

Best-First Search and Algorithm A* Revisited (More Informed)

Note Title

Recall: "Algorithm A"
is actually a class of heuristics for Best-First-Search.

Best-First Search is the GraphSearch algorithm, using a heuristic, $f(n)$ to order the nodes on the OPEN list.

Using Algorithm A means using a heuristic of the form

$$f(n) = \text{depth}(n) + \underline{h(n)}$$

↑
estimate of distance
from n to goal —

$f(n)$ is an estimate of the total distance (i.e., "path length") from start to goal if you go through node n .

Algorithm A^* is Algorithm A,

using a heuristic $h(n)$ that is guaranteed not to over-estimate the distance from n to goal.

Use of Algorithm A^* is guaranteed to find a shortest-path solution.

More informed heuristics for Algorithm A^* :

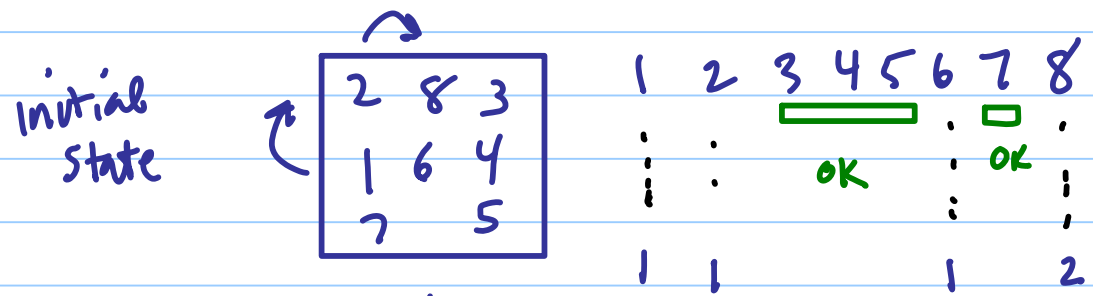
if $h_1(n)$ and $h_2(n)$ are both A^* heuristics ("admissible" heuristics)

then if $h_2(n) \geq h_1(n)$ for all n

$h_2(n)$ is more informed than $h_1(n)$

and $h_2(n)$ will result in no more total node expansions than $h_1(n)$.

New heuristic for 8-puzzle: $h_2(\text{node}) =$ Total # of spaces removed from the goal for each tile out of place



We can see $h_2(\text{state}) \geq h_1(\text{state})$

$h_2(\text{state}) \leq h^*(\text{state})$

actual #
of moves
needed.

$h_2(\text{state}) = 1 + 1 + 1 + 2 = 5$

$h_1(\text{state}) = 4$ (# tiles out of place)

So let's re-evaluate with $h_2(\text{node})$ also.

