

A Practical Introduction to the hpfracc library

High-Performance Fractional Calculus for Python

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Contents

Part I

Foundations

Chapter 1

Getting Started

1.1 Introduction

`hpfracc` is a high-performance framework for fractional calculus, designed to bridge the gap between rigorous mathematical modeling and scalable computational implementation. It supports a wide range of fractional operators (Caputo, Riemann-Liouville, Riesz, etc.) and integrates seamlessly with modern deep learning workflows.

1.2 Installation

To install `hpfracc`, use `pip`:

```
1 pip install hpfracc
```

Ensure you have the necessary backends installed (PyTorch, JAX, or Numba) depending on your performance requirements.

1.3 First Steps: Calculating a Derivative

The core of `hpfracc` is intuitive. Here is a simple example calculating the fractional derivative of $f(t) = t^2$.

```
1 import numpy as np
2 from hpfracc.core.derivatives import CaputoDerivative
3
4 # Define grid and function
5 t = np.linspace(0.01, 5, 100)
6 f = t**2
7
8 # Initialize operator with alpha=0.5
9 operator = CaputoDerivative(order=0.5)
10
11 # Compute
12 result = operator.compute(f, t)
```

1.4 Production Readiness

Version 3.2.0 introduces several production-ready features:

- ****Intelligent Backend Selection****: Automatically selects the fastest backend (Numba/NumPy for small arrays, JAX/Torch for large tensors).

- ****Standardized API****: Consistent ‘compute(function, points)’ interface across all operators.
- ****Validations****: rigorously validated against analytical solutions for standard functions.

Chapter 2

The Core API

2.1 Overview

The `hpfracc.core` module provides the fundamental building blocks for fractional calculus. It implements both derivatives and integrals using a factory pattern that ensures extensibility and consistency.

2.2 Supported Operators

2.2.1 Standard Derivatives

- **Riemann-Liouville**: The most fundamental definition, typically used for theoretical analysis.
- **Caputo**: The "physical" definition where initial conditions are standard integer derivatives.
- **Grunwald-Letnikov**: Discrete approximation suitable for numerical simulations.

2.2.2 Novel Derivatives

The library also supports modern definitions with non-singular kernels:

- **Caputo-Fabrizio**: Exponential kernel, useful for material science.
- **Atangana-Baleanu**: Mittag-Leffler kernel, capturing non-locality with memory fading.

2.3 Usage Example

```
1 from hpfracc.core.derivatives import create_fractional_derivative
2 import numpy as np
3
4 # Setup
5 x = np.linspace(0, 1, 100)
6 f = lambda x: x**3
7 alpha = 0.5
8
9 # 1. Riemann-Liouville
10 rl = create_fractional_derivative('riemann_liouville', alpha)
11 y_rl = rl.compute(f, x)
12
13 # 2. Caputo
14 caputo = create_fractional_derivative('caputo', alpha)
```

```
15 y_caputo = caputo.compute(f, x)
16
17 # 3. Grunwald-Letnikov
18 gl = create_fractional_derivative('grunwald_letnikov', alpha)
19 y_gl = gl.compute(f, x)
```

Listing 2.1: Comparing Operators

Each operator handles the boundary conditions and kernel singularities appropriately, ensuring numerical stability.

Chapter 3

Backend Intelligence

3.1 The Need for Hybrid Computation

Fractional calculus operations range from simple memory-efficient calculations (suitable for CPUs) to massive tensor convolutions (requiring GPUs). `hpfracc` solves this with an ****Intelligent Backend Selector****.

3.2 Architecture

The library abstracts the computation layer using a Strategy Pattern. The ‘BackendManager’ dynamically routes calls to:

- **NumPy**: For small arrays and scalar operations (lowest overhead).
- **Numba**: For JIT-compiled loops and iterative solvers.
- **JAX**: For automatic differentiation and TPU support.
- **PyTorch**: For deep learning integration and CUDA acceleration.

3.3 Automatic Selection

By default, `BackendType.AUTO` delegates the decision to the heuristic engine.

```
1 from hpfracc.ml.layers import LayerConfig, BackendManager
2 from hpfracc.ml.backends import BackendType
3
4 manager = BackendManager()
5 config = LayerConfig(backend=BackendType.AUTO)
6
7 # Case 1: Small Batch
8 # Heuristic: NumPy is faster due to zero kernel launch overhead
9 backend_small = manager.select_optimal_backend(config, (100, 10))
10 print(f"Backend for (100,10): {backend_small}") # Output: numpy
11
12 # Case 2: Large Batch
13 # Heuristic: GPU backends (Torch/JAX) dominate via parallelism
14 backend_large = manager.select_optimal_backend(config, (100000, 100))
15 print(f"Backend for (100k,100): {backend_large}") # Output: torch/jax
```

Listing 3.1: Intelligent Selection Demo

3.4 Manual Override

For research consistency, you can force a specific backend:

```
1 config_gpu = LayerConfig(backend=BackendType.TORCH)
```

Part II

Machine Learning with hpfracc

Chapter 4

Fractional Neural Networks

4.1 Introduction

The `hpfracc.ml` module provides a comprehensive suite of fractional deep learning components. These extend PyTorch's `nn.Module` enabling standard training workflows while incorporating fractional calculus dynamics.

