

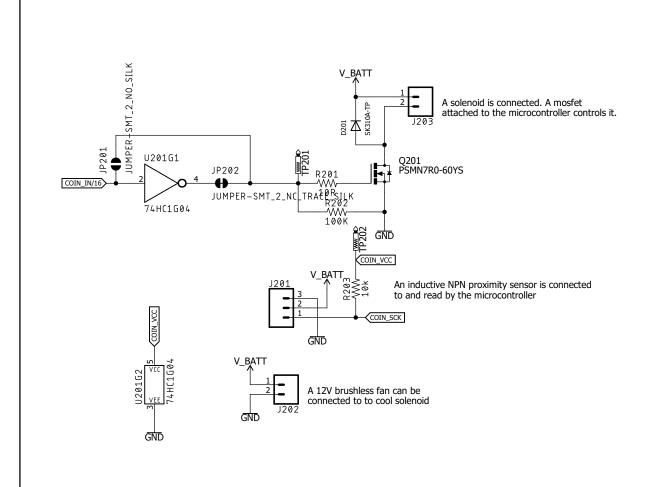
A reed switch is released by a magnet. The switch outputs a signal to begin the next transfer.

"Participants must detach and remove a magnet from the device; this action of detaching the magnet must begin the chain of events due to the removal of the magnetic force."

# STARTING ACTION

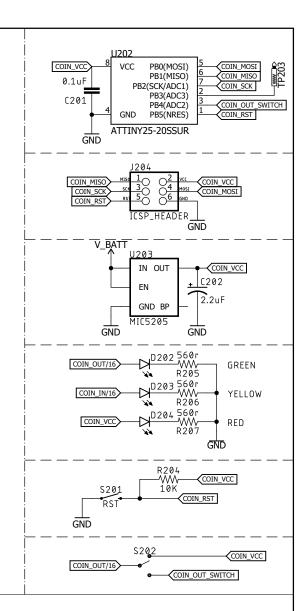
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A solenoid starts out on, with a penny sitting above its plunger, hanging off a ledge. The solenoid releases at the beginning of the transfer, flipping the penny airborne. The penny triggers an inductive proximity sensor which is connected to a microcontroller that triggers the next action.

"Flip an unmodified US quarter airborne so that it goes from heads up to tails up and begins the next action."



#### COIN FLIP ACTION

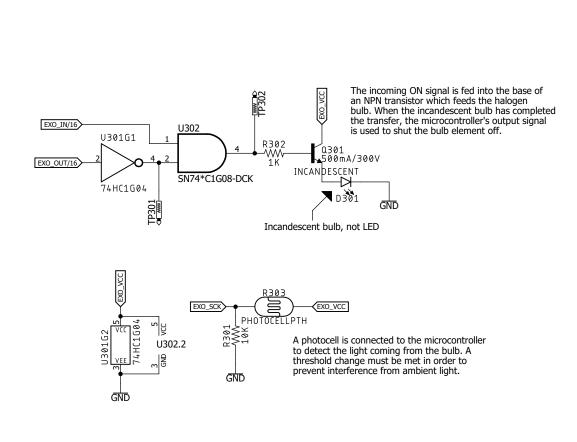
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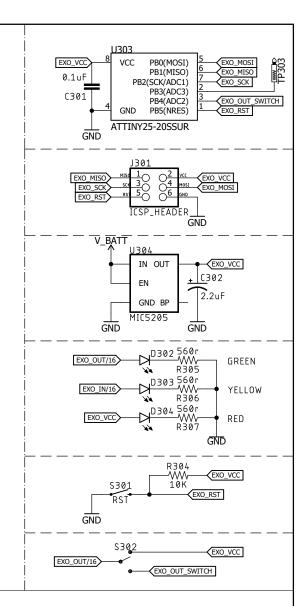
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An incandescent bulb is turned on by the previous transfer and turned off by the output of the transfer. The microcontroller turns on the output when the photocell resistance drops a certain amount.

"Use an exothermic action that produces light to activate a photocell and begins the next action."