$\text{depth} = 0$
 $h = 4$
 $f = 4$

2	8	3
1	6	7
7		5

A
 $h_2 = 5$
 $f_2 = 5$

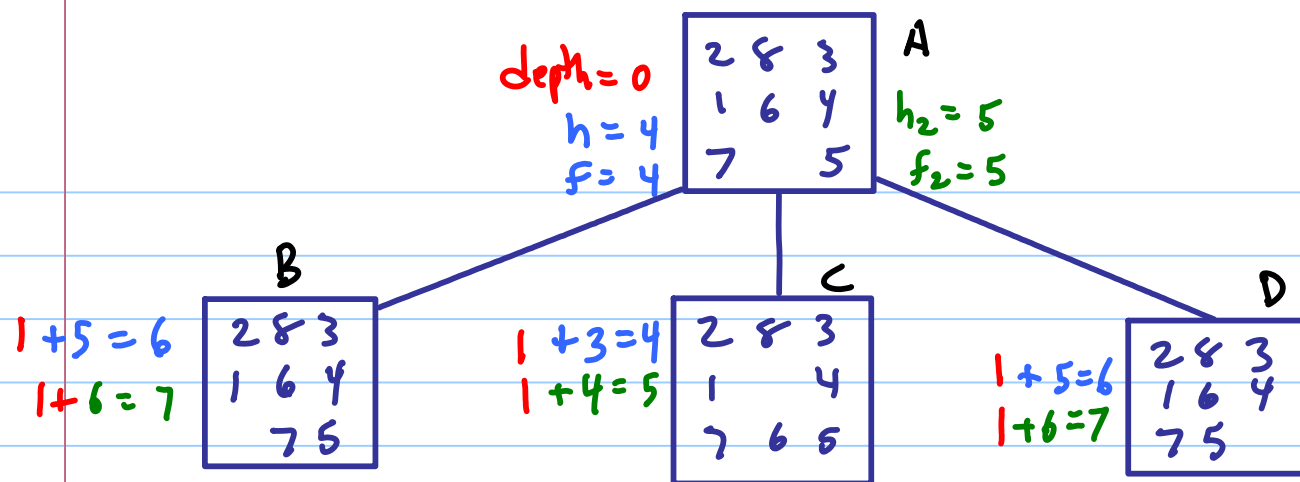
OPEN	A
CLOSED	

$h_2(n)$ = total distance between
 tiles out of place and
 the place they belong -

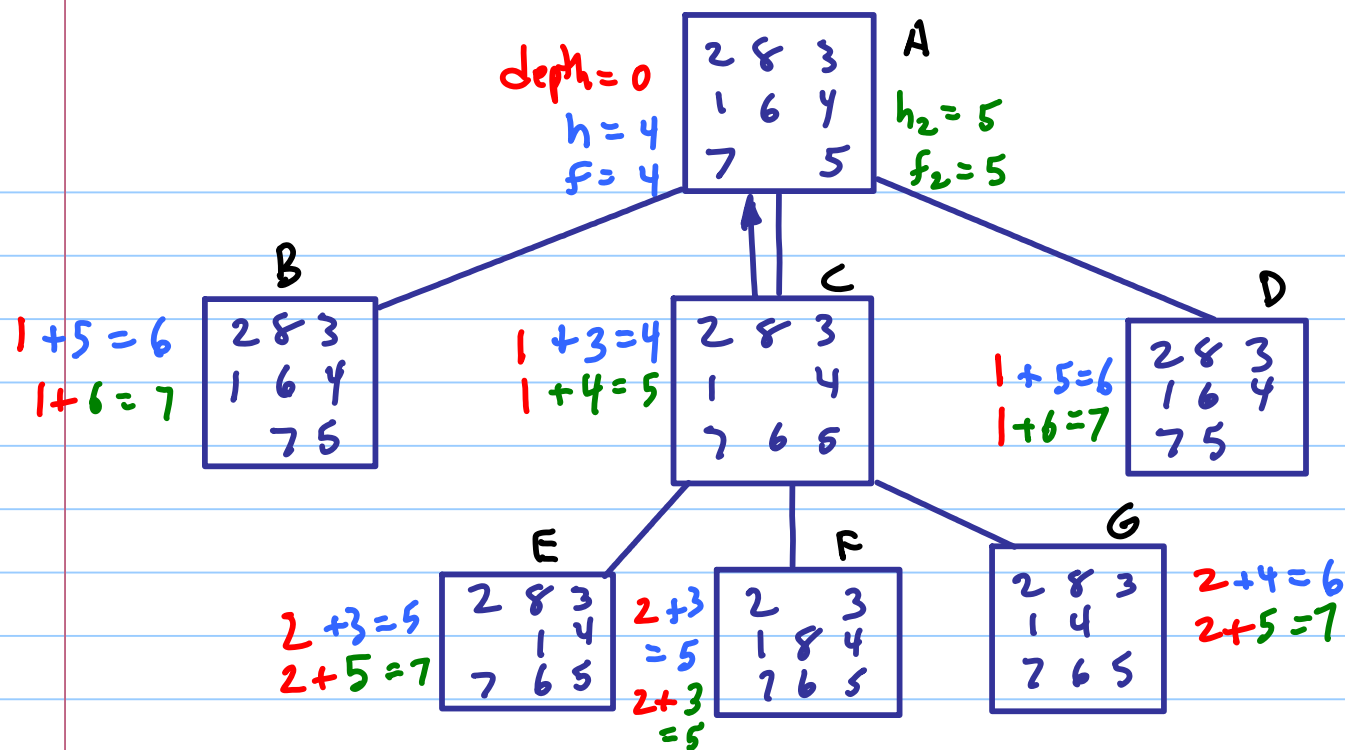
1	2	3	4	5	6	7	8
↓	↓	-	-	-	↓	-	↓
1	1				1		2

