

Knowledge Pool

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Preface

This is a continuously developing database, which is a part of the DAVeMoS project. It aims at gathering concepts and evidence of the systemic impact of transport digitalisation and automation. The authors of this work welcome any feedback, questions and contributions that the readers may have. For further inputs please contact the corresponding author Martyna Bogacz on the following email address: davemos.library@boku.ac.at.

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14. Alternative power sources

- Hydrogen fuel cell **NEW**
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- Plugin hybrid vehicles **NEW**

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Chapter 1

Introduction

This work gathers and defines essential concepts related to automation and digitalisation of transport system together with the description of their impact, both negative and positive on **individual**, **systemic** and **economy level**. This knowledge pool is driven by the fact that automation and digitalisation are progressing quickly, although not uniformly across all areas within transport context. Therefore, to understand spectrum of possibilities that they bring, it is necessary to explain key concepts, demonstrate their level of maturity and current market penetration, and finally assess their impact on different levels. Given this approach, the page of each topic contains the following elements: **definition** of the phenomenon, **key stakeholders** who are the main parties responsible for and affected by the given technological development. Then, we include two subsections on **current state of art in research and practice**. The former one summarizes the most recent research in a given topic while the latter explains the current stage of implementation of given technology in the real world. Further, section named **relevant initiatives in Austria** covers the leading initiatives within given topic and potential for Austrian actors. Moreover, we provide the summary table of the impacts of the concept on selected **sustainable development goals** (SDGs). Beyond, to provide an objective measure of technology maturity within each topic we include so-called **technology readiness scale** (Williamson & Beasley, 2011) as described below:

Furthermore, we evaluate the readiness of a given technology to be acceptable in the society and how well it contributes to the public good using **societal readiness scale** (McCulloch, 2019):

Finally, we provide a list of **outstanding questions** and **links to additional sources** on the topic.

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Figure 1.1: Technology readiness scale

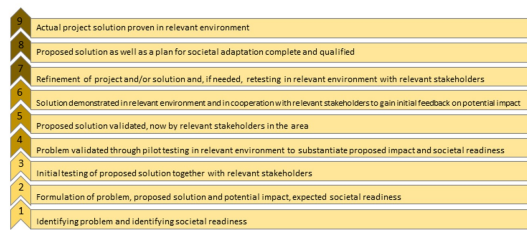


Figure 1.2: Societal readiness scale

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Chapter 2

Physical road infrastructure

2.1 Dedicated lanes for connected and automated vehicles (CAV)

Synonyms

AV-dedicated lanes, dedicated corridors

Definition

Dedicated lane for connected and autonomous vehicles features additional infrastructure or sensors to increase the reliability of Advanced Driver Assistant Systems (ADAS). Only automated driving vehicles are allowed to drive on these lanes. The typical applications include cooperative and adaptive cruise control based on sensors with the infrastructure, lane keeping, fuel use optimization and road pricing possibilities (Broek et al., 2011). The introduction of dedicated lanes for CAV is expected to have direct consequences on the traffic flow on the highways and a nearby road network. In particular, a study conducted in Singapore showed that dedicated lanes on the highways can reduce travel time of CAVs by approximately 25% (if the saturation on the lane is not reached) at the cost of a delay for conventional cars of approximately 7%, due to the reduced capacity (Ivanchev et al., 2017). They were also demonstrated to have a positive effect on fuel consumption. Moreover, the throughput, defined as a number of vehicles passing through the road in a given time interval, increased as a result of introduction of dedicated lanes for AVs (Kumar et al., 2020). This effect, however, was associated with a decrease in throughput of smaller roads due to the preference of AVs for highways because of time savings, which in turn can result in time loss for conventional cars. What is more, the benefits from

increased capacity of AV-only lanes can be further amplified through setting a higher speed limits for these lanes (Ye & Yamamoto, 2018). With respect to the demand for different road types the study found that the introduction of dedicated CAV lanes will increase the demand of conventional cars for major road (but smaller than highways) and minor roads as a substitution for more congested highways due to the dedicated AV lanes. In contrast, study by Chen et al. (2016) showed that the implementation of CAV dedicated lanes has a potential of maximizing traffic capacity on these lanes in a mix-traffic context while having effectively no impact on conventional traffic capacity. Further, in order to use efficiently CAV dedicated lanes, which may be underutilized at the early stage, it is proposed to allow conventional cars to enter the AVs-only lanes after toll payment. This solution stems from currently operational across the world High Occupancy Vehicle (HOV) lanes. This joint approach is claimed to improve the throughput of individual road as well as enhance system-wide flow distribution within the network (Liu & Song, 2019).

Key stakeholders

- **Affected:** Conventional Cars' Drivers, Car Manufacturers, Insurers
- **Responsible:** Road Infrastructure Agencies, Local and National Governments

Current state of art in research

Current research focuses on gathering the evidence of the impact of the introduction of dedicated lanes on traffic flow, driver behavior adoption, safety and efficiency. Furthermore, it analyses the factors which influence them, by testing different design and operation configurations, road types and utilization policies (Rad et al., 2020). Both, field operational testing and driving simulator studies have been conducted to investigate the influence of different designs of dedicated lanes on drivers in conventional cars and those featuring some degree of automation (Guin et al., 2008, Zhong, 2018). In particular, a number of studies compared distinct access types of dedicated lanes (Zhong, 2018, Yang et al., 2019). They showed that dedicated lanes with limited access performed better in terms of travel time and throughput compared to dedicated lanes with continuous access. Moreover, the probability of vehicles platooning was significantly higher on dedicated lanes with limited access. On the other hand, it was showed that collision rates near the entry or exit of these limited access lanes are higher (Rad et al. 2020).

Current state of art in practice

Currently state of Michigan together with several private partners including Ford and Alphabet Inc. are planning to dedicate 65 km of a highway between

2.1. DEDICATED LANES FOR CONNECTED AND AUTOMATED VEHICLES (CAV)17

Detroit and Ann Arbor for the sole movement of autonomous vehicles including buses and shuttles (Krisher & Eggert, 2020). Similar initiatives are taking place in other countries, for instance, China set out to build nearly 100 km of 8-lane highway linking Beijing and the Xiongan New Area, from which 2 lanes will be allocated for the automated traffic. The completion of the construction phase is predicted by the end of 2020, while its opening is for traffic is expected in June 2021 (Syncedreview.com, 2020). In Europe, there is on-going SHOW (SHared automation Operating models for Worldwide adoption) project which aims to deploy about seventy automated vehicles in 21 European cities. To assess how they can best be integrated vehicles will be used in different settings in mixed traffic and dedicated lanes. However, for safety reasons the driver will be on-board (CORDIS, 2020).

Relevant initiatives in Austria

- tugraz.at
- ait.ac.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Fuel consumption reduced	+	Environmental sustainability (7,12,13,15)	Ivanchev et al., 2017
Individual	Travel time reduced	+	Sustainable economic development (8,11)	Zhong, 2018; Yang et al., 2019
Systemic	Collision rate reduced	+	Health & Wellbeing (3)	Zhang et al., 2020
Systemic	Emissions rate reduced	+	Environmental sustainability (7,12,13,15)	Al Alam et al., 2010
Systemic	Congestion	~	Sustainable economic development (8,11)	Ivanchev et al., 2017; Kumar et al., 2020

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Novel designs tested	+	Innovation & Infrastructure (9)	Guin et al., 2008; Zhong, 2018; Krisher & Eggert, 2020
Systemic	SHOW EU initiative	+	Partnership & collaborations (17)	CORDIS, 2020

Technology and societal readiness level

TRL	SRL
5-6	1-3

Open questions

1. What are the potential benefits of dedicated AV lanes when coupled with smart platooning strategies?
2. How and to what degree will joint concepts by automotive sector, fleet and road operators will improve traffic management establishing dynamic traffic regulations even across borders?
3. What are the roles and responsibilities of the different stakeholders of physical infrastructure for connected and automated vehicles?
4. Should the vehicle cope with any road infrastructure, and if not, what demands can be set to adapt the existing infrastructure?
5. How to ensure continuity between those different environments?
6. Which tools (e.g. micro- and macroscopic transport modelling, impact assessment) can enable cities to assess the impact of automated vehicles on their physical road infrastructure and balance the needs of automated vehicles against the needs of existing modes (conventional vehicles, public transport, pedestrians and cyclists). (ERTRAC, 2019)

Further links

- knowledge base
- show project

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2.2 Operational design domains

2.3 Rail crossing information system

2.4 Electric road system

Synonyms

ERS

Definition

Electric Road System (ERS) is a technological solution that is aimed at charging and transferring power from the road to the vehicles driving along that road. It can be considered an alternative for sustainable transport where it supports the use of hybrid and electric vehicles. There are three main types of ERS (Muelaner, 2020):

- **Catenary Systems** are overhead lines suspended about 5 meters above the road which are typically used for trams and electric vehicles but sometimes can also be used along highways to power heavy commercial vehicles. Overhead lines are cheapest and the most mature form of ERS because of their resemblance with power systems used for railways or trams. They require vehicle to be equipped with pantograph which connects it with the line accommodating lateral and vertical movements. For this reason, catenary systems are the most suitable for large commercial vehicles and the lack of compatibility with small, private cars is considered a major disadvantage. What is more, the overhead lines provide a major hazard in case of road accidents for all road users. Moreover, they negatively impact the visual aspects within the areas in which they are installed, potentially posing issues for public acceptance (Muelaner, 2020).

