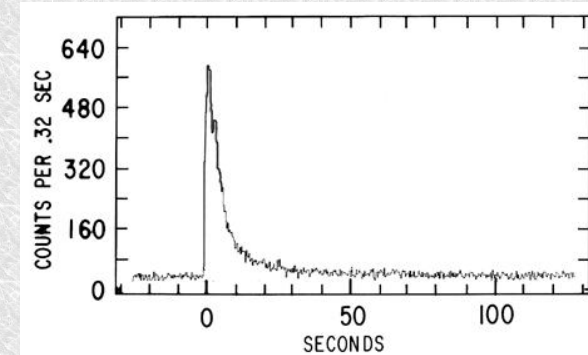


The Low Mach Number Approximation for Multidimensional Modeling of Type I X-ray Bursts

David J. Lin

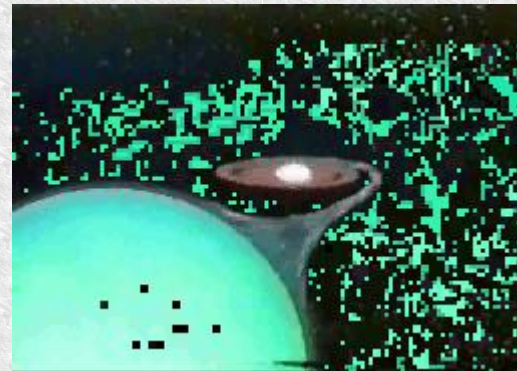
Main Project Goals ...

- Develop the *Low Mach Number Approximation* (LMNA) to study astrophysical deflagrations:
 - Sub-sonic flows $M < 0.1$
 - Strong gravity $g \sim 10^{14} \text{ cm s}^{-2}$
 - Large lateral variations $\delta T/T \sim 0.1$
- Simulate Type I X-ray burst (w/ 2D hydro)
 - ... through a complete burst: 1) heating, 2) peak, 3) cooling
 - Quantify:
 - burning front behavior
 - convective dynamics
 - size of thermodynamic fluctuations
 - compositional mixing
 - Calculate approximate light-curves



MXB 1728-34 Light Curve

(High Energy Astronomy Observatory-1 A2)



LMNA Motivation

- Substantial increase in time-step if $M \ll 1.0$

$$\Delta t = \lambda_{CFL} \frac{\Delta x}{(v_{flow} + v_{sound})} \rightarrow \lambda_{CFL} \frac{\Delta x}{(v_{flow})} \quad \text{if p-waves are absent}$$

- Speed up calculations by a factor of 10 or more
- Completely avoid artificial acoustic effects at the boundaries of both the computational domain and the convective layer

LMNA Advantages

	<u>Boussinesq</u>	<u>Implicit</u>	<u>Anelastic</u>	<u>LMNA</u>
Key method:	$\nabla \cdot \vec{v} = 0$	n, n-1	$\nabla \cdot \rho \vec{v} = 0$	$\frac{\partial P}{\partial t} = 0$ (<i>EOS</i> , <i>EOE</i>)
Compressible?	NO	YES	weakly	weakly
Acoustic boundary problems?	NO	YES	NO	NO
Allows for large lateral differences?	NO	YES	NO	YES

LMNA Current Implementations

- ***Terrestrial:***



Fire Dynamics Simulator

National Institute of Standards and Technology
(McGratten et al, 2004)



- ***Astrophysical:***

LBL Alternative LMNA method:

- 1) Evolves density
- 2) Currently neglects reaction, composition, & thermal diffusion
- 3) Allows for time-dependent base state
- 4) We reformulate pressure gradient and buoyancy terms: $\phi = P' - gK$

Lawrence Berkeley National Laboratory

(Bell et al., 2004; Zingale, et al., 2005; Almgren et al., 2006a, 2006b)

LMNA Essence

Non-dimensionalizing the Euler momentum equation is instructive:

$$\nabla P = -M^2 \left(\rho \frac{D\vec{v}}{Dt} + F_r^{-1} \rho \hat{g} \right)$$

where $P, \rho, \nabla, t, \vec{v}$ are non-dimensionalized quantities, and

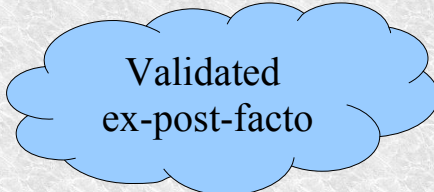
$$M = v_o / v_s \quad (\text{Mach Number}) \qquad F_r = \frac{(v_o^2 / L_o)}{g} \quad (\text{Froude Number})$$

$$P = P_1(t) + M^2 P_2(\vec{r}, t)$$

Perturbatively expand about a time-independent, hydrostatic base state:

$$P(\vec{r}, t) = P_{HS}(z) + P'(\vec{r}, t)$$

$$P' \sim M^2 P$$



Validated
ex-post-facto

Euler Equations

continuity $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$

momentum $\rho \frac{D\vec{v}}{Dt} + \nabla P = \rho \vec{g}$

energy $\rho T \frac{DS}{Dt} = \rho c_p \frac{DT}{Dt} - \delta \frac{DP}{Dt}$

state $\rho = F(T, P, X_l)$

species $\frac{DX_l}{Dt} = R_l$

LMNA Equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$$

$$\rho \frac{D\vec{v}}{Dt} + \nabla P' = \rho' \vec{g}$$

$$\rho T \frac{DS}{Dt} = \rho c_p \frac{DT}{Dt} - \delta \frac{DP_{HS}}{Dt}$$

$$\rho = F(T, P_{HS}, X_l)$$

$$\frac{DX_l}{Dt} = R_l$$

Essential approximation: $\frac{\partial P}{\partial t} \rightarrow 0$ in the equations of energy and state

LMNA Evolution Equations

$$\frac{\partial X_l}{\partial t} = -\vec{v} \cdot \nabla X_l + R_l$$

$$\frac{\partial T}{\partial t} = -\vec{v} \cdot \nabla T + \frac{1}{c_p} \left(\dot{s} - \frac{\delta}{\rho} w \rho_{HS} g + \frac{1}{\rho} \nabla \cdot \kappa \nabla T \right)$$

$$\rho, e \Leftarrow EOS(T, P_{HS}, X_l)$$

$$\nabla^2 \phi = \frac{\partial^2 \rho}{\partial t^2} - \nabla \cdot \{ \nabla \cdot (\rho \vec{v} \vec{v}) \} - \left\{ \frac{\partial^2 (gK)}{\partial y^2} \right\}$$

$$\phi = P' - gK$$

$$K = \int_0^{z'} \rho'(y, z') dz'$$

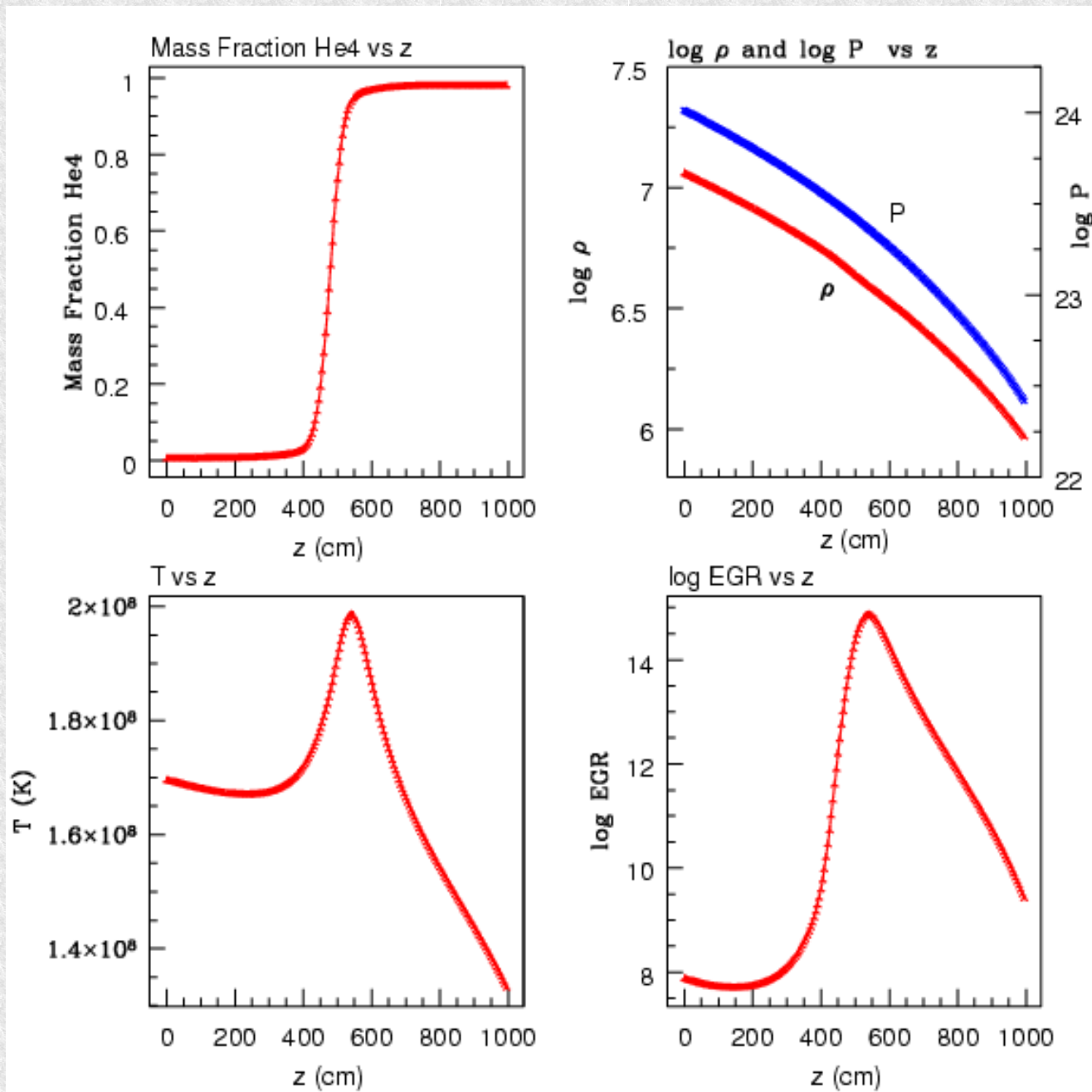
$$\frac{\partial(\rho \vec{v})}{\partial t} = -\nabla \cdot (\rho \vec{v} \vec{v}) - \nabla \phi - \left\{ \frac{\partial(gK)}{\partial y} \right\} \hat{j}$$

LMNA Model Specifications

- Split, explicit, finite-difference scheme
- Grid: 2D, uniform (1:1), staggered, Cartesian
- Space: central and upwind differencing
- Time: forward Euler, $CFL = 0.5$ (2D)
- Input physics:
 - thermal diffusion (opacity routines: Iben, 1975; Christy, 1966; Weaver, 1978)
 - realistic equation of state (tabulated Helmholtz EOS: Timmes & Swesty, 2000)
 - 3α ($3_2^4He \rightarrow 6^{12}C$) burner (Fushiki & Lamb, 1987)
 - strong gravity ($g = 2 \times 10^{14} \text{ cm s}^{-2}$)
- Language: Intel Fortran 90
- Parallelism: Message Passing Interface (MPI)
- Computing: *Hydra* (NU Applied Math) 32 node cluster