⇒ 5

This is admissible because
 each tile has to move
 at least that many
 times to reach goal state



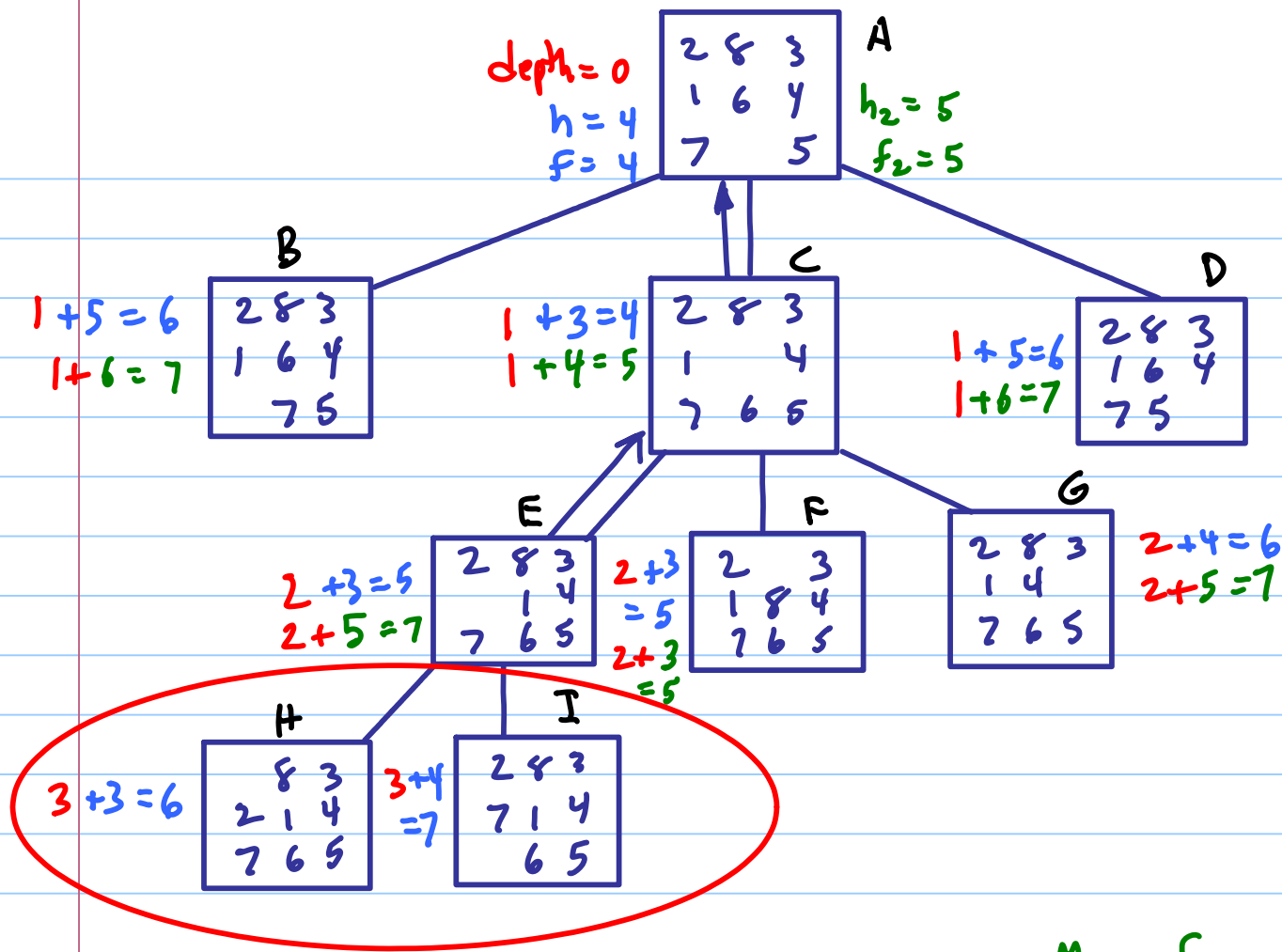
OPEN	A
CLOSED	
OPEN	C B D
CLOSED	A



OPEN	A
CLOSED	
OPEN	CBD
CLOSED	A
OPEN	E F C B D E
CLOSED	A C

Since E has a higher heuristic value with h_2 than it did with h_1 , it is placed farther back in the queue, rather than the beginning.