4.2 Building Models

The high-level `FractionalNeuralNetwork` class builds a configurable MLP where activations or connections can have fractional properties.

```
1 from hpfracc.ml import FractionalNeuralNetwork, FractionalOrder
2
3 model = FractionalNeuralNetwork(
4     input_size=10,
5     hidden_sizes=[64, 32],
6     output_size=3,
7     fractional_order=FractionalOrder(0.5), # alpha=0.5
8     activation="relu"
9 )
```

4.3 Fractional Layers

For custom architectures, individual layers are available:

- `FractionalConv1D / Conv2D`: Convolutions with fractional padding/kernels.
- `FractionalLSTM`: Long Short-Term Memory with fractional derivatives in the state update, enhancing long-range dependency capture.
- `FractionalAttention`: Attention mechanisms weighted by fractional distances.

4.4 Training

Training behaves like standard PyTorch, but with customized optimizers and loss functions that respect fractional gradients.

```
1 from hpfracc.ml import FractionalMSELoss, FractionalAdam
2
3 # Loss and Optimizer
4 criterion = FractionalMSELoss(fractional_order=FractionalOrder(0.5))
```

```
5 optimizer = FractionalAdam(model.parameters(), lr=0.001, fractional_order=
    FractionalOrder(0.5))
6
7 # Loop
8 for epoch in range(epochs):
9     optimizer.zero_grad()
10    outputs = model(inputs)
11    loss = criterion(outputs, targets)
12    loss.backward()
13    optimizer.step()
```


Chapter 5

MLOps and Production

5.1 The Fractional MLOps Lifecycle

Deploying fractional models requires specialized management of metadata (e.g., fractional order α , solver methods). `hpfracc` includes a built-in MLOps system inspired by MLflow but tailored for scientific machine learning.

5.2 Key Components

- **ModelRegistry**: A local database tracking model versions, hyperparameters, and artifacts.
- **DevelopmentWorkflow**: Manages experiment tracking and initial model registration.
- **ProductionWorkflow**: Enforces quality gates before models can be promoted to 'Production' status.

5.3 Workflow Example

5.3.1 1. Registration (Development)

```
1 dev_workflow = DevelopmentWorkflow()
2 model_id = dev_workflow.register_development_model(
3     model=model,
4     name="alpha_forecaster",
5     version="0.1.0",
6     fractional_order=0.6,
7     hyperparameters={"hidden_size": 32}
8 )
```

5.3.2 2. Validation

Quality gates ensure robustness.

```
1 validation_results = dev_workflow.validate_development_model(
2     model_id=model_id,
3     test_data=val_data,
4     test_labels=val_labels
5 )
```

5.3.3 3. Promotion

If validation passes, promote to production.

```
1 prod_workflow = ProductionWorkflow(registry=dev_workflow.registry)
2 prod_workflow.promote_to_production(model_id=model_id, version="0.1.0")
```

This system ensures reproducibility in scientific experiments, where parameter precise tracking is critical.

Part III

Scientific Applications

Chapter 6

Anomalous Diffusion

6.1 Introduction

Anomalous diffusion is a transport process where the mean squared displacement (MSD) scales as a non-linear power of time: $\langle x^2(t) \rangle \propto t^\alpha$. This contrasts with normal (Fickian) diffusion where $\alpha = 1$.

6.2 Simulation with Fractional Brownian Motion

`hpfracc` provides tools to simulate Fractional Brownian Motion (fBm), a continuous Gaussian process with stationary increments that exhibits anomalous diffusion behavior.

```
1 import numpy as np
2
3 def generate_fbm(n_samples, hurst):
4     # Spectral synthesis method
5     beta = 2 * hurst + 1
6     freqs = np.fft.rfftfreq(n_samples * 2)
7     magnitude = np.zeros_like(freqs)
8     magnitude[1:] = freqs[1:] ** (-beta / 2.0)
9     phase = np.random.uniform(0, 2*np.pi, size=len(freqs))
10    fgn = np.fft.irfft(magnitude * np.exp(1j * phase))
11    return np.cumsum(fgn[:n_samples])
```

6.3 Analysis

By characterizing the Hurst exponent ($H = \alpha/2$), researchers can identify the nature of the diffusion:

- $H < 0.5$: Subdiffusion (antipersistent, $\alpha < 1$).
- $H = 0.5$: Normal diffusion ($\alpha = 1$).
- $H > 0.5$: Superdiffusion (persistent, $\alpha > 1$).

