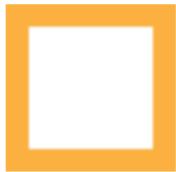


Algorithms and Data Structures

Graphs – Part III – Prim & Dijkstra

Jacob Trier Frederiksen & Anders Kalhauge



cphbusiness

Spring 2019

Program

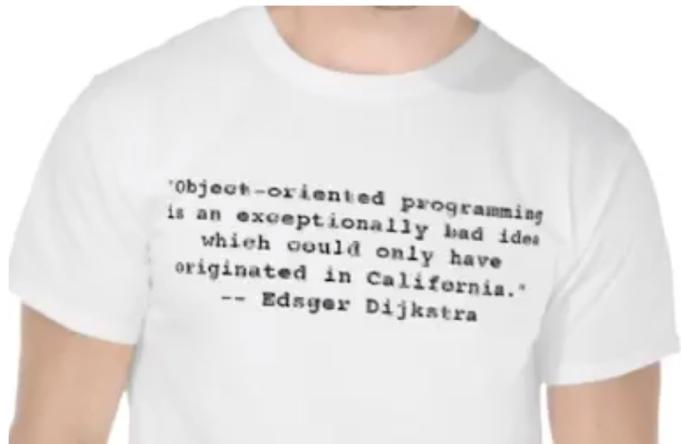
- Shortest Paths Tree; **Dijkstra's Algorithm**, recap by exploration.
- Shortest Path: the **A* Algorithm**, student presentation.

Benjamin has volunteered to present the A* Algorithm. Active student participation is encouraged.
Thank you Benjamin!

- Some Exercises
- Quiz – where do we stand? (a self-service check)
We're at a divide: should we fastforward, or fastreverse a bit from here?
- Time permitting: precedence scheduling, topological sort

Shortest Paths

1. Path Relaxation
2. Dijkstra's Algorithm – today for simple digraphs only.



The Shortest Paths Problem (single-source)

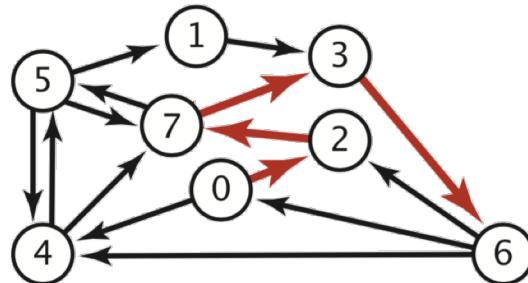
Given a digraph, find the shortest path between a vertex 's' (source) and one other vertex, or several (all) other vertices.

Assume simple digraphs only:

- *Single source*: from one vertex *s* to every other vertex.
- Weights positive
- No negative cycles

edge-weighted digraph

4->5	0.35
5->4	0.35
4->7	0.37
5->7	0.28
7->5	0.28
5->1	0.32
0->4	0.38
0->2	0.26
7->3	0.39
1->3	0.29
2->7	0.34
6->2	0.40
3->6	0.52
6->0	0.58
6->4	0.93

