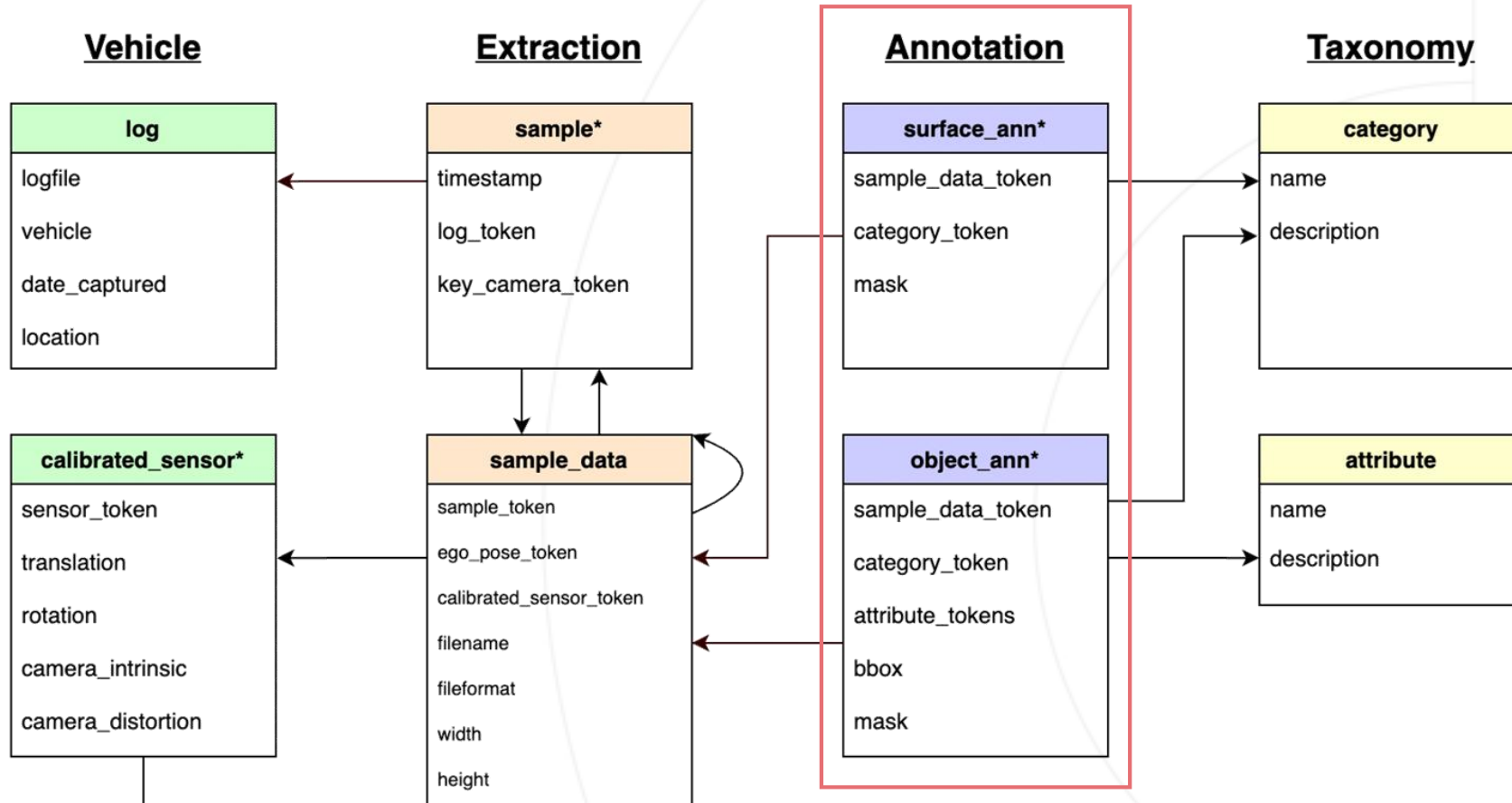
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```

