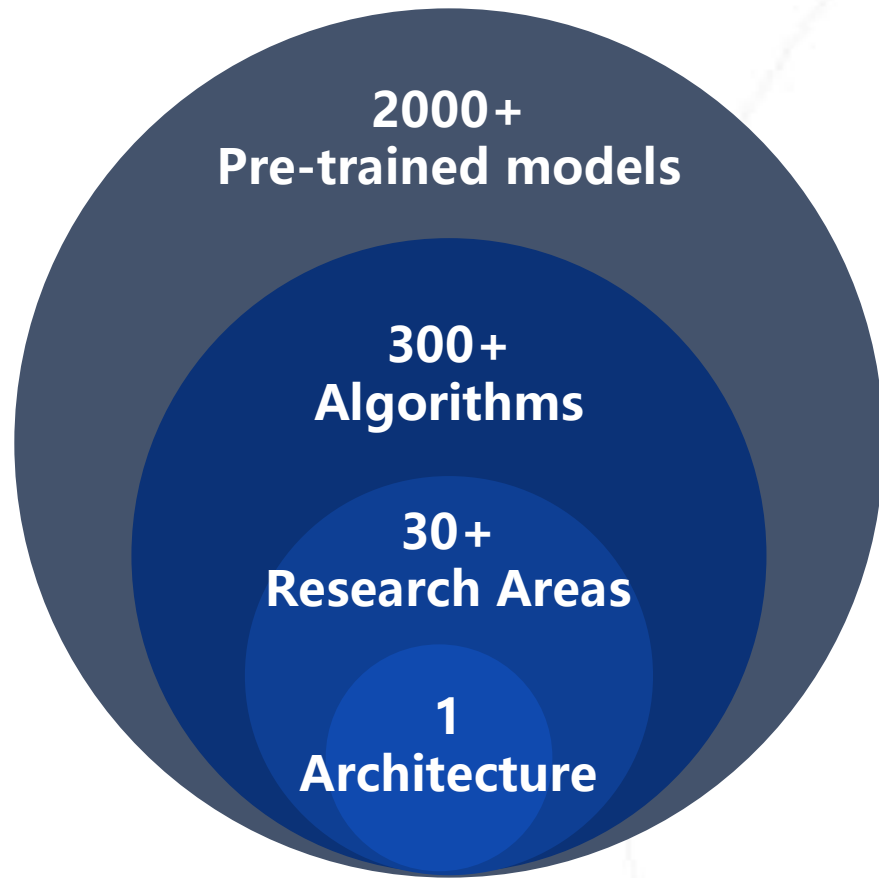


Overview and Recent Updates of OpenMMLab

Kai Chen
Shanghai AI Lab

Contents

- **Overview of OpenMMLab**
- **Recent Updates**
- **Technical Design**
- **Quick Tour for Developers and Researchers**



1 Architecture

- A unified architecture for all codebases

30+ Research Areas

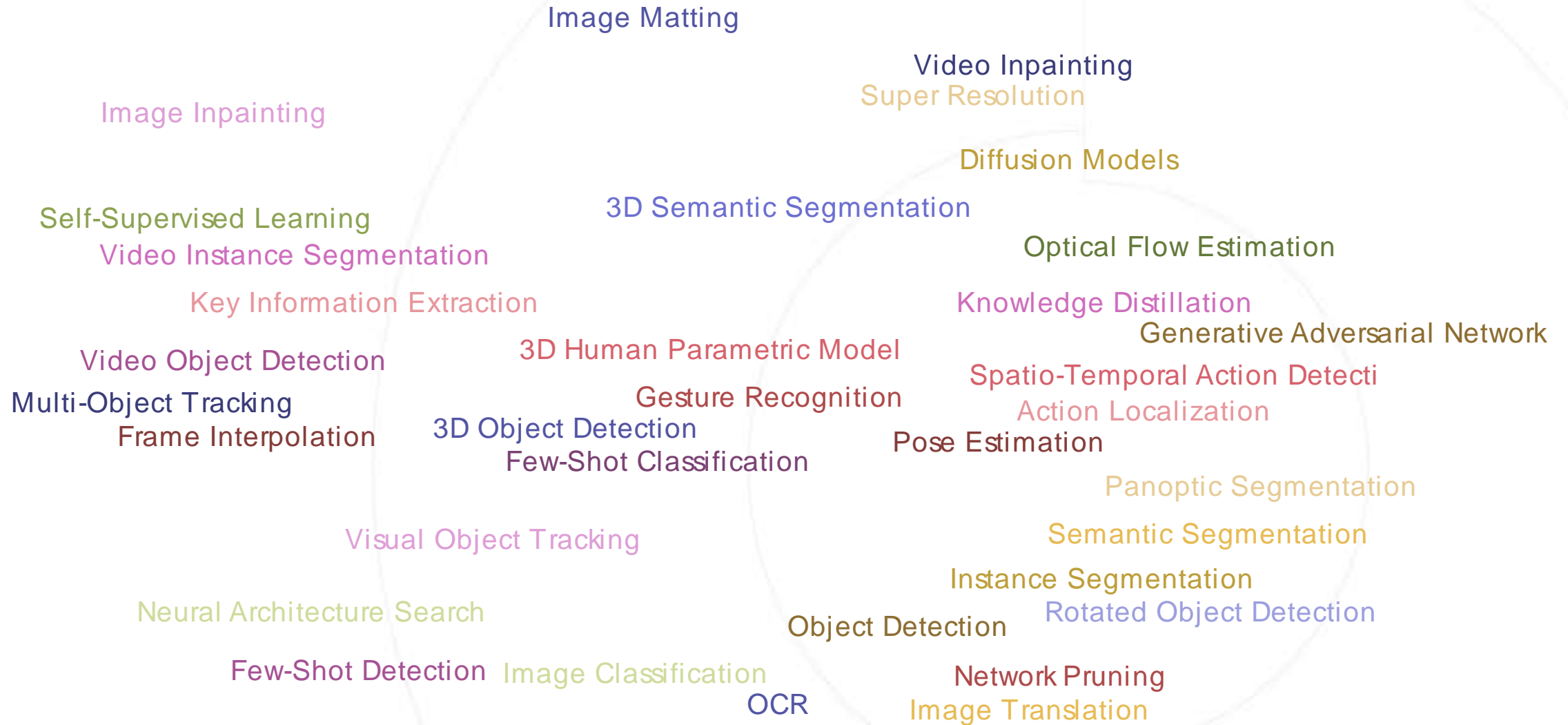
- Cover various areas of computer vision