- **Conductive tracks** are metal rails which are embedded on (or into) the road surface and provide power through a contact with a pick-up point underneath the vehicle. For safety reasons tracks are divided into small segments rather than continuous, so that the electrical connection is running only when the vehicle passes over them. In contrast to overhead lines, the conductive tracks can be used for vehicles of different sizes. Their advantage is also clear in terms of lower installation costs. Sweden has been a testing ground for larger scale use of this electric road system (Muelaner, 2020).
- **Inductive tracks** are conductive coils which are placed below the surface of the road to provide energy by inducing an electric current in the coil placed under the vehicle driving along the track. Their advantage is smaller maintenance requirement as compared to conductive tracks, however, a system failure would require costly work to access underground infrastructure.

Overall, the wider use of ERS would reduce the need for construction of costly charging station, eliminate waiting time while the vehicle is charging, significantly increase driving range of hybrid and electric vehicles and facilitate reduction in size of batteries installed in the private cars which directly translates into more efficient performance.

Key stakeholders

- **Affected:** Private and commercial drivers, Private transportation companies, General public
- **Responsible:** Local councils, National governments, Construction companies, Power and petroleum companies, Road power technology firms, Automotive manufacturers

Current state of art in research

Current, research focuses on testing of the ERS solutions to enable deployment on a larger scale, extend applicability to a new type of vehicles, increase their efficiency and assess their transport decarbonization potential.

Since 2008 the South Korean company OLEV (branch of KAIST University) has been working on inductive power transfer and since 2013 two electric buses have been in operation on public roads, inside university campus (Kelion, 2013). Nonetheless, this system is currently outdated and results as a low-speed system within local public transport. In 2016 an initial testing of the overhead lines has been conducted in Germany on Siemens' 2 km test track in Berlin, at the same time in Sweden a full integration with Scania vehicle has been achieved. More example include Volvo and Alstom's cooperation on testing of conductive

tracks on the 400 m test side in Hällered, Sweden (Möller, 2017). Similarly, Swedish Transport Administration in collaboration with Elonroad under EVolution Road project constructed a 1 km of demonstration road in Lund to test the performance of an electric bus. On the other hand, research on the efficiency of inductive tracks conducted in France and Italy showed that their performance depends on the precision of alignment between the track and the coil in the vehicle (Muelaner, 2020). Finally, a study by Börjesson et al. (2020) showed that use of electric road solution can decrease operational costs for freight operators due to a switch from diesel to electricity. Consequently, the social benefit of this technological solution outweighs its cost. Moreover, it has been concluded that use of ERS offers significant reduction in carbon emissions.

Current state of art in practice

At the moment, there are multiple companies offering power technologies such as Elways, Alstom or Elonroad, to name a few. The proliferation of such companies enabled active testing and implementation of different ERS solutions around the world.

Since 2016 overhead lines have been successfully deployed on public roads in Sweden (E16 highway outside Gävle) and the USA (City of Carson). Currently, in Germany three tests sponsored by Federal Ministry for the Environment, Nature Conservation and Nuclear Safety (BMU) are taking place. In Hesse and Schleswig-Holstein 5 km of motorway was electrified at the beginning of 2020 (Wettengel, 2019) while in Baden-Württemberg, 4 km of a national highway will have an overhead line system in operation at the beginning of 2021. For the moment, these overhead lines provide power to freight vehicles, however an issue arises among the truck fleets going through Germany from Eastern Europe, because they are lacking modern hybrid trucks equipped with pantographs on the roof.

Further, between 2016-2017 project VICTORIA led by Spanish energy company Endesa developed first dynamic inductive load systems for a bus line in Malaga, Spain. Similarly, EU project FABRIC has been conducted in Torino, Italy and Satory in France (Tongur & Sundelin, 2016).

In terms of cost analysis, an example from the UK shows that inductive tracks provide cost advantage, where the installation of 1 mile (1,6 km) of inductive tracks on a two-lane road costs around 1.4 million euros. If these were to be installed in all UK highways the costs would come up to around 13 billion euros. At the same time, the cost of additional electricity capacity required for hydrogen in FCEV sums up to 140 billion euros. Additionally, cost-benefit analysis showed that if most vehicles used ERS, the savings resulting from smaller batteries in electric cars would outweigh the costs of ERS construction.

Interestingly, ERS has not been particularly popular in Austria, potentially due to presence of well-developed railway network which, thus far, dominated

freight. In particular, critics describe the construction of electric highways as *a waste of money*, because it only benefits companies that equip their fleets with the necessary vehicles with overhead line system (Traktuell.at. 2020).

Relevant initiatives in Austria

- scania.com
- electrive.net

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Potential for lowering purchasing price of electric cars with smaller battery requirement	+	Sustainable economic development (8,11)	Muelaner, 2020
Systemic	Reduction in emissions and use of fossil fuels	+	Environmental sustainability (7,12,13,15)	Tongur & Sundelin, 2016; Moeller, 2017; Boerjesson et al., 2020
Systemic	Cost saving compared to hybrid vehicles; long-term maintenance costs uncertain	~	Sustainable economic development (8,11)	Muelaner, 2020; Boerjesson et al., 2020
Systemic	Novel designs tested	+	Innovation & Infrastructure (9)	Kelion, 2013

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Increased cross-industrial collaboration	+	Partnership & collaborations (17)	Kelion, 2013; Wettengel, 2019

Technology and societal readiness level

TRL	SRL
5-9	4-7

Open questions

1. What is the potential of the use of ERS beyond freight vehicles?
2. How do stakeholders develop new business models that support ERS deployment?
3. Do public authorities have to own the electric roads?
4. What are the long-term costs associated with the maintenance of ERS?

Further links

- fcirce.es
- engineering.com
- bbc.com
- cleanenergywire.org
- trimis.ec.europa.eu
- Alstom
- Elonroad
- KTH report
- Scania
- insideevs.com
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- Siemens
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2.5 High occupancy toll lanes

2.6 Public transport priority systems

Synonyms

pre-emption of public transport vehicles, public transport priority (PTP), Transit signal priority (TSP), road-space priority (RSP)

Definition

To encourage people to use public transport and thereby travel more sustainably, it is necessary that public transport operates reliably and efficiently. For example, public transport is the most efficient mode of transport at the intersections, where the difference in the number of people who can pass through a junction in a given time is particularly impressive between cars and public transport. The ratio is between 1 to 10 and 1 to 20 (Schwendinger, 2019). In contrast, a bus at full capacity that is stuck in congestion increases the travel time of many more passengers, compared to single cars in a similar position. Time delays due to traffic signals account for up to 25% of the total travel time of buses (Seredynski et al., 2015). Furthermore, energy prices and emissions generated become more relevant for public transport operators, to compete with the

motorized private transport (Gassel et al., 2012). The implementation of public transport priority measures can help improving time and energy efficiency of public transport service. The delays caused by traffic signals can be reduced by the introduction of Transit Signal Priority (TSP) such as early green, green extension, phase rotation, phase insertion and actuated transit phase, favouring public transport (Seredynski et al., 2015). TSP systems can increase the attractiveness of public transport, reduce the operation cost and reduce tailpipe emissions and energy use. On the other hand, they increase the travel time of general traffic, therefore the acceptance is limited (Seredynski et al., 2015). Another widely used systems are separated bus lanes or independent tracks for trams. These are especially relevant in 30 km/h zones, so the public transport vehicles can be excluded from the regulation. But since space is a limited good, independent lanes or tracks are not always possible to implement (Schwendinger, 2019). For Vienna priority of public transport vehicles is of high importance (WIENER STADTWERKE GmbH, 2018). The first measures to shorten the travel time of the bus route 15A at Wienerberg took effect in Autumn 2018. Measures to give priority to public transport are also becoming more important in other cities such as Linz, Graz or Innsbruck. Trams in Graz have priority switching at almost all traffic lights, while there is a further need for bus lines, especially for those from the surrounding area (Schwendinger, 2019). To promote e-mobility, some countries introduced bus lane access to e-vehicles (Figenbaum et al., 2015). Wiener Linien is clearly against this measure, because cars, regardless of their propulsion system, cause delays in the bus lanes and slow down public transport (WIENER STADTWERKE GmbH, 2018).