## 1. Preprocess the dataset



Screenshot from <https://www.nuscenes.org/nuiimages>

## 1. Preprocess the dataset

```
python -u nuim_converter.py \  
  --data-root $DATA \  
  --versions $VERSIONS \  
  --out-dir $OUT \  
  --nproc $NUM_WORKERS
```

```
project  
├─ nuimages  
│   └─ annotations  
│       ├── nuimages_v1.0-mini.json  
│       ├── nuimages_v1.0-train.json  
│       ├── nuimages_v1.0-val.json  
│       ├── nuimages_v1.0-val2400.json  
│       ├── nuimages_v1.0-test.json  
│       └─ semantic_masks  
│           ├── xxxxx.png  
│           └─ xxxxx.png  
└─ samples
```

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```



## 2. Implement a new dataset class

```
import os.path as osp

import mmcv
from mmcv.utils import print_log
from mmseg.datasets import CustomDataset
from mmseg.datasets.builder import DATASETS
from mmseg.utils import get_root_logger

@DATASETS.register_module()
class NuImagesDataset(CustomDataset):
    CLASSES = ()

    def load_annotations(self, img_dir, img_suffix, ann_dir,
                        seg_map_suffix, split):

        annotations = mmcv.load(split)
        img_infos = []
        for img in annotations['images']:
            img_info = dict(filename=img['file_name'])
            seg_map = img_info['filename'].replace(
                img_suffix, seg_map_suffix)
            img_info['ann'] = dict(
                seg_map=osp.join('semantic_masks', seg_map))
            img_infos.append(img_info)

        print_log(
            f'Loaded {len(img_infos)} images from {ann_dir}',
            logger=get_root_logger())
        return img_infos
```

Use MMSegmentation as a library  
like PyTorch and torchvision

Register the dataset into the DATASETS registry

Inherits from CustomDataset

Only need to override the load\_annotations  
function to convert the annotations into  
middle format in MMSegmentation

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## 3. Modify config file to use it

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```

A complete config file is decomposed into four basic configs for free combination without writing duplicated code.

## 3. Modify config file to use it

### Base config of nulumages dataset

```
dataset_type = 'NuImagesDataset'
data_root = 'data/nulimages/'
train_pipeline = [
    ...
]
test_pipeline = [
    ...
]
data = dict(
    samples_per_gpu=2,
    workers_per_gpu=2,
    train=dict(
        type=dataset_type,
        data_root=data_root,
        img_dir='',
        ann_dir='annotations/',
        split='annotations/nulimages_v1.0-train.json',
        pipeline=train_pipeline),
    val=dict(
        type=dataset_type,
        ...),
    test=dict(
        type=dataset_type,
        ...))
custom_imports = dict(
    imports=['nuim_dataset'],
    allow_failed_imports=False)
```

Define data pipeline of the dataset

Make the file imported so that nulimagesDataset can be registered

### Config to run PSPNet-R18 on nulimages dataset

```
_base_ = [
    '../_base_/models/pspnet_r50-d8.py',
    '../_base_/datasets/nulimages.py',
    '../_base_/default_runtime.py',
    '../_base_/schedules/schedule_80k.py'
]

model = dict(
    pretrained='open-mmlab://resnet18_v1c',
    backbone=dict(depth=18),
    decode_head=dict(
        in_channels=512,
        channels=128,
        num_classes=25),
    auxiliary_head=dict(
        in_channels=256,
        channels=64,
        num_classes=25))

# use cityscapes pre-trained models
load_from = (
    'https://download.openmmlab.com/mmdetection/v0.5/pspnet/'
    'pspnet_r18-d8_512x1024_80k_cityscapes/'
    'pspnet_r18-d8_512x1024_80k_cityscapes_20201225_021458-09ffa746.pth')
```

Use base configs to for simplicity

Only override the necessary keys

Use Cityscapes Pretrained model

## 4. Train and test the model

### Train the model

```
PYTHONPATH='.'$PYTHONPATH mim train mmseg \  
  configs/pspnet/pspnet_r18-d8_512x1024_80k_nuim.py  
  --work-dir $WORK_DIR \  
  --launcher slurm -G 8 -p $PARTITION
```

### Test the trained model

```
PYTHONPATH='.'$PYTHONPATH mim test mmseg \  
  configs/pspnet/pspnet_r18-d8_512x1024_80k_nuim.py  
  --checkpoint $WORK_DIR/latest.pth \  
  --launcher slurm -G 8 -p $PARTITION \  
  --eval mIoU
```

Wait.... What is MIM?