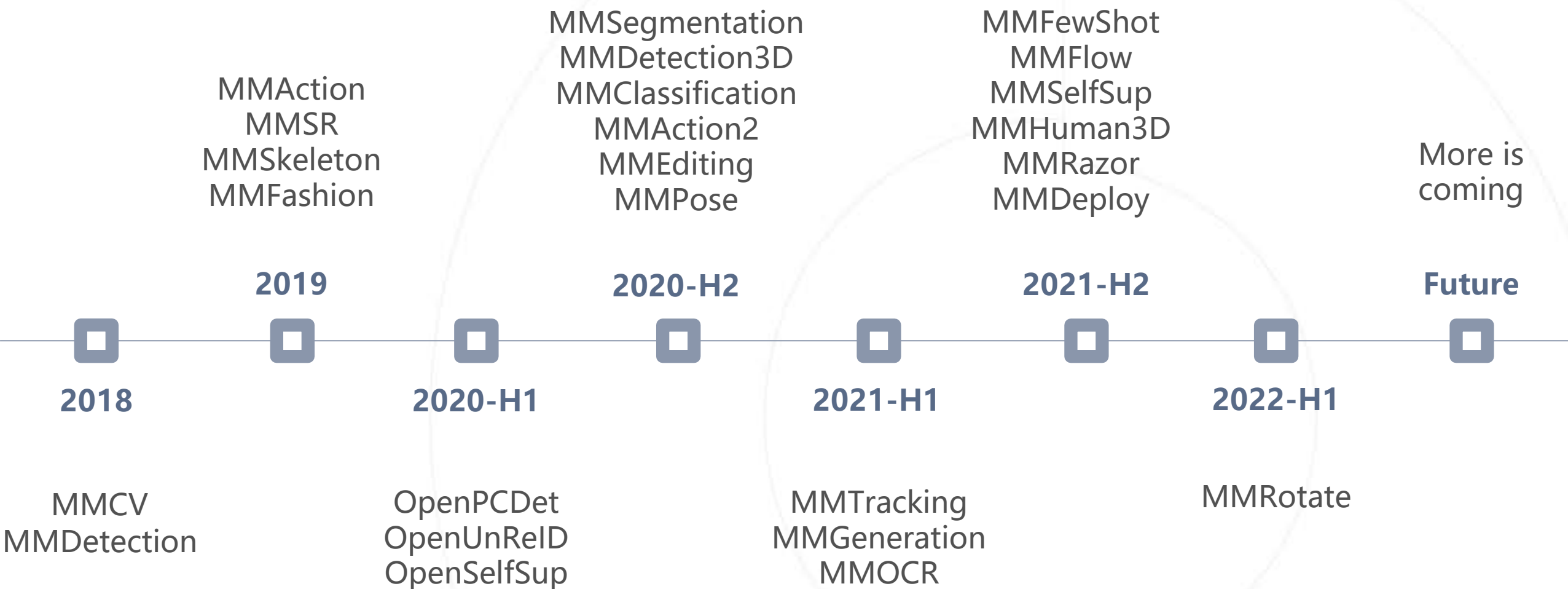
300+ Algorithms

- Implement both classical and most recent algorithms

2000+ Pretrained Models

- Unified benchmark and out-of-box usage
-





Model
Deployment

MMDeploy

Codebases

MMDetection

MMSegmentation

MMLTracking

MMSelfSup

MMDetection

MMEediting

MMPose

MMFlow

MMDetection3D

MMAAction2

MMGeneration

...

MMCV

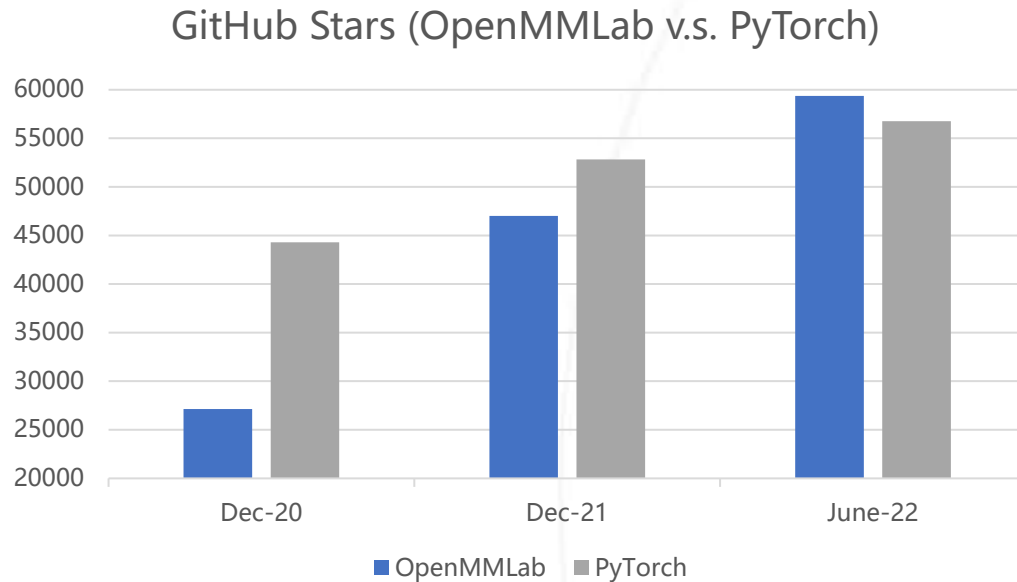
Common Modules

Training Engine

Deep Learning
Framework



GitHub Stars ~60,000



Users

- 110 countries/regions
- 600 colleges and research institutes
- 1M checkpoint downloads per year

Developers

- 1000+ contributors
- 500k lines of " import mmcv/mmdet/mmseg/..." on GitHub

Academic

- mentioned in 1000+ papers since released
- adopted by 76 papers in CVPR 2022
- 20+ challenge winners



6 new codebases in different areas

 SelfSup

 FewShot

 Flow

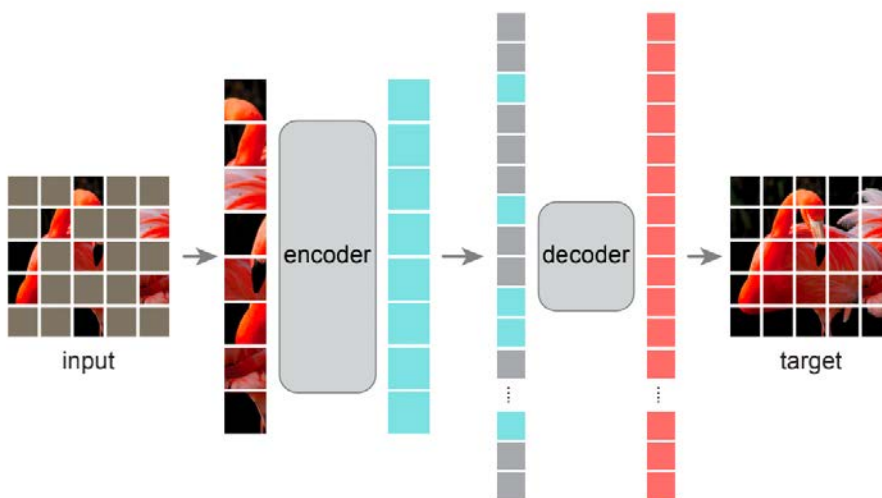
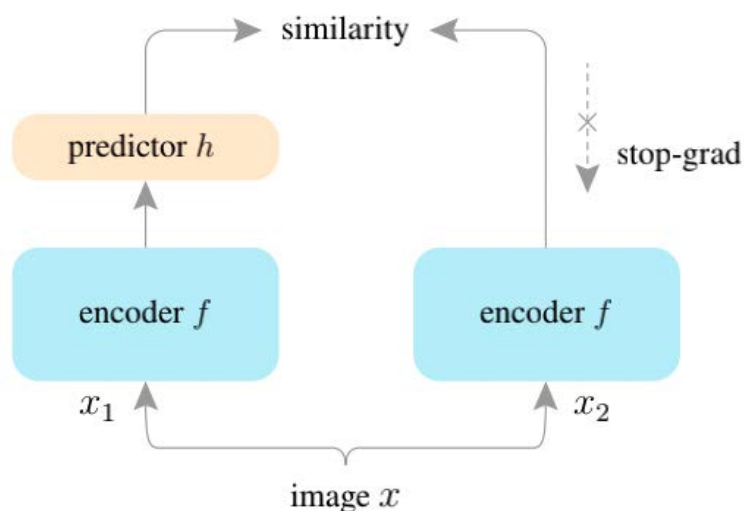
 Rotate