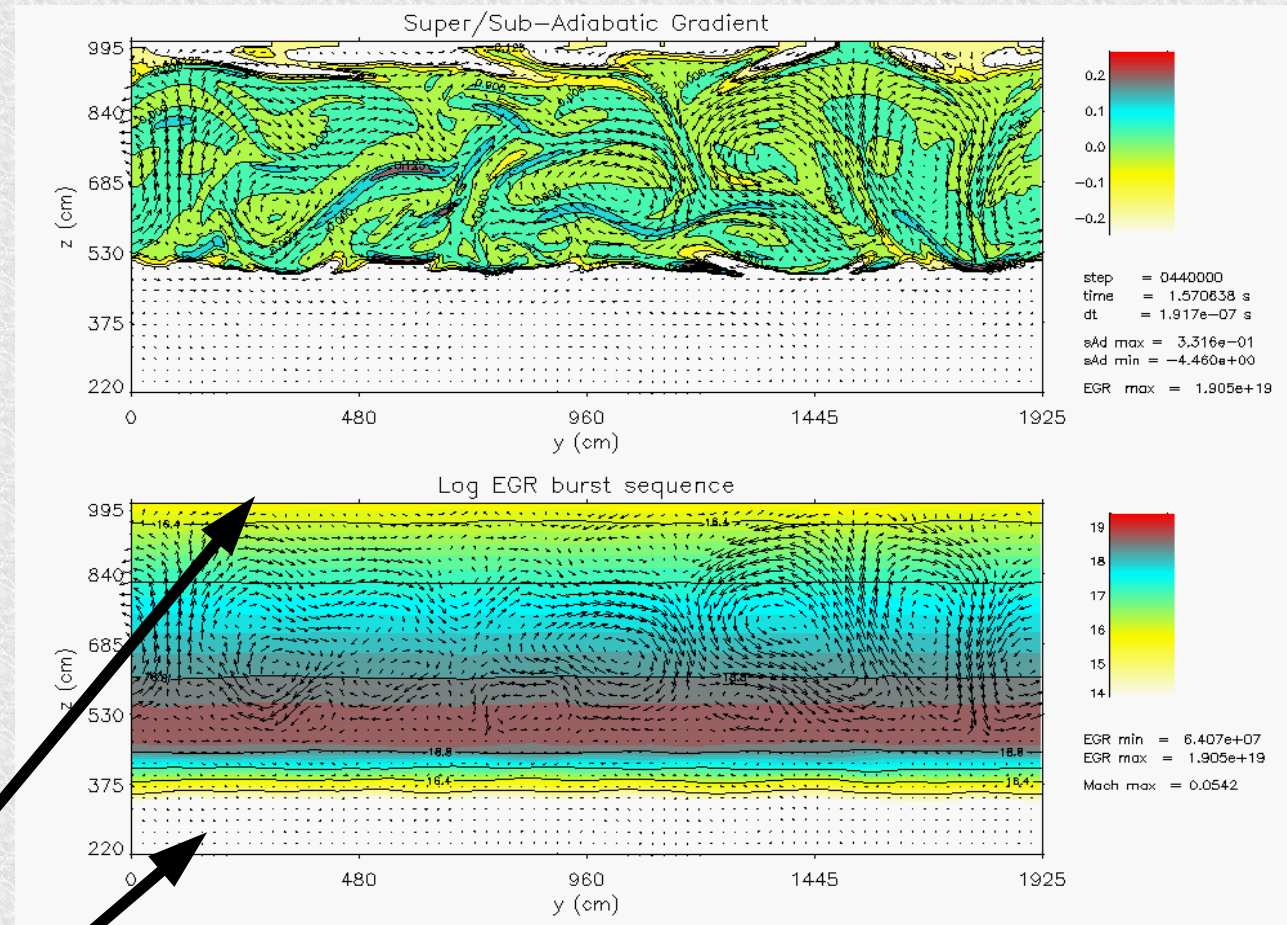
Neutron Star Initial Model

- 10^3 cm of upper neutron star envelope
 $M_{NS} = 1.4M_{\odot}$, $R_{NS} = 10^6$ cm
- 1 cm zone⁻¹ resolution
- hydrostatic & thermal equilibrium
- mass accretion rate:
 $\dot{m} = 5 \times 10^{-9} M_{\odot} \text{ yr}^{-1} \text{ cm}^{-2}$
- pressure scale height
 ~ 200 cm
- 1D diffusional-thermal evolution through multiple burst cycles
- initially sub-adiabatic



2D Complete Burst Model

- 386 x 200 zones
1930 x 1000 cm
- 5 cm zone⁻¹
- Plane parallel approx.
- Initial ρ perturbation
Gaussian, $10^{-6} \rho$, centered, $\sigma = 50$ cm
- $EGR_{init} = 7 \times 10^{14}$ erg g⁻¹ s⁻¹



$$\frac{\partial T}{\partial z} = \frac{-\rho T}{4N_{top}}$$

ρ consistent w/ T
 Dirichlet ($\phi=0$)
 $K, C.T.=0$
 $X_l, v, w: 0 \text{ grad}$

NS surface

Modeled burning patch

lateral
periodicity

$$T, \rho, X_l, v, K: 0 \text{ grad}$$

$$\text{Neumann} \left(\frac{\partial \phi}{\partial z} = 0 \right)$$

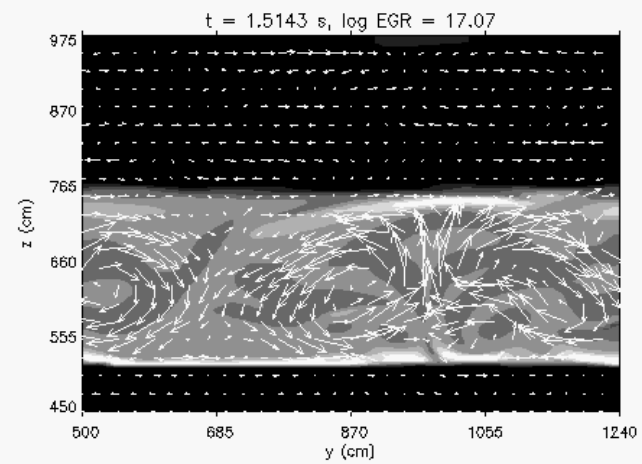
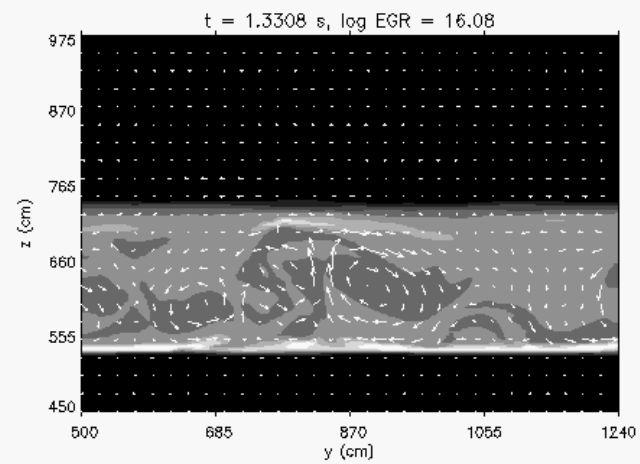
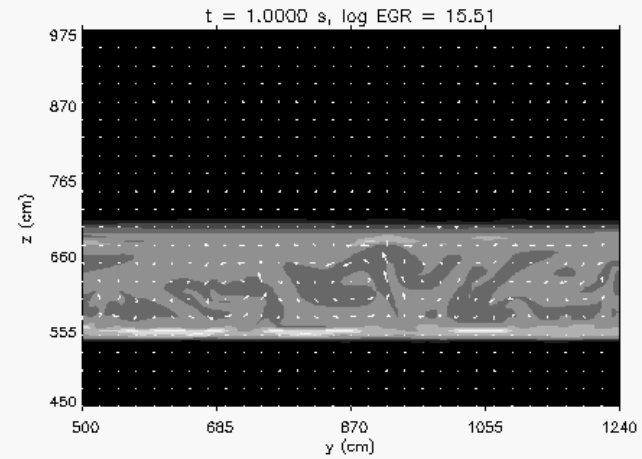
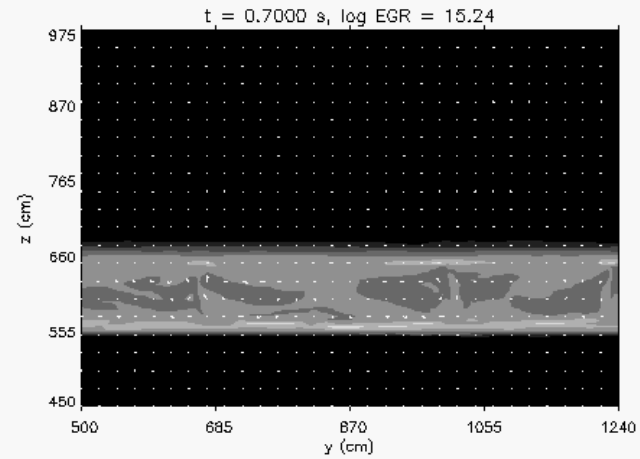
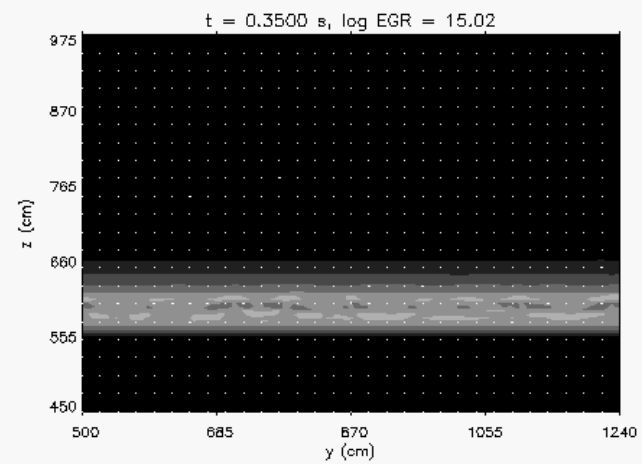
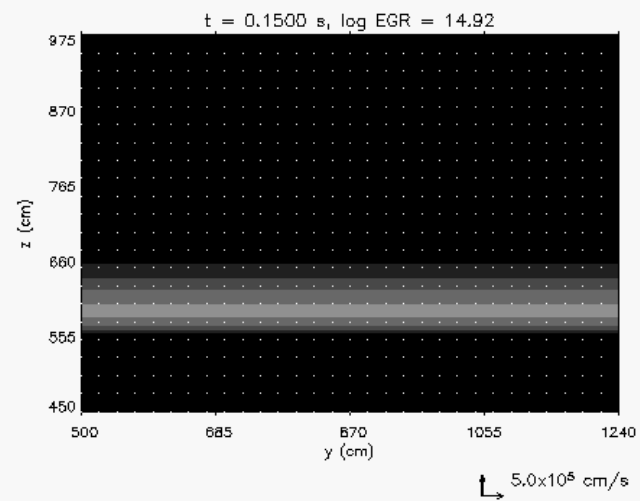
$$w, C.T.=0$$

