# Python Documentation

## version

June 12, 2020

# Contents

# Welcome to moseq2-pca's documentation!

## moseq2_pca package

### *CLI Module*

#### *moseq2-pca*

```
moseq2-pca [OPTIONS] COMMAND [ARGS]...
```

#### *apply-pca*

Computes PCA Scores of extraction data given a pre-trained PCA

```
moseq2-pca apply-pca [OPTIONS]
```

Options

**-i, --input-dir** <input_dir>
Directory to find h5 files [default: /Users/aymanzeine/Desktop/moseq/moseq2-pca/docs]

**--cluster-type** <cluster_type>
Cluster type [default: local]

**Options:** local|slurm|nodask

**-o, --output-dir** <output_dir>
Directory to store results [default: /Users/aymanzeine/Desktop/moseq/moseq2-pca/docs/_pca]

**--output-file** <output_file>
Name of h5 file for storing pca results [default: pca_scores]

**--h5-path** <h5_path>
Path to data in h5 files [default: /frames]

**--h5-mask-path** <h5_mask_path>
Path to log-likelihood mask in h5 files [default: /frames_mask]

**--pca-path** <pca_path>
Path to pca components [default: /components]

**--pca-file** <pca_file>
Path to PCA results

**--chunk-size** <chunk_size>
Number of frames per chunk [default: 4000]

**--fill-gaps** <fill_gaps>
Fill dropped frames with nans [default: True]

**--fps** <fps>
Fps (only used if no timestamps found) [default: 30]

**--detrend-window** <detrend_window>
Length of detrend window (in seconds, 0 for no detrending) [default: 0]

**--config-file** <config_file>
Path to configuration file

**-d, --dask-cache-path** <dask_cache_path>
Path to spill data to disk for dask local scheduler [default: /Users/aymanzeine/moseq2_pca]

**-q, --queue** <queue>
Cluster queue/partition for submitting jobs [default: debug]

**-n, --nworkers** <nworkers>

Number of workers [default: 10]

**-c, --cores** <cores>
Number of cores per worker [default: 1]

**-p, --processes** <processes>
Number of processes to run on each worker [default: 1]

**-m, --memory** <memory>
RAM usage per workers [default: 15GB]

**-w, --wall-time** <wall_time>
Wall time for workers [default: 06:00:00]

**--timeout** <timeout>
Time to wait for workers to initialize before proceeding (minutes) [default: 5]

### *clip-scores*

Clips speficied number of frames from PCA scores at the beginning or end

```
moseq2-pca clip-scores [OPTIONS] PCA_FILE CLIP_SAMPLES
```

Options

**--from-end**
[default: False]

Arguments

**PCA_FILE**
Required argument

**CLIP_SAMPLES**
Required argument

### *compute-changepoints*

Computes the Model-Free Syllable Changepoints based on the PCA/PCA_Scores

```
moseq2-pca compute-changepoints [OPTIONS]
```

Options

**-i, --input-dir** <input_dir>
Directory to find h5 files [default: /Users/aymanzeine/Desktop/moseq/moseq2-pca/docs]

**-o, --output-dir** <output_dir>
Directory to store results [default: /Users/aymanzeine/Desktop/moseq/moseq2-pca/docs/_pca/]

**--output-file** <output_file>
Name of h5 file for storing pca results [default: changepoints]

**--cluster-type** <cluster_type>
Cluster type [default: local]

**Options:** local|slurm

**--pca-file-components** <pca_file_components>
Path to PCA components

**--pca-file-scores** <pca_file_scores>
Path to PCA results

**--pca-path** <pca_path>
Path to pca components [default: /components]

**--neighbors** <neighbors>
Neighbors to use for peak identification [default: 1]

**--threshold** <threshold>

Peak threshold to use for changepoints [default: 0.5]

**-k, --klags** <klags>
Lag to use for derivative calculation [default: 6]

**-s, --sigma** <sigma>
Standard deviation of gaussian smoothing filter [default: 3.5]

**-d, --dims** <dims>
Number of random projections to use [default: 300]

**--fps** <fps>
Fps (only used if no timestamps found) [default: 30]

**--h5-path** <h5_path>
Path to data in h5 files [default: /frames]

**--h5-mask-path** <h5_mask_path>
Path to log-likelihood mask in h5 files [default: /frames_mask]

**--chunk-size** <chunk_size>
Number of frames per chunk [default: 4000]

**--config-file** <config_file>
Path to configuration file

**--dask-cache-path** <dask_cache_path>
Path to spill data to disk for dask local scheduler [default: /Users/aymanzeine/moseq2_pca]