 Razor

 Human3D

From research to production

 Deploy



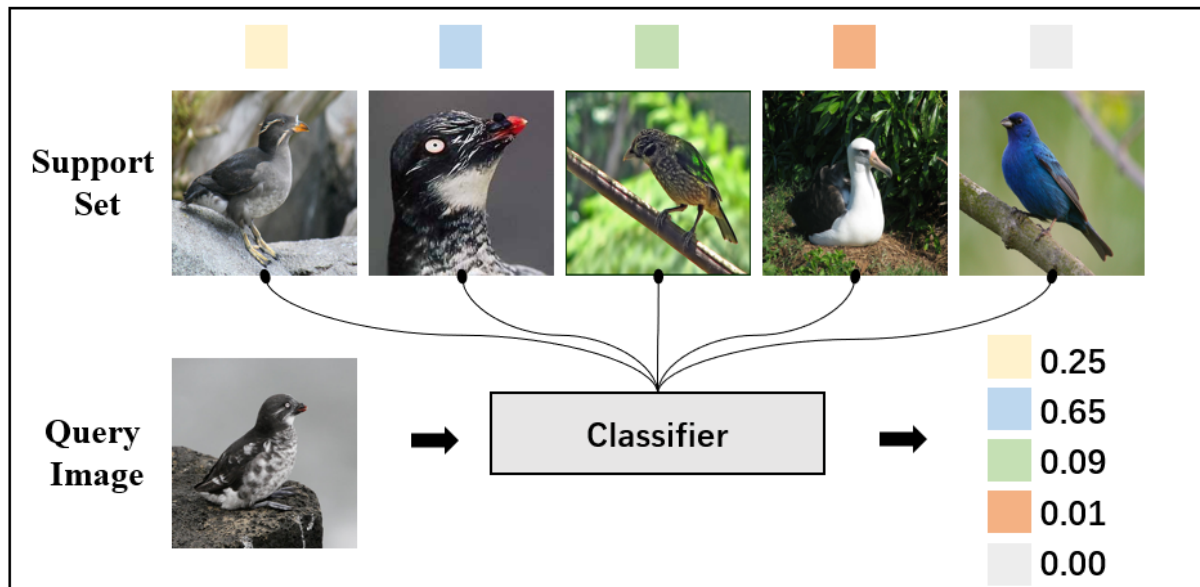
Popular self-supervised learning paradigms and algorithms

Benchmarks and downstream-tasks for evaluation

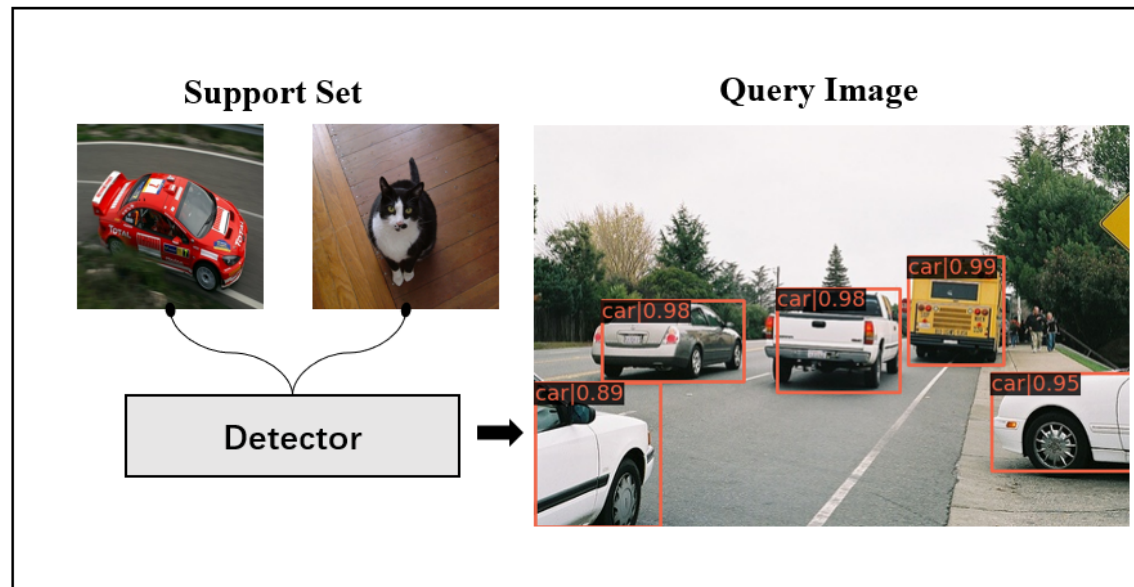


- ✓ Relative Location
- ✓ Rotation Prediction
- ✓ DeepCluster
- ✓ NPID
- ✓ ODC
- ✓ MoCo v1
- ✓ MoCo v2
- ✓ MoCo v3
- ✓ SimCLR
- ✓ BYOL
- ✓ SwAV
- ✓ DenseCL
- ✓ SimSiam
- ✓ Barlow Twins
- ✓ MAE
- ✓ SimMIM
- ✓ CAE

Few Shot Classification



Few Shot Detection



The **first** codebase that provides unified implementation and evaluation of few shot classification and detection.

Classification	Detection
Baseline Baseline++ NegMargin MatchingNet ProtoNet RelationNet MetaBaseline MAML	TFA FSCE AttentionRPN MetaRCNN FSDetView MPSR





The **first** systematic toolbox for optical flow estimation.

Supported methods

- ✓ FlowNet
- ✓ FlowNet2
- ✓ PWC-Net
- ✓ LiteFlowNet
- ✓ LiteFlowNet2
- ✓ IRR
- ✓ MaskFlowNet
- ✓ RAFT
- ✓ GMA





- ✓ Rotated RetinaNet-OBB/HBB
- ✓ Rotated FasterRCNN-OBB
- ✓ Rotated RepPoints-OBB
- ✓ Rotated FCOS
- ✓ RoI Transformer
- ✓ Gliding Vertex
- ✓ Rotated ATSS-OBB
- ✓ CSL
- ✓ R3Det
- ✓ S2A-Net
- ✓ ReDet
- ✓ Beyond Bounding-Box
- ✓ Oriented R-CNN
- ✓ GWD
- ✓ KLD
- ✓ SASM
- ✓ KFIOU