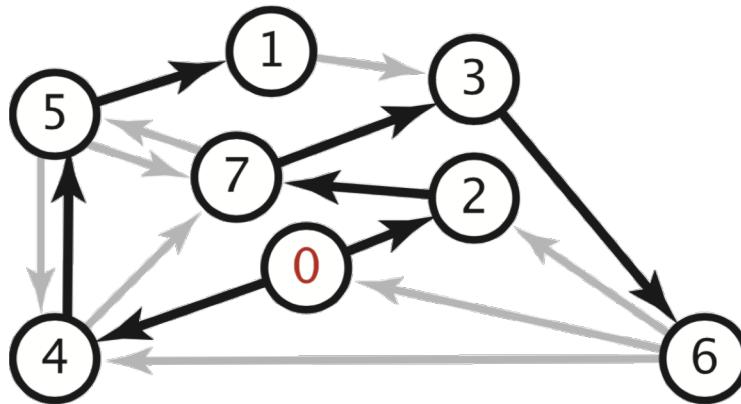


shortest path from 0 to 6

0->2	0.26
2->7	0.34
7->3	0.39
3->6	0.52

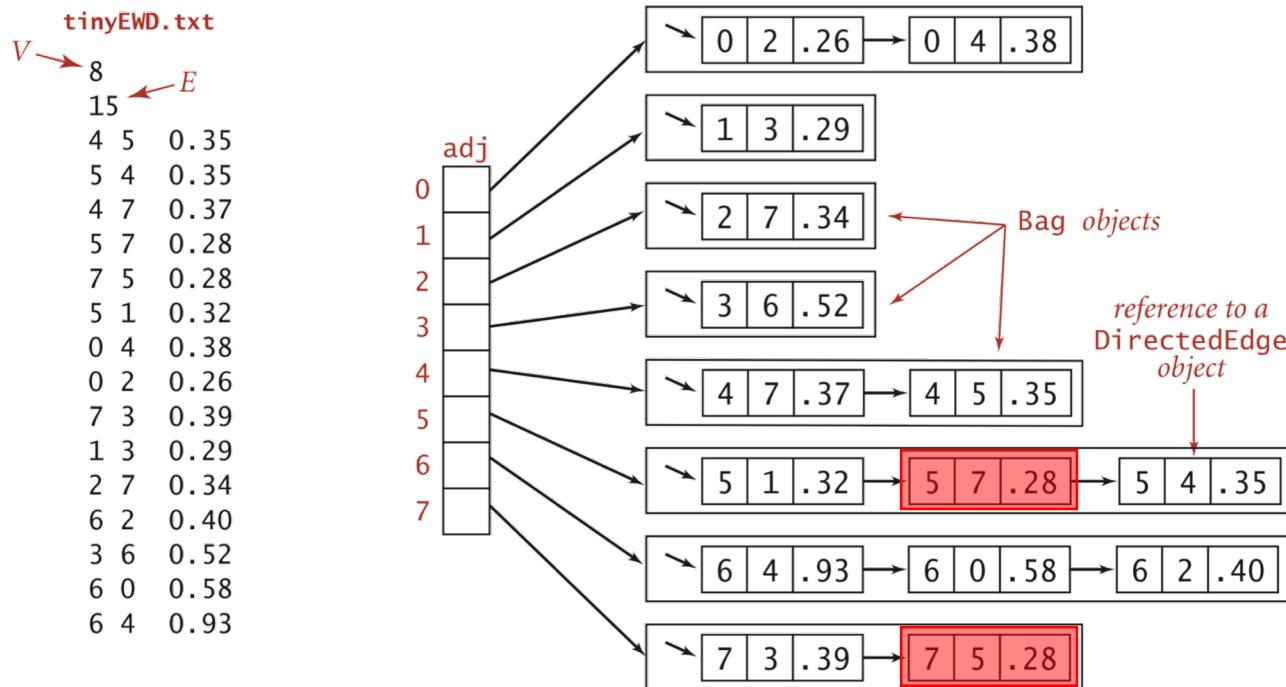
Shortest Path Tree

- Shortest Paths Tree, from computing all single-source paths from 's'.
- Represented by two arrays, `edgeTo[]` and `distTo[]`.



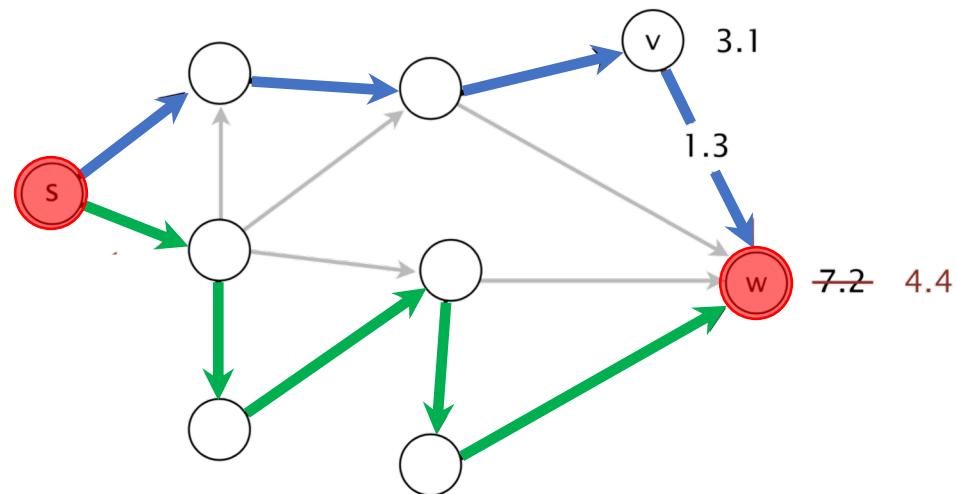
	<code>edgeTo[]</code>	<code>distTo[]</code>
0	null	0
1	5->1	0.32
2	0->2	0.26
3	7->3	0.37
4	0->4	0.38
5	4->5	0.35
6	3->6	0.52
7	2->7	0.34

What Data Structure for Dijkstra *et al.*?



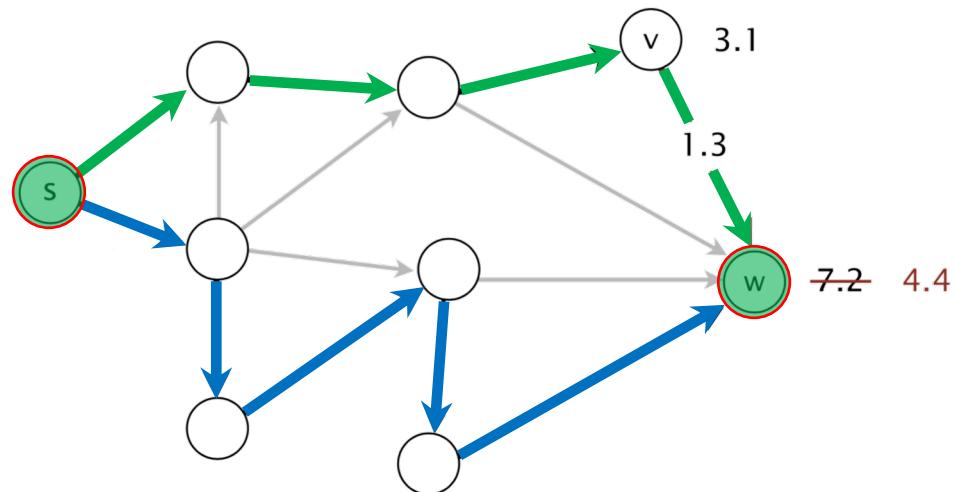
Edge Relaxation

If $e = v \rightarrow w$ gives shorter path to w through v , update both `distTo[w]` and `edgeTo[w]`.