More informed heuristic moves **E** to end.

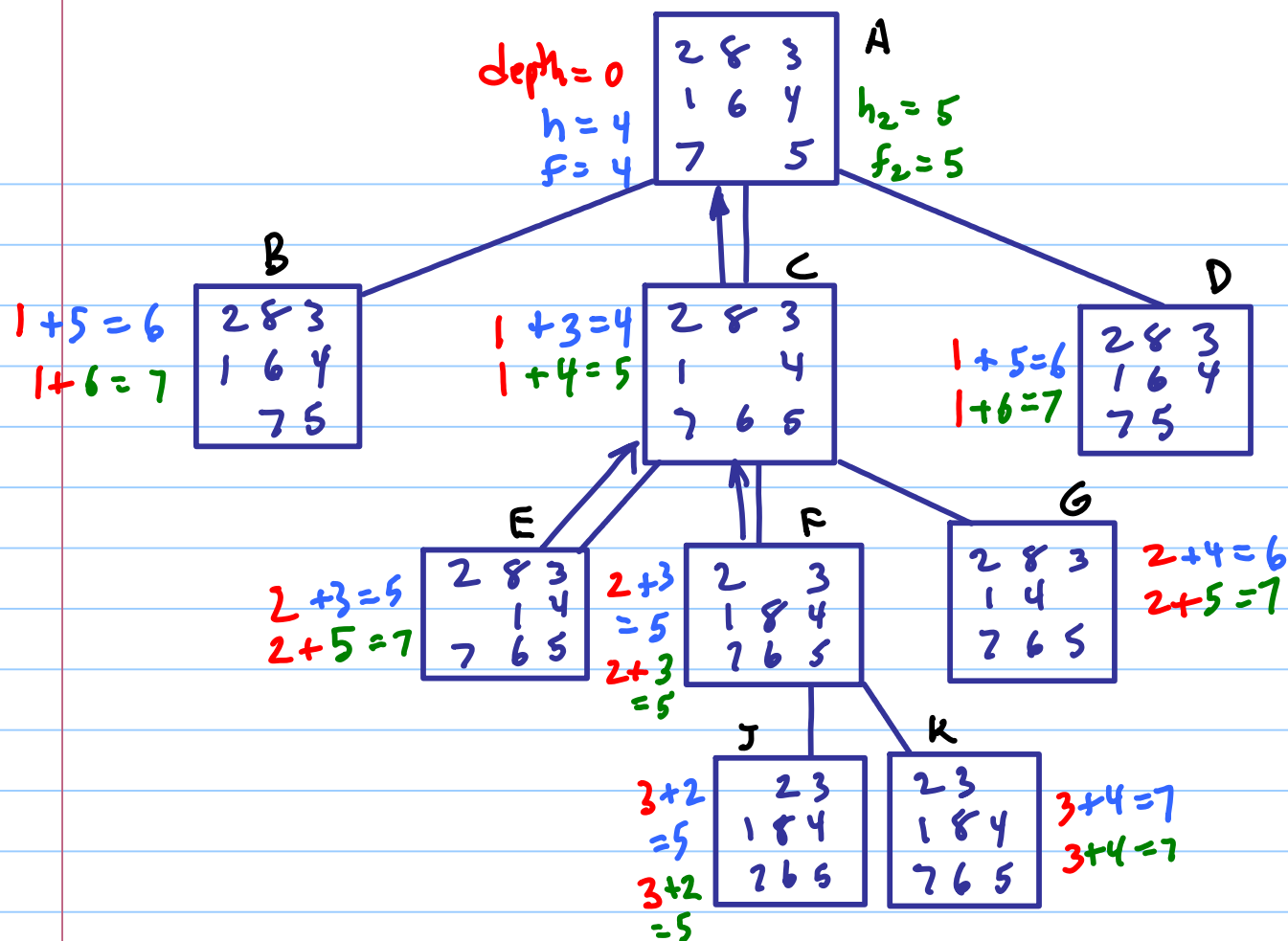


OPEN	A
CLOSED	
OPEN	CBD
CLOSED	A
OPEN	E F C B D E
CLOSED	AC
OPEN	F G B D E H I
CLOSED	AC

H and I are not placed in the queue, since E hasn't been expanded.