The most powerful and complete toolbox for rotated object detection

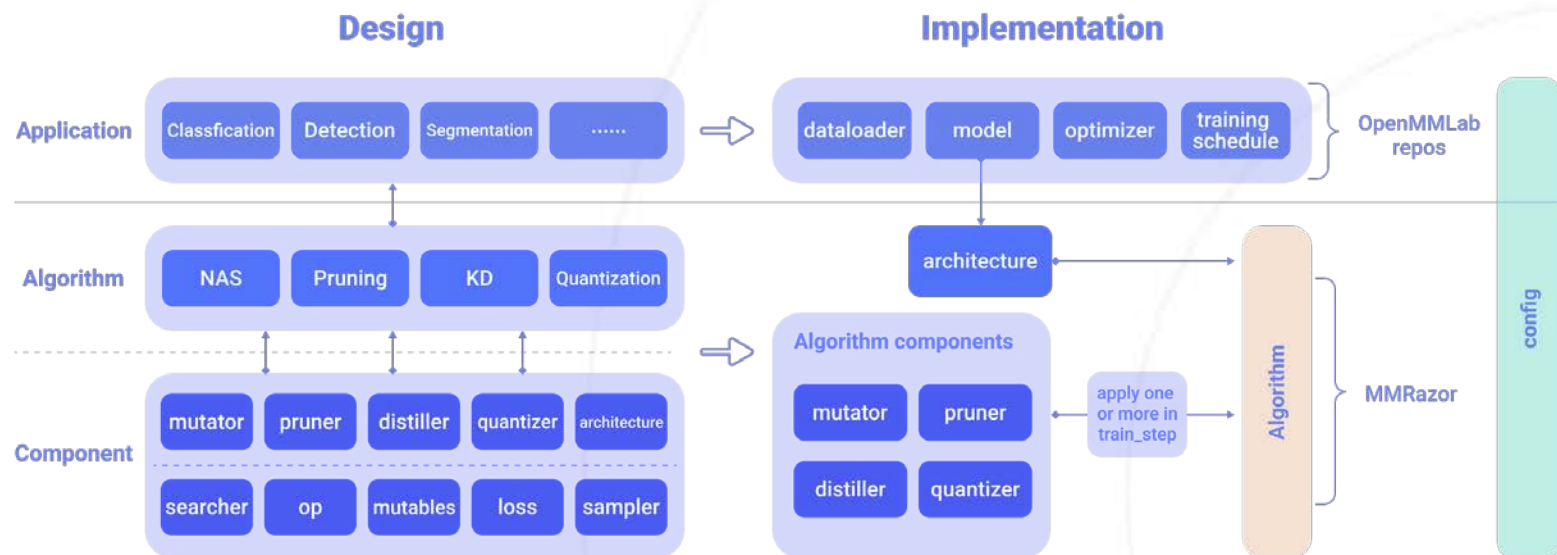


Reproducing popular methods with a modular framework

Supporting various datasets with a unified data convention

Versatile visualization toolbox





- ✓ NAS
- ✓ Network Pruning
- ✓ Knowledge Distillation



Training Framework

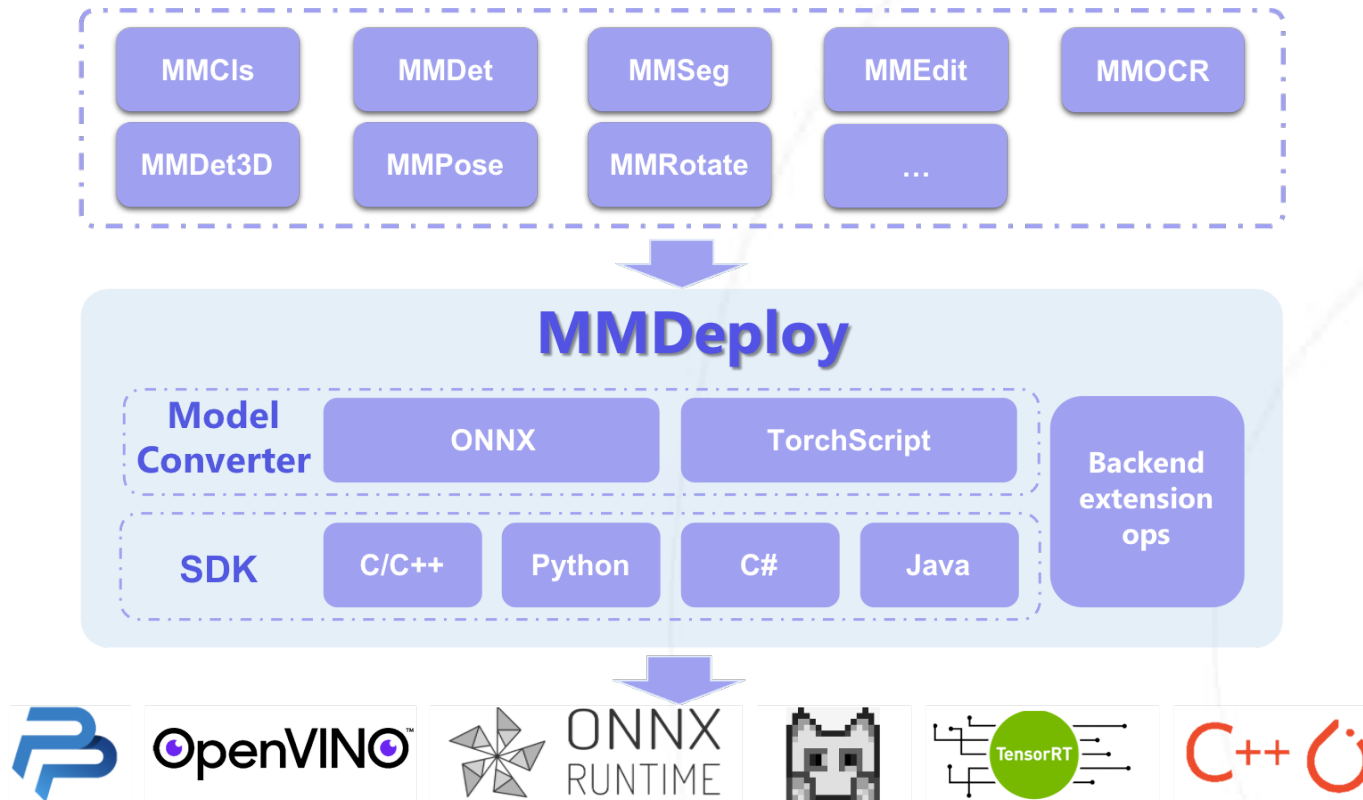


Intermediate Representation



Inference Engine





Various inference engines

TensorRT, ONNXRuntime, OpenVINO, ncnn, libtorch, PPL.NN

Multiple platforms

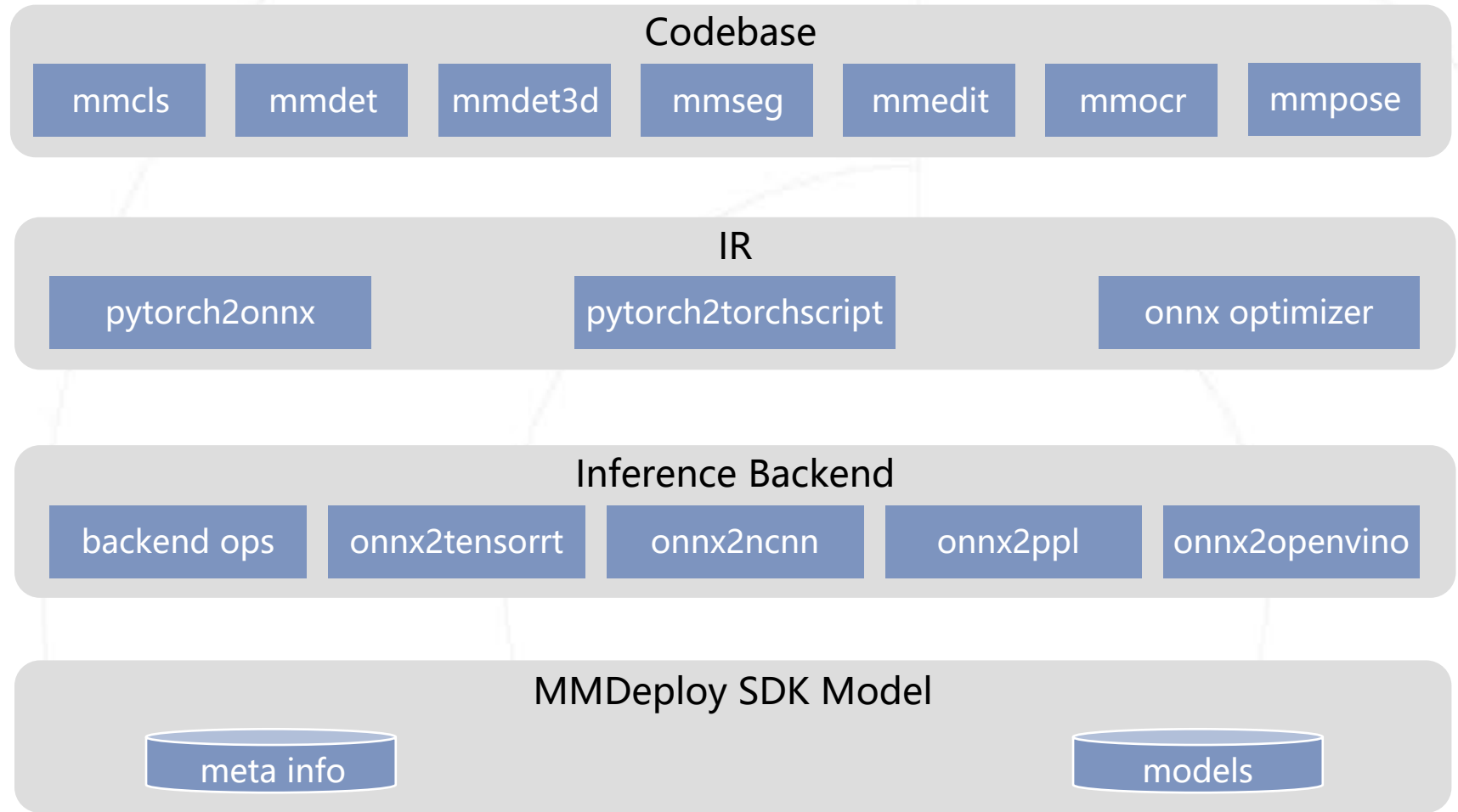
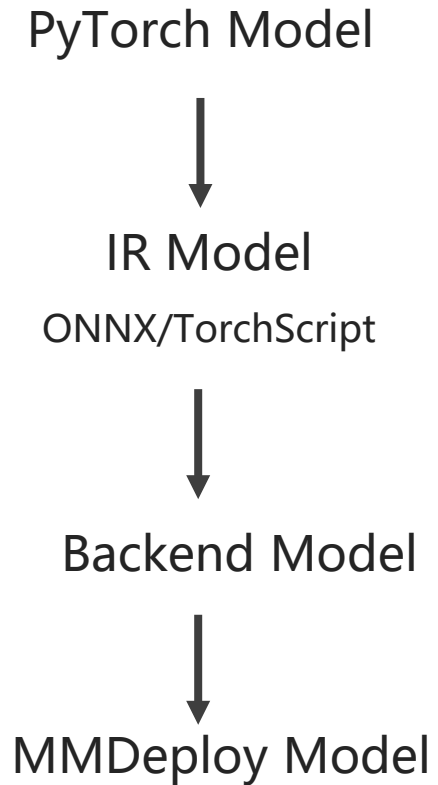
Linux, Windows, Android, macOS (WIP)

Multiple language support

C/C++, Python, Java, C#

Flexible integration to user system

IR models, Inference engine models, MMDeploy SDK



```
python tools/deploy.py \
  mmdet/deploy_configs/mmdet/detection/detection_tensorrt_dynamic-320x320-1344x1344.py \
  mmdetection/configs/retinanet/retinanet_r50_fpn_1x_coco.py \
  retinanet_r50_fpn_1x_coco_20200130-c2398f9e.pth \
  mmdetection/demo/demo.jpg \
  --work-dir retinanet/tensorrt \
  --device cuda:0 \
  --dump-info
```

Model Converter

MMDeploy Model

MMDeploy SDK



RetinaNet



```
retinanet/tensorrt
├── deploy.json
├── detail.json
├── end2end.engine
├── end2end.onnx
├── output_pytorch.jpg
├── output_tensorrt.jpg
└── pipeline.json
```

```
from mmdet_python import Detector
import cv2

model_path='retinanet/tensorrt'