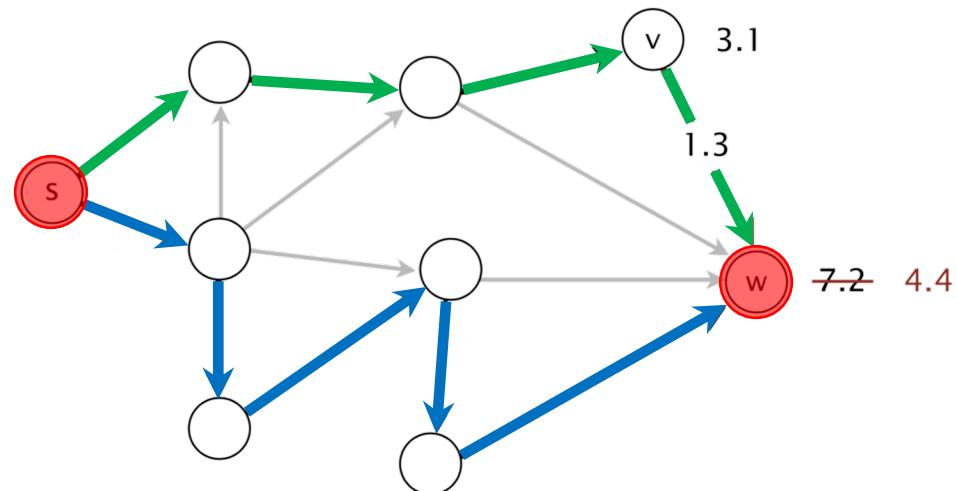
Edge Relaxation

If $e = v \rightarrow w$ gives shorter path to w through v , update both `distTo[w]` and `edgeTo[w]`.



A Generic SPT Algorithm

1. $\text{distTo}[s] = 0$
2. $\text{distTo}[v] = \infty$
3. While not all optimal:
Relax edges
4. Done.



Exercise 4

- $e = v \rightarrow w$ is an edge with weight 17.0.
- At some point, during the generic shortest paths algorithm, `distTo[v] = ∞` and `distTo[w] = 15.0`. What will `distTo[w]` be after calling `relax(e)`?

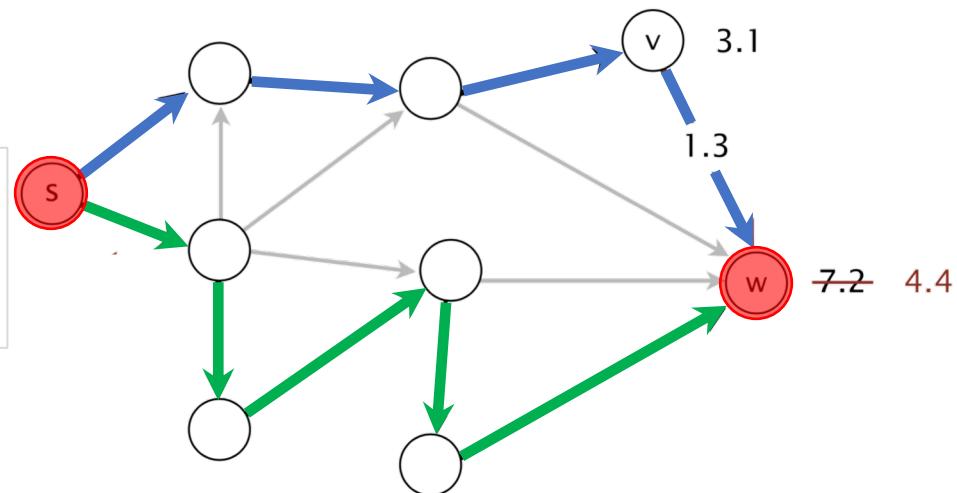
- The program will encounter a Java runtime exception
- 15.0
- 17.0
- ∞

Edge Relaxation HOWTO?

Three central algorithms exist:

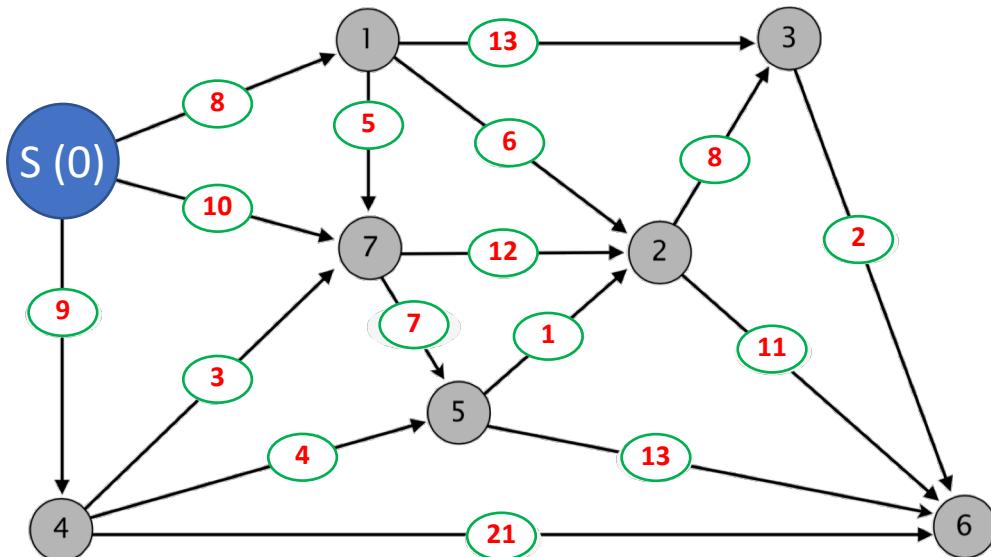
1. Dijkstra's Algorithm
2. Topological Sorting
3. Bellman-Ford Algorithm

We might just yet
do something
about number 2....



Exercise 5: Using Dijkstra's Algorithm

Find the SPT from source v=0 to all other vertices.



v	distTo[]	edgeTo[]
0	0.0	-
1	8.0	0 → 1
2		
3		
4		
5		
6		
7		

Trade-off hints:

- 1) [preferred!] you build the graph as a text file and run it through some software... requires some manual labor, though.
- 2) you can do it by brute force (paper/pen), keeping track like in the table here.. learning the algorithm first, though.