#### **EXOTHERMIC ACTION**

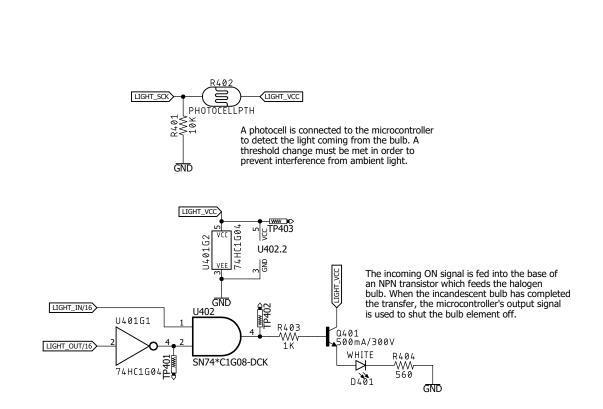
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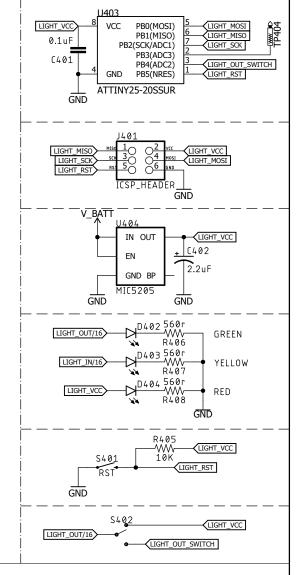
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An LED is turned on by the previous action. The LED makes the phototransistor change its resistance, signaling the microcontroller to proceed to the next action. The output signal turns the LED off again.

"Use light to initiate a chemical reaction to begin the next action."

#### **CLARIFICATION:**

"Use light to initiate the next action."

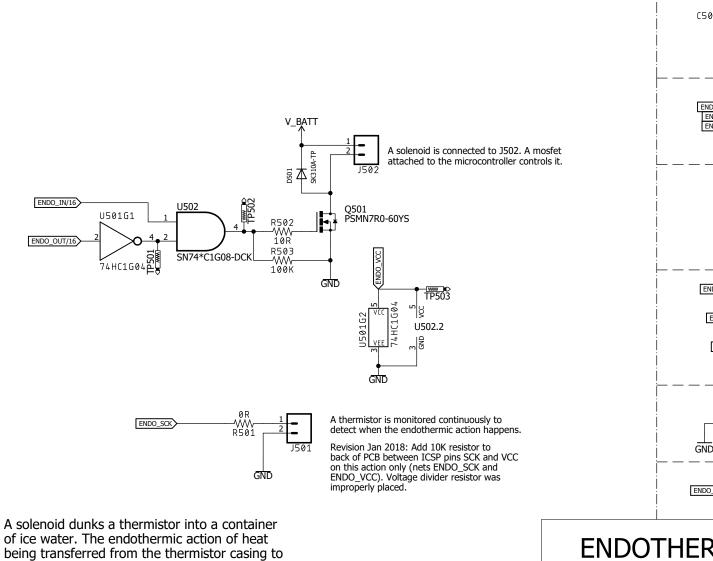
## LIGHT TRIGGERED ACTION

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PB0(MOSI) ENDO\_VCC VCC ENDO\_MOSI PB1(MISO) ENDO\_MISO 0.1uF PB2(SCK/ADC1) ENDO\_SCK PB3(ADC3) C501 PB4(ADC2) ENDO\_OUT\_SWITCH GND PB5(NRES) ENDO\_RST ATTINY25-20SSUR GND ENDO\_VCC GND V\_BATT IN OUT ENDO\_VCC <u>+</u> C502 GND BF MIC5205 GND GND ENDO\_OUT/16 GREEN R505 D503 560r WW ENDO IN/16 YELLOW R506 D504 560r WW ENDO\_VC RED R507 GND R504 -WW ENDO\_VCC 10K S501 ENDO\_RST **GND** S502 ENDO VCC ENDO\_OUT/16 ENDO OUT SWITCH