**--visualize-results** <visualize_results>
Visualize results [default: True]

**-q, --queue** <queue>
Cluster queue/partition for submitting jobs [default: debug]

**-n, --nworkers** <nworkers>
Number of workers [default: 10]

**-c, --cores** <cores>
Number of cores per worker [default: 1]

**-p, --processes** <processes>
Number of processes to run on each worker [default: 1]

**-m, --memory** <memory>
RAM usage per workers [default: 15GB]

**-w, --wall-time** <wall_time>
Wall time for workers [default: 06:00:00]

**--timeout** <timeout>
Time to wait for workers to initialize before proceeding (minutes) [default: 5]

### *train-pca*

Trains PCA on all extracted results (h5 files) in input directory

```
moseq2-pca train-pca [OPTIONS]
```

Options

**-i, --input-dir** <input_dir>
Directory to find h5 files [default: /Users/aymanzeine/Desktop/moseq/moseq2-pca/docs]

**--cluster-type** <cluster_type>
Cluster type [default: local]

**Options:** local|slurm

**-o, --output-dir** <output_dir>
Directory to store results [default: /Users/aymanzeine/Desktop/moseq/moseq2-pca/docs/_pca]

**--h5-path** <h5_path>
Path to data in h5 files [default: /frames]

**--h5-mask-path** <h5_mask_path>
Path to log-likelihood mask in h5 files [default: /frames_mask]

**--gaussfilter-space** <gaussfilter_space>
Spatial filter for data (Gaussian) [default: 1.5, 1]

**--gaussfilter-time** <gaussfilter_time>
Temporal filter for data (Gaussian) [default: 0]

**--medfilter-space** <medfilter_space>
Median spatial filter [default: 0]

**--medfilter-time** <medfilter_time>
Median temporal filter [default: 0]

**--missing-data**
Use missing data PCA [default: False]

**--missing-data-iters** <missing_data_iters>
Missing data PCA iterations [default: 10]

**--mask-threshold** <mask_threshold>
Threshold for mask (missing data only) [default: -16]

**--mask-height-threshold** <mask_height_threshold>
Threshold for mask based on floor height [default: 5]

**--min-height** <min_height>
Min mouse height from floor (mm) [default: 10]

**--max-height** <max_height>
Max mouse height from floor (mm) [default: 100]

**--tailfilter-size** <tailfilter_size>
Tail filter size [default: 9, 9]

**--tailfilter-shape** <tailfilter_shape>
Tail filter shape [default: ellipse]

**--use-fft**
Use 2D fft [default: False]

**--recon-pcs** <recon_pcs>
Number of PCs to use for missing data reconstruction [default: 10]

**--rank** <rank>
Rank for compressed SVD (generally>>nPCS) [default: 50]

**--output-file** <output_file>
Name of h5 file for storing pca results [default: pca]

**--chunk-size** <chunk_size>
Number of frames per chunk [default: 4000]

**--visualize-results** <visualize_results>
Visualize results [default: True]

**--config-file** <config_file>
Path to configuration file

**-d, --dask-cache-path** <dask_cache_path>
Path to spill data to disk for dask local scheduler [default: /Users/aymanzeine/moseq2_pca]

**--local-processes** <local_processes>
Use processes with local scheduler [default: True]

**-q, --queue** <queue>
Cluster queue/partition for submitting jobs [default: debug]

**-n, --nworkers** <nworkers>

Number of workers [default: 10]

**-c, --cores** <cores>
Number of cores per worker [default: 1]

**-p, --processes** <processes>
Number of processes to run on each worker [default: 1]

**-m, --memory** <memory>
Total RAM usage per worker [default: 15GB]

**-w, --wall-time** <wall_time>
Wall time for workers [default: 06:00:00]

**--timeout** <timeout>
Time to wait for workers to initialize before proceeding (minutes) [default: 5]

### *version*

Print version number

```
moseq2-pca version [OPTIONS]
```

## *GUI Module*

moseq2_pca.gui.**apply_pca_command** (input_dir, index_file, config_file, output_dir, output_file, output_directory=None)
Compute PCA Scores given trained PCA using Jupyter Notebook.

**Parameters:**
- **input_dir (str)** (*path to directory containing training data*)
- **index_file (str)** (*path to index file.*)
- **config_file (str)** (*path to config file*)
- **output_dir (str)** (*path to output pca directory*)
- **output_file (str)** (*name of output pca file.*)
- **output_directory (str)** (*alternative output directory path*)

**Returns:** **(str)**

**Return type:** success string.

moseq2_pca.gui.**compute_changepoints_command** (input_dir, config_file, output_dir, output_file, output_directory=None)
Compute Changepoint distribution using Jupyter Notebook.