## Package Management

Infer mmcv-full pre-build package automatically

Handle dependencies of OpenMMLab projects

```
pip install openmim>=0.1.1 # install mim through pypi
mim install mmcv-full==1.3.5
mim install mmdet==2.13.0
mim install mmsegmentation=0.14.0
```

## Unified Entrypoint for Scripts

mim train mmdet                   → mmdetection/tools/train.py

mim train mmseg                   → mmsegmentation/tools/train.py

mim train mmcls                   → mmclassification/tools/train.py

## Model Management

Use a similar format to store model information as Paper with Code (PWC)

You can

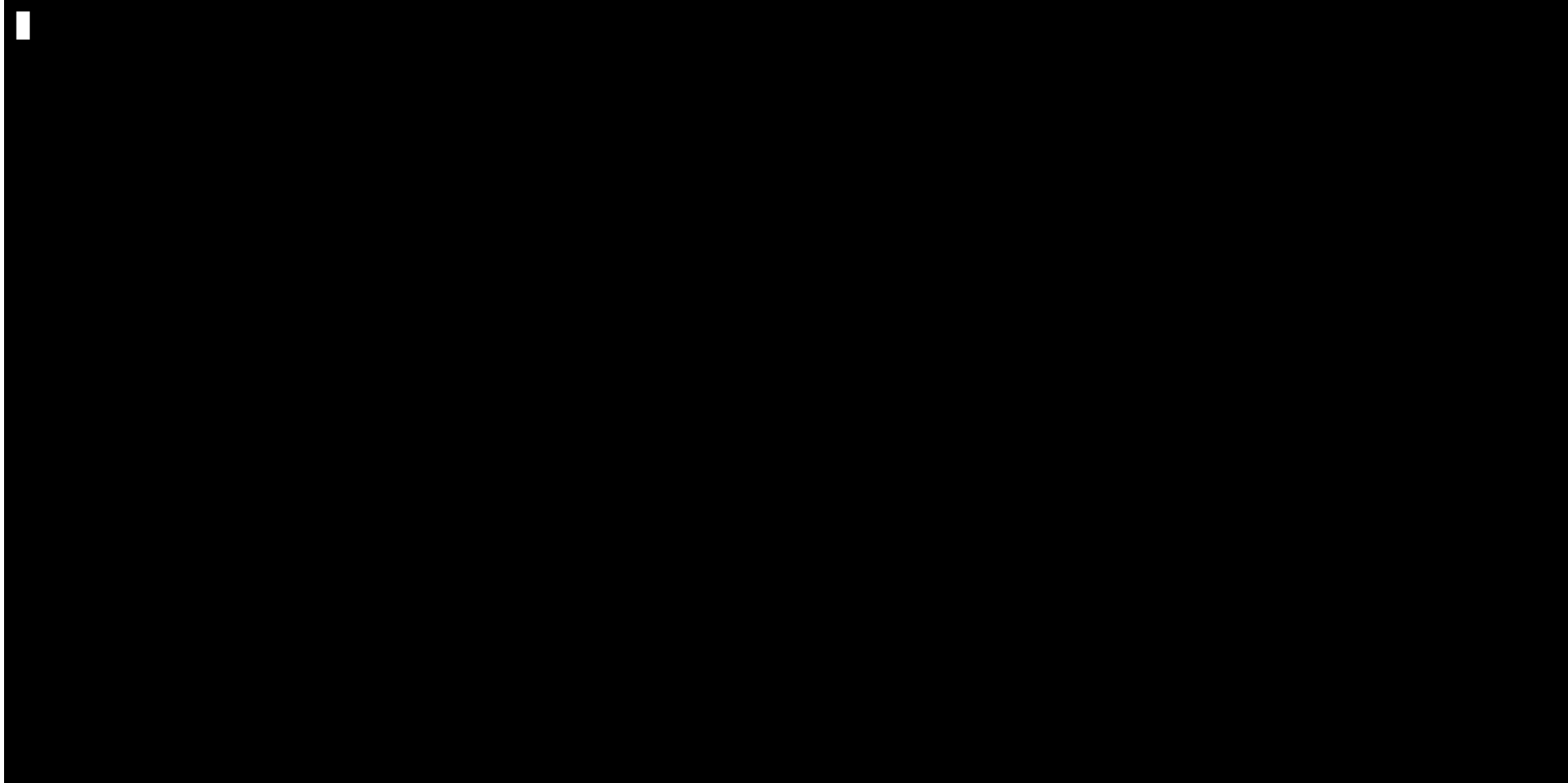
1. download models by name
2. search models that meet specific criteria