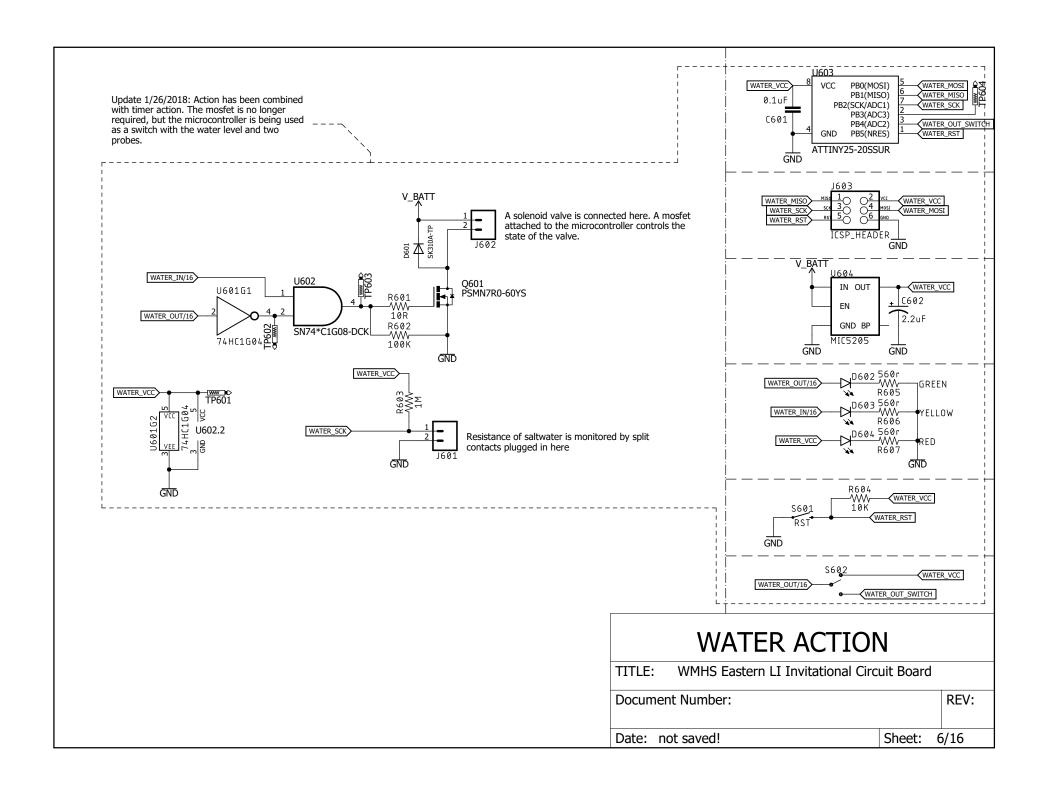
U503

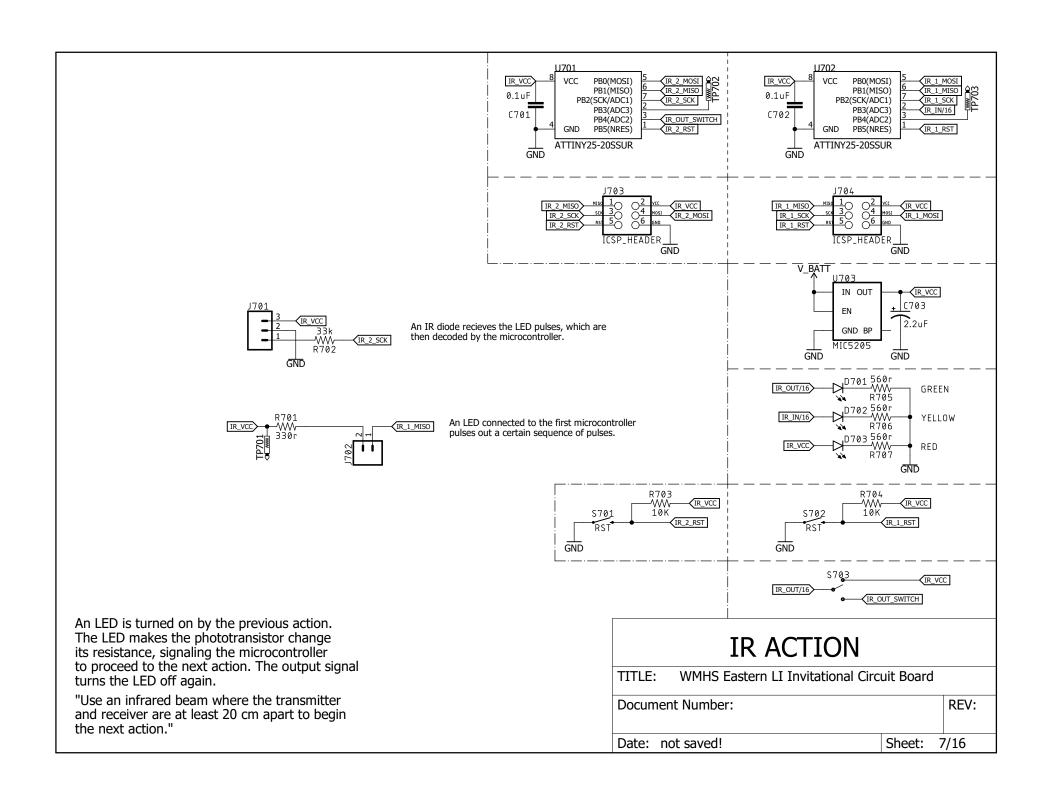
of ice water. The endothermic action of heat the water is detected by the microcontroller which begins the next action.