Key stakeholders

- **Affected:** Road Users, Public Transport Users, Public Transport Operators
- **Responsible:** State Authorities, Transport Infrastructure Operators, Technology Providers

Current state of art in research

Current research aims at building on the existing solutions such as TSP and proposes so-called Green Light Optimal Speed Advisory (GLOSA) driver assistance systems. A multi segment GLOSA can take several lights in a sequence on route of a bus into account and allows the driver to adjust the speed, so that the bus can arrive at the intersection when the light is green. By that, the comfort of passengers can be increased and the fuel consumption as well as the tailpipe emissions be decreased, without negatively affecting the general traffic (Seredynski et al., 2014). However, Stahlmann et al. (2018) argue that so far, most GLOSA simulation studies are too optimistic in terms of communication

performance and recommend further improvement of GLOSA systems. Moreover, the Green Light Optimal Dwell Time Advisory (GLODTA) systems look into exploiting additional dwell time at the near-side bus stop (Seredynski et al., 2014). According to Seredynski & Viti (2017) they can support on-route battery charging of electrical buses and also replace existing holding strategies used to regulate punctuality of bus services. Due the limited acceptance of TSP systems, more research regarding the efficient use of green time provided to public transport is needed. Therefore, the focus is on the improvement of the bus detection methods. The latest TSP are working with GPS-based Virtual Detectors (VD), which eliminate the need of on-street detection infrastructure, but their disadvantages is low accuracy (Seredynski et al., 2015). Haitao et al. (2019) developed an integrated and systematic framework for the optimization of bimodal urban networks using 3D-MFDs, considering the complexities of bimodality to manage traffic more efficiently and provide public transport priority. Results of the evaluation show that the proposed strategy always performs better than existing perimeter control schemes in terms of passenger mobility.

Current state of art in practice

A common measure in use is the positioning of stops before intersections, which combines the standing time at the traffic lights with the passenger change and thus leads to travel time reductions (Schwendinger, 2019). All around the world Bus Rapid Transit (BRT) systems have gained popularity. Cervero (2013) defines them as “bus-based system that mimics the high-capacity, high-performance characteristics of urban rail systems at a much lower price” that runs either on exclusive transit-ways, dedicated bus lanes or some grade of separation. Regarding TPS, the cloud-based systems using GPS locations are standard technology (see Figure 1). However, there are still many outdated systems in use that are based on short-range radio. These systems require that all traffic lights are equipped with receivers. All buses in a fleet need special transmitters and an onboard system for positioning, which makes it an overall expensive system. At the same time, this technology is rather unreliable and maintenance intensive (SWARCO, 2021).

Relevant initiatives in Austria

- digitales.wien.gv.at
- wienerlinien.at
- kapsch.net-1
- kapsch.net-2
- swarco.com
- mobility.siemens.com

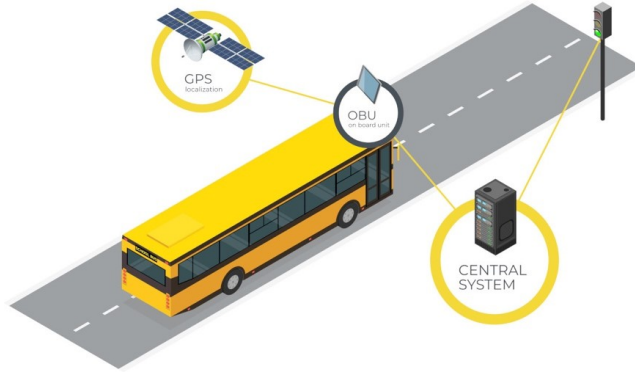


Figure 2.1: Smart priority for public transport (SWARCO, 2021)

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Higher equality for people who do not drive	+	Equality (5,10)	Litman, 2017; Cervero, 2013
Individual	Less travel time for public transport users, more travel time for car users	~	Sustainable economic development (8,11)	Seredynski et al., 2015
Systemic	Public transport becomes more competitive compared to other transport modes	+	Equality (5,10)	Schwendinger, 2019

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Less fuel consumption	+	Environmental sustainability (7,12,13,15)	Gassel et al., 2012; Seredynski et al., 2015
Systemic	Transit is often the most cost-effective mode	+	Sustainable economic development (8,11)	Litman, 2015
Systemic	More infrastructure for public transport	+	Innovation & Infrastructure (9)	Cuthill et al., 2019

Technology and societal readiness level

TRL	SRL
4-8	5-8

Open questions

1. Who is responsible for the implementation of PTP systems?
2. How will Vehicle-to-Vehicle (V2V), Vehicle-to-Infrastructure (V2I) and in future Vehicle-to-Pedestrian (V2P) change PTP systems?
3. How could also emergency vehicles be prioritised?
4. How to deal with mixed fleets - half new, half old?
5. What are the benefits compared to the costs?
6. Which standards should be used?

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2.7 Transformation of public space and digital solutions

Chapter 3

Highway infrastructure management

3.1 Unmanned aerial vehicles for infrastructure maintenance

Synonyms

Drones, remotely piloted vehicles, remotely piloted aircraft, uav

Definition

Unmanned Aerial Vehicles (UAVs), commonly known as drones are promising technologies that can be used in inspection and data gathering for infrastructure maintenance and management purposes. These include, for example, detection of wear and tear, monitoring of the progress at a highway construction site or the analysis of traffic (Frederiksen et al., 2019). UAVs typically include a portable control station for the human operator and under current legislation their operation in urban areas is limited to flying within visual line of sight (VLOS). UAVs typically feature various sensors and recorders, including video, far and near infrared, radar or laser-based range finders and specialized communication devices (Shaghlil & Khalafallah, 2018). Majority of them can transfer real-time data between the UAV and the control station. Moreover, some feature additional onboard data storage capabilities for enhanced data collection (Shaghlil & Khalafallah, 2018). The use of drones for infrastructure-related tasks provide not only savings with respect to time, labor and costs, but they also allow for reduction in risks when dangerous operations usually performed by human can be substituted with drones. Finally, the environmental impact is

diminished when drones, which produce considerably less CO₂, are used instead of currently employed helicopters. Nevertheless, the use of drones as a tool for inspecting infrastructure can also pose certain challenges with respect to current technology, legal framework, privacy concerns and social acceptance.

Key stakeholders

- **Affected:** Direct users of the roads and beneficiaries affected by the supply of transport services
- **Responsible:** Government agencies responsible for planning, executing, and financing of maintenance activities, citizens, contractors and subcontractors, private companies and manufacturers

Current state of art in research

Current research efforts and field trials-based studies are advocating the case of using UAVs for bridge inspection and monitoring. Previous study presented a proof of concept of utilising UAVs for bridge and high mast luminaires. Several experiments in controlled conditions were performed to test UAV response in relation to wind conditions. Moreover, image quality was examined in different flight scenarios, low light conditions, altitude and payload (Otero et al., 2015). Overall, the results are in favour of using drones for infrastructure inspections, not just in terms of saving human labor but also detecting the damages. The advantages of the drone use were also demonstrated in terms of reduced traffic control and decreased use of under bridge inspection vehicles (Zink and Lovelace, 2015). On the other hand, specific skills of the drone operators were found to hinder efficient use of drones for large-scale bridges (Wu et al., 2018). Further, some technological barriers also slow down the popularity of drones in infrastructure inspection, where an average flight time of the drone given its battery life is approximately 30 minutes. Therefore, current research aims at increasing the energy-efficiency by the use of path planning and algorithms to minimize energy utilization while maximizing coverage for traffic monitoring (Outay et al., 2020).

Current state of art in practice

Current use of drones is heavily regulated by national and international governments worldwide where the most considerable restriction is the requirement for drones to remain under VLOS of the controller. Beyond, the regulatory bodies put forward various specification with respect to physical aspects of the drones such as weight or sensors, training requirement of the operators and drones', data acquisition regulations and operation itself such as flight timeframe, altitude etc. (FAA, 2016; Outay et al., 2020). All of them, significantly restrict

fast and wide application of drones in different areas. Therefore, the authorities attempt to provide regulations to tackle safety and privacy as well as noise concerns of the citizens. At the moment drones are used in oil and gas industry to conduct local surveys in off-shore facilities (Undertaking, 2016). Meanwhile in the transport sector, Danish company Dronops, after safety clearance, has been granted permission from Danish Road Authority to fly along a highway to monitor the traffic, where drone provides data from multiple sensors as well as video recordings. At the moment, the drone can only fly in good weather conditions and it is cable-linked to its power source located on the ground to allow for continuous day-long monitoring at 120 m above the ground. Importantly, the output data is used by Danish Road Authority and local council (Frederiksen et al., 2019).

Relevant initiatives in Austria

- smartcity.wien

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Employees risk reduced	+	Health & Wellbeing (3)	Outay et al., 2020
Systemic	Road safety increased	+	Health & Wellbeing (3)	Outay et al., 2020
Systemic	Emissions rate reduced	+	Environmental sustainability (7,12,13,15)	Outay et al., 2020
Systemic	Job posts created	+	Sustainable economic development (8,11)	Jenkins & Vasigh, 2013
Systemic	Faster road infrastructure innovation	+	Innovation & Infrastructure (9)	Fan & Saadegh-vaziri, 2019

Technology and societal readiness level

TRL	SRL
3-4	5-7

Open questions

1. What are the factors influencing social acceptability of drones?
2. What actions from the policymakers need to be undertaken to minimize cyber-attacks?
3. What aspects need to be considered by the governments before the integration of more sensors to record other relevant data along with the integration of video data with other geospatial information?