Find out more at





Examples of MIM



Find out more at



Key steps:

1. Implement the Swin Transformer and register Swin Transformer into registry
2. Modify config file to use it
3. Train and test a model

File structure:

A minimal implementation of Swin Transformer

```
├─ configs
│   ├── swin_classifier
│   │   └─ swin_tiny_224_imagenet.py
│   ├── swin_mask_rcnn
│   │   └─ mask_rcnn_swin-t-p4-w7_fpn_1x_coco.py
│   └─ swin_upernet
│       └─ upernet_swin-t_512x512_160k_8x2_ade20k.py
└─ swin
    └─ swin_transformer.py
```

Key steps:

1. Implement the Swin Transformer and register Swin Transformer into registry
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│   │   └─ mask_rcnn_swin-t-p4-w7_fpn_1x_coco.py
│   └─ swin_upernet
│       └─ upernet_swin-t_512x512_160k_8x2_ade20k.py
└─ swin
    └─ swin_transformer.py
```

## Step 1: implement Swin transformer

```
from mmcIs.models import BACKBONES

@BACKBONES.register_module()
class SwinTransformer(nn.Module):
    # code implementation
    def __init__(self, *args, **kwargs):
        super().__init__()
```

Register

```
@BACKBONES.register_module()
class SwinTransformer(nn.Module)
```

Registry in MMCIs

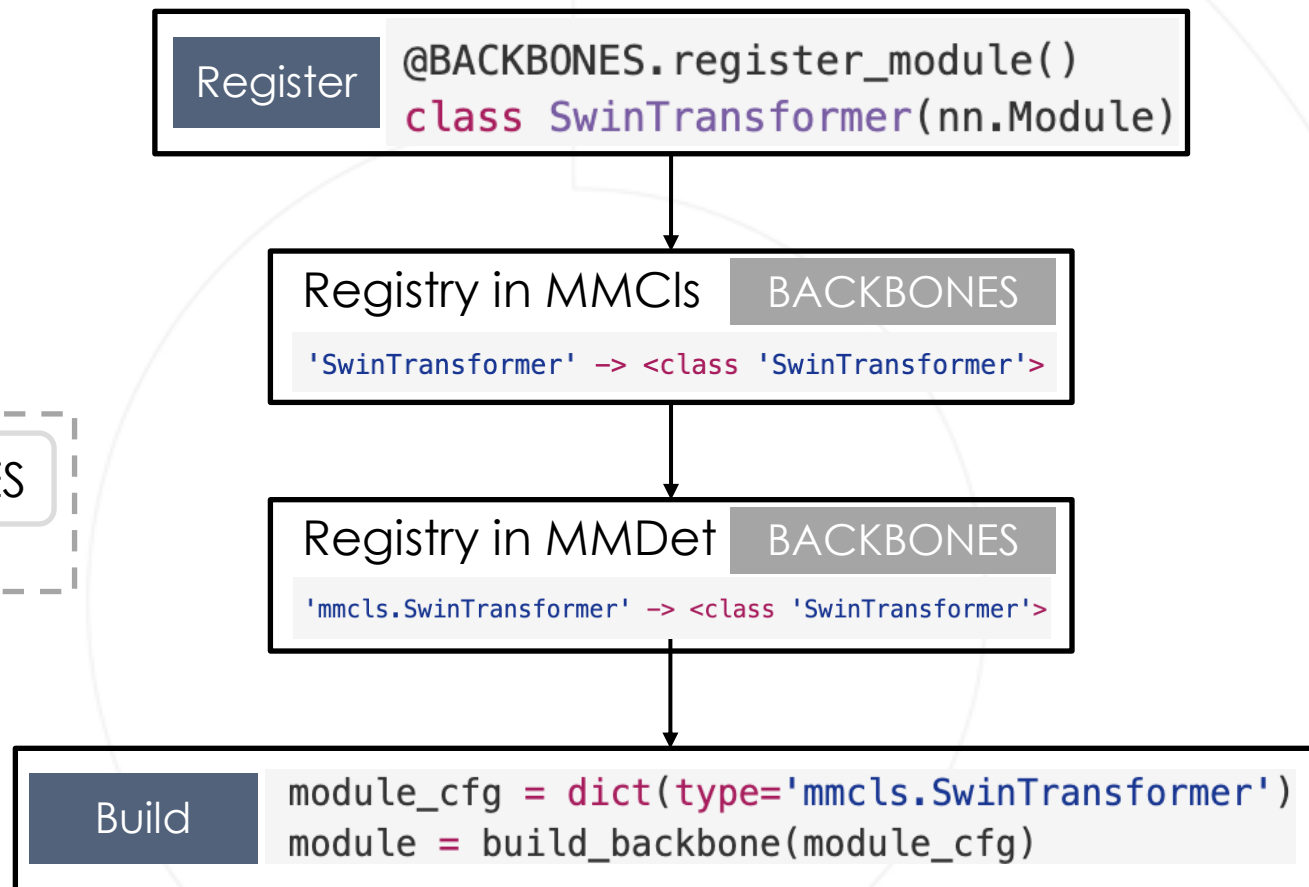
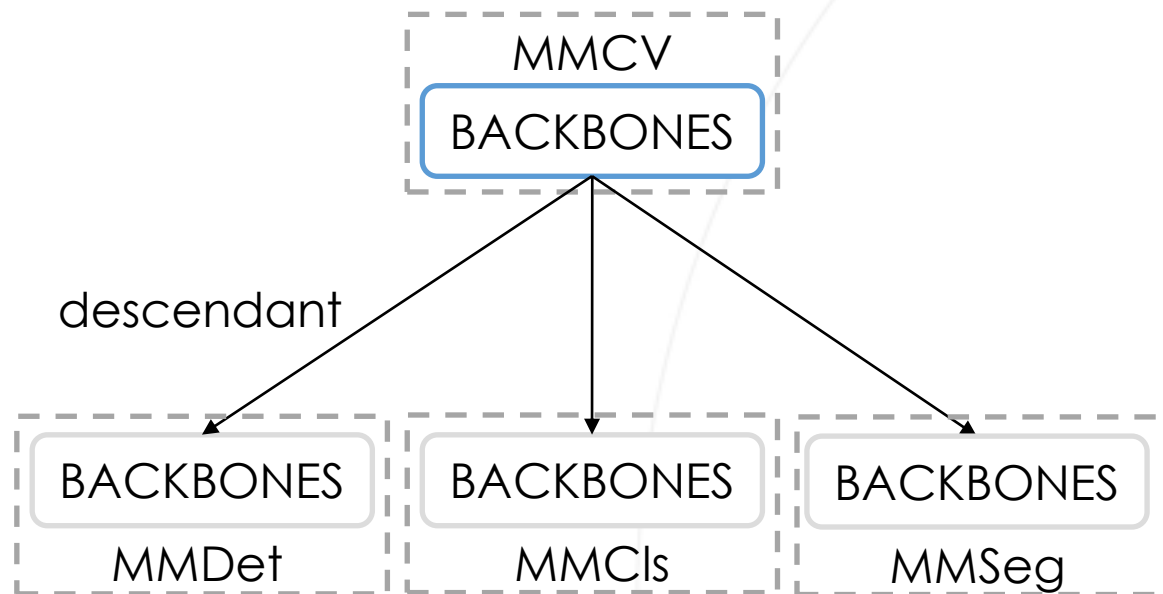
BACKBONES