**Parameters:**
- **input_dir (str)** (*path to directory containing training data*)
- **config_file (str)** (*path to config file*)
- **output_dir (str)** (*path to output pca directory*)
- **output_file (str)** (*name of output pca file.*)
- **output_directory (str)** (*alternative output directory path*)

**Returns:** **(str)**

**Return type:** success string.

moseq2_pca.gui.**train_pca_command** (input_dir, config_file, output_dir, output_file, output_directory=None)
Train PCA through Jupyter notebook, and updates config file.

**Parameters:**
- **input_dir (str)** (*path to directory containing training data*)
- **config_file (str)** (*path to config file*)
- **output_dir (str)** (*path to output pca directory*)
- **output_file (str)** (*name of output pca file.*)
- **output_directory (str)** (*alternative output directory path*)

**Returns:**

**Return type:** None

## Utilities Module

`moseq2_pca.util.`**`clean_frames`** (frames, medfilter_space=None, gaussfilter_space=None, medfilter_time=None, gaussfilter_time=None, detrend_time=None, tailfilter=None, tail_threshold=5)

Filters spatial/temporal noise from frames using Median and Gaussian filters, given kernel sizes for each respective requested filter.

**Parameters:**
- **frames (3D numpy array)** (*frames to filter.*)
- **medfilter_space (list)** (*median spatial filter kernel.*)
- **gaussfilter_space (list)** (*gaussian spatial filter kernel.*)
- **medfilter_time (list)** (*median temporal filter.*)
- **gaussfilter_time (list)** (*gaussian temporal filter.*)
- **detrend_time (int)** (*number of frames to lag for.*)
- **tailfilter (int)** (*size of tail-filter kernel.*)
- **tail_threshold (int)** (*threshold value to use for tail filtering*)

**Returns:** **out (3D numpy array)**

**Return type:** filtered frames.

`moseq2_pca.util.`**`command_with_config`** (config_file_param_name)

`moseq2_pca.util.`**`gauss_smooth`** (signal, win_length=None, sig=1.5, kernel=None)

Perform Gaussian Smoothing on a 1D signal.

**Parameters:**
- **signal (1d numpy array)** (*signal to perform smoothing*)
- **win_length (int)** (*window_size for gaussian kernel filter*)
- **sig (float)** (*variance of 1d gaussian kernel.*)
- **kernel (tuple)** (*kernel size to use for smoothing*)

**Returns:** **result (1d numpy array)**

**Return type:** smoothed signal

`moseq2_pca.util.`**`gaussian_kernel1d`** (n=None, sig=3)

Get 1D gaussian kernel.

**Parameters:**
- **n (int)** (*number of points to use.*)
- **sig (int)** (*variance of kernel to use.*)

**Returns:** **kernel (1d array)**

**Return type:** 1D numpy kernel.

`moseq2_pca.util.`**`get_changepoints`** (scores, k=5, sigma=3, peak_height=0.5, peak_neighbors=1, baseline=True, timestamps=None)

Compute changepoints distribution and CP Curve.

**Parameters:**
- **scores (3D numpy array)** (*nframes * r * c*)
- **k (int)** (*klags - Lag to use for derivative calculation.*)
- **sigma (int)** (*Standard deviation of gaussian smoothing filter.*)
- **peak_height (float)** (*user-defined peak Changepoint length.*)
- **peak_neighbors (int)** (*number of peaks in the CP curve.*)
- **baseline (bool)** (*normalize data.*)
- **timestamps (array)** (*loaded timestamps.*)

**Returns:** **cps (2D numpy array)** (*array of values for CP curve*) **normed_df (1D numpy array)** (*array of values for bar plot*)

moseq2_pca.util.**get_metadata_path** (h5file)
Return path within h5 file that contains the kinect extraction metadata.

**Parameters:** **h5file (str)** (*path to h5 file.*)
**Returns:** **(str)**
**Return type:** path to acquistion metadata within h5 file.

moseq2_pca.util.**get_rps** (frames, rps=600, normalize=True)
Get random projections of frames.