image_path='mmdetection/demo/demo.jpg'
img = cv2.imread(image_path)
detector = Detector(model_path=model_path,
                    device_name='cuda',
                    device_id=0)
bboxes, labels, _ = detector(img)
```

Unified architecture

Learn once, use everywhere; implement once, use everywhere

Unified benchmark

Provide fair baselines for academic research

Modular design

Fast to develop and try new components

High-quality Implementation

Efficient, high performance, good code style

Registry

The basis of modular design

Config

Construct modules
Manage experiments

Runner&Hook

Unified training interfaces
Customizable pipelines

Build an instance with custom configs

1. Register

```
BACKBONES = Registry('backbones')

@BACKBONES.register_module()
class ResNet(nn.Module):
    pass
```

2. Build

```
config = dict(type='ResNet')
backbone = build_backbone(config, BACKBONES)
```

Registry

BACKBONES

'ResNet' -> <class 'ResNet'>

Config

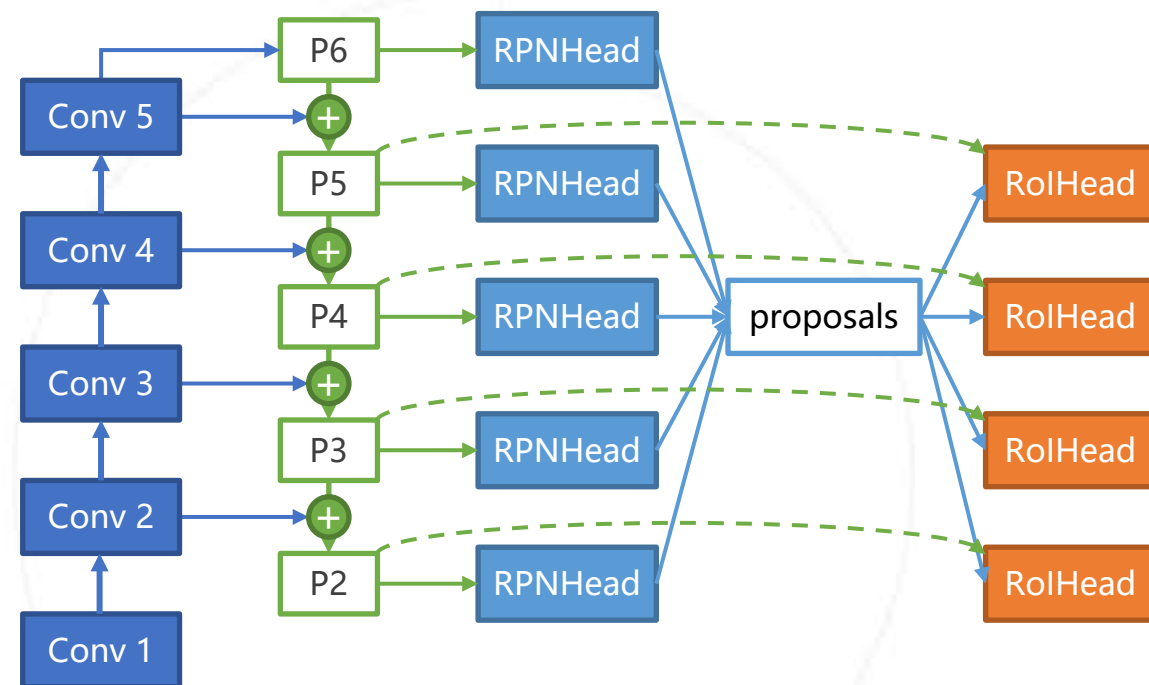
```

model = dict(
  type='FasterRCNN',
  pretrained='torchvision://resnet50',
  backbone=dict(
    type='ResNet',
    depth=50,
    ...),
  neck=dict(
    type='FPN',
    ...),
  rpn_head=dict(
    type='RPNHead',
    ...),
  roi_head=dict(
    type='StandardRoIHead',
    bbox_roi_extractor=dict(
      type='SingleRoIExtractor',
      ...),
    bbox_head=dict(
      type='Shared2FCBBoxHead',
      ...))
)