Dijkstra's Algorithm

- Keeping the queued vertices/edges on a minPQ (heap).

PQ implementation	insert	delete-min	decrease-key	total
unordered array	1	V	1	V^2
binary heap	$\log V$	$\log V$	$\log V$	$E \log V$
d-way heap	$\log_d V$	$d \log_d V$	$\log_d V$	$E \log_{E/V} V$
Fibonacci heap	1^\dagger	$\log V^\dagger$	1^\dagger	$E + V \log V$

Exercise 6

For the five example graphs

- `tinyEWG.txt` ($V=8, E=15$)
- `mediumEWG.txt` ($V=250, E=2546$)
- `1000EWG.txt` ($V=1000, E=16866$)
- `10000EWG.txt` ($V=10000, E=123462$)
- `largeEWG.txt` ($V=1000000, E=15172126$)

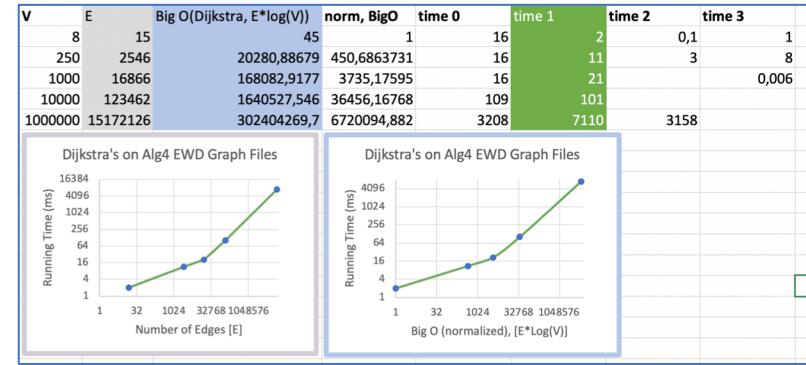
compare running times, using the `DijkstraSP()` class and the `SP()` class.

Time your computations. You can use fx the Book's `StopWatch()` class for this purpose. Or a system time diff, or you pick...

Exercise 6 – a few results.

For the five example graphs

- `tinyEWG.txt` ($V=8, E=15$)
- `mediumEWG.txt` ($V=250, E=2546$)
- `1000EWG.txt` ($V=1000, E=16866$)
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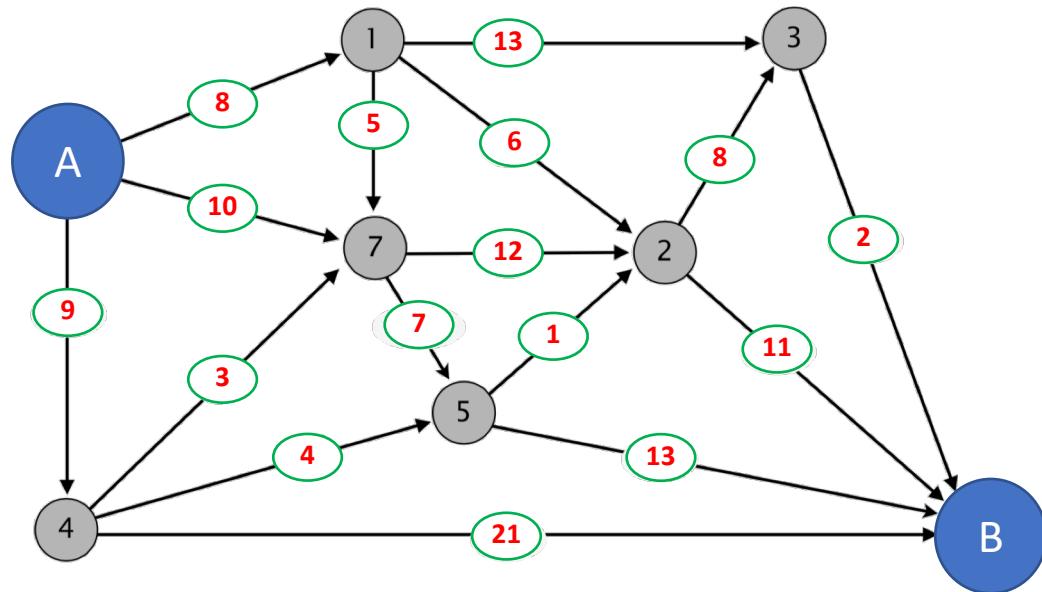
Exercise 7

Q: What is the BigO running time of Dijkstra's algorithm, using a binary heap?

- V
- E
- V^2
- $E \ Log \ V$

Benjamin presenting the A* Algorithm

Find the shortest path from A to B, with parametrized heuristic search algorithm.



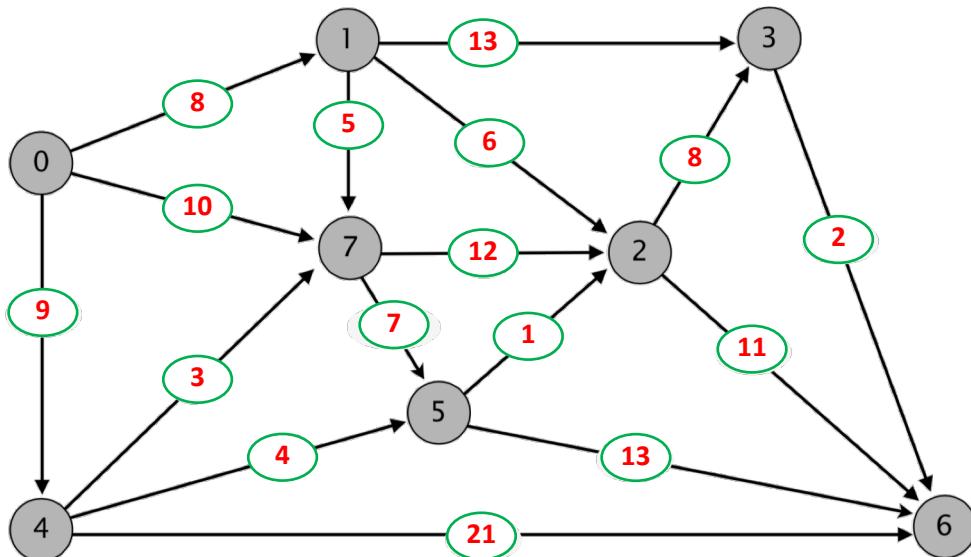
v	distTo[]	edgeTo[]
0	0.0	-
1	10.0	0 → 1
2		
3		
4		
5		
6		
7		