**Parameters:**
- **frames (2D or 3D numpy array)** (*Frames to get dimensions from.*)
- **rps (int)** (*Number of random projections.*)
- **normalize (bool)** (*indicates whether to normalize frames.*)

**Returns:** **rproj (2D or 3D numpy array)**
**Return type:** Computed random projections with same shape as frames

moseq2_pca.util.**get_timestamp_path** (h5file)
Return path within h5 file that contains the kinect timestamps

**Parameters:** **h5file (str)** (*path to h5 file.*)
**Returns:** **(str)**
**Return type:** path to metadata timestamps within h5 file

moseq2_pca.util.**initialize_dask** (nworkers=50, processes=1, memory='4GB', cores=1, wall_time='01:00:00', queue='debug', local_processes=False, cluster_type='local', scheduler='distributed', timeout=10, cache_path='/Users/aymanzeine/moseq2_pca', **kwargs)
Initialize dask client, cluster, workers, etc.

**Parameters:**
- **nworkers (int)** (*number of dask workers to initialize*)
- **processes (int)** (*number of processes per worker*)
- **memory (str)** (*amount of memory to allocate to dask cluster*)
- **cores (int)** (*number of cores to use.*)
- **wall_time (str)** (*amount of time to allow program to run*)
- **queue (str)** (*logging mode*)
- **local_processes (bool)** (*indicate whether the processes are local*)
- **cluster_type (str)** (*indicate what cluster to use*)
- **scheduler (str)** (*indicate what scheduler to use*)
- **timeout (int)** (*number of worker timeouts to allow*)
- **cache_path (str or Pathlike)** (*path to store cached data*)
- **kwargs** (*extra keyward arguments*)

**Returns:** **client (dask Client)** (*initialized Client*) **cluster (dask Cluster)** (*initialized Cluster*) **workers (dask Workers)** (*intialized workers or None if cluster_type = 'local'*) **cache (dask Chest)** (*initialized Chest (cache) object pointing to given cache path*)

`moseq2_pca.util.`**`insert_nans`** (timestamps, data, fps=30)
Fills NaN values with 0 in timestamps.

**Parameters:**
- **timestamps (1D array)** (*timestamp time-strs*)
- **data (1D array)** (*timestamp values*)
- **fps (int)** (*frames per second*)

**Returns:** **filled_data (1D array)** (*filled missing timestamp values.*) **data_idx (1D array)** (*indices of inserted 0s*) **filled_timestamps (1D array)** (*filled timestamp-strs*)

`moseq2_pca.util.`**`read_yaml`** (yaml_file)
Reads yaml file and returns dictionary representation of file contents.

**Parameters:** **yaml_file (str)** (*path to yaml file*)
**Returns:** **return_dict (dict)**
**Return type:** dict of yaml file contents

`moseq2_pca.util.`**`recursive_find_h5s`** (root_dir='/Users/aymanzeine/Desktop/moseq/moseq2-pca/docs', ext='.h5', yaml_string='{}.yaml')
Recursively find h5 files, along with yaml files with the same basename

**Parameters:**
- **root_dir (str or os.Pathlike)** (*path to directory to start recursive search*)
- **ext (str)** (*extension to search for, e.g. .h5*)
- **yaml_string (str)** (*a format to use to name yaml files*)

**Returns:** **h5s (list)** (*list of h5 file paths*) **dicts (list)** (*list of dicts containing metadata file contents*) **yamls (list)** (*list of yaml file paths*)

`moseq2_pca.util.`**`recursively_load_dict_contents_from_group`** (h5file, path)
Reads all contents from h5 and returns them in a nested dict object.

**Parameters:**
- **h5file (str)** (*path to h5 file*)
- **path (str)** (*path to group within h5 file*)

**Returns:** **ans (dict)**
**Return type:** dictionary of all h5 group contents

`moseq2_pca.util.`**`select_strel`** (string='e', size=10, 10)
Selects Structuring Element Shape

**Parameters:**
- **string (str)** (*e for Ellipse, r for Rectangle*)
- **size (tuple)** (*size of StructuringElement*)

**Returns:** **strel (cv2.StructuringElement)**
**Return type:** returned StructuringElement with specified size.

`moseq2_pca.util.`**`shutdown_dask`** (scheduler, workers=None)
Graceful shutdown dask scheduler. source: https://github.com/dask/distributed/issues/1703#issuecomment-361291492

**Parameters:** **scheduler (dask Scheduler)** (*scheduler to shutdown.*)
**Returns:**
**Return type:** None

## *Visualization Module*

`moseq2_pca.viz.`**`changepoint_dist`** (cps, headless=False)

Creates bar plot describing computed Changepoint Distribution.