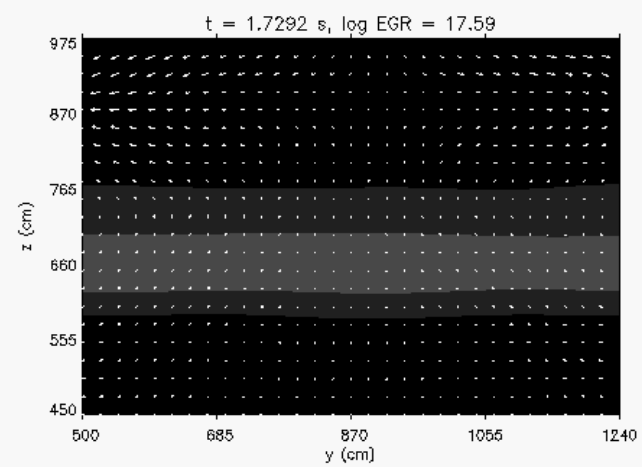
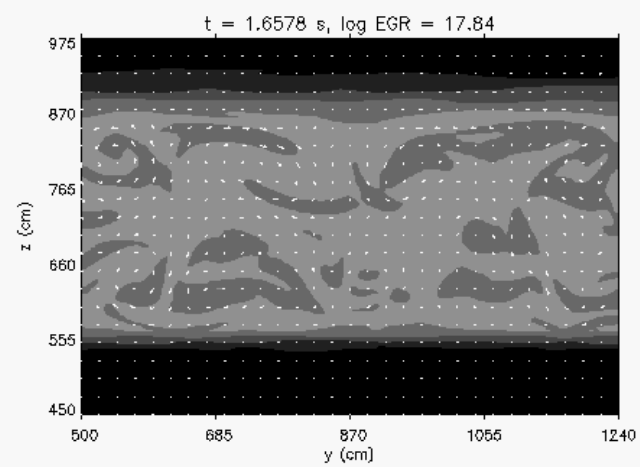
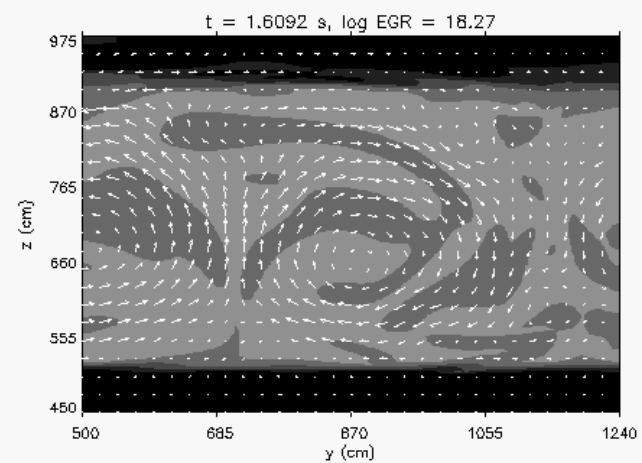
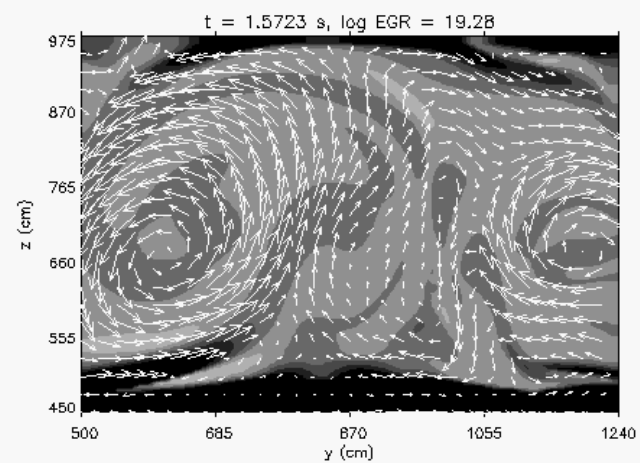
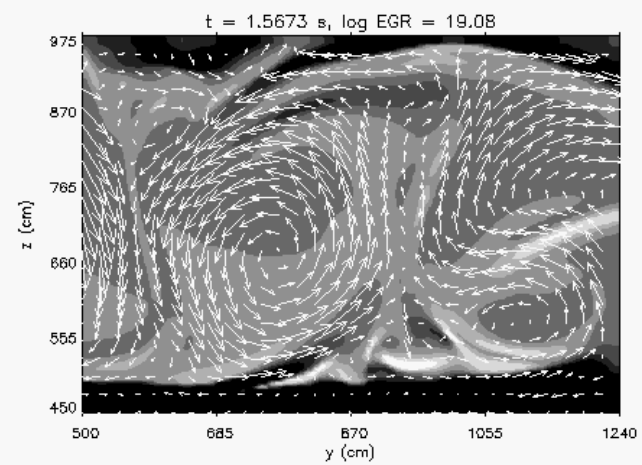
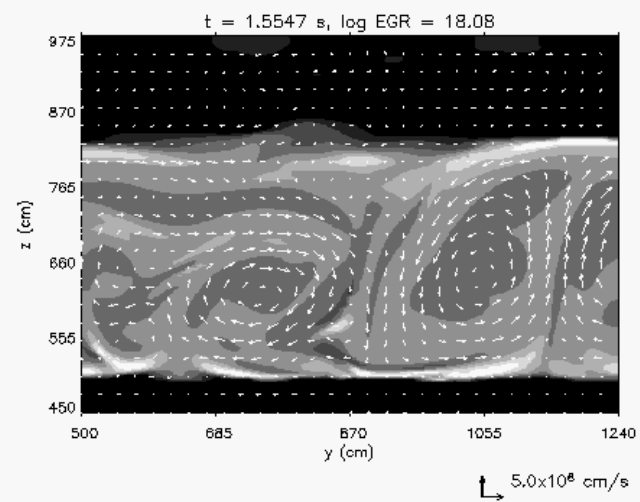
Neutron Star Envelope Type I X-ray Burst Sequence

386x200

5 cm/zone

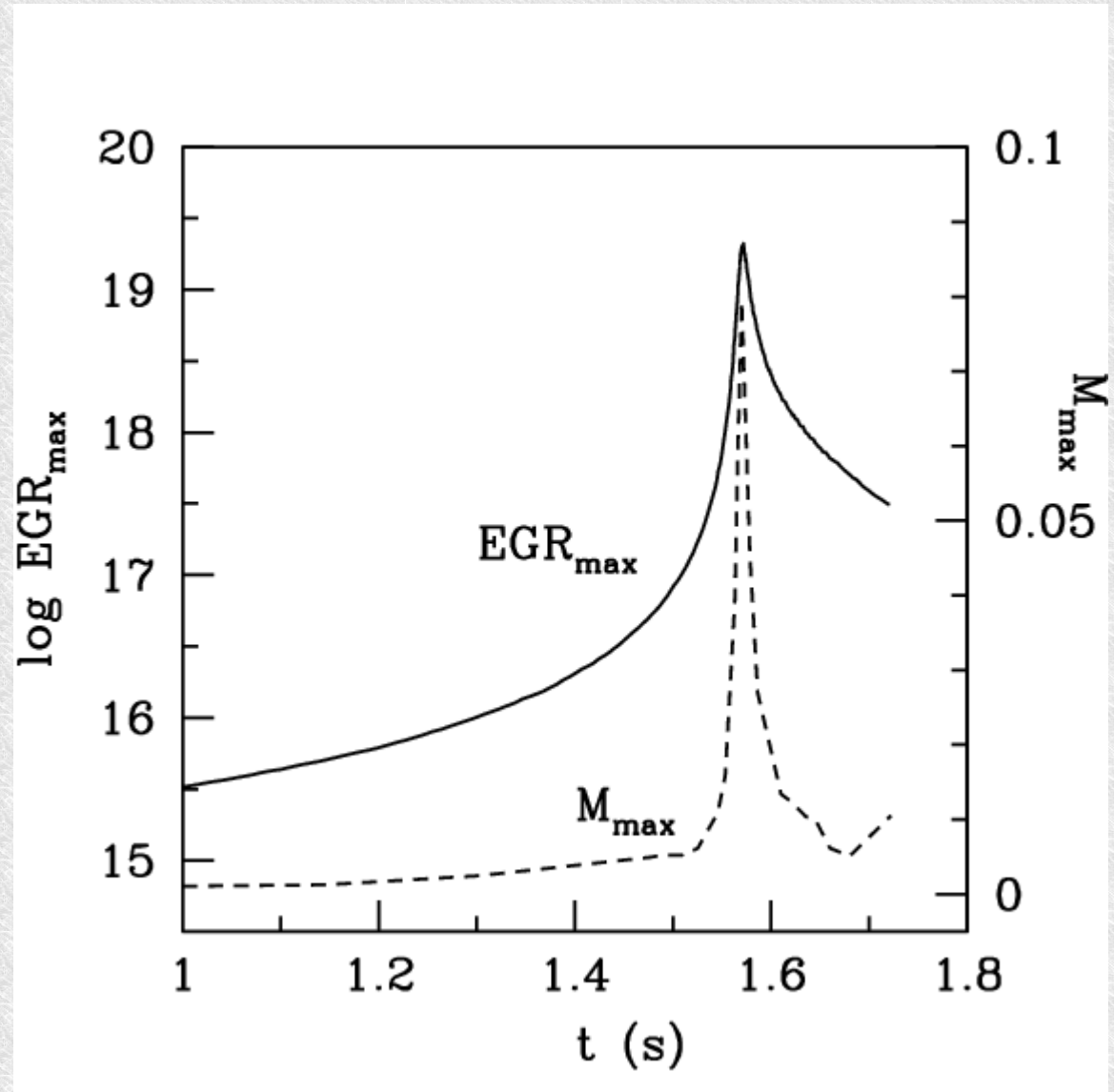
LMNA Model





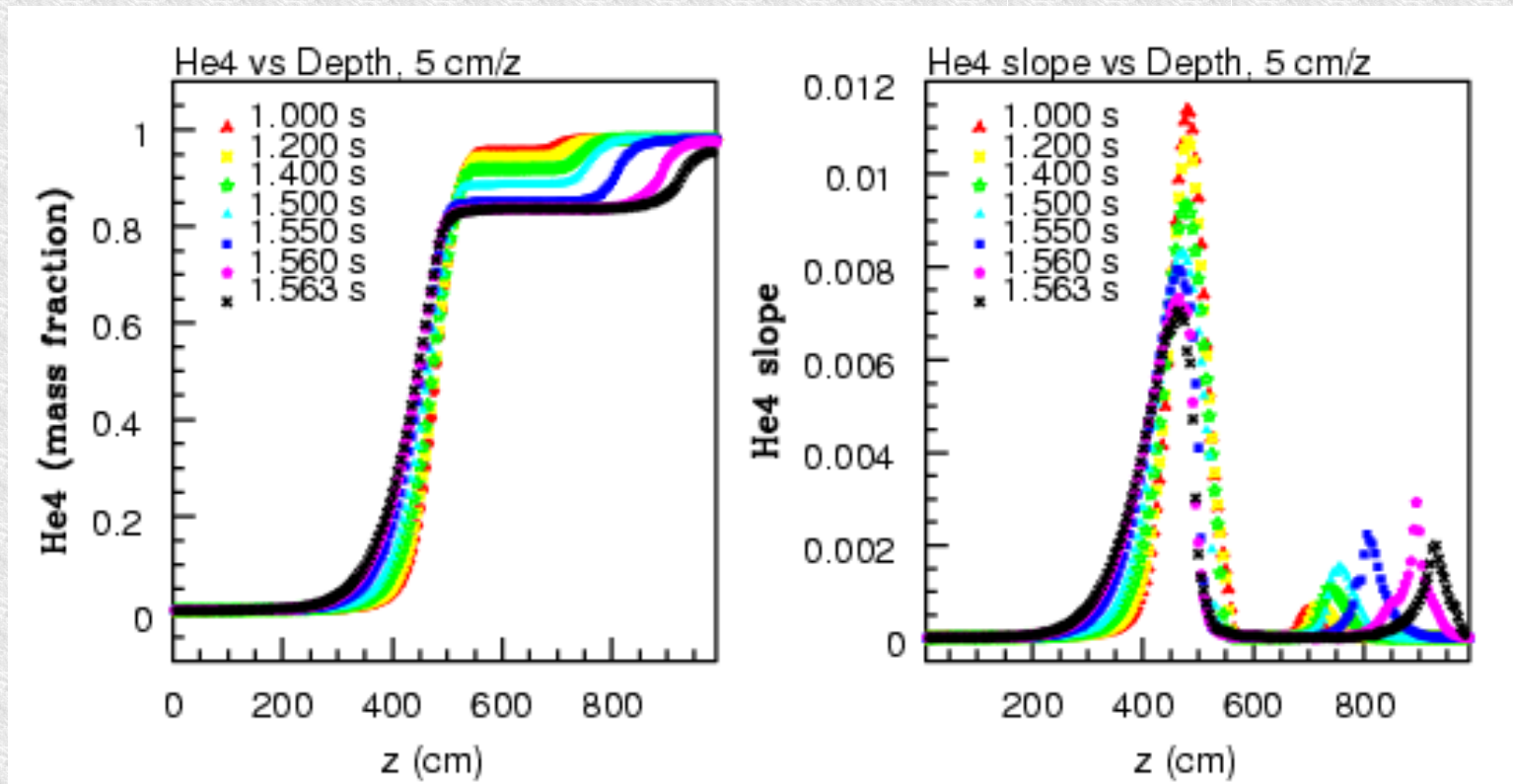
Burst Evolution: Global Diagnostics

- $\text{EGR}_{\text{peak}} \sim 2 \times 10^{19} \text{ erg g}^{-1} \text{ s}^{-1}$
($t_{\text{peak}} = 1.572 \text{ s}$)
- $T_{\text{peak}} \sim 1.7 \times 10^9 \text{ K}$
- $M_{\text{peak}} = 0.085$
- Consumed $\sim 75\%$ of fuel



Convective Layer Expansion Speeds

- Convective layer expands due to thermal diffusion of heat from bursting layer
- Lower boundary velocity $\sim 10^2 \text{ cm s}^{-1}$
- Upper boundary velocity $\sim 10^4 \text{ cm s}^{-1}$



Velocity Correlation, Gradients

Velocity correlations help quantify the extent and evolution of the convective layer:

$$W_{(corr)} = \frac{\langle w_k w_{ref} \rangle}{\langle w_k \rangle^{1/2} \langle w_{ref} \rangle^{1/2}}$$

k_{ref} = center of conv. layer at $\log EGR = 16$

Actual temperature gradient:

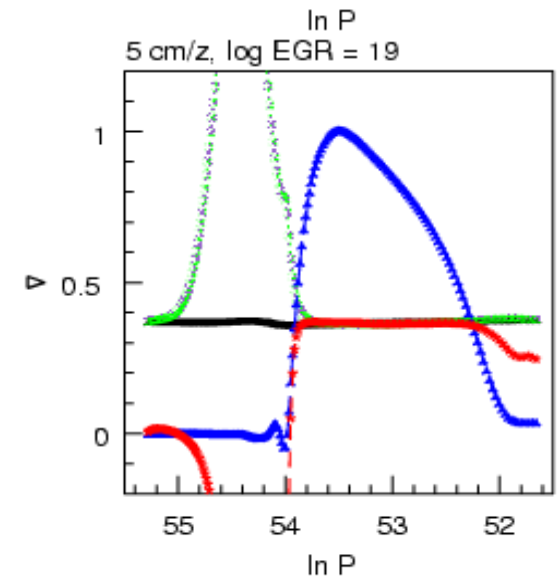
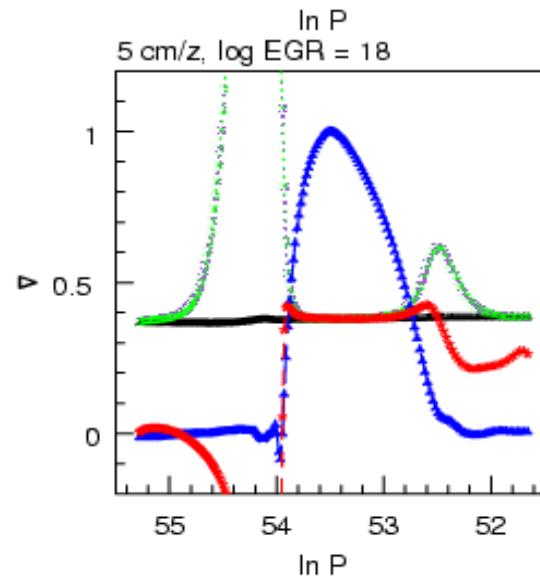
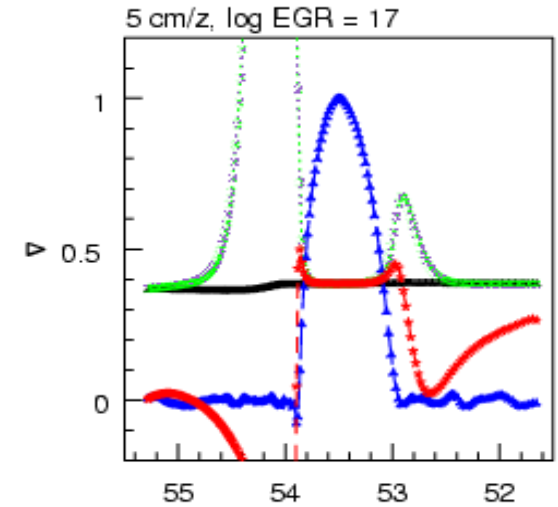
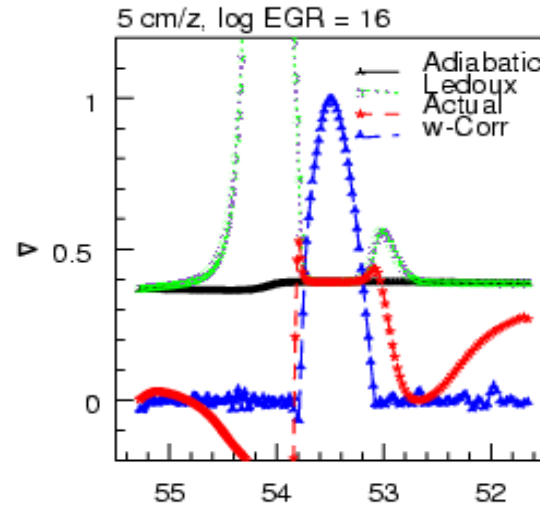
$$\nabla = \left(\frac{\partial \ln T}{\partial \ln P} \right)_{actual}$$

Adiabatic temperature gradient:

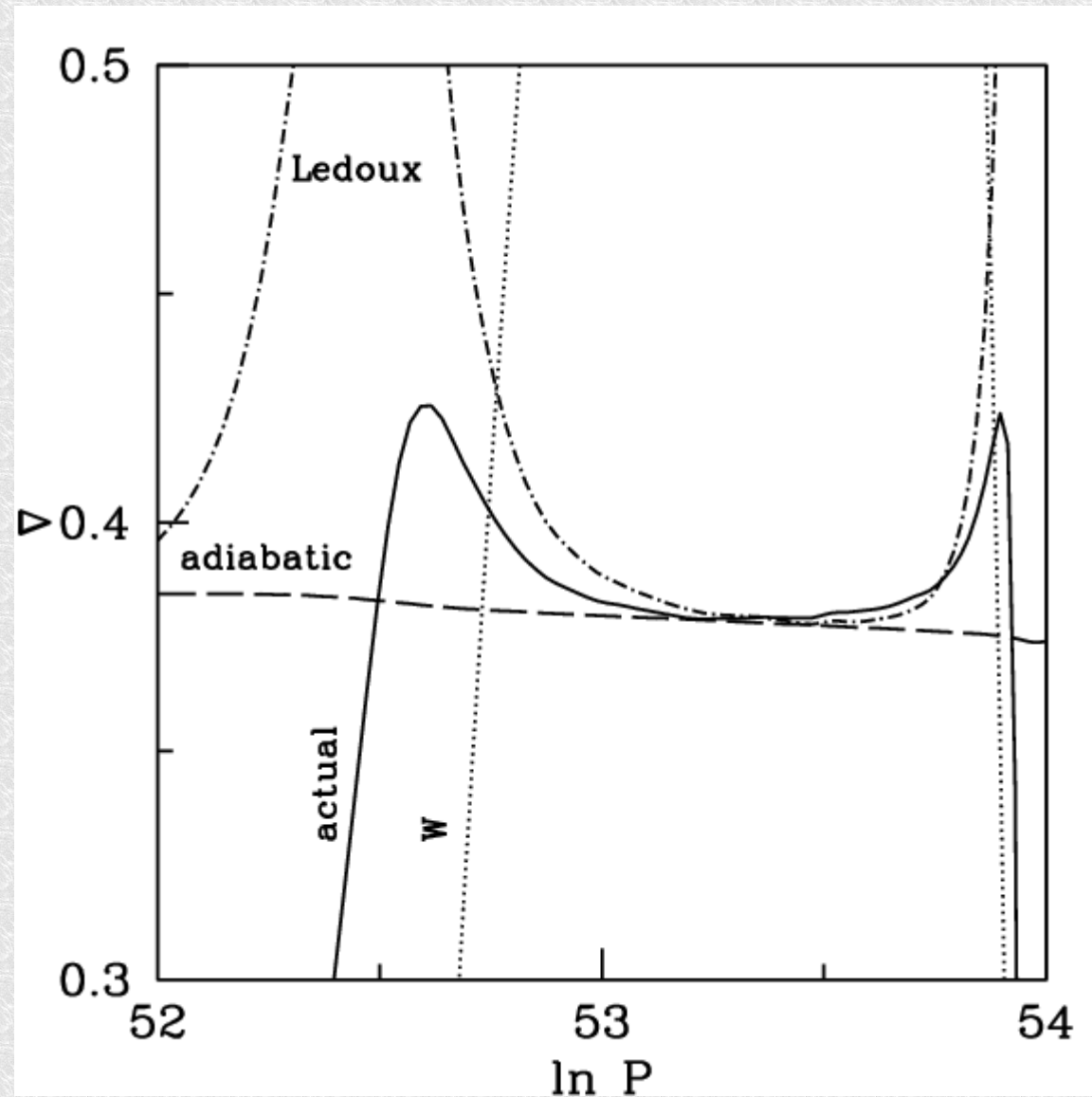
$$\nabla_{ad} = \left(\frac{\partial \ln T}{\partial \ln P} \right)_s$$

Ledoux temperature gradient:

$$\nabla_L = \nabla_{ad} + \frac{c_1}{c_2} \left(\frac{\partial \ln \mu}{\partial \ln P} \right)$$

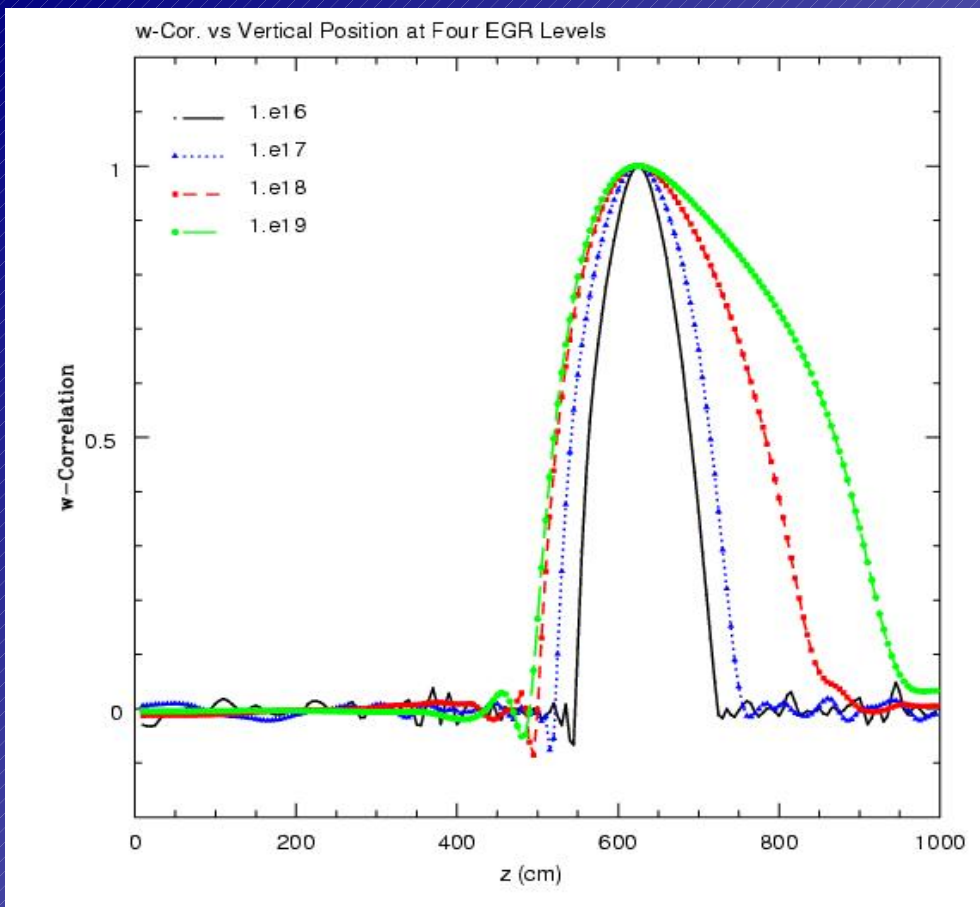


Velocity Correlation, Gradients

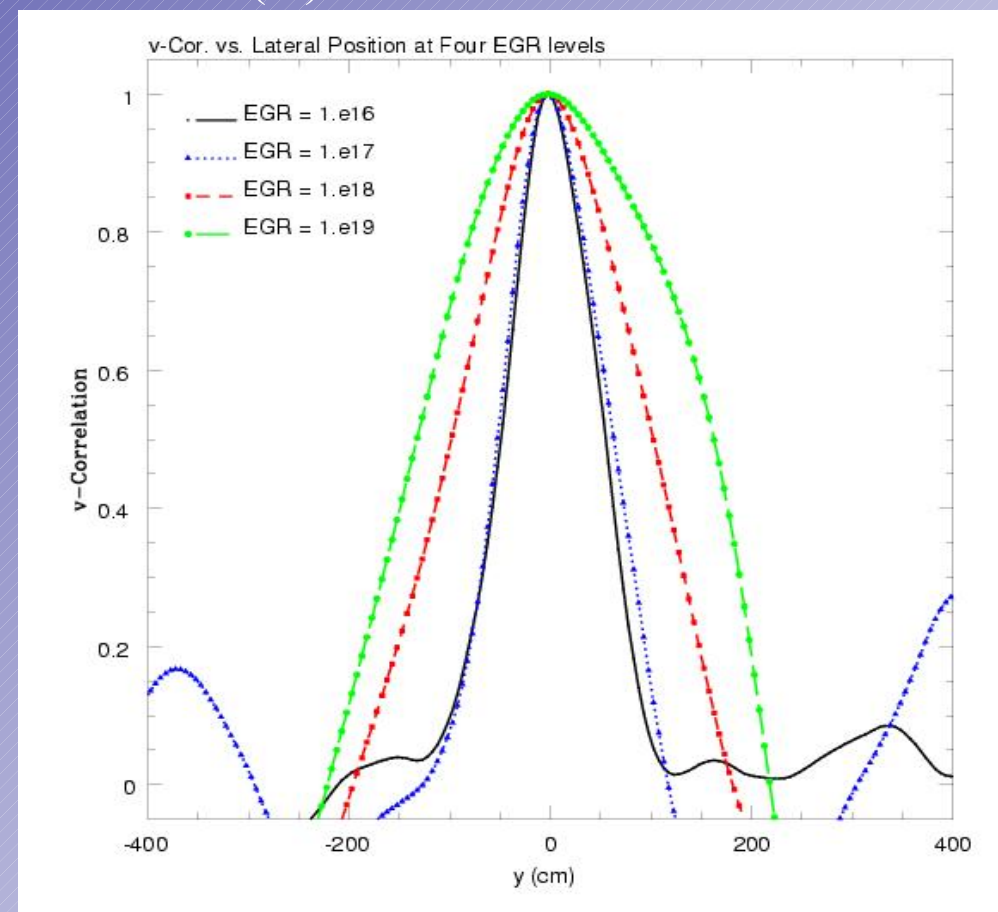


Log EGR 18

Vertical (W) Correlations



Lateral (V) Correlations



Thermodynamic Fluctuations I

- Fluctuations in temperature T and composition Y are calculated from lateral averages:

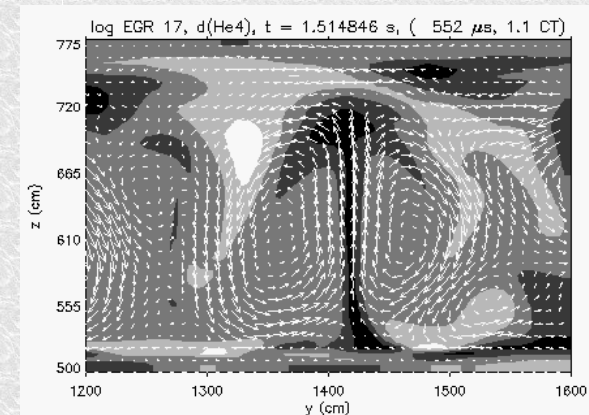
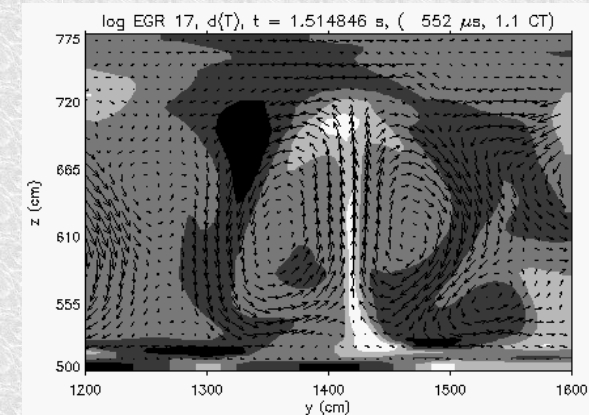
$$d(A)_{j,k} = A_{j,k} - A_{k\text{ave}} \quad A_{k\text{ave}} = \frac{\sum_{j=1}^{j_{\max}-1} A_{j,k}}{j_{\max}-1}$$

	<u>$d(T)$</u>	<u>$d(Y)$</u>
Upflows:	> 0	< 0
Downflows:	< 0	> 0

- Complementary behavior between T and Y always holds!

$$-0.10 < d(T)/T < +0.10$$

$$-0.02 < d(Y)/Y < +0.02$$



Neutron Star Envelope

d(T) & d(Y)

log EGR = 18.5 (t = 1.559-1.563)

386x200

5 cm/zone

LMNA Model

Thermodynamic Fluctuations II

- Fluctuations in adiabaticity SAd and Ledoux excess $SLed$:

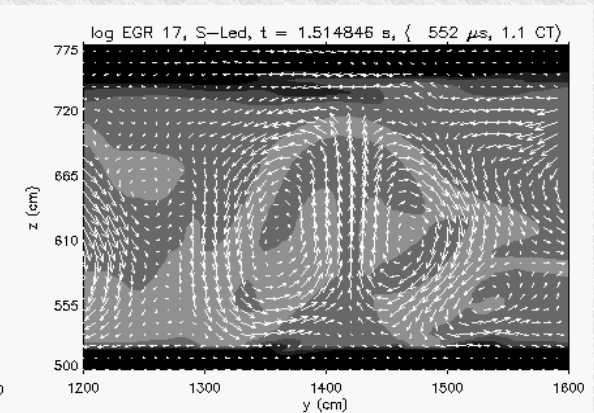
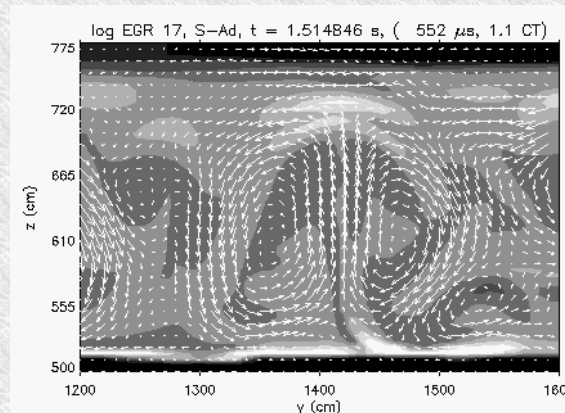
$$SAd_{j,k} = \nabla_{(j,k)} - \nabla_{ad(j,k)}$$

$$-0.25 < SAd < +0.25$$

$$SLed_{j,k} = \nabla_{(j,k)} - \nabla_{L(j,k)}$$

$$-0.25 < SLed < +0.25$$

- SAd is *not* obviously correlated with any instantaneous values
- SAd correlations with total time-integrated Δ in $\partial/\partial z$ due to:
 - Y advection: **strong** correlation
 - T advection: **strong** correlation
 - burning: minor role
 - diffusion: negligible



Neutron Star Envelope

SAd & SLed

$\log \text{EGR} = 18.5$ ($t = 1.559\text{-}1.564\text{s}$)

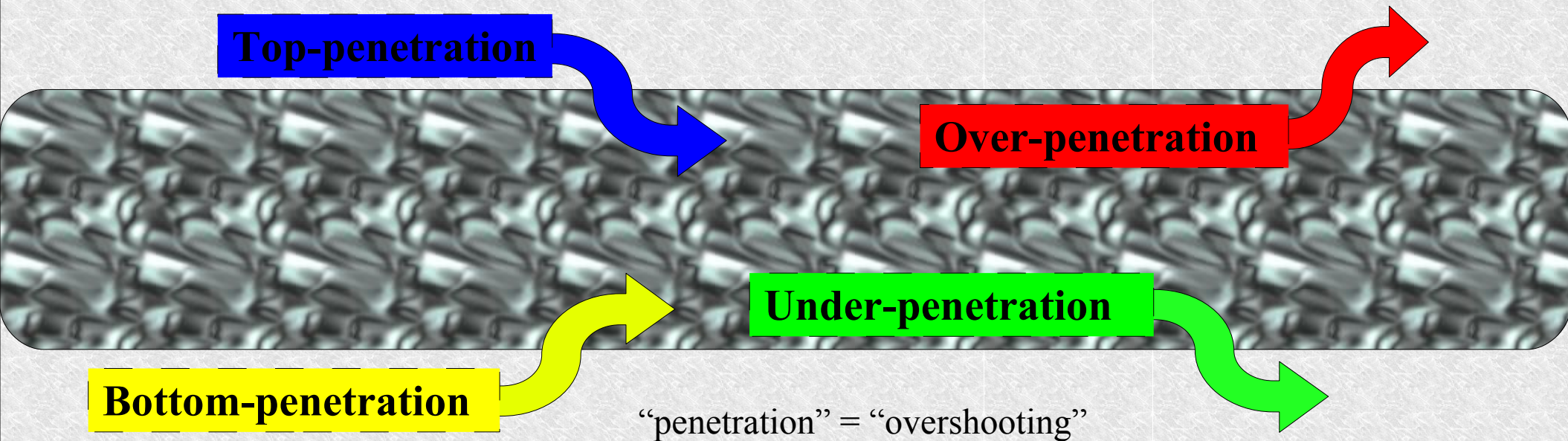
386x200

5 cm/zone

LMNA Model

Tracer Particle Analysis

Quantify transport of material through convective boundaries:

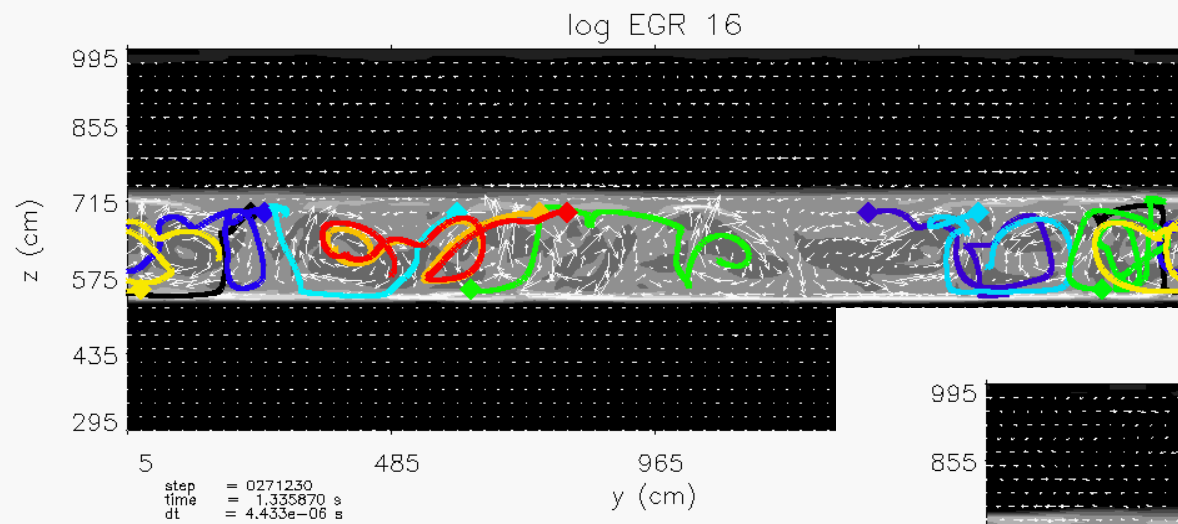


770 tracer particles (2 per lateral position)