Trade-off methods:

- 1) [preferred!] you build the graph as a text file and run it through some software... requires some manual labor, though.
- 2) you can do it by brute force (paper/pen), keeping track like in the table here.. learning the algorithm first, though.

Exercise 8: Using the A* Algorithm

Find the shortest path from source $v=0$ to $v=6$.



v	distTo[]	edgeTo[]
0	0.0	-
1	10.0	$0 \rightarrow 1$
2		
3		
4		
5		
6		
7		

Trade-off hints:

- 1) you build the graph as a text file and run it through some software... requires some manual labor, though.
- 2) you can do it by brute force (paper/pen), keeping track like in the table here.. learning the algorithm first, though.

Quiz – where do we stand?

A self-service check.

- 1) Take a piece of paper ...
- 2) ... and a pen ...
- 3) ... and score the following review in terms of what you think don't know/remember, per item on slide #....
- 4) let's collect and see what to review asap.
- 5) ☺



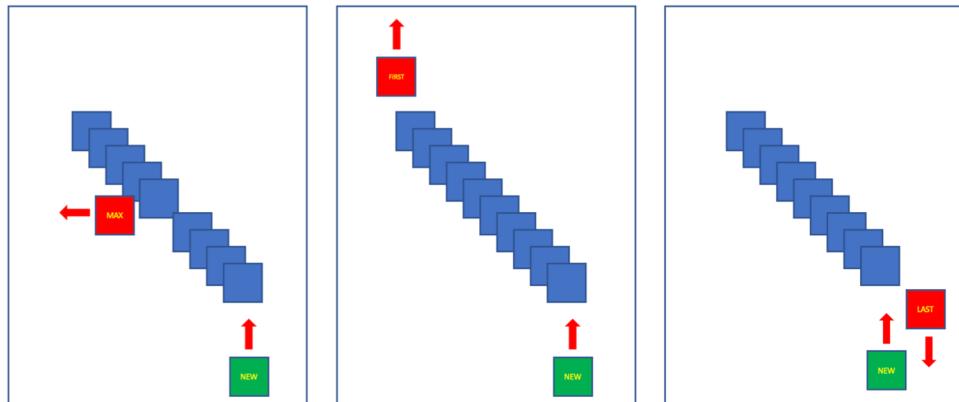
Quiz – Chapter 1: *'Fundamentals'*

Data structures

- Bags, queues, stacks

Analysis of Algorithms

- Running time
- Memory usage
- Big O notation



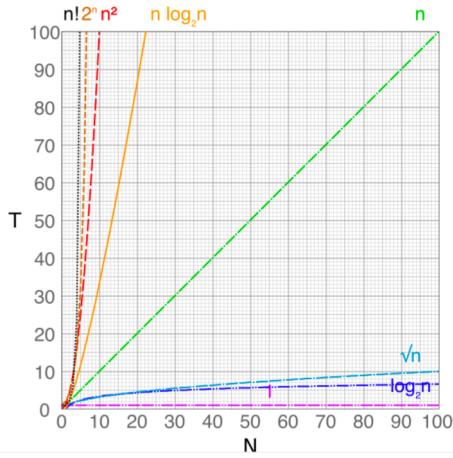
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 $\mathcal{O}(2^N)$

```
// We will measure the following in time units only,
// neglecting any movement of data and excess storage
// needs.
int count(int[] a) {
    int n = a.length;                                // ~ 1
    int count = 0;                                   // ~ 1
    for (int i = 0; i < n; i++)                      // ~ N
        for (int j = i + 1; j < n; j++)              // ~ N
            for (int k = j + 1; k < n; k++)          // ~ N
                if (a[i] + a[j] + a[k] == 0) count++; // ~ 1
    return count;
}
```

Total units of time consumption:

$$\mathcal{O}(1 + 1 + N + N^2 + N^3 + 1) \approx \mathcal{O}(N^3)$$

Exercise 3

- Show by any means (perhaps a summation series) that the running time complexity of computing the brute force ‘Two-Sum-Zero’ is $O(N^2)$:

$$C(\text{twosumzero}) \approx \frac{N(N - 1)}{2} \sim O(N^2).$$

- Extend your argument to show that the running time complexity of computing the brute force ‘Three-Sum-Zero’ is $O(N^3)$.
- What is the worst case order of growth – in terms of Big O?

description	order of growth	typical code framework	description	example
constant	1	<code>a = b + c;</code>	statement	add two numbers
logarithmic	$\log N$	[see page 47]	divide in half	binary search
linear	N	<code>double max = a[0]; for (int i = 1; i < N; i++) if (a[i] > max) max = a[i];</code>	loop	find the maximum
linearithmic	$N \log N$	[see ALGORITHM 2.4]	divide and conquer	mergesort
quadratic	N^2	<code>for (int i = 0; i < N; i++) for (int j = i+1; j < N; j++) if (a[i] + a[j] == 0) cnt++;</code>	double loop	check all pairs
cubic	N^3	<code>for (int i = 0; i < N; i++) for (int j = i+1; j < N; j++) for (int k = j+1; k < N; k++) if (a[i] + a[j] + a[k] == 0) cnt++;</code>	triple loop	check all triples
exponential	2^N	[see CHAPTER 6]	exhaustive search	check all subsets

Summary of common order-of-growth hypotheses

Quiz – Chapter 2: 'Sorting'

Elementary Sorts

- Insertion sort
- Selection sort

Mergesort

Quicksort

Priority Queues, heaps

Sorting Algorithms Animations

The following animations illustrate how effectively data sets from different starting points can be sorted using different algorithms.

