Algorithm 1 Soft Actor-Critic Initialize parameter vectors ψ , $\bar{\psi}$, θ , ϕ .

for each iteration do for each environment step do

end for end for

$$\mathbf{a}_{t} \sim \pi_{\phi}(\mathbf{a}_{t}|\mathbf{s}_{t})$$

$$\mathbf{s}_{t+1} \sim p(\mathbf{s}_{t+1}|\mathbf{s}_{t}, \mathbf{a}_{t})$$

$$\mathcal{D} \leftarrow \mathcal{D} \cup \{(\mathbf{s}_{t}, \mathbf{a}_{t}, r(\mathbf{s}_{t}, \mathbf{a}_{t}), \mathbf{s}_{t+1})\}$$

end for for each gradient step do

$$\psi \leftarrow \psi - \lambda_V \hat{\nabla}_{\psi} J_V(\psi)
\theta_i \leftarrow \theta_i - \lambda_Q \hat{\nabla}_{\theta_i} J_Q(\theta_i)
\phi \leftarrow \phi - \lambda_{\pi} \hat{\nabla}_{\phi} J_{\pi}(\underline{\phi})$$

$$\psi \leftarrow \psi - \lambda_V \nabla_{\psi} J_V(\psi)
\theta_i \leftarrow \theta_i - \lambda_Q \hat{\nabla}_{\theta_i} J_Q(\theta_i) \text{ for } i \in \{1, 2\}
\phi \leftarrow \phi - \lambda_\pi \hat{\nabla}_{\phi} J_\pi(\phi)
\bar{\psi} \leftarrow \tau \psi + (1 - \tau) \bar{\psi}$$