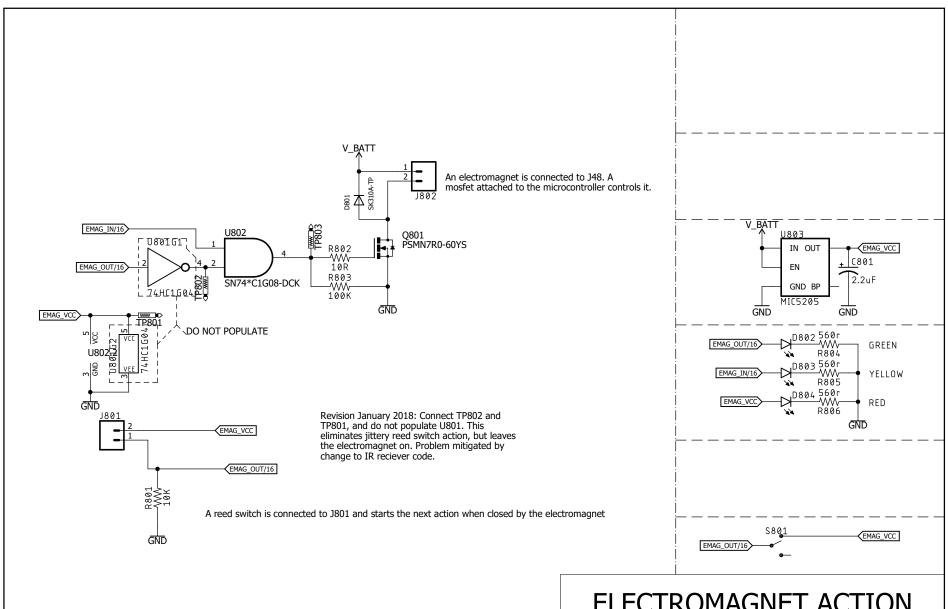
"Use an endothermic action that begins the next action as a result of the reduction in temperature."