Further links

- rolandberger

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3.2 Electric charging stations

Chapter 4

Traffic management

4.1 Congestion charging

Synonyms

Congestion charging scheme, CCS

Definition

The congestion charging is an example of (urban) road pricing system aimed at reducing congestion and pollution in zones where it applies. The regulations and prices of congestion charges can vary based on spatial, temporal or modal basis (Santos, 2005). Congestion charges are used to influence the traffic demand and discourage the use of roads at congested times (Valletta, 2015). The major congestion charge zone in Europe was introduced in London in 2003 and it imposed a fee for all the vehicles that drove into or through the designated area in the city centre between 7:00 and 18:00 (Mon-Fri) (Munford, 2017). It included a 90% discount for residents, nevertheless, at the time it was considered the most radical transport policy to have been implemented in the recent decades (Banister, 2003). Nearly 20 years later, congestion charges are an effective measure to protect city centres, used in several cities around the world such as London, Singapore, New York, Stockholm, Milan, Bergen or Gothenburg, even though they are still rather unpopular within the society. The research findings with respect of the effectiveness of this transport policy on a number of aspects are summarized in the *research section*, below.

Key stakeholders

- **Affected:** Local residents, car and truck drivers, motor bikers, cyclists, pedestrians
- **Responsible:** Local and national governments, transport authorities

Current state of art in research

Given that congestion charging has been used for some time now, the existing research focuses mainly on the effects of the introduction of congestion charges on different areas that may be affected, such as air quality, housing prices, traffic improvements, travel behavior and road safety, economic aspects and social acceptability.

Starting with public attitude towards congestion charging schemes, it is fair to say that public opinion is divided and there are several factors which influence the outlook on this transport policy. For example, study by Grisolia et al. (2015) showed the differences in acceptance levels between drivers and non-drivers, where the latter ones are more favorable to congestion charging systems. Moreover, Hamilton (2011) came to a similar conclusion where he found that higher frequency of car use was associated with lower acceptance of congestion charges. Further, the study showed that public acceptance of congestion charging is likely to increase with more experience with the charging system but also among individuals with high value of time and pro-environmental interests as well as those who are in favour of high degree of government intervention.

What is more, a number of studies showed that congestion charging has led to a significant improvement in traffic conditions where travel times decreased by 19% on average. Beyond, 14.5% decrease of the private vehicles' presence in the affected area was observed and the use of public transport increased by up to 18% (What Works Centre for Local Economic Growth, 2020; Gibson & Carnovale, 2015; Amelsfort & Swedish, 2015).

With respect to road safety the results are ambiguous depending on the location. For example, the road safety improved in London and Milan, however in Rome it deteriorated following the switch from cars to motorcycles leading to higher accidents rate (Amelsfort & Swedish, 2015).

Next, a number of studies demonstrated the positive impact of congestion charges on air pollution within the targeted zones, where the levels of CO_2 decreased by 19.5% on average and NO_x (nitrogen oxides) decreased by 10.5% (Amelsfort & Swedish, 2015).

In terms of economic effects, it has been showed that implementation of congestion charges can increase house values within the zone (potentially due to additional exemptions for residents). For example, following the introduction of congestion charge in London residential property values rose by 5%. At the

same time, congestion charging can lead to a reduction in retail property values. In Singapore after the implementation of road pricing scheme the retail real estate prices decreased in the targeted zone (Amelsfort & Swedish, 2015; Agarwal, 2015). Further, study by Percoco (2014) found that the introduction of road pricing system reduced house prices in the affected zone. In conclusion, literature shows a mixed effect of congestion charges on property values, depending on specific location and additional regulation and exceptions that are in place.

Current state of art in practice

Nowadays there are different functioning models of congestion charging schemes around the world. One broadly used model is the *zone/cordon-based charges* which is based on the idea of geographic boundary so that charges are implemented when entering or leaving the zone (or both). Henceforth, travelers within the zone do not incur the cost. This contrasts with so-called *area charging* where the fees apply to all the drivers traveling or parking within the designated area. The first one may be thought of as a ‘per passage charge’ and the latter ‘once per 24h charge’ when the fees are charged daily. Cordon-based charging is currently used in multiple Norwegian cities (eg. Bergen and Oslo), Milan or Durham while area charging systems is present in London.

What is more, initially a number of exemptions were available for low emission and alternative fuel vehicles such as all-electric cars and plug-in hybrids however local authorities gradually moved away from these discounts (Chris, 2016). For example, in Vienna there are several regulations for the entry of company vehicles with different levels of emissions into the city center. These were first introduced in 2014 and they require all the business vehicles to have an environmental badge known as ‘Umwelt Pickerl’ to access the city. Moreover, there is an ‘Emergency Scheme’ in Vienna which becomes effective as soon as the certain pollution limits are exceeded. As a result, and depending on the severity of the event, either a recommendation to switch to public transport is announced or vehicles with internal combustion engines can be banned from driving (Sadler Consultants Ltd, 2021).

Relevant initiatives in Austria

- urbanaccessregulations.eu
- environmentalbadge.com

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Social contacts within zone reduced & air quality improved	~	Health & Wellbeing (3)	Munford, 2017; Beevers & Carslaw, 2005
Individual	Increased costs of car use	-	Equality (5,10)	Amelsfort & Swedish, 2015
Individual	Ambiguous effect on housing value	~	Sustainable economic development (8,11)	Keat Tang, 2016
Systemic	Reduced emissions & increased use of public transport within the affected zone	+	Environmental sustainability (7,12-13,15)	Beevers & Carslaw, 2005; Gibson & Carnovale, 2015
Systemic	Increased revenues from charges & increased use of public transport	+	Sustainable economic development (8,11)	Amelsfort & Swedish, 2015

Technology and societal readiness level

TRL	SRL
7-9	5-7

Open questions

1. What are the implications of congestion charges on overall welfare in the affected zone?

2. What are the effects of different congestion charge designs such as exemptions of different nature?
3. What effect the implementation of congestion charge zone will have on the traffic in neighboring areas (due to eg. re-routing)?
4. What is the potential for expansion of more sustainable transport mode within the targeted zone ?
 - What is the actual modal split?
 - What is the proportion of road space occupied by different modes?
 - What is the potential of future investment in public transport?
 - To what extent road capacity is used for parking (formally and informally)? (Van Amelsfort & Swedish, 2015)

Further links

- whatworksgrowth.org
- adb.org
- epomm.eu

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4.2 Platooning

Synonyms

Platoon Leader (PL), Platoon Member (PM), Truck Platooning

Definition

Trucks form a platoon on motorways by lining up in one lane. The trucks that line up behind the first truck in the platoon can save fuel because their air resistance is reduced. The energy efficiency of a vehicle is influenced by factors such as engine, road friction and air resistance, which accounts for more than 40 % of the total energy consumption of a vehicle (Song et al., 2021). In a truck platoon, various technologies such as the ACC (Adaptive Cruise Control) system and the V2V (Vehicle-to-Vehicle) communication protocol are used to effectively control the trucks in the platoon. The camera sensors measure the distance between contiguous trucks in the platoon and these sensor measurements rely on the ACC system. Based on these sensor measurements, the ACC system controls the truck speed via in-vehicle network protocols such as the Controller Area Network (Ghosal et al., 2021).

Key stakeholders

- **Affected:** Truck drivers, Other road users
- **Responsible:** National Governments, City government, Private Companies, Truck manufacturers

Current state of art in research

A considerable amount of research has actively addressed the technical aspects of platooning, such as maintenance between platoon vehicles and safe driving techniques for platoons (Amoozadeh et al., 2015). One focus in research is the security of this innovation. According to Ghosal et al. (2021), the data transmitted between vehicles is not encrypted and this makes the V2V communication protocol vulnerable to cyber-attacks that can disable the radio channels between the trucks in the train. Furthermore, the research looks into the efficiency of vehicles platooning, where the results of a Dutch study showed that a three-truck platooning with a vehicle spacing of 6.7 metres and an overall length of 69.75 metres has a positive impact on traffic flow near junction and passing areas on Dutch motorways with large-scale truck platooning. But as platoon intensity increased, traffic efficiency and safety decreased (Yang et al., 2019). As an innovation in platooning, a lateral offset of the vehicles was proposed which refers to change in the lateral driving position of the subsequent trucks to reduce the abrasion of the road surface. The side shifting of the vehicles results in a use of a wider area of the roadway, but extends the life of the pavement. A value between 100 mm and 150 mm was proposed as the lateral offset, resulting in an average fuel saving of 8% and a reduction in damage of over 30% (Song et al., 2021). In terms of public opinion, the results of a survey in Germany and California showed that the majority of respondents were convinced of the usefulness of truck platooning, but had concerns about driving on the highway at the same time as truck platoons. In fact, safety issues and problems with surrounding traffic were seen as the biggest concerns. The risk of hacking, job loss and legal liability issues were seen as less important. Therefore, it is crucial to increase public awareness on platooning technology and related safety concerns. It is particularly vital because general traffic vehicles cut-ins can significantly affect the efficiency of truck platooning. Therefore, further research should focus on the main factors that influence the cut-in behaviour and finding appropriate countermeasures or communication strategies to further investigate and address the intention to cut-in between platoon vehicles (Castritius et al., 2020).