Chapter 7

Physiological Signal Analysis

7.1 Fractional Dynamics in Physiology

Physiological signals like EEG and HRV often exhibit long-range dependence and self-similarity, properties well-captured by fractional calculus.

7.2 Fractional State Space (FOSS)

Traditional state space reconstruction uses time delays $(x(t), x(t - \tau))$. The FOSS method replaces delays with fractional derivatives:

$$\mathbf{X}(t) = [x(t), D^\alpha x(t), D^{2\alpha} x(t), \dots] \quad (7.1)$$

This captures the "velocity" and "acceleration" of the system with memory, providing a richer phase space embedding.

7.3 Feature Extraction Code

```
1 from hpfracc.analytics import FractionalFeatures
2
3 def analyze_eeg(signal):
4     # Extract Hurst exponent
5     H = FractionalFeatures.hurst_exponent(signal)
6
7     # Extract Fractal Dimension
8     D = FractionalFeatures.fractal_dimension(signal)
9
10    return H, D
```

These features have been shown to improve classification accuracy in seizure detection tasks compared to standard spectral features.

Chapter 8

Advanced Solvers

8.1 Fractional Differential Equations

Solving standard FDEs requires specialized numerical methods. `hpfracc` implements spectral and finite difference solvers for the Fractional Laplacian: $(-\Delta)^{\alpha/2}u(x) = f(x)$.

8.2 The Fractional Laplacian

The fractional Laplacian is a non-local operator defined via the Fourier transform:

$$\mathcal{F}[(-\Delta)^s u](\xi) = |\xi|^{2s} \mathcal{F}[u](\xi) \quad (8.1)$$

8.3 Python Implementation

```
1 from hpfracc.algorithms.special_methods import FractionalLaplacian
2
3 # Initialize solver
4 solver = FractionalLaplacian(alpha=1.5)
5
6 # Compute on a grid
7 x = np.linspace(-5, 5, 200)
8 u = np.exp(-x**2) # Gaussian
9 Lu = solver.compute(u, x, method="spectral")
```

This spectral method (using FFT) is $O(N \log N)$ and highly accurate for smooth functions on periodic domains.

Part IV

Research and Performance

Chapter 9

Real-World Integration

9.1 Research Workflow

When applying fractional calculus to novel research, reproducibility and performance are paramount. `hpfracc` facilitates this via ‘GPUProfiler’ and ‘VarianceMonitor’.

9.2 Case Study: Viscoelastic Materials

Modeling stress relaxation in polymers often uses the fractional Kelvin-Voigt model:

$$\sigma(t) = E\varepsilon(t) + \eta D^\alpha \varepsilon(t) \quad (9.1)$$

```
1 from hpfracc.core.derivatives import CaputoDerivative
2
3 def stress_response(strain, t, E, eta, alpha):
4     # Elastic part
5     elastic = E * strain
6
7     # Viscous part (fractional derivative)
8     caputo = CaputoDerivative(order=alpha)
9     viscous = eta * caputo.compute(strain, t)
10
11     return elastic + viscous
```

9.3 GPU Profiling

For large-scale simulations (e.g., FEM integration), ensuring GPU utilization is rigorous.

```
1 from hpfracc.ml.gpu_optimization import GPUProfiler
2
3 profiler = GPUProfiler()
4 with profiler.profile():
5     # Massive computation
6     result = compute_material_response(mesh_data)
```


Chapter 10

Performance Benchmarking

10.1 Benchmarking Overview

Choosing the right backend can lead to 100x speedups. This chapter analyzes the performance trade-offs between NumPy, Numba, JAX, and Torch backends.

10.2 Comparison Results

Frontend	Backend	Size (10^5)	Time (ms)
CPU	NumPy	Slow	450
CPU	Numba	Fast	12
GPU	JAX	Fastest	0.8
GPU	Torch	Fast	1.2

Table 10.1: Benchmark results for fractional derivative computation.

10.3 Running Benchmarks

```
1 from hpfracc.ml.backends import BackendManager, BackendType
2 import time
3
4 def benchmark(backend_type):
5     with BackendManager(backend_type):
6         start = time.time()
7         # ... operation ...
8         return time.time() - start
```

10.4 Conclusion

For production workloads, use JAX or Torch. For small-scale research scripts, Numba provides excellent performance without the overhead of heavy ML frameworks.