3.8K SHARES   

HOW TO USE: Press "Play all", or choose the ▶ button for the individual row/column to animate.



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Quiz – Chapter 3: 'Searching'

Symbol Tables

- Sequential Search (un-ordered list)
- Binary Search (ordered list)

Binary Search Trees

Balanced Search Trees

implementation	guarantee			average case			ordered ops?	key interface
	search	insert	delete	search hit	insert	delete		
sequential search (unordered list)	N	N	N	$\frac{1}{2}N$	N	$\frac{1}{2}N$		equals()
binary search (ordered array)	$\lg N$	N	N	$\lg N$	$\frac{1}{2}N$	$\frac{1}{2}N$	✓	compareTo()
BST	N	N	N	$1.39 \lg N$	$1.39 \lg N$	\sqrt{N}	✓	compareTo()
2-3 tree	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	✓	compareTo()

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BST	N	N	N	$1.39 \lg N$	$1.39 \lg N$	\sqrt{N}	✓	compareTo()
2-3 tree	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	✓	compareTo()

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2-3 tree	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	✓	compareTo()

Quiz – Chapter 4: *'Graphs'*

Un-directed Graphs

- Adjacency lists data structure representation
- Depth-first search (DFS, stack)
- Breadth-first Search (BFS, queue)
- Connected components

Directed Graphs

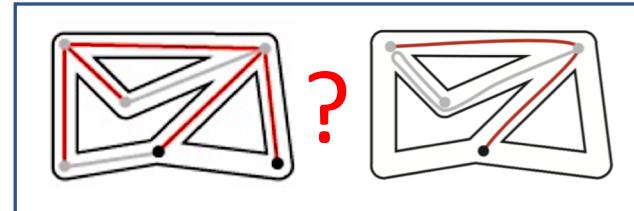
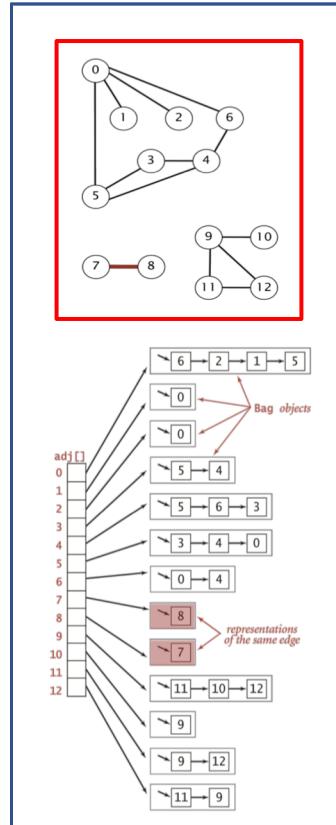
- Precedence-constrained Scheduling
- Topological Sort

Minimum Spanning Trees

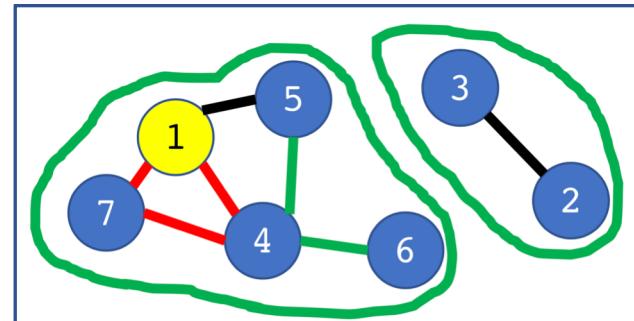
- Greedy Algorithm
- Prim's Algorithm

Shortest Paths

- Dijkstra's Algorithm
- A* Algorithm



representation	space	add edge	edge between v and w?	iterate over vertices adjacent to v?
list of edges	E	1	E	E
adjacency matrix	V^2	1^*	1	V
adjacency lists	$E + V$	1	$degree(v)$	$degree(v)$



Quiz – Chapter 4: 'Graphs'

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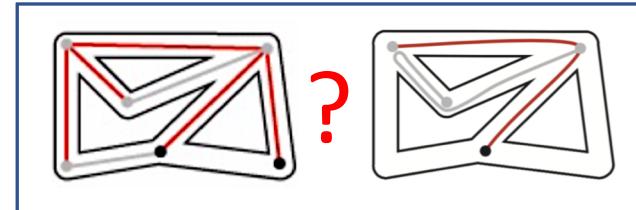
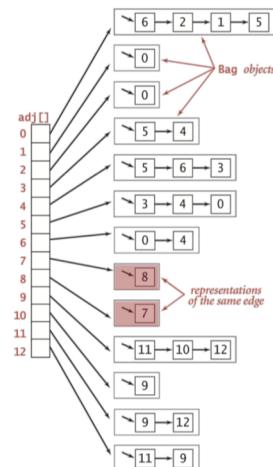
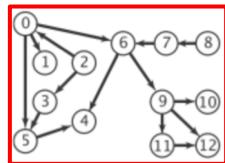
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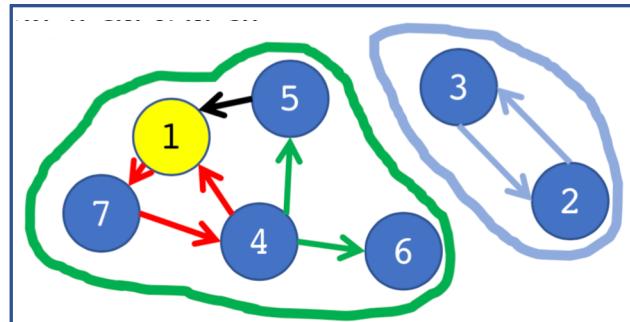
Shortest Paths