Current state of art in practice

Comprehensive and transnational demonstrations were carried out as part of the *European Truck Platooning Challenge*, which was initiated in the Netherlands in 2016 and involved trucks from different manufacturers. Truck platoons were on the public roads in five European countries (Belgium, Denmark, Germany, Netherlands, Sweden) to get one step closer to practical implementation. One focus of the demonstration drives was the analysis of the risk, especially in relation to the length of the formation, the distance as well as the communication between the vehicles. The tests were also observed from the air to observe the interaction with other road users. Potential problems identified were:

- disruption of traffic flow,
- road and bridge wear,
- restrictions in complex traffic situations,
- untrained truck drivers and system failures in certain situations such as tunnels.

In Germany, truck platoons have been tested in regular operation since 2018 as part of a cooperation between logistics group DB Schenker and vehicle manufacturer MAN. The truck convoys are in use on the A9 motorway between the DB Schenker branches in Munich and Nuremberg. The truck convoys, which consist of a maximum of two vehicles, each marked as test vehicle, are not driven by professional drivers. The key questions addressed by this project are: *when to form a truck convoy* and *how to best join and break up depending on the situation*. Furthermore, the acceptance of the new technology in the professional group of drivers will be investigated within the framework of this project. In an accompanying study, the experiences of the participating truck drivers will be systematically evaluated and recordings from the test drives on the interaction with other road users will be analysed. The data will also provide information on what other activities the driver in the rear truck can perform during the phases of autonomous driving. The *Sweden4Platooning* project, which run until 2020, aimed at harmonising the systems of different manufacturers in DB Schenker's operations. Further, in the UK, platoons with vehicles from the manufacturer DAF also have been tested on public roads since 2018. Equally noteworthy is the current *ENSEMBLE* project, which aims at demonstrating truck platoons with vehicles from six manufacturers by 2021. The main goal of the *ENSEMBLE* project is to form safe truck convoys with vehicles from different manufacturers. At motorway entrances, exits and junctions, the distances between the vehicles in the convoy will automatically adjust to make room for other road users. Moreover, the goal is to facilitate the approval requirements for a cross-border demonstration. All efforts need to consider the results of the individual projects and initiatives, most of which show a need for further research. Some of the unresolved aspects are (Danzl et al., 2019):

- Infrastructure equipment and sensor technology in relation to different levels of automation;
- Networking with existing traffic management centres and traffic management concepts;
- Communication between different actors (road, vehicle, centre, other road users, users);
- Energy-efficient formation, implementation and resolution of truck platoons, based on recognised control strategies and protocols;
- Interurban and urban application scenarios.

Relevant initiatives in Austria

The technology of truck platooning has many potentials: savings in fuel consumption and emissions and it can partly prevent the everyday problem of traffic congestion. Above all, however, it has the potential to lead to more safety on Austria's roads and to come a step closer to the *Vision Zero*. Taking these aspects into account, the flagship project *Connecting Austria - Linking efficient and automated freight transport from the motorway to the city* was launched in Austria at the beginning of 2018. The project was funded in the ninth call for proposals of the Austrian Research Promotion Agency (FFG) within the framework of the funding programme *Mobility of the Future*. However, in order to be able to test truck platooning under real conditions on Austrian roads, amendments to the StVO and the Automated Driving Ordinance (AutomatFahrV) are required. Testing truck platooning only makes sense if a small safety distance is maintained. However, § 18 Abs 1 StVO defines the safety distance when driving behind each other in the sense that every driver must be able to stop his vehicle in case of sudden braking of the vehicle in front. As a general rule, a two-second distance - corresponding to 2 x reaction distance - must be maintained for trucks. However, not only the StVO, but also the AutomatFahrV must be modified after the StVO has been amended to enable the testing of truck platoons. Currently, this only regulates the testing of the following use cases: (1) autonomous minibus, (2) motorway pilot with automatic lane change and (3) self-driving army vehicle. Testing truck platooning on roads with public traffic in Austria is currently not possible from a legal point of view - in contrast to the legal situation in Germany (Danzl et al., 2019).

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Reduced emission	+	Environmental sustainability (7,12-13,15)	Song et al., 2021
Systemic	Fuel savings	+	Sustainable economic development (8,11)	Ghosal et al., 2021
Systemic	Transnational platooning demonstrations	+	Partnership & collaborations (17)	Danzl et al., 2019

Technology and societal readiness level

TRL	SRL
7-9	5-8

Open questions

1. What are the digital infrastructure needs of platooning beyond on-board sensors and how can they be addressed?
2. What are the possible solutions for platoon merging issues and how can lane changing cut-ins be minimised?
3. How platooning will influence the role of the drivers in the engaged trucks?

Further links

- acea.be
- mantruckandbus.com
- cohdaireless.com

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4.3 Real-time traffic information and monitoring

4.4 Cooperative - intelligent transport system

4.5 Dynamic route guidance

4.6 Variable speed limits and dynamic signage system

Synonyms

Variable speed limits (VSL), dynamic speed limits (DSL), Verkehrsbeeinflussungsanlagen (VBA), Changeable Message Signs (CMS), Dynamic Signage System

Definition

Speed limits are based on safety, mobility and environmental considerations. While fixed speed limits represent the appropriate speed for average conditions, variable or dynamic speed limits (DSL) take account of the real time traffic, or the road and weather conditions. Therefore, the latter reflect the safe speed better (Mobility and Transport, 2020). The road users are typically informed of the current speed limit by electronic signs above or beside the lanes (De Pauw et al., 2018), as shown in figure 1. These can be supplemented with warning signs (dynamic signage system). For example, if the usual speed limit is 100 km/h, the DSL could change to 80 km/h and further to 60 km/h, to limit rear-end collisions, if there is e.g., a traffic jam ahead or weather conditions are difficult.

With respect to the impact on the societal level, a Belgian study, by E. De Pauw et al. showed a significant decrease (-18 %) in the number of injury crashes after the introduction of a DSL system (De Pauw et al., 2018). F.G. Habtemichael and L. de Picado Santos (2013) found that a DSL system has the highest safety benefit during highly congested traffic conditions. The operational benefit in turn was the highest during lightly congested traffic conditions. However, the success of DSL is highly dependent on the level of driver compliance (Habtemichael & de Picado Santos, 2013). Besides the safety aspects, the goal of DSL is to harmonize the traffic flow. Heavy traffic can cause shock waves, which result in longer travel times and large variations in the speeds of the vehicles. The latter again may lead to unsafe situations. By using DSL this phenomenon could be reduced (Hegyi et al., 2005). Traffic flow efficiency can be improved more, when



Figure 4.1: Dynamic signage system in Austria (ASFiNAG, 2019b)

DSL is combined with coordinated ramp metering (Carlson, 2010). Speed limits can also be temporary lowered, due to high emission values. If the emission values combined with the amount of traffic, reach a specific level, the DSL-System responds automatically and lowers the speed limit for a certain time. How high that level is, depends on the local policies (ASFiNAG, 2019c).

Key stakeholders

- **Affected:** Motorways users
- **Responsible:** Motorway Infrastructure Agencies, Technology Providers, Policymakers, State authorities

Current state of art in research

Studies show, that in retrospect most DSL implementations in Europe were efficient traffic safety and flow improvement. In the United States the increase in safety was significant as well, but the flow improvement was controversial (Lu & Shladover, 2014). Hassan et al. (2012) discovered that during bad weather conditions the combination of Changeable Message Signs (CMS) and DSL was the best way to improve safety. Current research shows that the benefits of DSL systems could be improved by integrating it in a fully connected vehicles (CV) environment (Wu et al., 2020). Currently, research focuses on the integration of C-ITS, to connect the infrastructure to the vehicles. European standards should be developed during the next years (Erhart, 2019).

Current state of art in practice

DSL systems are implemented and used around the world. The used algorithms differ, however. DSL integrated with C-ITS has been implemented in a test environment (Erhart, 2019). Austrian motorways are managed by the ASFiNAG - currently they have 17 DSL systems in use. That means that about 19 % of the Austrian Motorway-System are currently equipped by an DSL system (ASFiNAG, 2019a). So, there is potential for expansion. One global player in traffic management is the Austrian company Kapsch TrafficCom. Worldwide they have implemented their systems on more than 3.500 km of motorway (Kapsch TrafficCom). Kapsch TrafficCom's approximately 5,000 employees generated revenues of EUR 738 million in the fiscal year 2018/19.