## **ENDOTHERMIC ACTION**

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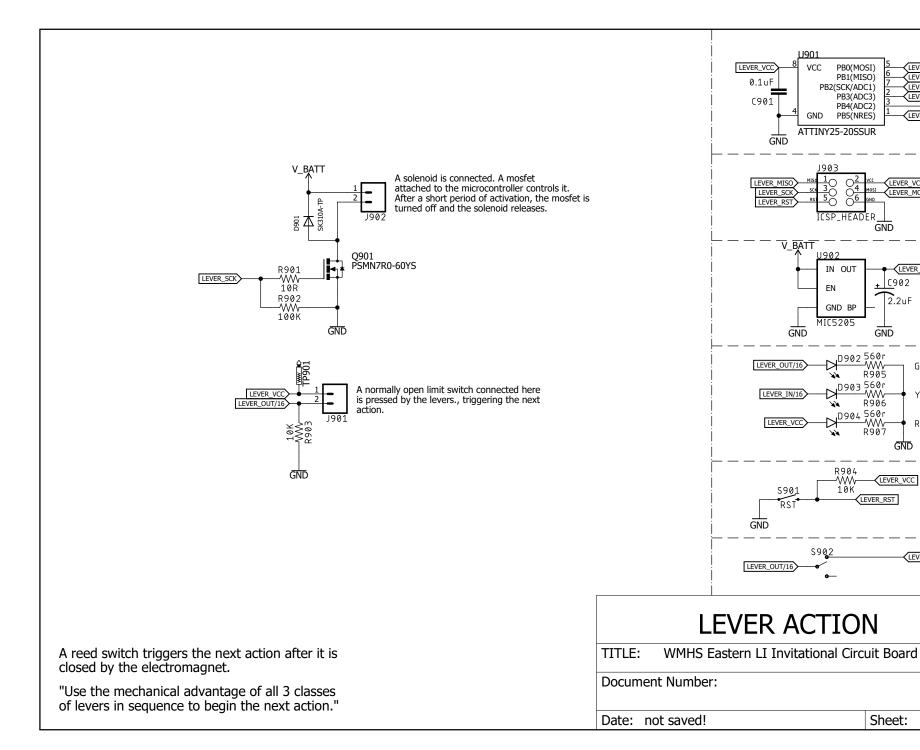


A reed switch triggers the next action after it is closed by the electromagnet.

"Activate a student-made electromagnet that begins the next action."

# **ELECTROMAGNET ACTION**

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PB0(MOSI)

PB1(MISO)

PB3(ADC3)

PB4(ADC2) PB5(NRES)

LEVER\_MISO

LEVER\_SCK

LEVER\_IN/16

LEVER\_RST

LEVER VCC

LEVER\_VCC

GREEN

YELLOW

RED

LEVER VCC

REV:

9/16

GND

LEVER\_VCC

Sheet:

GND

<u>+</u> [902

GND

R905 р903 560г

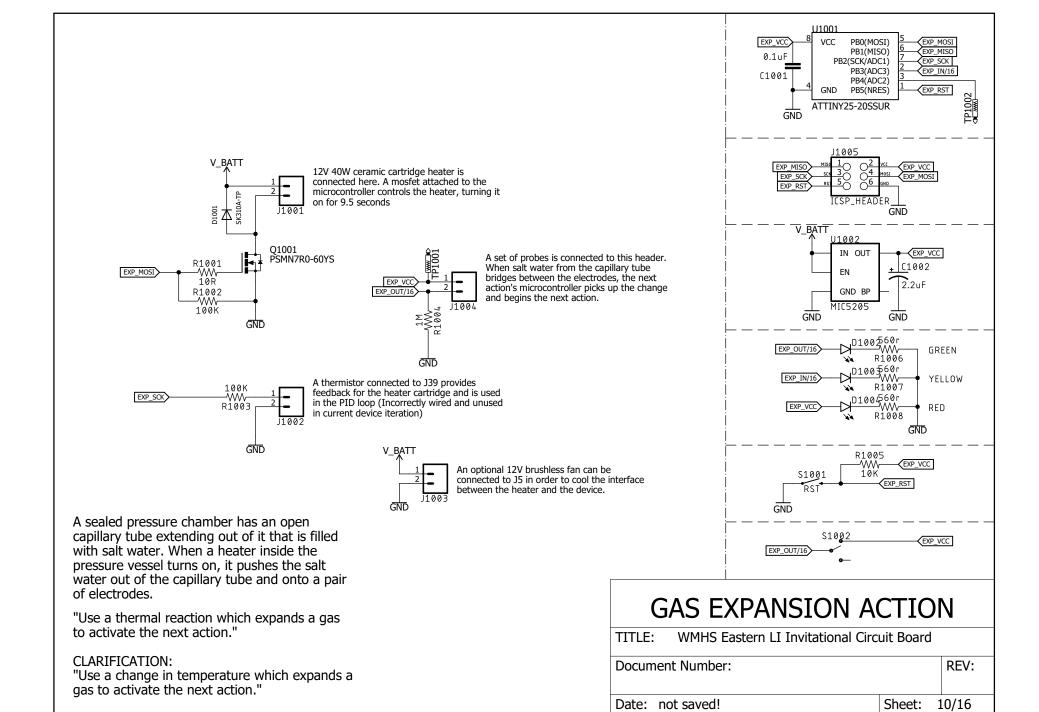
WW

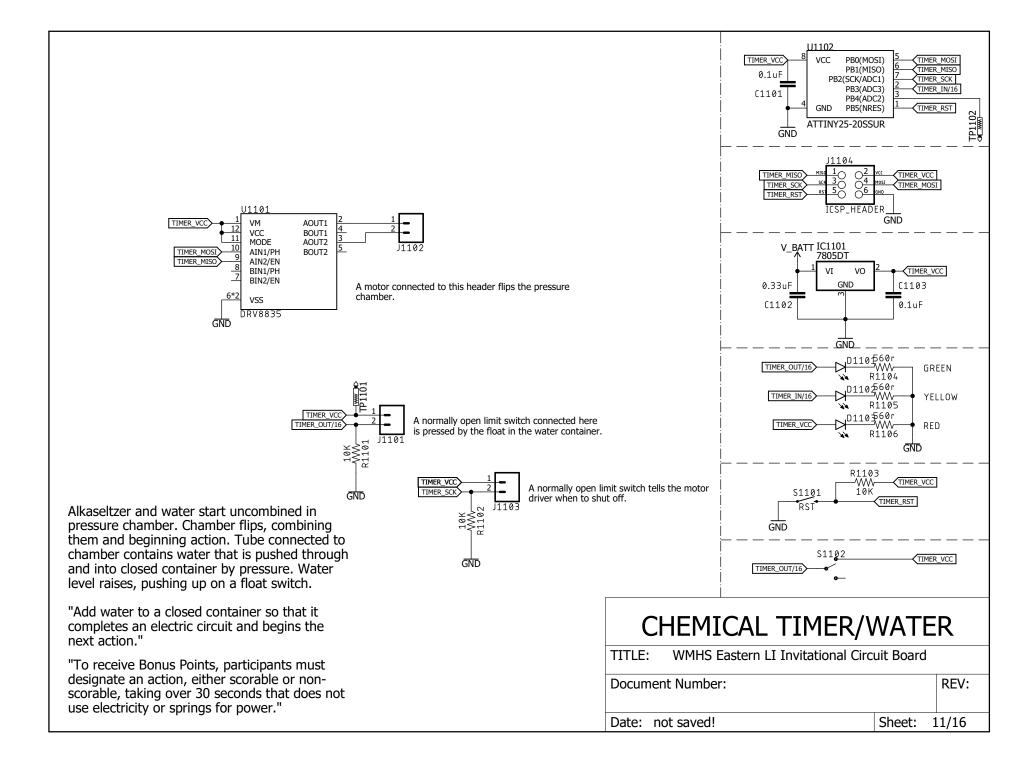
R906

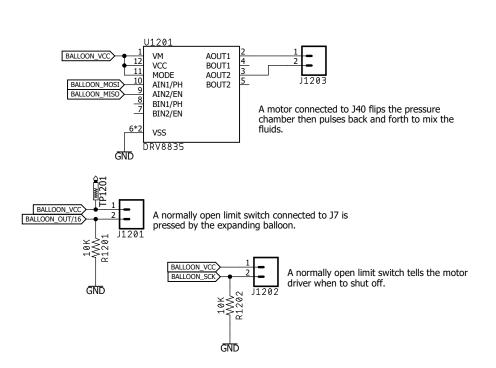
LEVER\_RST

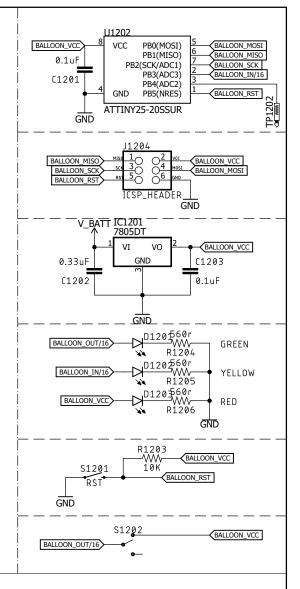
D904 560r WW-R907

10K









Pressure chamber with baking soda and 30% warm vinegar is flipped, the two react and the resulting reaction inflates a balloon which hits a limit switch 20cm away.