**Parameters:**
- **cps (np.ndarray)** (*changepoints to graph*)
- **headless (bool)** (*trim first element in PC list*)

**Returns:** **plt (plt.figure)** (*figure to save/graph*) **ax (plt.ax)** (*figure axis variable*)

`moseq2_pca.viz.`**`display_components`** (components, cmap='gray', headless=False)

Creates grid of computed Principal Components.

**Parameters:**
- **components (2D np.ndarray)** (*components to graph*)
- **cmap (str)** (*color map to use*)
- **headless (bool)** (*trim first element in PC list*)

**Returns:** **plt (plt.figure)** (*figure to save/graph*) **ax (plt.ax)** (*figure axis variable*)

`moseq2_pca.viz.`**`scree_plot`** (explained_variance_ratio, headless=False)

Creates Scree plot describing principal components.

**Parameters:**
- **explained_variance_ratio (1D np.array)** (*explained variance ratio of each principal component*)
- **headless (bool)** (*trim first element in PC list*)

**Returns:** **plt (plt.figure)**

**Return type:** figure to save/graph

## Subpackages

### moseq2_pca.helpers package

#### Helpers - Data Module

`moseq2_pca.helpers.data.`**`get_pca_yaml_data`** (pca_yaml)

Reads PCA yaml file and returns metadata

**Parameters:** **pca_yaml (str)** (*path to pca.yaml*)

**Returns:** **use_fft (bool)** (*indicates whether to use FFT*) **clean_params (dict)** (*dict of image filtering parameters*) **mask_params (dict)** (*dict of mask parameters)*) **missing_data (bool)** (*indicates whether to use mask_params*)

`moseq2_pca.helpers.data.`**`load_pcs_for_cp`** (pca_file_components, config_data)

Load computed Principal Components for Model-free Changepoint Analysis.

**Parameters:**
- **pca_file_components (str)** (*path to pca h5 file to read PCs*)
- **config_data (dict)** (*config parameters*)

**Returns:** **pca_components (str)** (*path to pca components*) **changepoint_params (dict)** (*dict of relevant changepoint parameters*) **cluster (dask Cluster)** (*Dask Cluster object.*) **client (dask Client)** (*Dask Client Object*) **workers (dask Workers)** (*intialized workers or None if cluster_type = 'local'*) **cache (dask Chest)** (*initialized Chest (cache) object pointing to given cache path*) **missing_data (bool)** (*Indicates whether to use mask_params*) **mask_params (dict)** (*Mask parameters to use when computing CPs*)

`moseq2_pca.helpers.data.`**`setup_cp_command`** (input_dir, config_data, output_dir, output_file, output_directory=None)

Helper function for changepoints_wrapper to perform data-path existence checks.

**Parameters:**
- **input_dir (int)** (*path to directory containing all h5+yaml files*)
- **config_data (dict)** (*dict of relevant PCA parameters (image filtering etc.)*)
- **output_dir (str)** (*path to directory to store PCA data*)
- **output_file (str)** (*pca model filename*)
- **output_directory (str)** (*alternative output_dir*)

**Returns:** **config_data (dict)** (*updated config_data dict with the proper paths*) **pca_file_components (str)** (*path to trained pca file*) **pca_file_scores (str)** (*path to pca_scores file*) **h5s (list)** (*list of relevant pca h5 files*) **yamls (list)** (*list of relevant pca metadata yaml files*) **save_file (str)** (*path to save changepoints*)

### *Helpers - Wrapper Module*

`moseq2_pca.helpers.wrappers.`**`apply_pca_wrapper`** (input_dir, config_data, output_dir, output_file, output_directory=None, gui=False)

Wrapper function to obtain PCA Scores.

**Parameters:**
- **input_dir (int)** (*path to directory containing all h5+yaml files*)
- **config_data (dict)** (*dict of relevant PCA parameters (image filtering etc.)*)
- **output_dir (str)** (*path to directory to store PCA data*)
- **output_file (str)** (*pca model filename*)
- **output_directory (str)** (*alternative output_dir*)
- **gui (bool)** (*indicate GUI is running*)

**Returns:** **config_data (dict)**

**Return type:** updated config_data variable to write back in GUI API

`moseq2_pca.helpers.wrappers.`**`compute_changepoints_wrapper`** (input_dir, config_data, output_dir, output_file, gui=False, output_directory=None)

Wrapper function to compute model-free (PCA based) Changepoints.