Relevant initiatives in Austria

- Asfinag
- Asifinag blog
- kapsch.net
- strabag-iss.com
- pke.at
- aigner-stahlbau.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Fatal collisions reduced	+	Health & Wellbeing (3)	Hegyi et al., 2005
Individual	Travel time reduced	+	Environmental sustainability (7,12,13,15)	Habtemichael & de Picado Santos, 2013
Systemic	Fatal collisions reduced	+	Health & Wellbeing (3)	Hegyi et al., 2005
Systemic	Annual greenhouse gas emissions decrease	+	Environmental sustainability (7,12-13,15)	Schimany, 2011

Technology and societal readiness level

TRL	SRL
7-9	8-9

Open questions

1. Which algorithms for DSL are the most efficient ones?
2. How can DSL be further developed?
3. How can fail-safe operation be improved?
4. How can DSL be combined with C-ITS?

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4.7 Adaptive traffic signal control

Synonyms

Adaptive Traffic Signal Control (ATSC), Traffic Signal Timing (TST), Traffic Signal Control (TSC)

Definition

In the recent years, the increasing population and the urgent need for efficient transport have led to severe traffic problems, especially in urban areas. Congestion mitigation solutions such as optimising the road network and improving basic urban management facilities have been proposed to cope with the pressure caused by the large traffic flow during peak hours. Among all possible methods, the adaptive traffic signal control (ATSC) which combine the intelligence into traffic light control systems has proven to be both, economical and efficient in relieving traffic pressure at congested intersections. With the development of deep learning techniques, ATSC strategies have shown great potential in integrating state-of-the-art intelligent methods (Wang, Cao and Hussain, 2021). Existing traffic light control systems either employ fixed programs without incorporating real-time traffic or take little account of traffic (Casas, 2017). They either set

the traffic lights to the same duration every cycle or vary the duration depending on historical information. Some of them take input information from the underground sensors, such as inductive loop detectors, to detect vehicles near the traffic lights. However, such data is processed very crudely to determine the duration of green and red traffic lights. Consequently, they work in some cases (with low efficiency); however, during events such as sports, festivals, weather conditions or a typical high traffic volume scenario, the existing control systems tend to be paralysed. The recent research paper by Liang et al., 2019 reports that an experienced police officer can efficiently and directly control the intersection by waving signals. Especially, in high traffic volume scenarios, a human operator observes the real-time traffic condition at the intersecting streets and adjusts the duration of the passage time accordingly. The aim of the adaptive traffic signal control is to provide flexibility and efficiency in traffic management comparable to that provided by a human operator through the employment of V2X and Deep Reinforcement learning (Wang, Cao and Hussain, 2021).

Key stakeholders

- **Affected:** Road drivers, cyclists, pedestrians
- **Responsible:** Local governments, Local or national road infrastructure provides, car manufacturers

Current state of art in research

Existing ATSC methods focus on varying the duration of green or red cycles based on real-time information. Nevertheless, this approach is not optimal because it neglects the impact of the current green and red lights durations on the upcoming traffic. Therefore, ATSC performs better than the fixed duration system but worse than more flexible methods because the optimal phase duration in the last cycles does not perform better in the future considering updated information about complex traffic conditions.

With Deep Learning (DL) methods (which serve as input to the intersection controls), the optimal design of the basic control indices such as green phase duration and phase sequence of the traffic light at an intersection can be considered as an optimal decision-making procedure. Next, the reinforcement learning (RL) is applied to signal control to obtain the best control procedure for a signalised intersection. However, in order to achieve instantaneous data acquisition and transmission with low latency, Cooperative Vehicle Infrastructure System (CVIS) is needed to support inter-vehicle communication and vehicles with road-side infrastructure communication (see V2X section). Compared to traditional sensor detectors, V2X can collect more accurate traffic data to provide comprehensive information for traffic control, resulting in better RL decision-making (Wang et al., 2021). Moreover, the analysis of the recent literature for the optimisation of TSC systems, which have been published from January 2015 to

January 2020 revealed that only two papers deal with signalised roundabouts. Roundabouts have different traffic dynamics compared to regular intersections. With an increasing use of signalised roundabouts, especially in urban areas, it is believed that TSC for signalised roundabouts is a particular research gap in this area. Although there are studies conducted using real data and real-time control, there are scarce results and/or methods applied or adapted in real life. One of the main challenges for researchers in this field would be to bring these methods to decision makers and implementers. Moreover, a vast majority of work found on this topic deals with the timing of traffic signals and their impact on average delay and/or emissions. An important part of busy intersections, especially in metropolitan areas, is pedestrian traffic. With the exception of Vilarinho et al., (2017) and Yu et al., (2017), pedestrians and the effects of their behaviour are not modelled in the studies. The same applies for drivers' behaviour. An important research direction would be to analyse the effects of pedestrian and driver behaviour on the models. Furthermore, the number of studies dealing with autonomous vehicles and technologies is growing rapidly. The most recent studies address the general area of how autonomous vehicles can be introduced safely and/or efficiently and/or environmentally friendly into the traffic flow (Qadri et al., 2020a). While learning from trial and error is the key idea in RL, the learning cost of RL for complicated problems might be unacceptable. Therefore, how to learn efficiently (e.g. from limited data samples, efficient exploration, transfer of learned knowledge) is a critical issue for the application of RL in traffic signal control (Wei et al., 2019).

Current state of art in practice

A number of stakeholders are focusing on the development of adaptive traffic control systems that support a range of smart city traffic applications, such as public transport signal priority (see PTSP section for further details), eco-driving support, messaging, intelligent traffic signal control (STSC) and emergency vehicle signal pre-emption (EVSP). Due to these factors and steady advances in sensors, artificial intelligence (AI) and machine learning, the global market for adaptive traffic control systems is forecasted to reach the market value of US\$21.9 billion by the end of 2030. Governments and city administrations in different regions of the world are looking for new ways to respond to the increasing number of traffic accidents and managing road congestion, which is why adaptive traffic control systems have attracted a lot of interest in recent years as a viable alternative to address the existing challenges (The Sentinel Newspaper, 2021). There are many options already existing and more are still under development. Currently available adaptive signal control technologies include:

- Split Cycle Offset Optimisation Technique (SCOOT);
- Sydney Coordinated Adaptive Traffic System (SCATS),

- Real Time Hierarchical Optimised Distributed Effective System (RHODES);
- Optimised Policies for Adaptive Control (OPAC) *Virtual Fixed Cycle*
- ACS Lite

Real-time control of traffic systems have proven performance record, yet these systems have been deployed in less than 1% of existing traffic signals in America. The Federal Highway Administration is now working to roll out these technologies to the rest of the country (Curtis, 2017). Further, for example, in Germany the adaptive signal control system has been installed on a 6 km long arterial in Muenster, where it was demonstrated to have positive effect on traffic quality and improve the bus transit by 30% based on the adopted performance index (Brilon & Wietholt, 2013).

Relevant initiatives in Austria

- Asfinag
- ATC

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Scarcity of studies that include the effects of pedestrians behaviour	-	Equality (5,10)	Qadri et al., 2020b
Systemic	Decrease in congestion at the intersections	+	Sustainable economic development (8,11)	Wang et al., 2021
Systemic	Progress in the use of RL algorithms and V2X technologies	+	Innovation & Infrastructure (9)	Wang et al., 2021

Technology and societal readiness level

TRL	SRL
7-9	7-8

Open questions

1. How can ATSC for signalised roundabouts be designed, developed and implemented?
2. How can pedestrian movement be included to a larger extent into the algorithms of ATSC?
3. How can reinforcement learning algorithms learn efficiently from limited data samples for the purpose traffic signal control?

Further links

- rapidflowtech.com
- [fhwa.dot.gov](https://www.fhwa.dot.gov)

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4.8 Passengers and goods fleet management

4.9 Urban access management

Synonyms

Access Regulation Schemes (ARS), Urban Vehicle Access Regulations (UVARs), Low Emission Zones (LEZ), Access Restrictions, Traffic Restrictions, Limited Traffic Zones, Permit Schemes

Definition

Urban Access Management can be seen as regulations, restrictions or bans, for traffic entering cities. Factors like congestion, air pollution, traffic noise or damage to historic buildings are influencing the liveability of cities negatively. Therefore, many cities have been introducing Access Regulation Schemes (ARS) with the goal of less vehicles entering the particular city or area. Implementing a pedestrian zone, is the simplest type of ARS and can improve the attractiveness of tourist attractions or shopping streets significantly (Sadler Consultants Europe GmbH, n.d. c). ARS can be differentiated by vehicle type, vehicle weight, by type of trip (e.g. delivery), by driver (e.g. residents or access), or applies to all vehicles (Sadler Consultants Europe GmbH, n.d. c). Furthermore, ARS can be static or dynamic, depending, for example, on the time of the day or air pollution levels. A list below provides examples of current measures used in the urban areas:

- Low Emission Zones (LEZ)
- Limited Access Zones
- Urban Toll Schemes / Congestion Charging (CS)
- Emergency Air Pollution Schemes
- Zero Emission Zones (ZEZ)
- Other Access Regulations (like Limited Traffic Zones, Through traffic bans, ‘Superblocks’ etc.)
- Smaller Regulations / Restrictions (like school streets or shared spaces) (Sandler Consultants Europe GmbH, n.d. d).