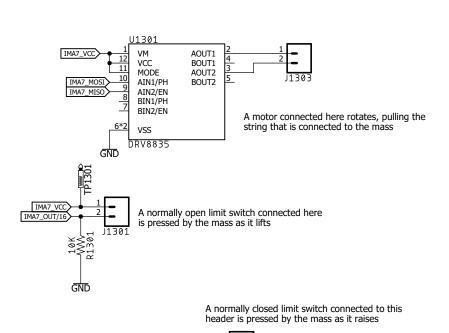
"Use a chemical reaction that inflates a balloon so that the balloon strikes an object that originally was at least 20 cm away from the balloon, so that the action of striking the object continues the sequence of events."

### **BALLOON ACTION**

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IMA7\_VCC

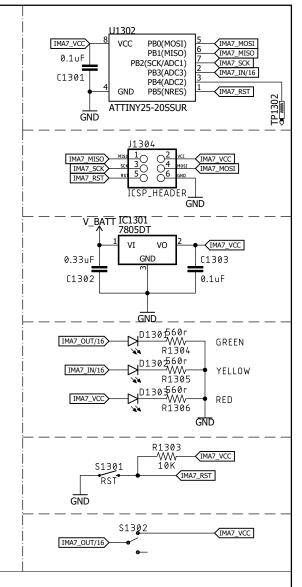
IMA7 SCK

The pulley system, powered by the motor, lifts a mass up 10cm and hits two limit switches, one turns off the motor and the other triggers the next action.

100uF, 25V capacitor was added following MIT invitational because of jerky motor

performance. Connected between IMA7\_VCC and GND on ICSP header on rear of board.

"Use a Pulley system with an ideal mechanical advantage (IMA) of at least 7, that lifts an object that is at least 500 g at least 10 vertical cm before the object initiates the next action."