```



Module



```
model = torch.nn.parallel.DistributedDataParallel(SomeNet(), device_ids=[args.gpu])
optimizer = torch.optim.SGD(...)
train_loader = torch.utils.data.DataLoader(...)
```

```
def adjust_learning_rate():
    pass
```

```
def record_and_log_loss():
    pass
```

```
for epoch in range(args.epochs):
```

```
    adjust_learning_rate(optimizer, epoch, args)
```

```
    # train for one epoch
```

```
    for i, (images, target) in enumerate(train_loader):
```

```
        # measure data loading time
```

```
        data_time.update(time.time() - end)
```

```
        # compute output
```

```
        output = model(images)
```

```
        loss = criterion(output, target)
```

```
        # compute gradient and do SGD step
```

```
        optimizer.zero_grad()
```

```
        loss.backward()
```

```
        optimizer.step()
```

```
        # measure accuracy and record loss
```

```
        record_and_log_loss(loss)
```

```
        # measure elapsed time
```

```
        batch_time.update(time.time() - end)
```

```
        end = time.time()
```

```
        # print progress
```

```
        if i % args.print_freq == 0:
```

```
            progress.display(i)
```

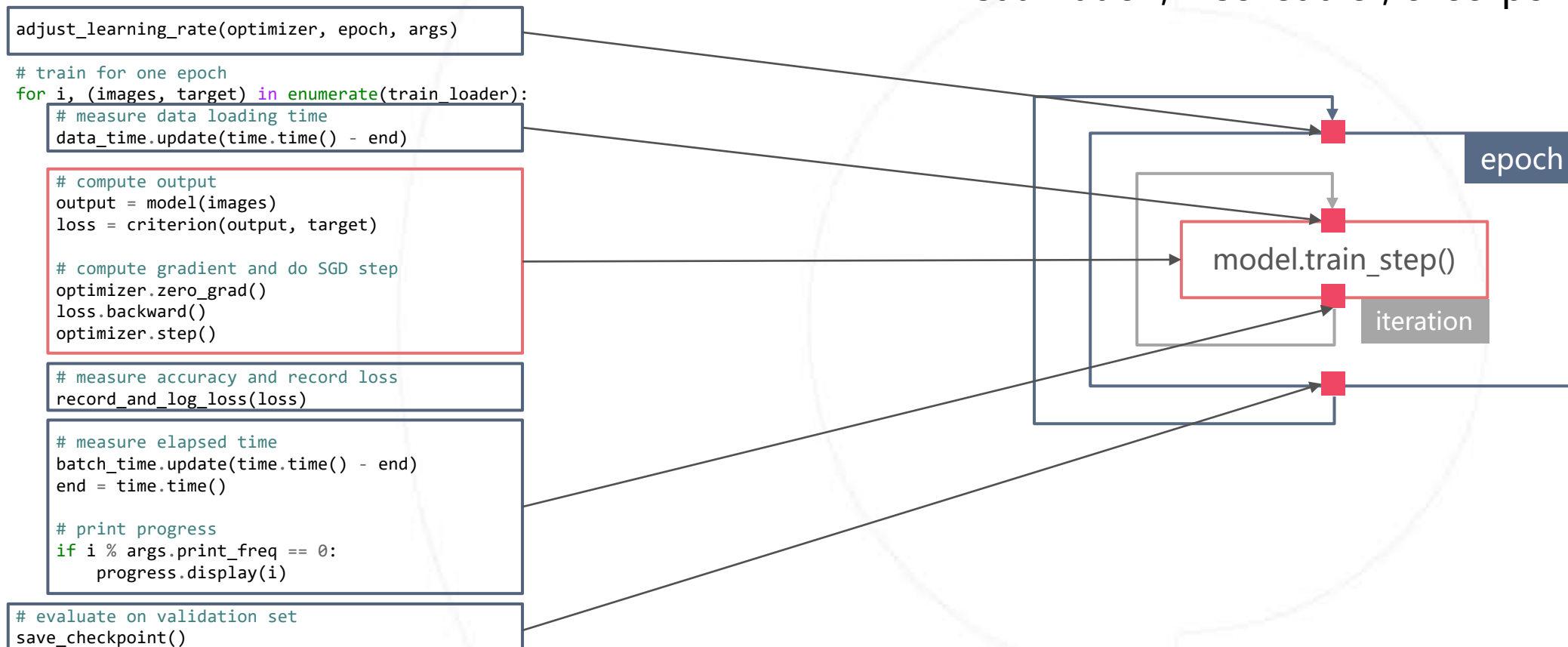
```
    # evaluate on validation set
```

```
    save_checkpoint()
```

