All the following is subject to $w, s \ge 0$:

$$\mathcal{L} = \min_{\boldsymbol{w}, s} ||M\boldsymbol{w}||^{2} + \mu||\mathbf{1} - A\boldsymbol{w} - s||^{2}$$

$$= \min_{\boldsymbol{w}, s} \boldsymbol{w}^{T} M^{T} M \boldsymbol{w} + \mu \left((\mathbf{1}^{T} - \boldsymbol{w}^{T} A^{T} - s^{T})(\mathbf{1} - A\boldsymbol{w} - s) \right)$$

$$= \min_{\boldsymbol{w}, s} \boldsymbol{w}^{T} M^{T} M \boldsymbol{w} + \mu \left(\mathbf{1}^{T} \mathbf{1} - \mathbf{1}^{T} A \boldsymbol{w} - \mathbf{1}^{T} s - \boldsymbol{w}^{T} A^{T} \mathbf{1} + \boldsymbol{w}^{T} A^{T} A \boldsymbol{w} + \boldsymbol{w}^{T} A^{T} s - s^{T} \mathbf{1} + s^{T} A \boldsymbol{w} + s^{T} s \right)$$

$$= \min_{\boldsymbol{w}, s} \boldsymbol{w}^{T} (M^{T} M + \mu A^{T} A) \boldsymbol{w} + \mu s^{T} I^{T} I s + \mu \left(1 - 2 \mathbf{1}^{T} A \boldsymbol{w} - 2 \mathbf{1}^{T} s + 2 \boldsymbol{w}^{T} A^{T} s \right)$$

$$= \min_{\boldsymbol{w}, s} \boldsymbol{y}^{T} \left(\underbrace{M^{T} M + \mu A^{T} A \quad \mu A^{T}}_{L^{T}} \right) \boldsymbol{y} - 2 \left(\underbrace{\mu \mathbf{1}^{T} A}_{\mu \mathbf{1}^{T}} \right) \boldsymbol{y} + \underbrace{\mu \mathbf{1}^{T} \mathbf{1}}_{d^{T} d}$$

$$= \min_{\boldsymbol{y}} \boldsymbol{y}^{T} H \boldsymbol{y} + \boldsymbol{f} \boldsymbol{y}$$

where \boldsymbol{y} is the m+n vector $\begin{pmatrix} \boldsymbol{w} \\ \boldsymbol{s} \end{pmatrix} \geq 0$. Yet it still does not look like:

$$\min_{\boldsymbol{y}} ||C\boldsymbol{y} - \boldsymbol{d}||^2 = \min_{\boldsymbol{y}} \boldsymbol{y}^T C^T C \boldsymbol{y} - 2 \boldsymbol{d}^T C \boldsymbol{y} + \boldsymbol{d}^T \boldsymbol{d}$$

because of M.