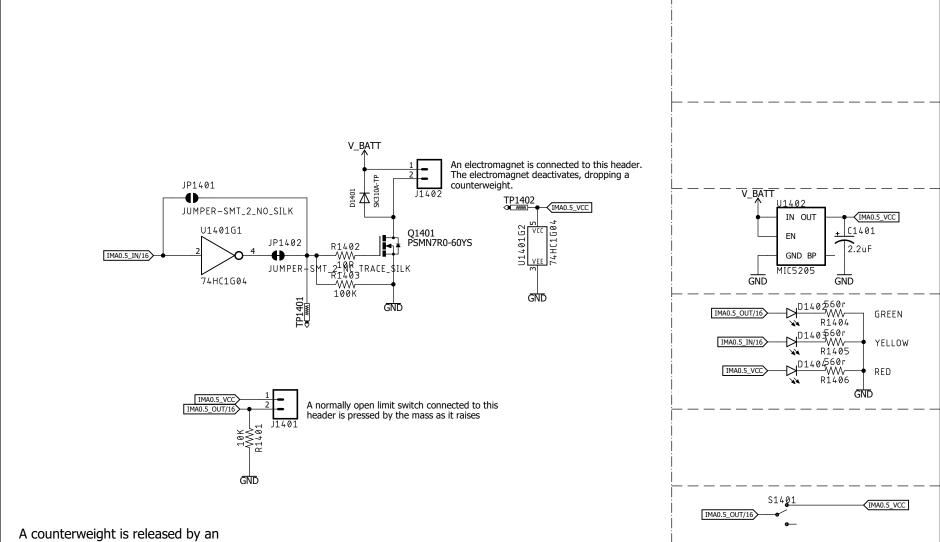
# **IMA 7 PULLEY ACTION**

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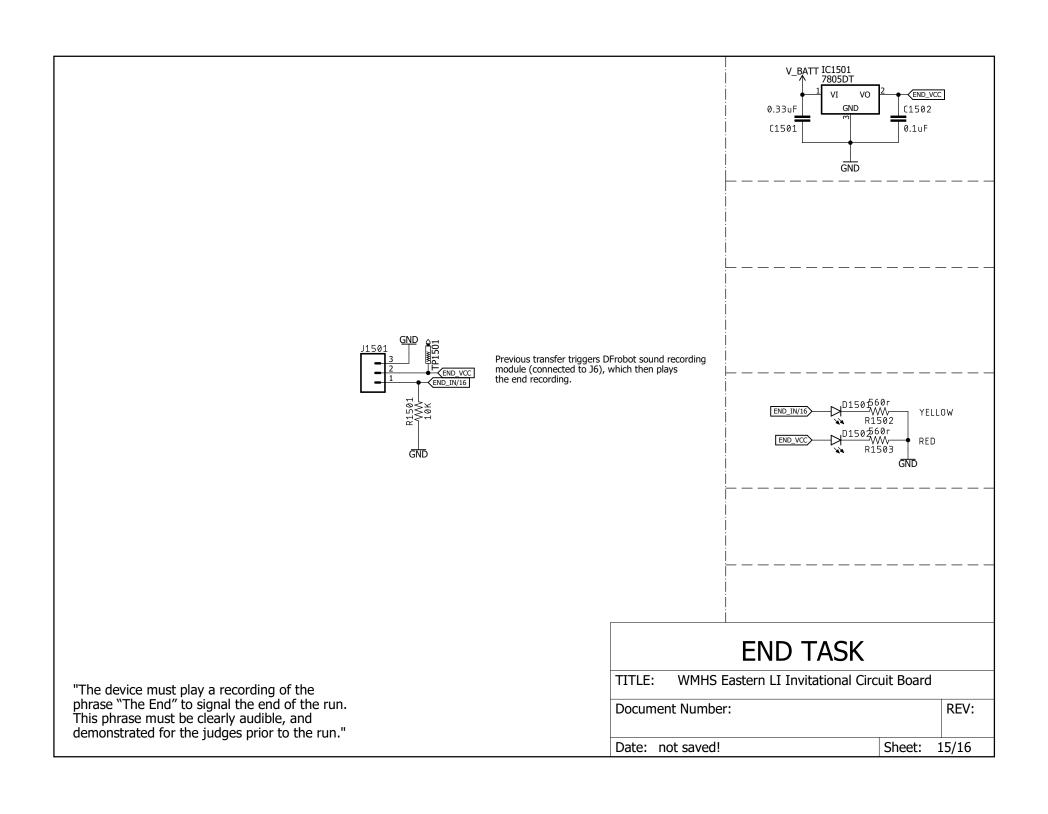


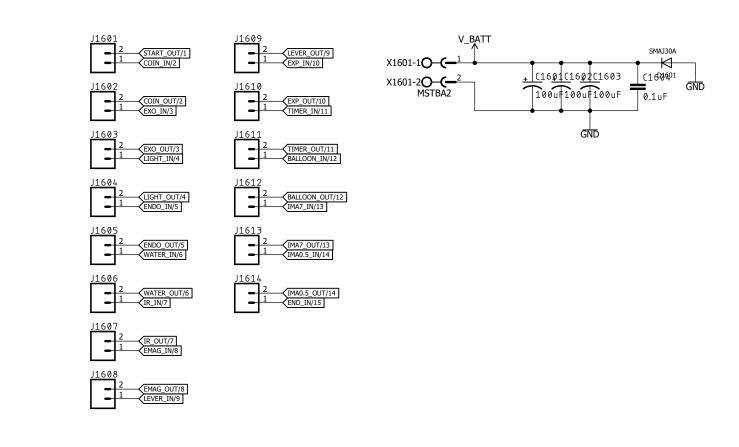
A counterweight is released by an electromagnet, which drops and pulls up a 500g mass. The mass raises 10cm then hits a limit switch, triggering the next action.

"Use a Pulley system that has an ideal mechanical advantage (IMA) of 0.50 that lifts an object that is at least 500 g at least 10 vertical cm before the object initiates the next action."

## **IMA 0.5 PULLEY ACTION**

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Jumpers are installed on all of the above headers, with the following exceptions:

J1605 ENDO\_OUT -> J1606 IR\_IN J1606 WATER\_OUT -> J1611 BALLOON\_IN

	Power and Inter-A	ction	
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