**Parameters:**
- **input_dir (int)** (*path to directory containing all h5+yaml files*)
- **config_data (dict)** (*dict of relevant PCA parameters (image filtering etc.)*)
- **output_dir (str)** (*path to directory to store PCA data*)
- **output_file (str)** (*pca model filename*)
- **output_directory (str)** (*alternative output_dir*)
- **gui (bool)** (*indicate GUI is running*)

**Returns:** **config_data (dict)**

**Return type:** updated config_data variable to write back in GUI API

`moseq2_pca.helpers.wrappers.`**`train_pca_wrapper`** (input_dir, config_data, output_dir, output_file, output_directory=None, gui=False)

Wrapper function to train PCA.

**Parameters:**
- **input_dir (int)** (*path to directory containing all h5+yaml files*)
- **config_data (dict)** (*dict of relevant PCA parameters (image filtering etc.)*)
- **output_dir (str)** (*path to directory to store PCA data*)
- **output_file (str)** (*pca model filename*)
- **output_directory (str)** (*alternative output_dir*)
- **gui (bool)** (*indicate GUI is running*)

**Returns:** **config_data (dict)**

**Return type:** updated config_data variable to write back in GUI API

## *moseq2_pca.pca package*

### *PCA - Utilties Module*

`moseq2_pca.pca.util.`**`apply_pca_dask`** (pca_components, h5s, yamls, use_fft, clean_params, save_file, chunk_size, mask_params, missing_data, client, fps=30, h5_path='/frames', h5_mask_path='/frames_mask')

"Apply" trained PCA on input frame data to obtain PCA Scores using Distributed Dask cluster.

**Parameters:**

- **pca_components (np.array)** (*array of computed Principal Components*)
- **h5s (list)** (*list of h5 files*)
- **yamls (list)** (*list of yaml files*)
- **use_fft (bool)** (*indicate whether to use 2D-FFT*)
- **clean_params (dict)** (*dictionary containing filtering options*)
- **save_file (str)** (*path to pca_scores filename to save*)
- **chunk_size (int)** (*size of chunks to process*)
- **mask_params (dict)** (*dictionary of masking parameters (if missing data)*)
- **missing_data (bool)** (*indicates whether to use mask arrays.*)
- **fps (int)** (*frames per second*)
- **h5_path (str)** (*path to frames within selected h5 file (default: '/frames')*)
- **h5_mask_path (str)** (*path to masked frames within selected h5 file (default: '/frames_mask')*)

**Returns:**

**Return type:** None

`moseq2_pca.pca.util.`**`apply_pca_local`** (pca_components, h5s, yamls, use_fft, clean_params, save_file, chunk_size, mask_params, missing_data, fps=30, h5_path='/frames', h5_mask_path='/frames_mask')

"Apply" trained PCA on input frame data to obtain PCA Scores using local cluster/platform.

**Parameters:**

- **pca_components (np.array)** (*array of computed Principal Components*)
- **h5s (list)** (*list of h5 files*)
- **yamls (list)** (*list of yaml files*)
- **use_fft (bool)** (*indicate whether to use 2D-FFT*)
- **clean_params (dict)** (*dictionary containing filtering options*)
- **save_file (str)** (*path to pca_scores filename to save*)
- **chunk_size (int)** (*size of chunks to process*)
- **mask_params (dict)** (*dictionary of masking parameters (if missing data)*)
- **missing_data (bool)** (*indicates whether to use mask arrays.*)
- **fps (int)** (*frames per second*)
- **h5_path (str)** (*path to frames within selected h5 file (default: '/frames')*)
- **h5_mask_path (str)** (*path to masked frames within selected h5 file (default: '/frames_mask')*)

**Returns:**

**Return type:** None

`moseq2_pca.pca.util.`**`compute_explained_variance`** (s, nsamples, total_var)

Computes the explained variance and explained variance ratio contributed by each computed Principal Component.

**Parameters:**
- **s (1d array)** (*computed singular values.*)
- **nsamples (int)** (*number of included samples.*)
- **total_var (float)** (*total variance captured by principal components.*)

**Returns:** **explained_variance (1d-array)** (*list of floats denoting the explained variance per PC.*) **explained_variance_ratio (1d-array)** (*list of floats denoting the explained variance ratios per PC.*)

`moseq2_pca.pca.util.`**`compute_svd`** (dask_array, mean, rank, iters, missing_data, mask, recon_pcs, min_height, max_height, client, gui=False)

Runs Singular Vector Decomposition on the inputted frames of shape (nframes, nfeatures). Data is centered by subtracting it by the mean value of the data. If missing_data == True, It will iteratively recompute the svd on the mean-centered data to reconstruct the PCs from the missing data until it converges.