Solutions for ARS can be enforced by physical barriers or cameras, based on automatic number plate recognition (ANPR) systems and/or dedicated short-range communication (DSRC) technology, using on-board units (OBUs) (Kapsch TrafficCom., n.d. b) or by police or local authority officers (Sandler Consultants Europe GmbH, n.d. c).

The impact of Urban Vehicle Access Regulations differs according the implemented schemes, but several common goals are addressed: - Air quality improvement - Traffic congestion reduction - Urban landscape preservation (historical town centres) - Climate change mitigation - Quality of life - Noise mitigation - Road safety - Raising revenues (Sandler Consultants Europe GmbH, n.d. d).

In Austria, several cities and regions have implemented Low Emission Zones (LEZ) for lorries. For example, the city of Salzburg has Access Regulations (AR) for the city centre in place, so only vehicles with a specific reason (delivery or police) are allowed to enter. On the other hand, Tirol introduces occasionally traffic bans during the summer months (Sandler Consultants Europe GmbH, n.d. a). While, the city of Vienna aims at implementing a traffic-calmed city centre by 2022 (Stadt Wien, 2020).

Key stakeholders

- **Affected:** Car Users – especially users of old or high polluting cars, truck drivers, Shippers/producers, Wholesalers, Logistics providers, Retailers, Consumers, Citizens, Authorities
- **Responsible:** Municipalities, Road Operators, Urban Traffic Management, Authorities

Current state of art in research

Current research addresses the evaluation of UVAR implementations and identifies their positive and negative effects. For example, Lopez (2018) found that Urban Consolidation Centres (UCCs), Cargo Bikes (CBs) and Off-hour Deliveries (OHDs) are the three preferred types of solutions to assist in mitigating unwanted side-effects of UVARs on the logistic sector. Further, current research

focuses on the sustainable urban planning in cities affected by mass tourism (García Hernández, 2019; Nolasco-Cirugeda, 2020). Additionally, most recent area of research deals with geofencing that aims at creating digital zones defined on a map, with specific rules, that can be transmitted to the vehicles (Arnesen et al., 2020).

Current state of art in practice

According to Lopez (2018) there are the two preferred UVAR schemes: Low Emission Zones (LEZ) and Congestion Charging (CC). The implementation of these schemes is widely spread within Europe but follows different approaches. Lopez (2018) identified two dominant LEZ enforcement models, first visual surveillance using windscreen stickers and second, cameras with ANPR technology. Furthermore it is argued that *“It is very important to consider that the degree of impact of each measure not only varies from city to city but also depends on the presence of a mix of access regulations”* (Lopez, 2018).

Relevant initiatives in Austria

- ris.bka.gv.at
- wien.gv.at
- kapsch.net

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Noise & pollution reduced	+	Health & Wellbeing (3)	Sandler Consultants Europe GmbH, n.d. b
Individual	Travel time & congestion reduced	+	Sustainable economic development (8,11)	Sandler Consultants Europe GmbH, n.d. b

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Road safety increased	+	Health & Wellbeing (3)	Sandler Consultants Europe GmbH, n.d. b
Systemic	Space for sustainable transport users increased	+	Equality (5,10)	Sandler Consultants Europe GmbH, n.d. d
Systemic	Air quality improved	+	Environmental sustainability (7,12,13,15)	Sandler Consultants Europe GmbH, n.d. d
Systemic	Congestion reduced, revenues increased	+	Sustainable economic development (8,11)	Sandler Consultants Europe GmbH, n.d. b
Systemic	Urban landscape preservation	+	Innovation & Infrastructure (9)	Sandler Consultants Europe GmbH, n.d. b

Technology and societal readiness level

TRL	SRL
7-9	7-9

Open questions

1. What effect will autonomous vehicles have on Urban Access Management?
2. How can geofencing be implemented on a wider scale and what are the barriers?
3. What standards would be useful to aggregate, to support affected stakeholders?

4. How can Urban Access Management engage with the Internet of Things (IoT)?

Further links

- [urbanaccessregulations.eu-1](#)
- [urbanaccessregulations.eu-2](#)

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Chapter 5

Digital road infrastructure and connectivity

5.1 Vehicle to everything communication

Synonyms

Connected Vehicle (CV), Connected Vehicle technologies (CVT), Vehicle-to-x (car and infrastructure) (C2x/V2x), Cooperative Intelligent Transport Systems (C-ITS), Cellular-V2X technology (C-V2X)

Definition

Through Intelligent Transportation Systems (ITS), various Connected Vehicle (CV) technologies have been developed in recent years to contribute to safer roads through cooperative situational awareness and hazard avoidance. Two main types of communication have been proposed: vehicle-to-vehicle (V2V) and vehicle-to-infrastructure (V2I) communication (Outay et al., 2019). C2X (car to everything) or more broadly V2X (vehicle to everything) is the new technology that enables both communication between vehicles (car-to-car) and information exchange with infrastructure (car-to-infrastructure) (ADAC, 2021). V2V offers benefits in terms of increased safety, as it can prevent accidents by allowing a vehicle to exchange real-time information about speed, location and direction with other vehicles in the surrounding area. In addition to their safety applications, V2V and V2I communications can potentially help reduce fuel consumption and emissions due to the fact that excessive pollutant emissions are often associated with heavy braking, changing traveling speeds and acceleration/deceleration, especially at signalised intersections. In the context

of smart cities, many researchers are exploring the potential use of connected vehicles to support eco-friendly driving by reducing CO₂ emissions. This is often achieved through vehicle-to-vehicle (V2V) and vehicle-to-roadside unit RSU (V2I) inter-connectivity to harmonise vehicle speeds by maintaining traffic flow and reducing unnecessary stops and starts (Outay et al., 2019). In terms of the communication technology used for V2X, according to Dey et al. (2016) Dedicated Short Range Communication (DSRC) was considered the primary option for CVT security applications in 2016. However, the use of other radio technologies such as Wi-Fi, LTE or WiMAX enables communication with greater range and provides higher throughput requirements that could not be supported by DSRC alone. In addition, the use of other radio technologies potentially reduces the need for costly DSRC infrastructure.

Key stakeholders

- **Affected:** Car drivers, Insurers
- **Responsible:** National Governments, Private Companies, Car Manufacturers, Infrastructure operators

Current state of art in research

Many research papers focus on the technical performance of this technology, the comparison of V2V with V2I and the mixing of V2V vehicles with non-V2V equipped vehicles. As in 2019, the idea of combining V2V and V2I communications into a hybrid V2X alert system has already become reality (Outay et al., 2019). Moreover, research is conducted on the comparison of available communication technology to ensure the fastest, most efficient and error-free solution. Currently, there are two possibilities under discussion for Car2X communication. Firstly, the IEEE 802.11p Dedicated Short Range Communication (DSRC) and secondly, the Cellular-V2X technology (C-V2X). The former is based on the IEEE 802.11 WiFi standard, while C-V2X is based on 4G LTE, with a roadmap towards 5G C-V-to-X. While China and USA primarily rely on C-V2X, Europe is still undecided as to whether car networking should take place via pWLAN or via C-V2X. This creates an international confusion of languages. As a result, vehicles may not be able to communicate without errors because they use different languages (Köllner, 2020). IEEE 802.11p is technically very advanced and operates with minimal latencies. But the advantage of 5GAA technology is that 5G is to be introduced globally on a massive scale in the near future and the fast-mobile radio standard will be in the car anyway, if only to transmit the huge amounts of data generated by autonomous driving. Moreover, in a dense 5G network, far fewer of the 5.9 GHz units needed for direct communication have to be integrated into the infrastructure than with the 802.11p solution. Some of the tasks of these units will then be taken over by the 5G network (Knecht, 2018).

Current state of art in practice

So far, C2X is only available from some German manufacturers. Only Ford models, the Volkswagen Golf 8 and all Volvo models always have C2X on board as standard. This is desirable from the point of view of consumer protection, because more cars are equipped with C2X, more accurate this system is in preventing accidents. Again, only Golf and Volvo models have C2X free of charge after purchase. All other manufacturers charge money for C2X after one to three years. Moreover, C2X is never available on its own, but only in a package with other Connect services that do not necessarily have anything to do with road safety (ADAC, 2021). Several important technical specificities should be considered for V2V communication:

- The time it takes for a warning to reach another car. This varies greatly between manufacturers, ranging from 0.1 seconds to 2 minutes - with the latter value being far too slow for many situations (e.g. the end of a traffic jam behind a bend).
- Various transmission techniques currently prevent cars from all manufacturers from warning each other.
- With many manufacturers, warnings cannot be passed on if the car is in a cellular network dead zone.
- The number of dangerous situations that are warned about varies from manufacturer to manufacturer.