```
'SwinTransformer' -> <class 'SwinTransformer'>
```

Build

```
module_cfg = dict(type='SwinTransformer')
module = build_backbone(module_cfg)
```

## Structure of registry



Key steps:

1. Implement the Swin Transformer and register Swin Transformer into registry
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File structure:

A minimal implementation of Swin Transformer


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│   ├── swin_mask_rcnn
│   │   └── mask_rcnn_swin-t-p4-w7_fpn_1x_coco.py
│   └── swin_upernet
│       └── upernet_swin-t_512x512_160k_8x2_ade20k.py
└── swin
    └── swin_transformer.py
```

## Step 2: Modify config files to use Swin Transformer

Key components in the config for instance segmentation

```
_base_ = [  
    '../_base_/models/mask_rcnn_r50_fpn.py',  
    '../_base_/datasets/coco_instance.py',  
    '../_base_/schedules/schedule_1x.py',  
    '../_base_/default_runtime_det.py'  
]  
  
model = dict(  
    pretrained='./pretrain/swin/swin_tiny_patch4_window7_224.pth',  
    backbone=dict(type='mmls.SwinTransformer'))  
  
custom_imports = dict(  
    imports=['swin.swin_transformer'], allow_failed_imports=False)
```

Make the file imported  
so that SwinTransformer  
can be registered



## Step 2: Modify config files to use Swin Transformer

Key components in the config for semantic segmentation

```
_base_ = [  
    '../_base_/models/upernet_r50.py',  
    '../_base_/datasets/ade20k.py',  
    '../_base_/default_runtime_seg.py',  
    '../_base_/schedules/schedule_160k.py'  
]  
  
model = dict(  
    pretrained='./pretrain/swin/swin_tiny_patch4_window7_224.pth',  
    backbone=dict(type='mmls.SwinTransformer'))  
  
custom_imports = dict(  
    imports=['swin.swin_transformer'], allow_failed_imports=False)
```



## Step 2: Modify config files to use Swin Transformer

Key components in the config for image classification

```
_base_ = [  
    '../_base_/datasets/imagenet_bs128_swin_224.py',  
    '../_base_/schedules/imagenet_bs1024_adamw_swin.py',  
    '../_base_/default_runtime.py'  
]  
  
model = dict(  
    type='ImageClassifier',  
    backbone=dict(  
        type='SwinTransformer', arch='tiny', img_size=224, drop_path_rate=0.2),  
    neck=dict(type='GlobalAveragePooling', dim=1),  
    head=dict(  
        type='SwinLinearClsHead',  
        num_classes=1000,  
        in_channels=768,  
        loss=dict(type='CrossEntropyLoss', use_soft=True),  
        cal_acc=False,  
    train_cfg=dict(  
        cutmixup=dict(  
            mixup_alpha=0.8,  
            cutmix_alpha=1.0,  
            prob=1.0,  
            switch_prob=0.5,  
            mode='batch',  
            label_smoothing=0.1)))  
  
custom_imports = dict(  
    imports=['swin.swin_transformer'], allow_failed_imports=False)
```

## Step 3: Train the model

### Train Swin Mask-RCNN with MMDetection

```
PYTHONPATH='.':$PYTHONPATH mim train mmdet \  
  configs/swin_mask_rcnn/mask_rcnn_swin-t-p4-w7_fpn_fp16_1x_coco.py \  
  --work-dir ../work_dir/mask_rcnn_swin-t-p4-w7_fpn_fp16_1x_coco.py \  
  --launcher slurm --partition $PARTITION -G 8 --gpus-per-node 8 \  
  --srun-args $SRUN_ARGS
```

### Train Swin Upernet with MMSegmentation

```
PYTHONPATH='.':$PYTHONPATH mim train mmseg \  
  configs/upernet/upernet_swin-t_512x512_160k_8x2_ade20k.py \  
  --work-dir ../work_dir/upernet_swin-t_512x512_160k_8x2_ade20k.py \  
  --launcher slurm --partition $PARTITION -G 8 --gpus-per-node 8 \  
  --srun-args $SRUN_ARGS
```

Find out more at



## Takeaway:

1. Use `MIM` to launch training and testing in your projects
2. Use registry to freely implement modules and extend OpenMMLab libraries, rather than forking and modifying the library
3. General modules like backbones only need one implementation for multiple tasks by specifying the scopes of the modules

**Thank You!**