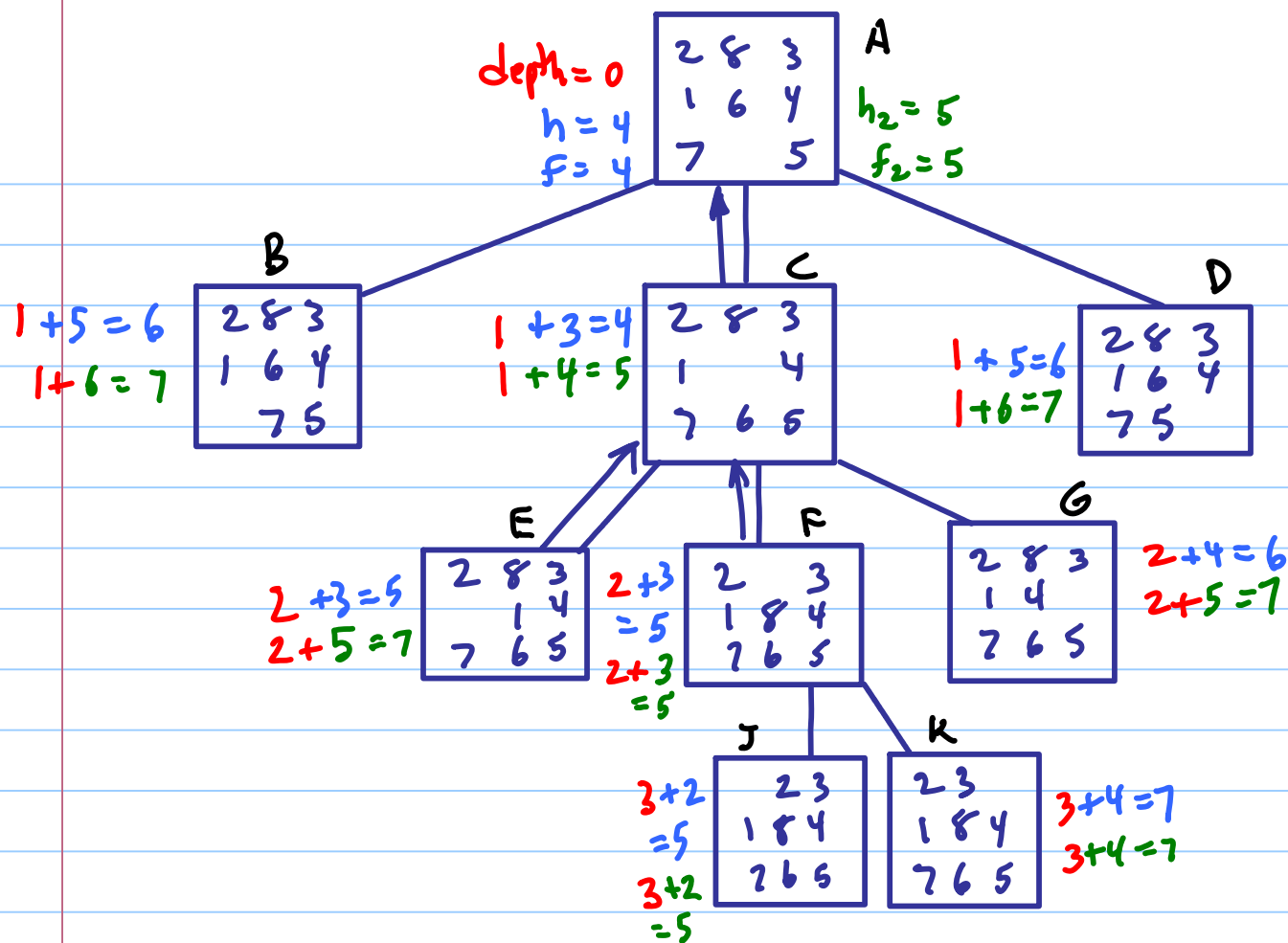
These nodes are not expanded when using $h_2(\text{node})$

More informed heuristic moves E to end.
 HI nodes are never generated.