Listing 1: Solving minimization problem with the subset method

```
function [w, Aw, L] = compute_graph(X, kind, mu)
[n, d] = size(X);
m = nchoosek(n, 2);
M = sparse(d*n, m);
U = sparse(n, m);
w = [];
MAX_ITER = 50;
nb_iter = 0;
bin_lower = n*(0:n-1) - cumsum(0:n-1);
considered_last_time = [];
% At the end, we cannot have more than \frac{d+1}{n} edges according to
% Theorem 3.1. But we must start with only a small subset of them. So we first
% select randomly 7% of them (for no specific reason but cinematographic
% one). Actually, it may be more sensitive to use some kind of heuristic like
% nearest neighbors at this stage to be more efficient later.
edges = randi(m, 1, floor(0.33*(d+1)*n));
while (numel(edges) > 0 && nb_iter < MAX_ITER)</pre>
  % Then we update the corresponding element (i,j)=e of U with
  % respectively 1 and -1.
  vertex_i = arrayfun(@(x) find(x' <= bin_lower, 1, 'first'), edges) - 1;</pre>
```

```
vertex_j = vertex_i + edges - bin_lower(vertex_i);
positive = bsxfun (@(x,y) sub2ind(size(U), x, y), vertex_i, edges);
negative = bsxfun (@(x,y) sub2ind(size(U), x, y), vertex_j, edges);
U(positive) = 1;
U(negative) = -1;
A = abs(U);
assert(sum(A(:))/2 <= (d+1)*n, 'there are too many edges');
T = U'*X; % y^{(k)} = U^T x^k is thus the kth column of T
% TODO: use parfor
for k=1:d
  first_row = 1 + (k-1)*n;
  last_row = n + (k-1)*n;
  Yk = spdiags(T(:,k), [0], m, m);
  M(first_row:last_row, :) = U*Yk;
end
% Now that we have built our matrices, we can solve the minimization problem
% TODO use SDPT3, although the documentation is quite intimidating:
% http://www.math.nus.edu.sg/ mattohkc/sdpt3/guide4-0-draft.pdf
% It would be especially usefull as MATLAB seems to convert M'*M to
\% a full matrice, which takes around 2n^4 bytes of memory (so 8GB for
n = 250.
if strcmpi(kind, 'hard')
  % we only want to constrain the nodes that have edges to be of
  % degree at least 1.
  o = optimoptions(@quadprog, 'Algorithm', 'active-set', 'Display', 'final-detailed
      <sup>'</sup>);
  [w, f, flag, output, lambda] = quadprog(M'*M, sparse(m, 1), -A, -(sum(A, 2)>0),
      [], [], [], w, o);
  z = lambda.ineqlin;
  derivative = 2*M'*M*w - A'*z;
  save('out', 'M', 'w', 'A', 'lambda', 'derivative');
else
  % According to the paper, we want to solve
  \min_{w,s} ||Mw||^2 + \mu ||\mathbf{1} - Aw - s||
  % subject to w,s\geq 0, but I don't see how to formulate that for
  % quadprog or lsqnonneg (see http://math.stackexchange.com/q/545280)
  error(strcat(kind, ' is not yet implemented'));
end
[val, may_be_added] = sort (derivative (find (derivative <0)));</pre>
if ((length(may_be_added) == 0) || (length(may_be_added) == length(
   considered_last_time) && all(may_be_added' == considered_last_time)))
  break:
end
% The paper says: we add to our quadratic program the edges with the smallest
% \frac{d\Lambda}{dw_{i,i}} values, which I think mean not all. For now,
% let's take half of them. TODO take only the one below average or look at
% diff.
```

```
edges = may_be_added(1:max(1, floor(end/2)));
  considered_last_time = may_be_added;
  nb_iter = nb_iter + 1;
end
Aw = A*w;
W = spdiags (w, [0], m, m);
L = U*W*U';
end
                                   Listing 2: Computing hard graph
function [w, Aw, L] = compute_hard_graph(X)
  [w, Aw, L] = compute_graph(X, 'hard');
end
                                  Listing 3: Computing \alpha-soft graph
function [w, Aw, L] = compute_alpha_graph(X, alpha, tol)
[n, d] = size(X);
m = nchoosek(n, 2);
mu = 5*rand();
tau0 = 1.5;
MAX_ITER = 50;
% Set \lambda so that 	au \geq 1 with equality at MAX_ITER.
lambda = (tau0 - 1)/MAX_ITER;
can_improve = true;
while (can_improve)
  w, Aw, L = compute_graph(X, 'soft', mu);
  tmp = \max(zeros(m, 1), ones(m, 1) - A*w);
  alpha_bar = tmp'*tmp/n;
  % Maybe we don't need this complication and keep a fixed \tau=	au_0.
  tau = tau0/(1 + nb_iter*lambda);
  if (alpha_bar < alpha)</pre>
    % We want to increase \bar{\alpha} so we need decrease \mu\text{,} which in
    % turn require \tau \leq 1
    tau = 1/tau;
  % It is supposed to correspond to: "we then adjust \mu up or down
  % proportionally to how far rac{\eta(w)}{n}=ar{lpha} is from the
  \% desired value of \alpha."
  mu = tau*abs(alpha_bar - alpha)/alpha
  nb_iter = nb_iter + 1;
  can_improve = abs(alpha_bar - alpha) < tol && nb_iter < MAX_ITER;</pre>
end
end
                            Listing 4: Use the built graph to classify samples
function result = graph_classify(labelled, label, unlabelled)
n = numel(label);
```

```
u = size(unlabelled, 1);
X = [labelled; unlabelled];
[w, Aw, L] = compute_hard_graph(X);
beq = [label; zeros(u, 1)];
Aeq = [eye(n) zeros(n, u); zeros(u, n+u)];
% TODO look at the fast method suggested in the paper: Spielman, D. A.,
% Teng, S.-H. (2004). Nearly-linear time algorithms for graph partitioning,
% graph sparsification, and solving linear systems. Proc. 36th ACM STOC.
x = quadprog(L, [], [], Aeq, beq);
result = x(n+1:end) > 0.5;
end
```