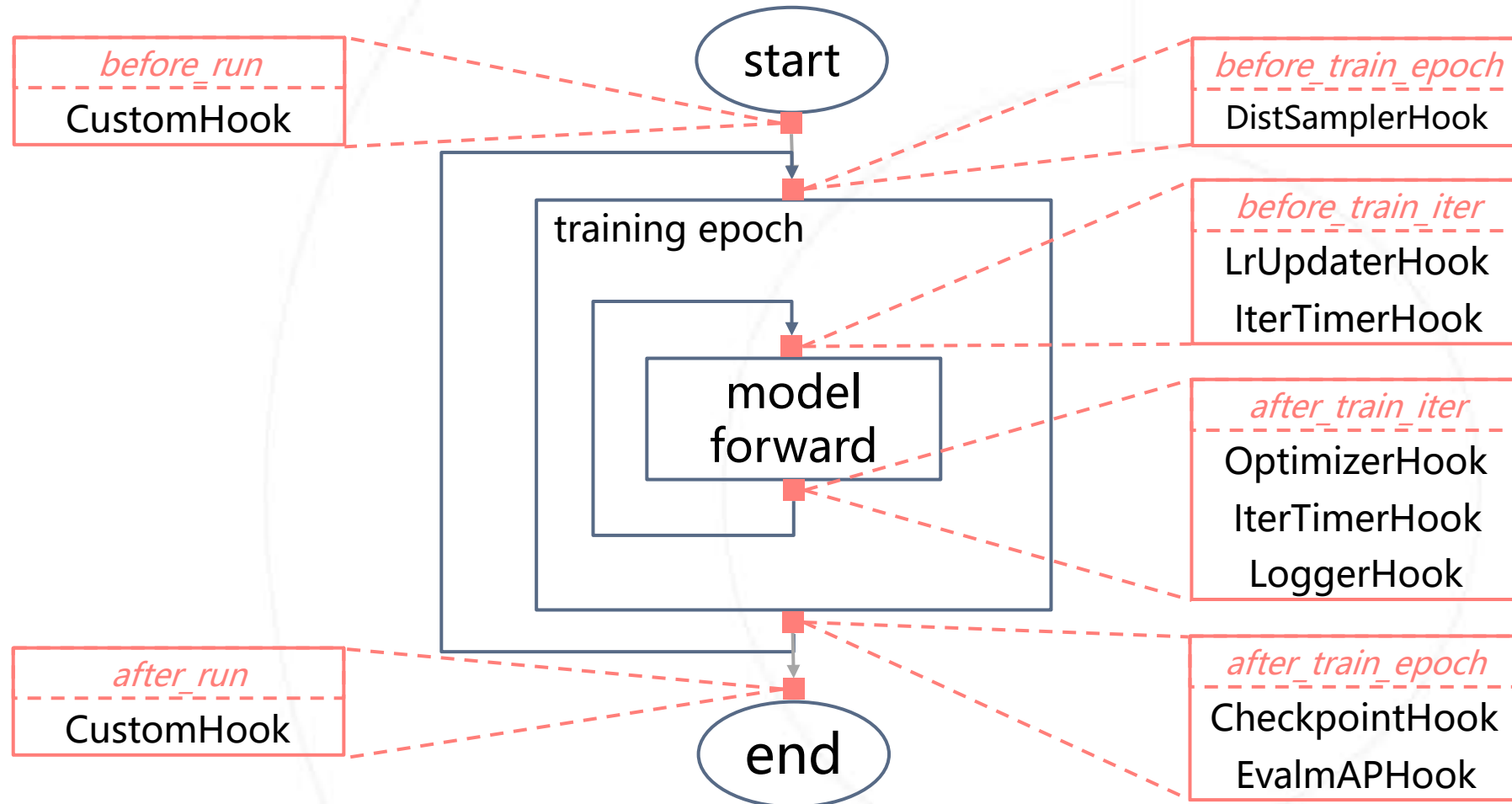
ImageNet Example

Runner: execution loop and core logic (fetch data and forward model)

Hook: custom logic and facilities (logging, visualization, lr scheduler, checkpointing, etc)



Another example



1

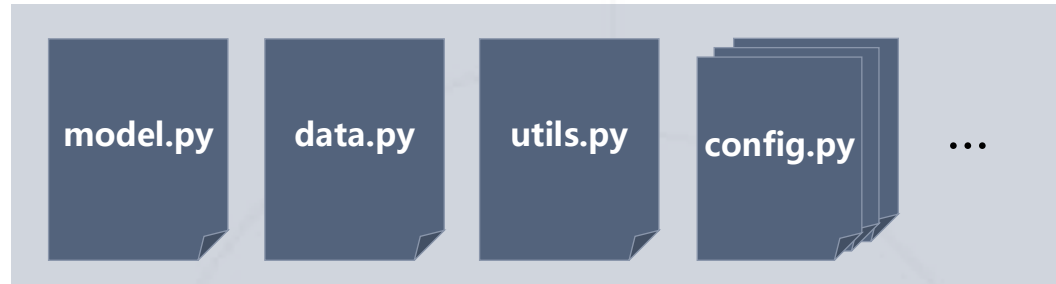
How to support a new dataset

2

How to develop a new model

Project

Maintained in an isolated folder



Dependencies

Use pip to install the libraries

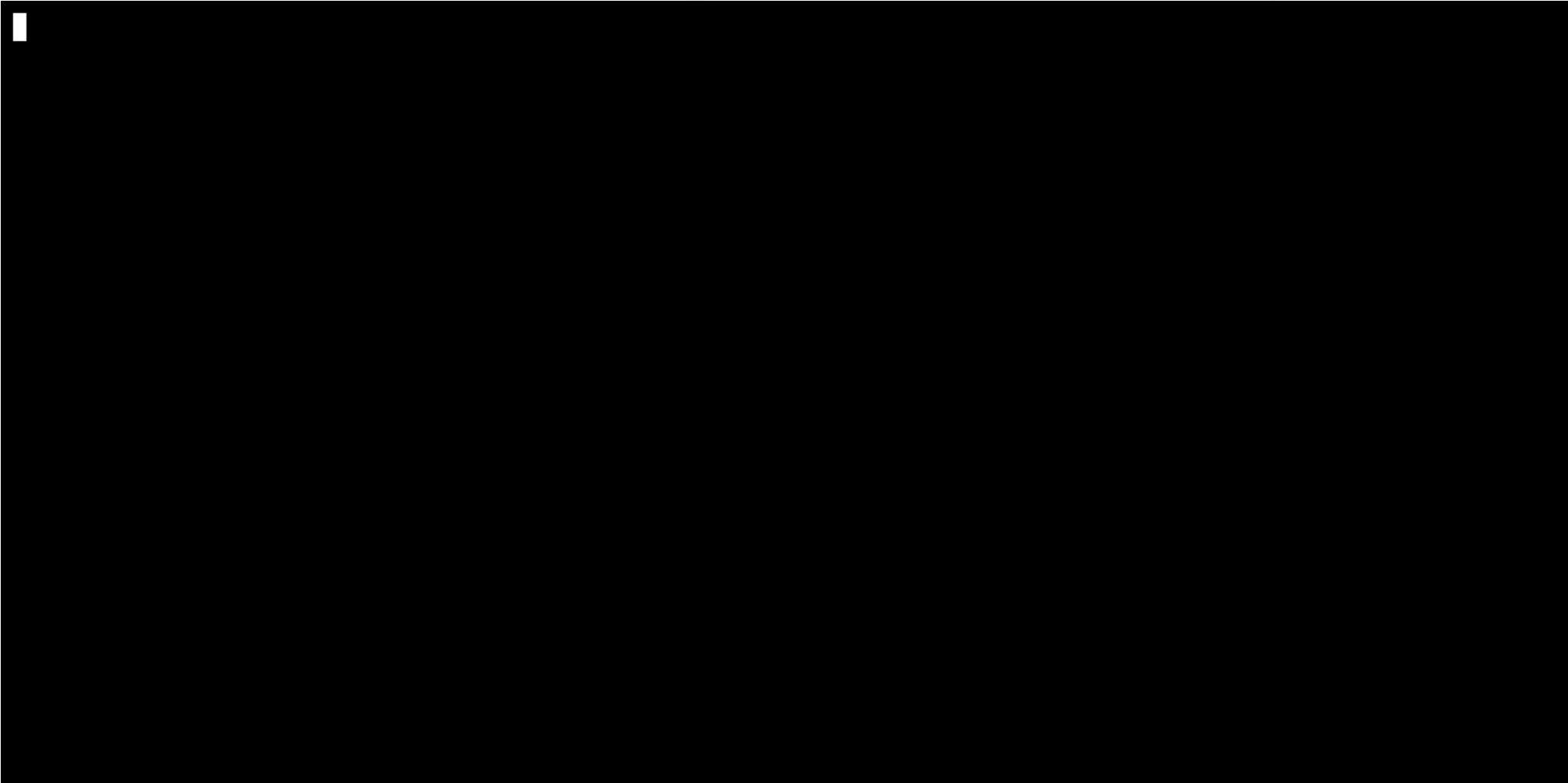


Package management

```
pip install openmim>=0.1.1 # install mim through pypi
mim install mmcv-full==1.3.5
mim install mmdet==2.13.0
mim install mmsegmentation=0.14.0
```

Unified entrypoint for scripts

mim train mmdet	—————→	mmdetection/tools/train.py
mim test mmseg	—————→	mmsegmentation/tools/test.py
mim train mmcls	—————→	mmclassification/tools/train.py



Find out more at



Process the dataset

optional

Implement a new class

Modify the config file

Train and test

Process the dataset

```
python -u nuim_converter.py \  
  --data-root $DATA \  
  --versions $VERSIONS \  
  --out-dir $OUT \  
  --nproc $NUM_WORKERS
```



```
project  
├── nuimages  
│   ├── annotations  
│   │   ├── nuimages_v1.0-mini.json  
│   │   ├── nuimages_v1.0-train.json  
│   │   ├── nuimages_v1.0-val.json  
│   │   ├── nuimages_v1.0-val2400.json  
│   │   └── nuimages_v1.0-test.json  
│   └── semantic_masks  
│       ├── xxxxx.png  
│       └── xxxxx.png  
└── samples
```