OPEN	A
CLOSED	
OPEN	CBD
CLOSED	A
OPEN	EFGBDE
CLOSED	AC
OPEN	FGBDEHI
CLOSED	AC
OPEN	JGBDEHIK
CLOSED	ACF

More informed heuristic moves E to end.
HI nodes are never generated.



OPEN	A
CLOSED	
OPEN	CBD
CLOSED	A
OPEN	E F G B D E
CLOSED	A C
OPEN	F G B D E H I
CLOSED	A C
OPEN	J G B D E H I K
CLOSED	A C F

...
↑
Continue to goal as before.

... etc.

More informed heuristic moves E to end.
H I nodes are never generated.

$h_2(n)$ is more informed than $h_1(n)$.

Since $h_2(n)$ and $h_1(n)$ are both admissible heuristics, each guarantees it will find a shortest-path solution to goal when used with Algorithm A and Best-First Search.

Since $h_2(n)$ is more informed than $h_1(n)$, $h_2(n)$ will use no more total node expansions than $h_1(n)$ to find a shortest-path solution.

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- Note: Can I trick Algorithm A* by using $h(n) = 0$ for all n ?

[clearly, $h(n)$ never exceeds actual distance from n to goal—
So I will find shortest path to goal, guaranteed!]

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$$\begin{aligned} \text{(so } f(n) &= \text{depth}(n) + 0 \text{)} \\ &= \text{depth}(n) \end{aligned}$$

This is breadth-first search!

(And of course, we will find shortest path to goal with breadth-first search)

Note that $h(n) = \# \text{ tiles out of place}$ is a more informed heuristic than $h(n) = 0$ —

$$\text{So } h_2(n) \geq h_1(n) \geq h(n)$$

breadth-first search
more informed search
even more informed search

Suppose $h_1(n) > h_2(n)$ sometimes

and $h_2(n) > h_1(n)$ sometimes

Where $h_1(n), h_2(n)$ are both admissible?

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Where $h_1(n), h_2(n)$ are both admissible?

Let $h_3(n) = \max \{ h_1(n), h_2(n) \}$

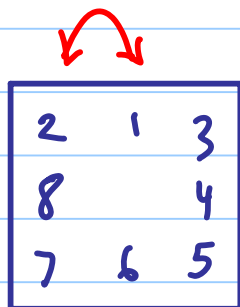
Note $h_3(n) \geq h_1(n)$

$h_3(n) \geq h_2(n)$

$h_3(n)$ is more informed
than either
heuristic

Even more informed?

We need to swap two adjacent tiles - can this be solved?



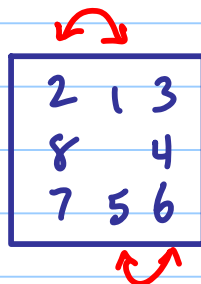
2	1	3
8		4
7	6	5

We need to swap two sets of adjacent tiles

$$h_1(n) = 4$$

$$h_2(n) = 4$$

$$h_4(n) = 8$$



2	1	3
8		4
7	5	6

$$h(n) = 0$$

$$h_1(n) = \# \text{ tiles out of place}$$

$$h_2(n) = \# \text{ of spaces the out-of-place tiles must move}$$

$$h_2(n) \geq h_1(n) \geq h(n)$$

$$\text{let } h_4(n) = h_2(n) + 2 * (\# \text{ of pairs of adjacent out-of-place tiles})$$

probably admissible

$$\text{definitely } h_4(n) \geq h_2(n)$$

Sample puzzle with 2 pairs of tiles
that need to be switched with
their immediate neighbors:

Winning moves for the game:
{2,1,3,8,0,4,7,5,6}

Move #1 : Blank Up
Move #2 : Blank Right
Move #3 : Blank Down
Move #4 : Blank Down
Move #5 : Blank Left
Move #6 : Blank Left
Move #7 : Blank Up
Move #8 : Blank Right
Move #9 : Blank Right
Move #10 : Blank Up
Move #11 : Blank Left
Move #12 : Blank Left
Move #13 : Blank Down
Move #14 : Blank Down
Move #15 : Blank Right
Move #16 : Blank Up

Solution from software provided
at
www.8puzzle.com

SOLUTION

=====INITIAL STATE

2 1 3
8 0 4
7 5 6

=====STEP 1

2 0 3
8 1 4
7 5 6

=====STEP 2

2 3 0
8 1 4
7 5 6

=====STEP 3

2 3 4
8 1 0
7 5 6

=====STEP 4

2 3 4
8 1 6
7 5 0

=====STEP 5

2 3 4
8 1 6
7 0 5

=====STEP 6

2 3 4
8 1 6
0 7 5

=====STEP 7

2 3 4
0 1 6
8 7 5

=====STEP 8

2 3 4
1 0 6
8 7 5

=====STEP 9

2 3 4
1 6 0
8 7 5

=====STEP 10

2 3 0
1 6 4
8 7 5

=====STEP 11

2 0 3
1 6 4
8 7 5

=====STEP 12

0 2 3
1 6 4
8 7 5

=====STEP 13

1 2 3
0 6 4
8 7 5

=====STEP 14

1 2 3
8 6 4
0 7 5

=====STEP 15

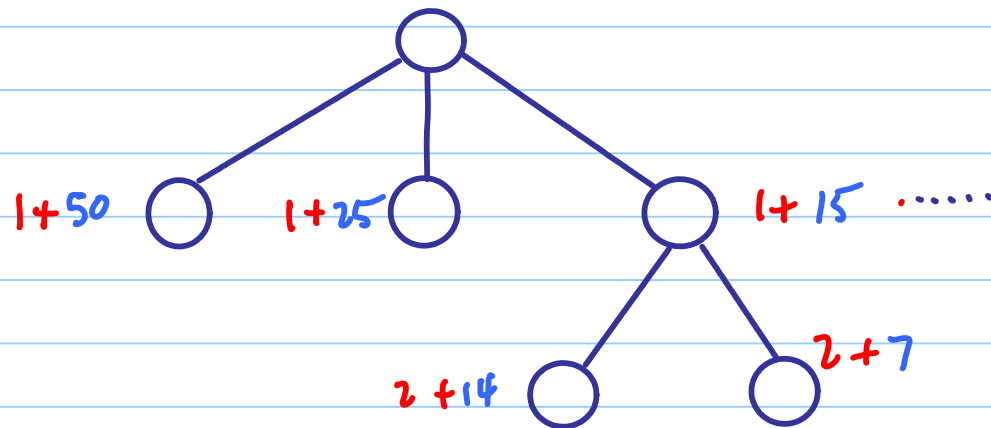
1 2 3
8 6 4
7 0 5

=====STEP 16

1 2 3
8 0 4
7 6 5

Algorithm A**

Example (Uniform Cost):



Since $h()$ is admissible, this node is at least 15 from goal

..... this node is at least 7 from Goal
[but we know it is further than that
because parent is at least 15 from goal]

Algorithm A** :