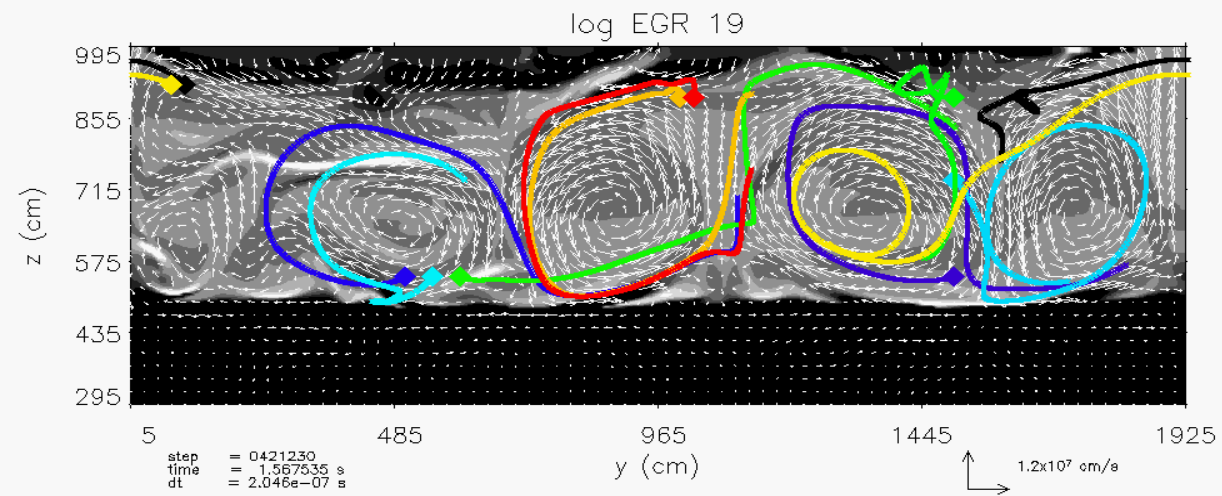
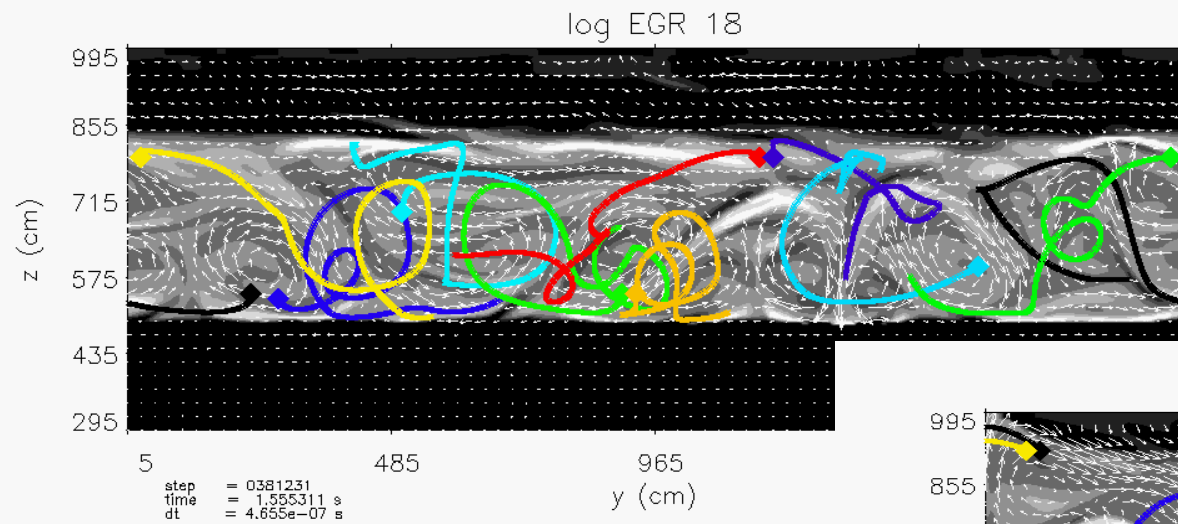
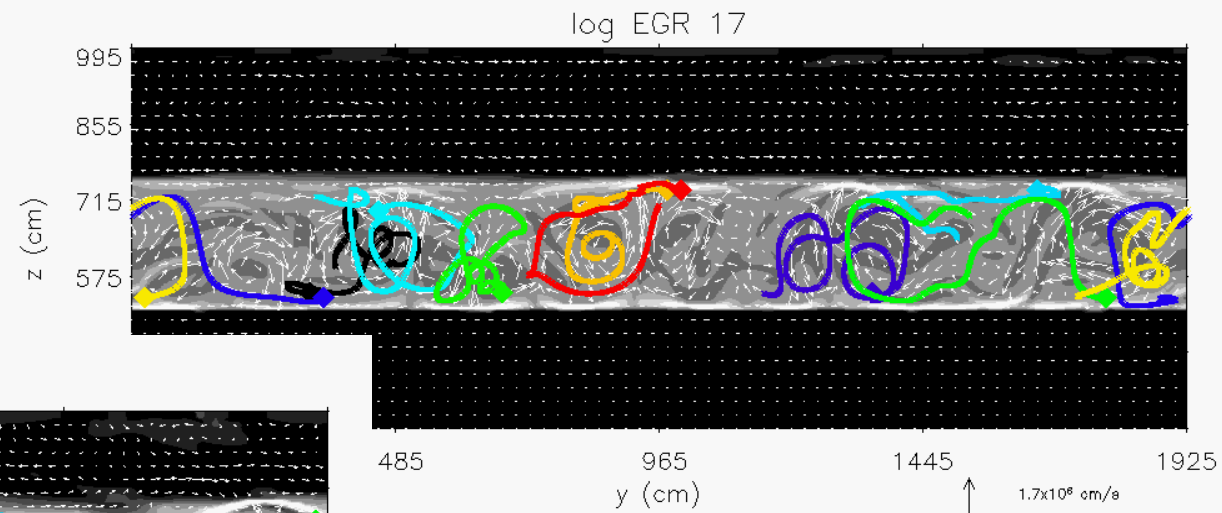
5 representative EGR levels (16, 17, 18, 18.5, 19)

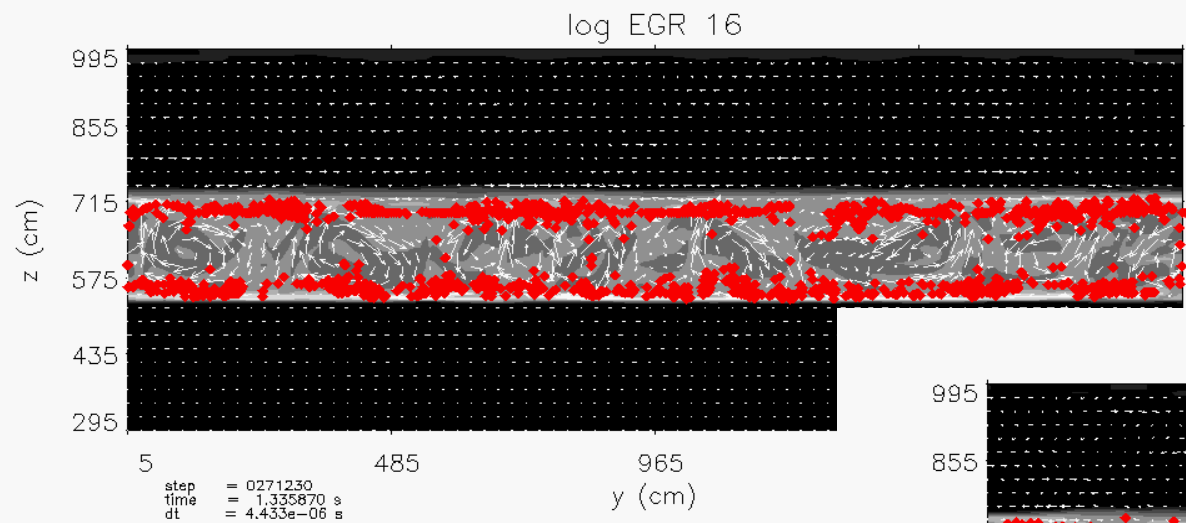
Several convective times

Forward Euler with 2D linear interpolation

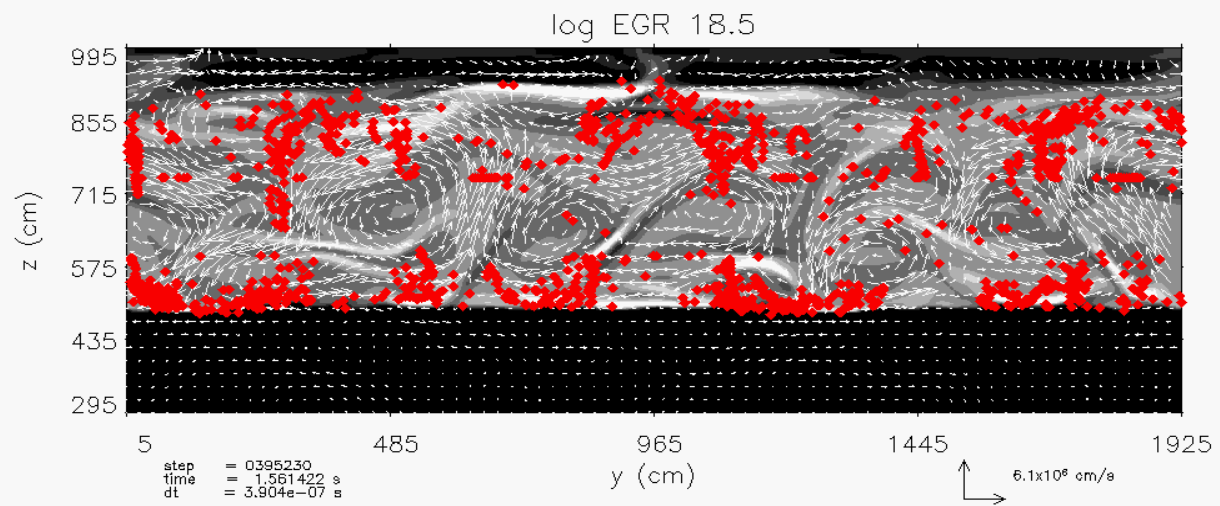
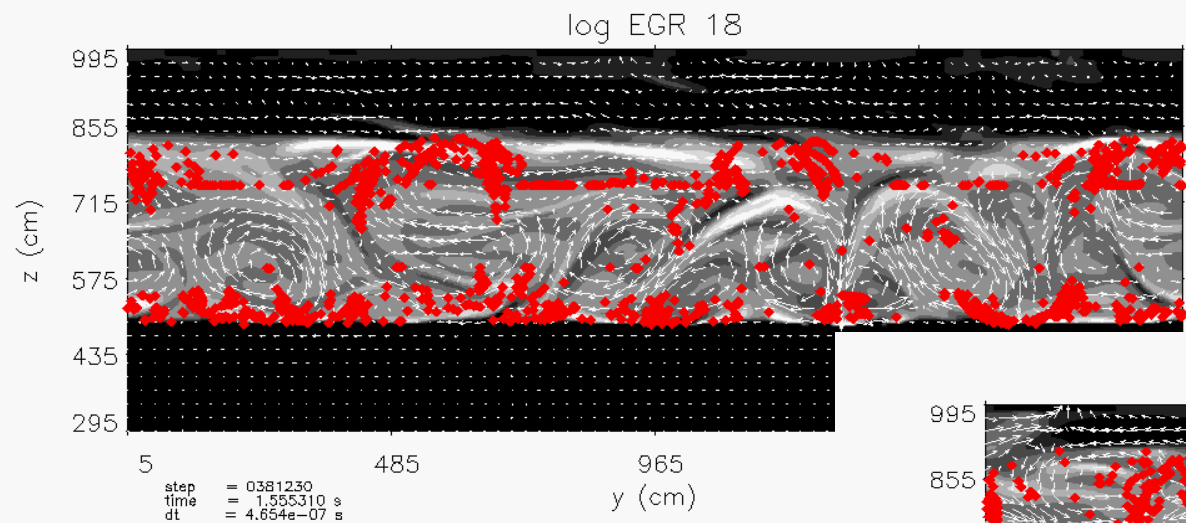
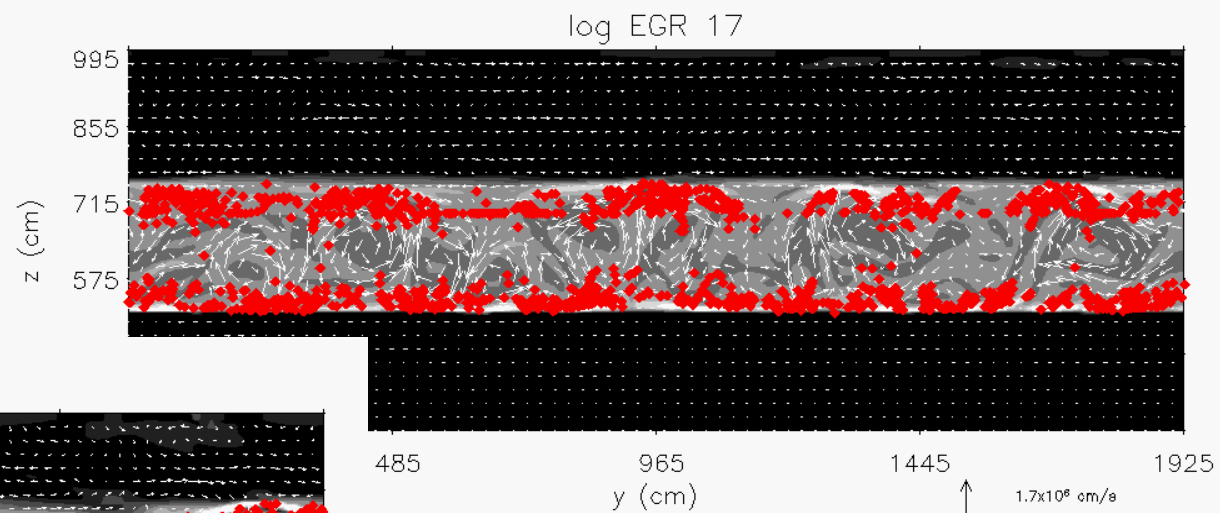