Implement a new class

```
project
├── configs
│   ├── _base_
│   │   ├── datasets
│   │   │   ├── nuimages.py
│   │   ├── default_runtime.py
│   │   ├── models
│   │   │   ├── pspnet_r50-d8.py
│   │   ├── schedules
│   │   │   ├── schedule_80k.py
│   ├── pspnet
│   │   ├── pspnet_r18-d8_512x1024_80k_nuim.py
│   ├── nuim_converter.py
│   └── nuim_dataset.py
```

```
import os.path as osp

import mmcv
from mmcv.utils import print_log
from mmseg.datasets import CustomDataset
from mmseg.datasets.builder import DATASETS
from mmseg.utils import get_root_logger

@DATASETS.register_module()
class NuImagesDataset(CustomDataset):
    CLASSES = ()

    def load_annotations(self, img_dir, img_suffix, ann_dir,
                        seg_map_suffix, split):

        annotations = mmcv.load(split)
        img_infos = []
        for img in annotations['images']:
            img_info = dict(filename=img['file_name'])
            seg_map = img_info['filename'].replace(
                img_suffix, seg_map_suffix)
            img_info['ann'] = dict(
                seg_map=osp.join('semantic_masks', seg_map))
            img_infos.append(img_info)

        print_log(
            f'Loaded {len(img_infos)} images from {ann_dir}',
            logger=get_root_logger())
        return img_infos
```

Use mmseg as a library like PyTorch and torchvision

Register the dataset into the DATASETS registry

Inherits from CustomDataset

Override the load_annotations method

Modify the config file

```
project
├── configs
│   ├── _base_
│   │   ├── datasets
│   │   │   └── nuimages.py
│   │   ├── default_runtime.py
│   │   ├── models
│   │   │   ├── pspnet_r50-d8.py
│   │   │   └── schedules
│   │   │       └── schedule_80k.py
│   │   └── pspnet
│   │       └── pspnet_r18-d8_512x1024_80k_nuim.py
│   ├── nuim_converter.py
│   └── nuim_dataset.py
```

```
dataset_type = 'NuImagesDataset'
data_root = 'data/nuimages/'
train_pipeline = [
```

```
    ...
```

```
]
test_pipeline = [
```

```
    ...
```

```
data = dict(
    samples_per_gpu=2,
    workers_per_gpu=2,
    train=dict(
        type=dataset_type,
        data_root=data_root,
        img_dir='',
        ann_dir='annotations/',
        split='annotations/nuimages_v1.0-train.json',
        pipeline=train_pipeline),
```

```
    val=dict(
        type=dataset_type,
        ...),
```

```
    test=dict(
        type=dataset_type,
        ...))
```

```
custom_imports = dict(
    imports=['nuim_dataset'],
    allow_failed_imports=False)
```

Define data pipeline of the dataset

Make the file imported so that
nuimagesDataset can be registered

Train and test

Train the model

```
PYTHONPATH='.'$PYTHONPATH mim train mmseg \  
  configs/pspnet/pspnet_r18-d8_512x1024_80k_nuim.py  
  --work-dir $WORK_DIR \  
  --launcher slurm -G 8 -p $PARTITION
```

Test the trained model

```
PYTHONPATH='.'$PYTHONPATH mim test mmseg \  
  configs/pspnet/pspnet_r18-d8_512x1024_80k_nuim.py  
  --checkpoint $WORK_DIR/latest.pth \  
  --launcher slurm -G 8 -p $PARTITION \  
  --eval mIoU
```

Implement the model

Modify the config file

Train and test

Implement the model

```
├── configs
│   ├── swin_classifier
│   │   └── swin_tiny_224_imagenet.py
│   ├── swin_mask_rcnn
│   │   └── mask_rcnn_swin-t-p4-w7_fpn_1x_coco.py
│   └── swin_upernet
│       └── upernet_swin-t_512x512_160k_8x2_ade20k.py
└── swin
    └── swin_transformer.py
```

```
from mmcls.models import BACKBONES
```

```
@BACKBONES.register_module()
class SwinTransformer(nn.Module):
    # code implementation
    def __init__(self, *args, **kwargs):
        super().__init__()
```

Register

```
@BACKBONES.register_module()
class SwinTransformer(nn.Module)
```

Registry in MMCls

BACKBONES

```
'SwinTransformer' -> <class 'SwinTransformer'>
```

Build

```
module_cfg = dict(type='SwinTransformer')
module = build_backbone(module_cfg)
```

Modify the config file

```
├─ configs
│   ├── swin_classifier
│   │   └─ swin_tiny_224_imagenet.py
│   ├── swin_mask_rcnn
│   │   └─ mask_rcnn_swin-t-p4-w7_fpn_1x_coco.py
│   ├── swin_upernet
│   │   └─ upernet_swin-t_512x512_160k_8x2_ade20k.py
├─ swin
│   └─ swin_transformer.py
```

```
_base_ = [
    '../_base_/datasets/imagenet_bs128_swin_224.py',
    '../_base_/schedules/imagenet_bs1024_adamw_swin.py',
    '../_base_/default_runtime.py'
]

model = dict(
    type='ImageClassifier',
    backbone=dict(
        type='SwinTransformer', arch='tiny', img_size=224, drop_path_rate=0.2),
    neck=dict(type='GlobalAveragePooling', dim=1),
    head=dict(
        type='SwinLinearClsHead',
        num_classes=1000,
        in_channels=768,
        loss=dict(type='CrossEntropyLoss', use_soft=True),
        cal_acc=False),
    train_cfg=dict(
        cutmixup=dict(
            mixup_alpha=0.8,
            cutmix_alpha=1.0,
            prob=1.0,
            switch_prob=0.5,
            mode='batch',
            label_smoothing=0.1)))

custom_imports = dict(
    imports=['swin.swin_transformer'], allow_failed_imports=False)
```

Modify the config file

```
├─ configs
│   ├── swin_classifier
│   │   └─ swin_tiny_224_imagenet.py
│   ├── swin_mask_rcnn
│   │   └─ mask_rcnn_swin-t-p4-w7_fpn_1x_coco.py
│   ├── swin_upernet
│   │   └─ upernet_swin-t_512x512_160k_8x2_ade20k.py
├─ swin
│   └─ swin_transformer.py
```

```
_base_ = [
    '../_base_/models/mask_rcnn_r50_fpn.py',
    '../_base_/datasets/coco_instance.py',
    '../_base_/schedules/schedule_1x.py',
    '../_base_/default_runtime_det.py'
]

model = dict(
    pretrained='./pretrain/swin/swin_tiny_patch4_window7_224.pth',
    backbone=dict(type='mmcls.SwinTransformer'))

custom_imports = dict(
    imports=['swin.swin_transformer'], allow_failed_imports=False)
```

Train and test

Train Swin Mask-RCNN with MMDetection

```
PYTHONPATH='.':$PYTHONPATH mim train mmdet \  
  configs/swin_mask_rcnn/mask_rcnn_swin-t-p4-w7_fpn_fp16_1x_coco.py \  
  --work-dir ../work_dir/mask_rcnn_swin-t-p4-w7_fpn_fp16_1x_coco.py \  
  --launcher slurm --partition $PARTITION -G 8 --gpus-per-node 8 \  
  --srun-args $SRUN_ARGS
```

Find out more at



Homepage

<https://openmmlab.com/>



GitHub

<https://github.com/open-mmlab>



Twitter

[@OpenMMLab](https://twitter.com/OpenMMLab)



Thank you!