If Algorithm A^k uses heuristic

$$f(\text{node}) = \text{depth}(\text{node}) + h(\text{node})$$

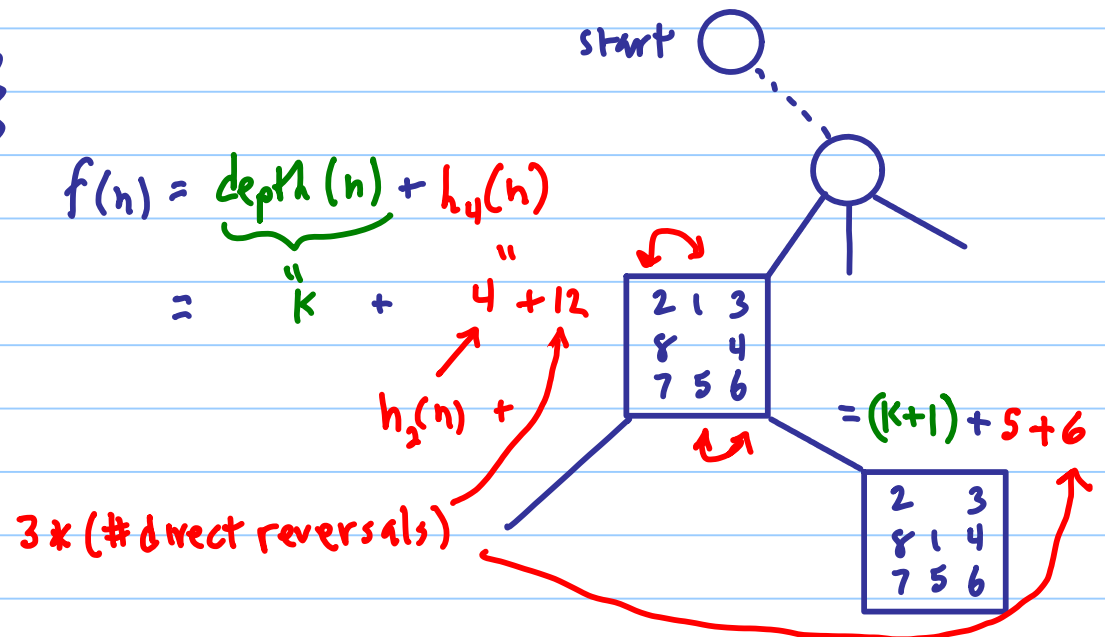
Then Algorithm A** uses the following heuristic :
 $\hat{f}(\text{node})$

Where $\hat{f}(\text{node}) = \max \{ f(n) \}$
 $n \in \text{path}$
 from start
 to node

$$f(n) = \underbrace{\text{depth}(n)}_k + h_4(n)$$

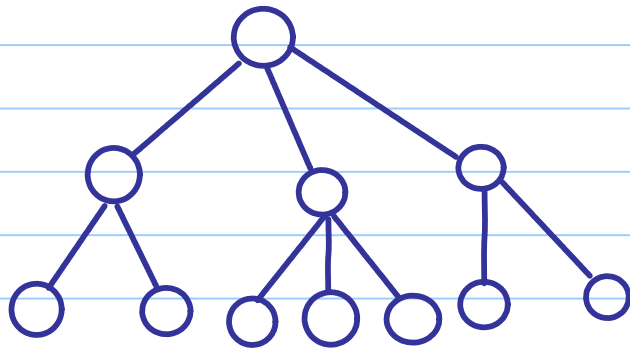
$$= k + 4 + 12$$

for example, in 8-puzzle
 example, a heuristic
 that adds a suitably
 large number when
 two adjacent tiles need
 to be switched



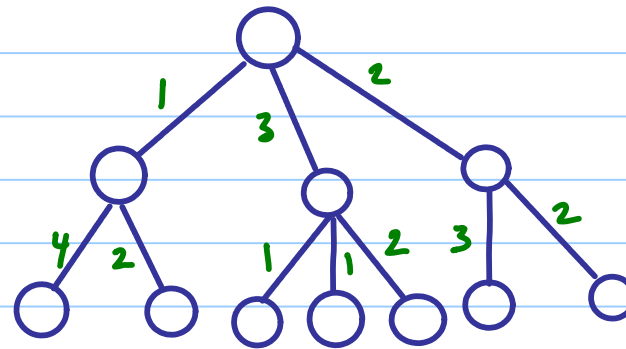
[Estimate at level k is higher
 than estimate at level $k+1$]

Uniform vs. non-uniform costs:



Uniform:

every edge has
the same value/weight
(=1)



non-uniform:

depth = sum of edge weights
along path.

total distance = sum of edge weights
from start → goal

Graph search for
non-uniform cost
case

=

Shortest path algorithms
for a graph



$h(n)$ = estimate of total distance
to goal (sum of edge weights)

$$f(n) = \text{depth}(n) + h(n)$$

use $f(n)$ to order OPEN from
least to most

$$\text{depth}(s) = \text{depth}(\text{parent}(s)) + \text{cost}(\text{edge}(\text{parent}(s), s))$$