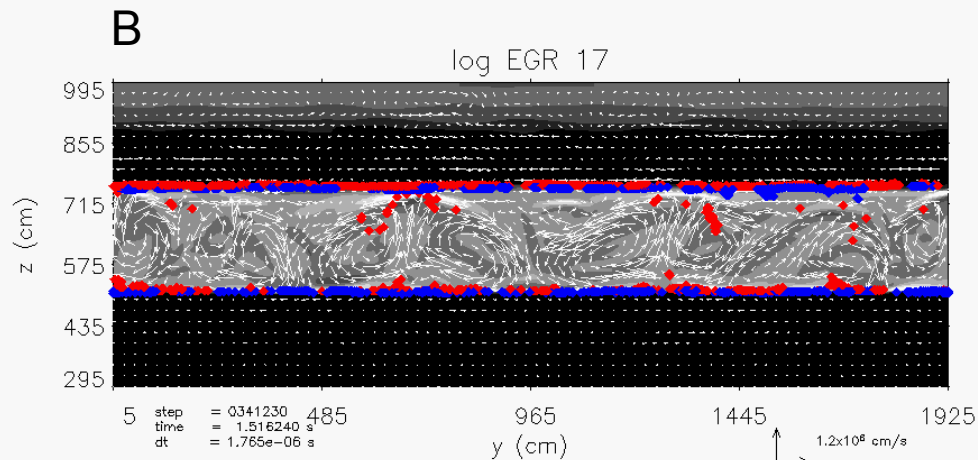
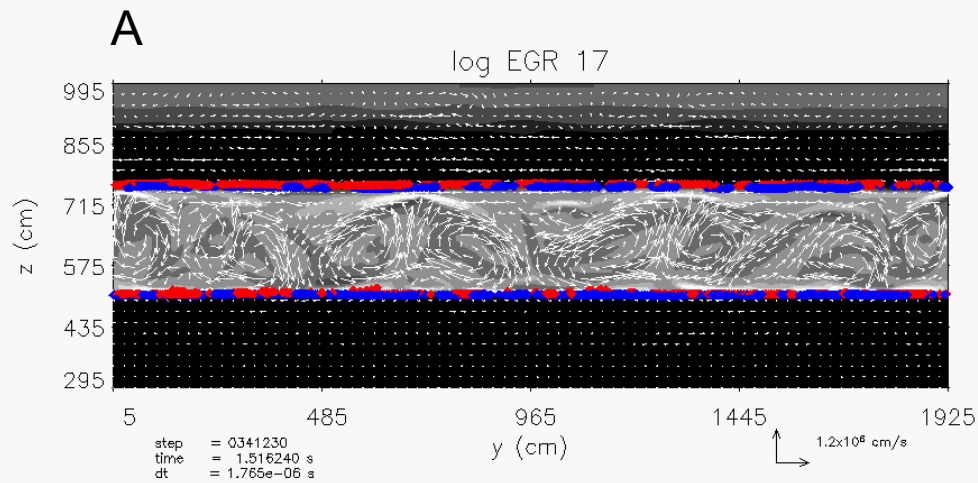
Under-, Over- penetration:
10 representative particle paths
(stream lines)





Under-, Over- penetration:
770 particle max/min position limits



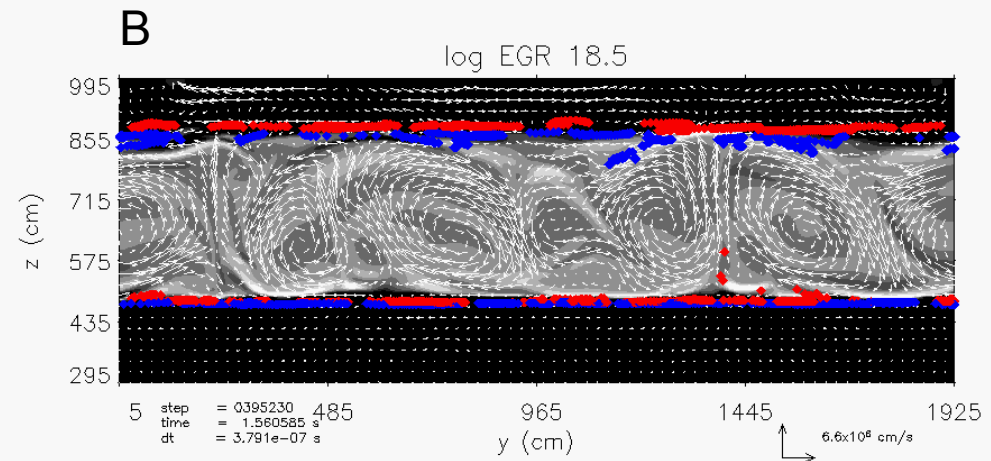
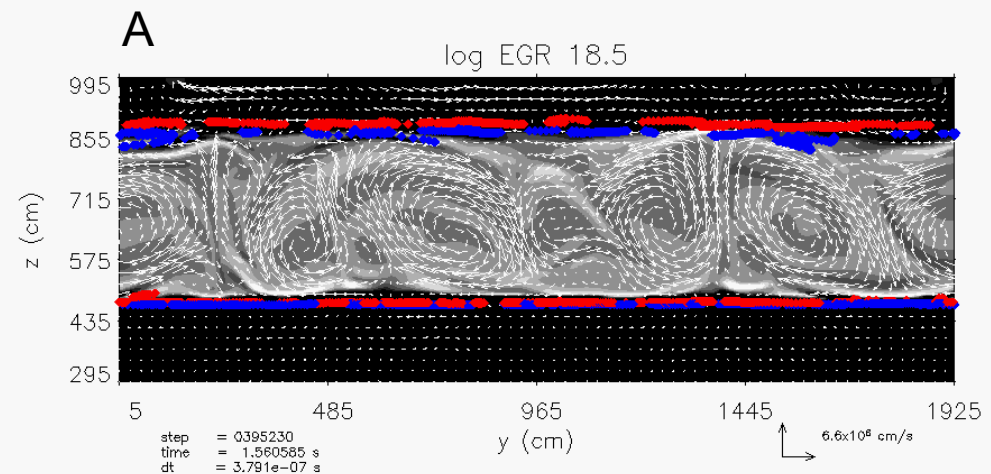


Blue = lowest particle position
Red = highest particle position

Reproducible results with extended domain
(386x205)

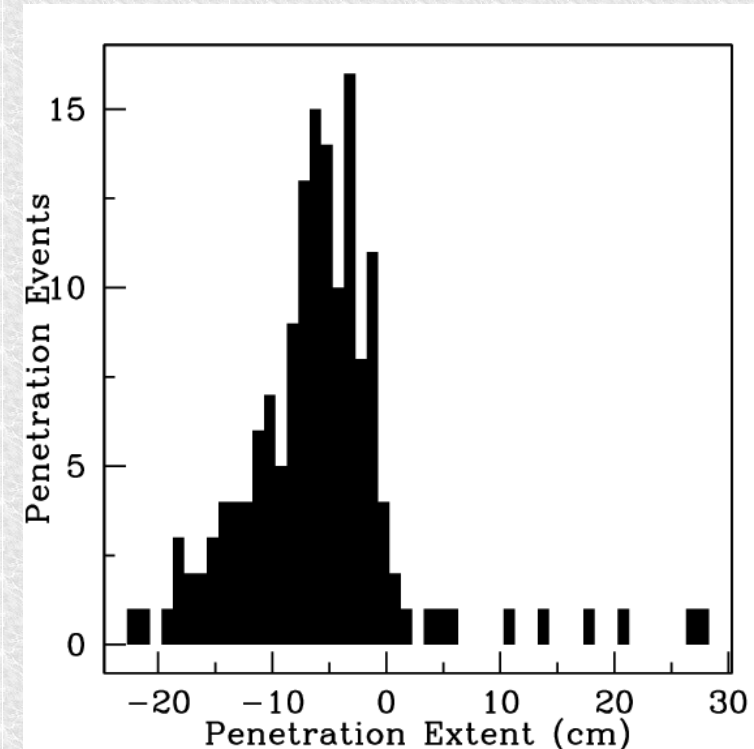
Bottom-, Top- penetration:
770 particle max/min position limits

For each EGR level, Study A's initial placement is 1 zone higher than Study B's



Tracer Analysis Findings

Log EGR	Under-penetration	Over-penetration
16	None	None
17	5 cm (1/40)	None
18	10 cm (1/20)	None
18.5	20 cm (1/10)	40 cm (1/5)
19	60 cm (1/3)	Indeterminate



- Under-, over-penetration are relatively *rare* events: < 15%
- Under-, over-penetration events are *temporary* and *spatially limited*
- Bottom-, top-penetration are very *sensitive* to initial placement
- *Vertical flows* stop while *lateral flows* dominate at convective boundaries
- *Convective modes* are necessary but not sufficient for penetration to occur

Non-Local Convection

- Mixing Length Theory: a *local* theory of convection commonly used as a model for convection in simulations

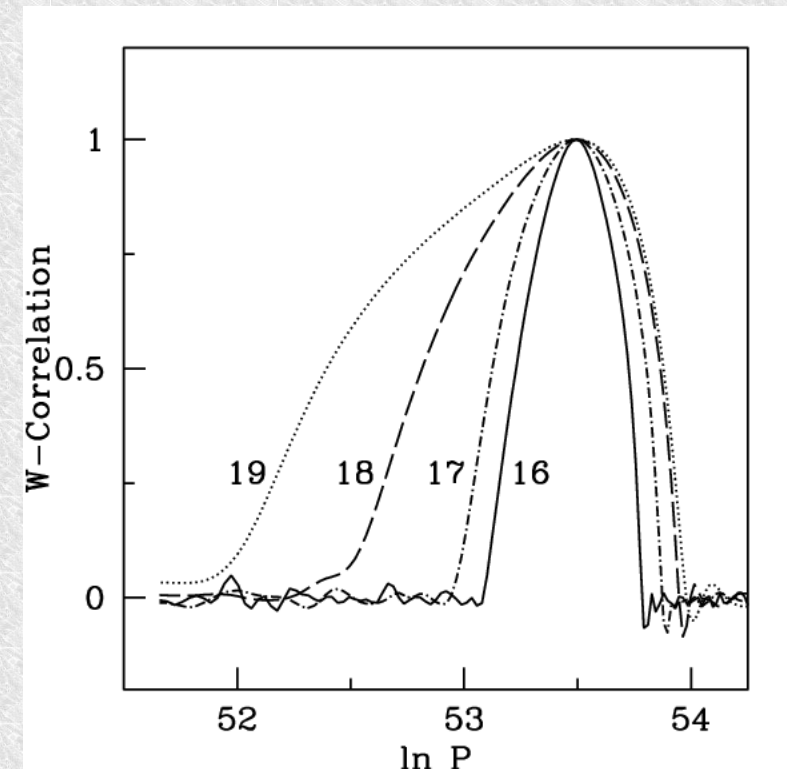
$$l = \alpha H_p \quad w \propto \alpha^2 \Delta \nabla$$

$$\Delta \nabla = \nabla - \nabla_{ad} \quad T' \propto \alpha T \Delta \nabla$$

$$F_{conv} \propto \frac{w'}{\alpha}$$

$$F_{conv}^2 \propto \alpha T'^3$$

- No consistent value of α can be determined from these relationships
- Practical value of $\alpha \sim 1$ to 2
- Present results suggest our simulated convection is *non-local*



Fluxes

- Fluxes: nuclear (F_{nuc}), radiative (F_{rad}), advective (F_{adv})

$$F_{nuc} = \int_0^{z_{top}} \rho \dot{s}_{3\alpha} dz$$

$$F_{rad} = -\kappa \nabla T$$

$$\frac{\partial F_{adv}}{\partial z} = w \left(\rho c_p \frac{\partial T}{\partial z} - \delta \frac{\partial P}{\partial z} \right)$$
$$F_{adv}(z') = \int_0^{z'} \frac{\partial F_{adv}}{\partial z} dz$$

- Light-curves cannot be accurately calculated with current model, because the surface of star is not presently modeled
- Significant differences between 1D and 2D flux behavior, attributable to convective energy transport in 2D
- 1D models need to properly account for the effects of convection in order to produce more realistic light-curves