**Parameters:**
- **dask_array (dask 2d-array)** (*Reshaped input data array of shape (nframes x nfeatures)*)
- **mean (1d array)** (*Means of each row in dask_array.*)
- **rank (int)** (*Rank of the desired thin SVD decomposition.*)
- **iters (int)** (*Number of SVD iterations*)
- **missing_data (bool)** (*Indicates whether to compute SVD with a masked array*)
- **mask (dask 2d-array)** (*None if missing_data == False, else mask array of shape dask_array*)
- **recon_pcs (int)** (*Number of PCs to reconstruct for missing data.*)
- **min_height (int)** (*Minimum height of mouse above the ground, used to filter reconstructed PCs.*)
- **max_height (int)** (*Maximum height of mouse above the ground, used to filter reconstructed PCs.*)
- **client (dask Client)** (*Dask client to process batches.*)
- **gui (bool)** (*Indicates to dask to show a progress bar in Jupyter*)

**Returns:** **s (1d array)** (*computed singular values (eigen-values).*) **v (2d array)** (*computed principal components (eigen-vectors).*) **mean (1d array)** (*updated mean of dask array if missing_data == True.*) **total_var (float)** (*total variance captured by principal components.*)

`moseq2_pca.pca.util.`**`copy_metadatas_to_scores`** (f, f_scores, uuid)

Copies metadata from individual session extract h5 files to the PCA scores h5 file.

**Parameters:**
- **f (read-open h5py File)** (*open "results_00.h5" h5py.File object in read-mode*)
- **f_scores (read-open h5py File)** (*open "pca_scores.h5" h5py.File object in read-mode*)
- **uuid (str)** (*uuid of inputted session h5 "f".*)

**Returns:**

**Return type:** None

`moseq2_pca.pca.util.`**`get_changepoints_dask`** (changepoint_params, pca_components, h5s, yamls, save_file, chunk_size, mask_params, missing_data, client, fps=30, pca_scores=None, progress_bar=False, h5_path='/frames', h5_mask_path='/frames_mask')

Computes model-free changepoints using PCs and PC Scores on distributed dask cluster.

**Parameters:**
- **changepoint_params (dict)** (*dict of changepoint parameters*)
- **pca_components (np.array)** (*computed principal components*)
- **h5s (list)** (*list of h5 files*)
- **yamls (list)** (*list of yaml files*)
- **save_file (str)** (*path to save changepoint files*)
- **chunk_size (int)** (*size of chunks to process in dask.*)
- **mask_params (dict)** (*dict of missing_data mask parameters.*)
- **missing_data (bool)** (*indicate whether to use mask_params*)
- **client (dask Client)** (*initialized Dask Client object*)
- **fps (int)** (*frames per second*)
- **pca_scores (np.array)** (*computed principal component scores*)
- **progress_bar (bool)** (*display progress bar*)
- **h5_path (str)** (*path to frames within selected h5 file (default: '/frames')*)
- **h5_mask_path (str)** (*path to masked frames within selected h5 file (default: '/frames_mask')*)

**Returns:**

**Return type:** None

`moseq2_pca.pca.util.`**`get_timestamps`** (f, frames, fps=30)

Reads the timestamps from a given h5 file.

**Parameters:**
- **f (read-open h5py File)** (*open "results_00.h5" h5py.File object in read-mode*)
- **frames (3d-array)** (*list of 2d frames contained in opened h5 File.*)
- **fps (int)** (*frames per second.*)

**Returns:** **timestamps (1d array)**

**Return type:** array of timestamps for inputted frames variable

`moseq2_pca.pca.util.`**`mask_data`** (original_data, mask, new_data)

Create a mask subregion given a boolean mask if missing data flag is used.

**Parameters:**
- **original_data (3d np.ndarray)** (*input frames*)
- **mask (3d boolean np.ndarray)** (*mask array*)
- **new_data (3d np.ndarray)** (*frames to use*)

**Returns:** **output (3d np.ndarray)**

**Return type:** masked data array

`moseq2_pca.pca.util.`**`train_pca_dask`** (dask_array, clean_params, use_fft, rank, cluster_type, client, workers, cache, mask=None, iters=10, recon_pcs=10, min_height=10, max_height=100, gui=False)

Train PCA using dask arrays.