- Dijkstra's Algorithm
- A* Algorithm

"Every undirected graph is a digraph (with edges in both directions)."



representation	space	add edge	edge between v and w?	iterate over vertices adjacent to v?
list of edges	E	1	E	E
adjacency matrix	V^2	1^*	1	V
adjacency lists	$E + V$	1	$degree(v)$	$degree(v)$



Quiz – Chapter 4: 'Graphs'

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Directed Graphs

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Minimum Spanning Trees

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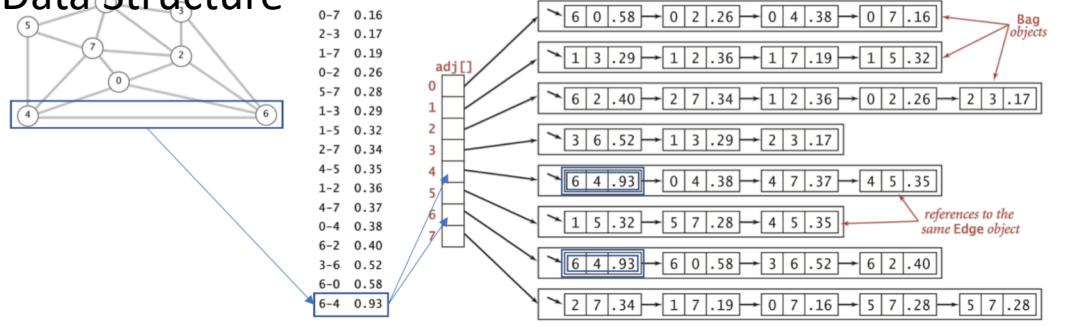
Shortest Paths

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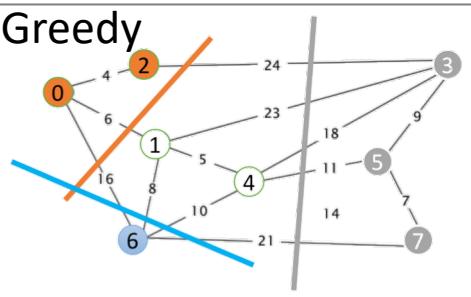
MST Complexity; "All" Algorithms.

Algorithm	Space	Time
Lazy Prim	E	E Log E
Eager Prim	V	E Log V
Kruskal	F	E Log F

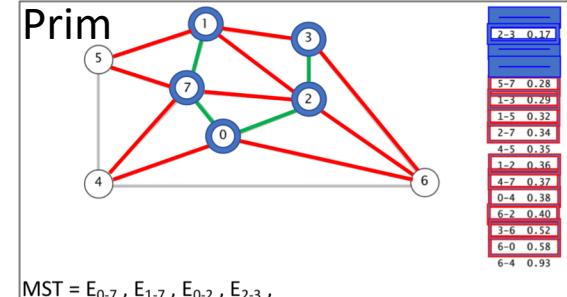
Data Structure



Greedy



Prim



Quiz – Chapter 4: 'Graphs'

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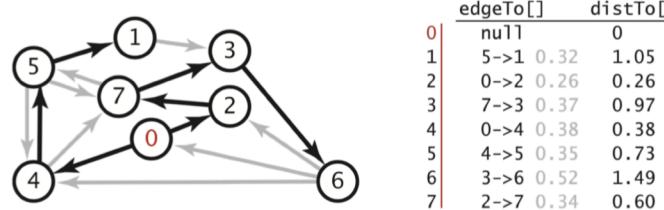
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Shortest Paths

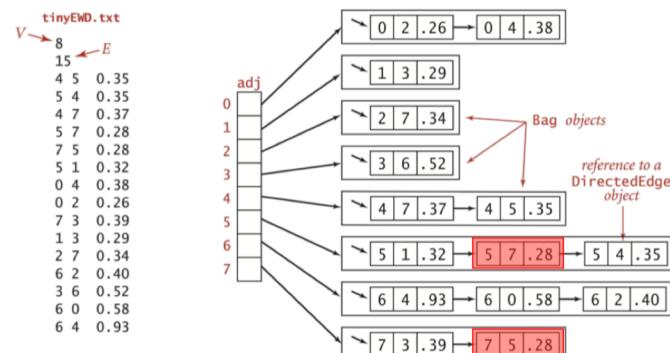
- Dijkstra's Algorithm
- A* Algorithm

Shortest Path Tree

- Shortest Paths Tree, from computing all single-source paths from 's'.
- Represented by two arrays, `edgeTo[]` and `distTo[]`.



What Data Structure for Dijkstra et al.?



Precedence Constrained Scheduling

... and topological sort: the Kosaraju-Sharir algorithm

Topological Sort

- Theorem:

"A reverse DFS postorder on a DAG is a topological order"

POSTPONED

Topological Sort on DAGs

General problem of solving order of precedence for any system.

Must have a Directed Acyclic Graph (DAG), otherwise there is ambivalence.