Model	Rise time (s)	Fall time (s)
-------	---------------	---------------

1D	0.030	0.032
----	-------	-------

2D	0.103	0.014
----	-------	-------

$$F_{\text{Edd}} = 2.5 \times 10^{25} \text{ erg s}^{-1} \text{ cm}^{-2}$$

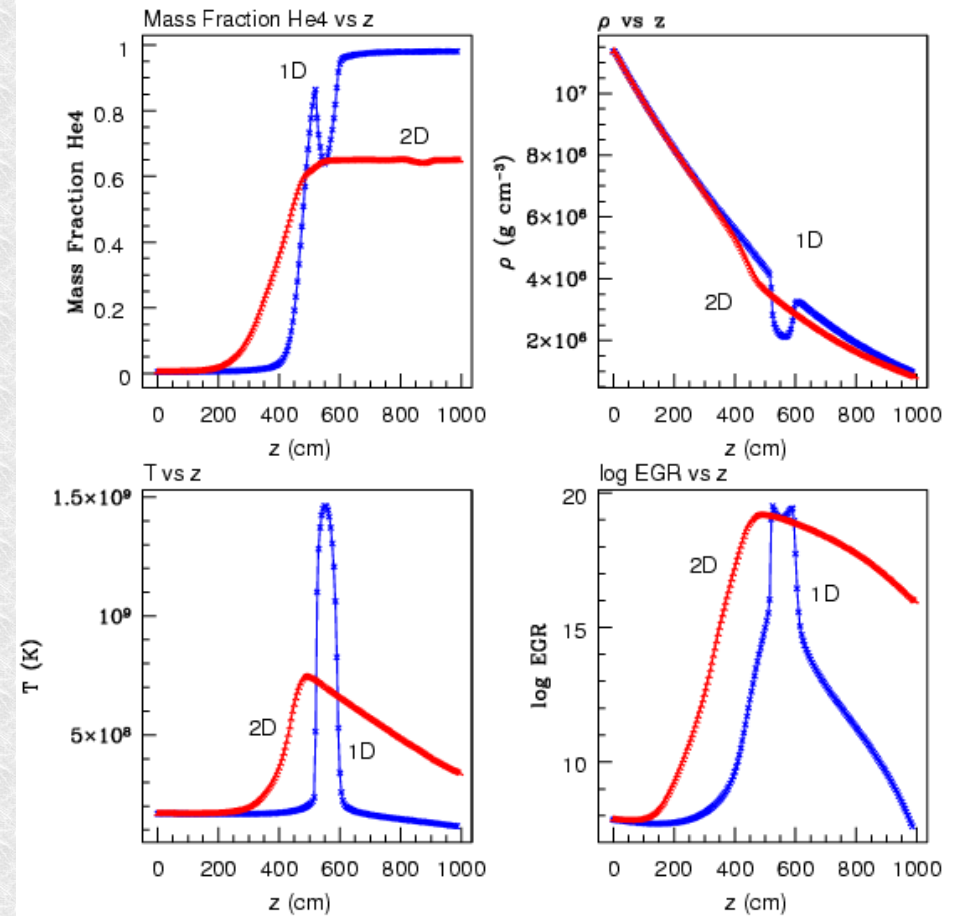
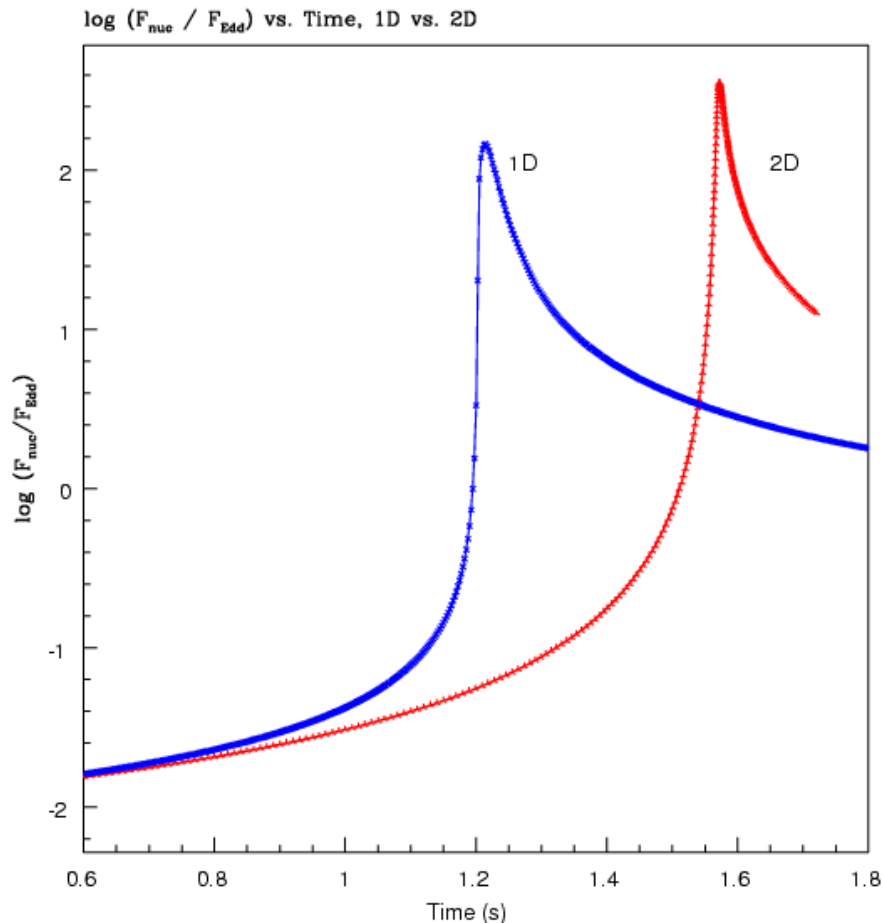
Rise time = $t(\text{Edd})$ to $t(\text{peak})$

Fall time = $t(e^{-1} \text{ peak})$ to $t(\text{peak})$

Nuclear Flux

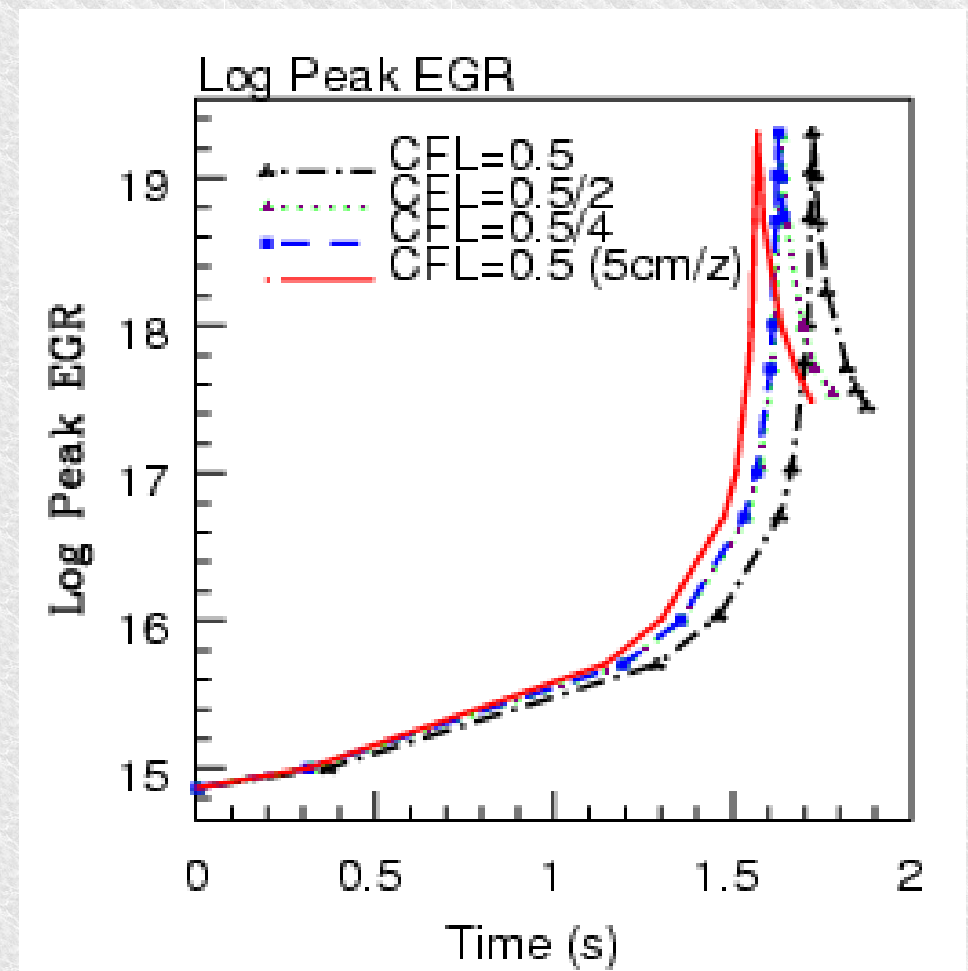
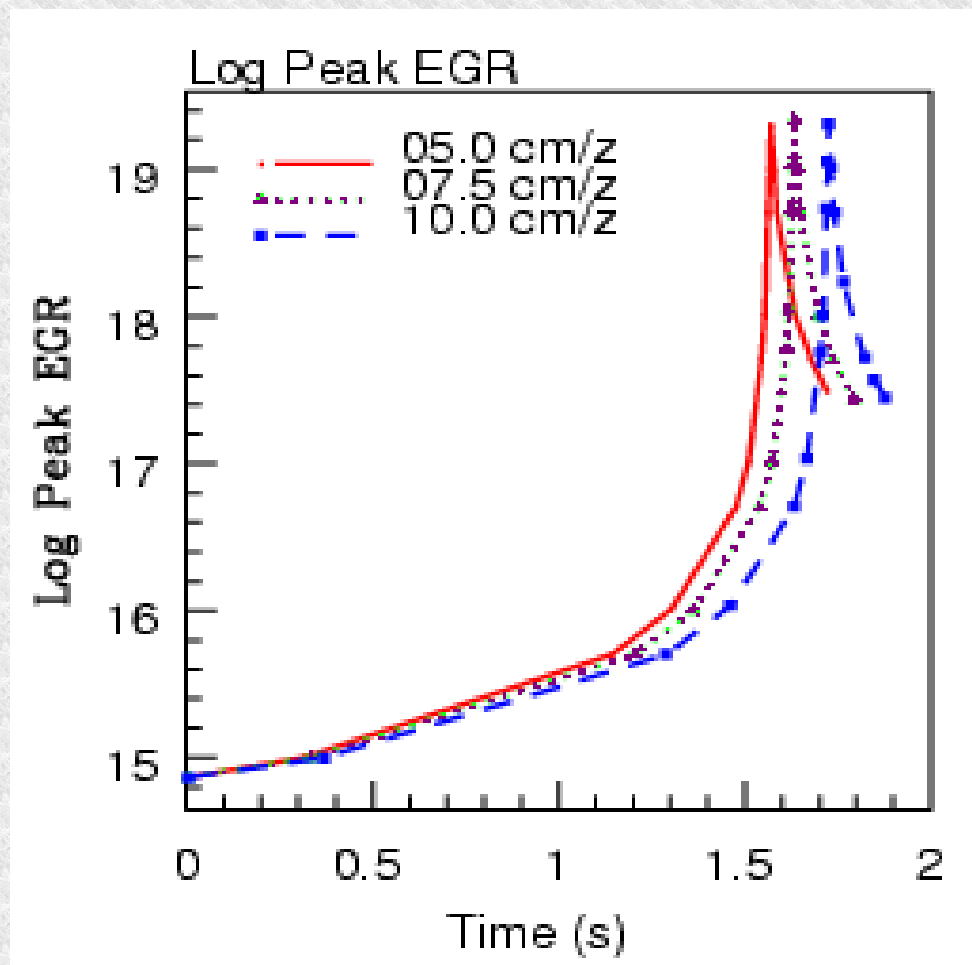
2D burst significantly delayed and greater in magnitude due to:

- convective cooling
- convective modification of ∇
- convective mixing of fuel



LMNA Model Validation

- Rigorous testing of separate modules for consistency (e.g. advection, burning, diffusion, elliptic solver, parallelism, etc)
- Refinements: spatial and temporal resolution, domain sizes:



The Present

Computational

- ✓ LMNA model successfully implemented in 2D
- ✓ LMNA verified by zone, time, domain refinements
- ✓ LMNA applied to model Type I X-ray burst in a 2D patch
- ✓ Computational time savings about a factor of 10-100 compared to fully explicit Eulerian methods

Astrophysical

- ✓ Burning layer relatively stationary
- ✓ Decidedly subsonic ($M < 0.10$)
- ✓ Convection self-organizes into Benard-like cells which fill up the convective layer:
 - height of major cells = height of layer
 - superadiabatic on average
 - vertically expands due to thermal diffusion, facilitates mixing from radiative regions
 - mixing is very efficient within it
 - limited penetration through convective boundaries on convective time-scales
 - $\nabla_{\text{ad}} < \nabla < \nabla_{\text{L}}$
 - $\nabla \sim \nabla_{\text{L}}$ at convective boundaries
- ✓ Convective dynamics significantly affects energy transport

The Future

Computational

- Time-dependent base state
- *3D*
- Rotation
- Additional nuclear burning networks
- Other coordinate systems
- Adaptive gridding
- Turbulence model

Astrophysical

- Astrophysical deflagrations:
 - Type I X-ray bursts
 - Pre-ejection stage of classical novae
 - Pre-detonation stage of supernovae
 - Hydrodynamics and burning in cores of main sequence stars