**Parameters:**

- **dask_array (dask array)** (*chunked frames to train PCA*)
- **clean_params (dict)** (*dictionary containing filtering parameters*)
- **use_fft (bool)** (*indicates whether to use 2d-FFT on images.*)
- **rank (int)** (*Matrix rank to use*)
- **cluster_type (str)** (*indicates which cluster to use.*)
- **client (Dask.Client)** (*client object to execute dask operations*)
- **workers (int)** (*number of dask workers*)
- **cache (str)** (*path to cache directory*)
- **mask (dask array)** (*dask array of masked data if missing_data parameter==True*)
- **iters (int)** (*number of SVD iterations*)
- **recon_pcs (int)** (*number of PCs to reconstruct. (if missing_data = True)*)
- **min_height (int)** (*minimum mouse height from floor in (mm)*)
- **max_height (int)** (*maximum mouse height from floor in (mm)*)
- **gui (bool)** (*Indicates to dask to show a progress bar in Jupyter*)

**Returns:** **output_dict (dict)**

**Return type:** dictionary containing PCA training results.

# Indices and tables

- **genindex**
- **modindex**
- **search**

# Index

## *Symbols*

--output-dir <output_dir> moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

--output-file <output_file> moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

--pca-file <pca_file> moseq2-pca-apply-pca command line option

le-components <pca_file_components> moseq2-pca-compute-changepoints command line option

a-file-scores <pca_file_scores> moseq2-pca-compute-changepoints command line option

--pca-path <pca_path> moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

--processes <processes> moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

--queue <queue> moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

--rank <rank> moseq2-pca-train-pca command line option

--recon-pcs <recon_pcs> moseq2-pca-train-pca command line option

--sigma <sigma> moseq2-pca-compute-changepoints command line option

--tailfilter-shape <tailfilter_shape> moseq2-pca-train-pca command line option

--tailfilter-size <tailfilter_size> moseq2-pca-train-pca command line option

--threshold <threshold> moseq2-pca-compute-changepoints command line option

--timeout <timeout> moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

--use-fft moseq2-pca-train-pca command line option

--visualize-results <visualize_results> moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

--wall-time <wall_time> moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

-c moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

-d moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

-i moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

-k moseq2-pca-compute-changepoints command line option

-m moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

-n moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

-o moseq2-pca-apply-pca command line option

moseq2-pca-compute-changepoints command line option

moseq2-pca-train-pca command line option

## A



## C



## D



## G



## I



## L



## M

--pca-file <pca_file>
--pca-path <pca_path>
--processes <processes>
--queue <queue>
--timeout <timeout>
--wall-time <wall_time>
-c
-d
-i
-m
-n
-o
-p
-q
-w

**moseq2-pca-clip-scores command line option**

--from-end
CLIP_SAMPLES
PCA_FILE

**moseq2-pca-compute-changepoints command line option**

--chunk-size <chunk_size>
--cluster-type <cluster_type>
--config-file <config_file>
--cores <cores>
--dask-cache-path <dask_cache_path>
--dims <dims>
--fps <fps>
--h5-mask-path <h5_mask_path>
--h5-path <h5_path>
--input-dir <input_dir>
--klags <klags>
--memory <memory>
--neighbors <neighbors>
--nworkers <nworkers>
--output-dir <output_dir>
--output-file <output_file>
--pca-file-components <pca_file_components>
--pca-file-scores <pca_file_scores>
--pca-path <pca_path>
--processes <processes>
--queue <queue>
--sigma <sigma>
--threshold <threshold>
--timeout <timeout>
--visualize-results <visualize_results>
--wall-time <wall_time>
-c
-d
-i
-k
-m
-n
-o
-p
-q
-s
-w

**moseq2-pca-train-pca command line option**

--chunk-size <chunk_size>
--cluster-type <cluster_type>
--config-file <config_file>
--cores <cores>
--dask-cache-path <dask_cache_path>
--gaussfilter-space <gaussfilter_space>
--gaussfilter-time <gaussfilter_time>
--h5-mask-path <h5_mask_path>
--h5-path <h5_path>
--input-dir <input_dir>
--local-processes <local_processes>
--mask-height-threshold <mask_height_threshold>
--mask-threshold <mask_threshold>
--max-height <max_height>
--medfilter-space <medfilter_space>
--medfilter-time <medfilter_time>
--memory <memory>
--min-height <min_height>
--missing-data
--missing-data-iters <missing_data_iters>
--nworkers <nworkers>
--output-dir <output_dir>
--output-file <output_file>
--processes <processes>
--queue <queue>
--rank <rank>

## *P*



## *R*



## *S*



## *T*

# Python Module Index

## *m*