Redraw all edges so they point in same direction.

Theorem: a reverse DFS postorder stack of a DAG is a topological order.

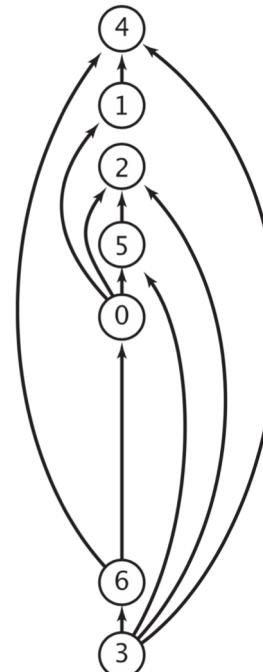
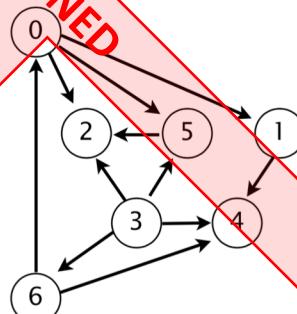
EXERCISE

- show by demo'ing.....on the white board.
- does the order of visits matter?

Example of use of Top.Sort. on DAGs is order of precedence scheduling.

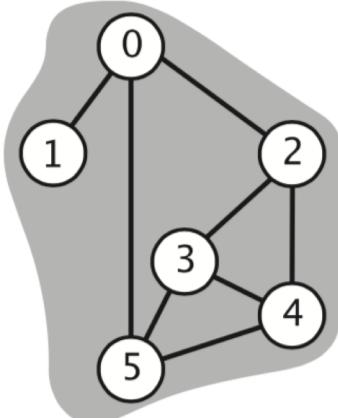
0. Algorithms
1. Complexity Theory
2. Artificial Intelligence
3. Intro to CS
4. Cryptography
5. Scientific Computing
6. Advanced Programming

POSTPONED



Strong connectivity in digraphs

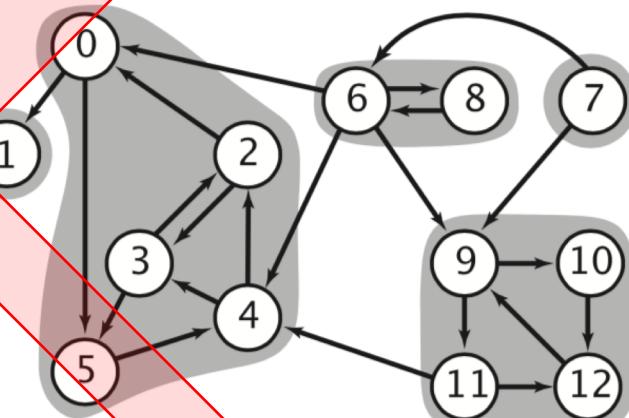
Un-directed graphs



3 connected components

Digraphs

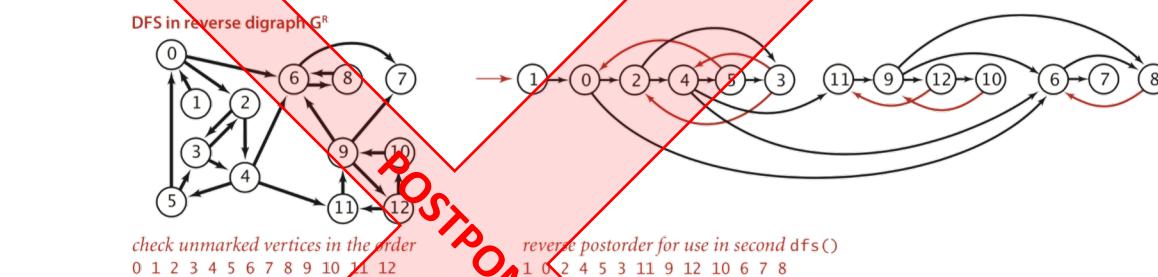
POSTPONED



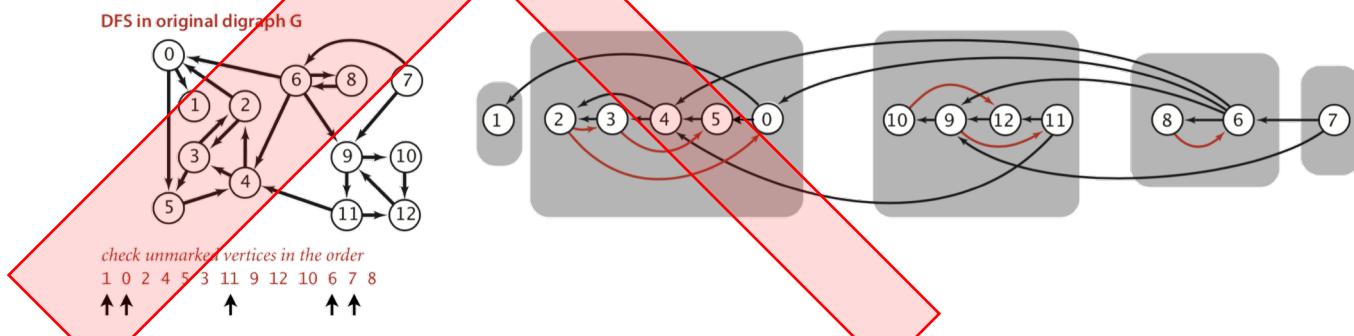
5 strongly-connected components

Kosaraju-Sharir algorithm: compute strong components using twice DFS.

Step 1



Step 2





Acknowledgement

- Some material has been taken from the Princeton course 'Algorithms 4th Edition', by Sedgewick & Wayne.