In the table below, we compare how the warnings specification differ between three car manufactures:

Audi	Ford	Mercedes
broken-down vehicles	broken-down vehicles	breakdown
accidents	general traffic warning	accident
end of traffic jam	end of traffic jam	-
fog, black ice	dangerous road	heavy rain,
	conditions (icy, heavy	fog, crosswind and icy
	rain, oil, etc.)	roads
online traffic sign	-	hazard warning lights
information		switched on
-	-	additional hazard
		manually reported by
		the driver through the
		navigation menu
display of the	-	-
probability of free		
parking spaces along		
roads incl. additional		
information such as		
prices		

Audi	Ford	Mercedes
speed recommendation to reach the next traffic light in a green phase	-	-
-	road works	-
-	objects, animals, people on the road	-
-	wrong-way drivers	-

Moreover, the ADAC's recommendations to the manufacturers are the following (ADAC, 2021):

- The manufacturers should quickly agree on a transmission technology.
- C2X should quickly become standard equipment
- Safety-relevant C2X functions should not cause any follow-up costs

A basis for cooperative systems is currently being established in Europe. The procedures for testing under real traffic conditions are being defined and coordinated among the partners involved. A large part of the technical solutions for data communication is standardised. The non-technical aspects (e.g. organisational structures, safety concept) are currently being worked out in preparation for the market launch in a public-private partnership. On this basis, German, Dutch and Austrian road operators, together with partners from industry, are starting the step-by-step introduction of cooperative systems in Europe within the framework of the C-ITS corridor from Rotterdam to Frankfurt am Main and Vienna (Cooperative ITS Corridor, no date). In Austria, with the award of a comprehensive framework contract, ASFINAG has now become the first infrastructure provider in Europe to reach a further milestone in networking vehicles and roads. The total volume of the framework contract is 14.5 million euros. This will make it possible to equip the entire motorway network in Austria with C-ITS in the coming years. The equipment, which will be installed step by step along the motorways starting in November, includes up to 525 so-called road units as well as a control centre. The first C-ITS services for hazard warning are expected to go into operation within the next 16 months. Further expansion will focus on the support of automated driving and networked traffic management. The C-ITS equipment is part of the digitalisation of the road infrastructure and is funded by the Climate and Energy Fund and the EU (Močnik, 2020).

Relevant initiatives in Austria

- infothek.bmk.gv.at
- c-its-korridor.de
- asfinag.at

- kununu.com
- hitech.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Improvement of road safety	+	Health & Wellbeing (3)	Filippi et al., 2016
Individual	V2X communications will come at no cost to the end user	+	Sustainable economic development (8,11)	Hainen et al., 2019
Systemic	Emissions reduced	+	Environmental sustainability (7,12,13,15)	Outay et al., 2019
Systemic	Increased efficiency of transport systems	+	Sustainable economic development (8,11)	Filippi et al., 2016

Technology and societal readiness level

TRL	SRL
6-8	5-7

Open questions

1. Which combination of the different communication options is the best?
2. Which communication technology is the most suitable for Europe?
3. Are infrastructure operators already taking care of making data internationally compatible so that cars can communicate with it?

Further links

- c-its-korridor.de

- [nhtsa.gov](https://www.nhtsa.gov)

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5.2 Infrastructure support levels for automated driving

5.3 Wireless communication

Chapter 6

Passenger information system

6.1 Digital journey planner

6.2 Rail telematics for passenger services

6.3 Multimodal information and route planning

Synonyms

Multi-Modal Transport Information Services (MMTIS)

Definition

Information systems that ensure reliable, efficient operations and widely accessible, accurate passenger information are essential to the use of public transportation. These systems are being used for a number of specific purposes such as setting schedules and timetables, managing vehicle fleets, issuing tickets and receipts, providing real time information on service running (European Commission, n.d. b). It is particularly crucial for multimodal transport, where passengers use several transport modes or systems operators within a single trip. Therefore, it is essential to provide accurate information to ensure smooth transfer and minimise waiting times. Since 2006 the Transmodel (European Standard Public Transport Reference Data Model (EN 12896)) has been developed in Europe. It provides a framework for defining and agreeing data models to cover the

whole area of public transport operations. Among other things, the standard facilitates interoperability between the information processing systems of transport operators and agencies by using matching definitions, structures and data formats for the component systems. Therefore, it is possible for operators, authorities and software suppliers to work together more easily towards integrated systems. Beyond, future system developments can be accommodated with the minimum difficulty (European Commission, n.d. b). Furthermore, Transmodel is particularly suitable as (1) a specification of an organization's "information architecture," (2) a specification of a database, and (3) a specification of a data exchange interface (European Commission, n.d. a) and has been a fundamental input for the design of the following EU standards:

- DVC (Data Communication on Vehicles);
- IFOPT (Identification of Fixed Objects in Public Transport);
- SIRI (Standard Interface for Real-Time Information);
- DJP/OJP (Open API for distributed journey planning);
- NeTEx (Network Timetable Exchange);
- OpRa (Operating Raw Data and statistics exchange).

Belgium, Denmark, Finland, France, Germany, Hungary, Italy, Netherlands, Norway, Spain, Slovenia, Sweden Switzerland and the UK are involved in the implementation of Transmodel at a certain level – Austria, so far, has not been (European Commission, n.d. c).

The *Commission Delegated Regulation (EU) 2017/1926 of 31 May 2017 supplementing Directive 2010/40/EU of the European Parliament and of the Council with regard to the provision of EU-wide multimodal travel information services* required each EU Member State, among other things, to establish the National Access Points (NAP) by 1st December 2019 (European Commission, 2021a). NAPs were aimed at facilitating the access, easy exchange and reuse of transport-related data to enable the provision of EU-wide interoperable travel and transport services to end-users (European Commission, 2021b). In Austria the NPA is managed by AustriaTech.

Key stakeholders

- **Affected:** Public Transport Users
- **Responsible:** European Commission, NPAs, Transport service providers and public transport operators, National Governments, IT System Providers

Current state of art in research

Presently, the research aims at improving compatibility, connectivity and flexibility of the system. For example, Dinko et al. (2020) looked at what real-time

information would be needed in the future to make the trip planner system resilient and easily adaptable to changing needs, considering the changes and challenges that will bring post-pandemic transportation requirements. Further Chang et al. (2020) conducted research on the accessible indoor navigation application for smartphones, combining information of floor plans, Bluetooth beacons, Wi-Fi/cellular data connectivity, 2D/3D visual models, and user preferences. The aim was to provide visual, audio, and haptic feedback for targeted users to find the optimal route to their destination within a building. Moreover, Huang et al. (2018) looked at the approaches to better connect static (e.g. public transport) and dynamic (e.g. carpooling) networks without limiting flexibility. They found that a merged network, based on the concept of drive-time areas and points of action, could enable multimodal route planning that can provide users with trips from a starting point to a destination using different combinations of modes.

What is more, the additional research addresses Mobility as a Service (MaaS) solutions. For further information see section Mobility as a service (Maas) of this work.

Current state of art in practice

Verkehrsankunft Österreich (VAO) is a nationwide multimodal routing platform authorized by Austrian transport infrastructure, means of transport and transport editorial operators, coordinated among themselves. Highly up-to-date, real-time routing information is provided for most modes of transport and their linking options, such as: car, public transport, bicycle, bike & ride, park & ride, rental bikes, car sharing, etc. The basis for the VAO is the *Graph Integration Platform (GIP)*, a routable and intermodal graph for the entire Austrian transport network and *Basemap*, an Austrian-wide, detailed administrative map based on the geodata of the Austrian federal provinces and the GIP (Verkehrsankunft Österreich, n.d.).

Rome2rio is an international door-to-door travel information and booking engine which provides flight, train, bus, ferry, rideshare or rental car info as well as estimated prices, journey duration and booking details. The platform uses data from over 5000 companies of more than 160 countries (Rome2rio Pty Ltd, 2021a) and provides a simple XML/JSON interface for integrating multi-modal search capability to any website, app or service (Rome2rio Pty Ltd, 2021b).

With *Google Routs*, integrated in *Google Maps*, routes can also be called up for journeys by public transport, bicycle and car, as well as for journeys by foot. Based on real-time information on traffic conditions, current or future travel times are determined (Google, n.d.). Furthermore, the public transportation planning feature *Google Transit* combines the latest agency data (provided with *Google Routs*) with the power of *Google Maps*. It integrates transit stop, route, schedule, and fare information to make trip planning quick and easy for users.

For the integration public transit agencies need to meet a few basic requirements, as providing their static and real-time data in the general transit feed specification (GTFS) format (Google, 2021).

Finally, in 2020 *Apple* launched a new online map, including the features of real-time transit information and indoor maps for airports and malls, but not yet worldwide (Apple, 2020).

Relevant initiatives in Austria

- verkehrsaskunft.at
- gip.gv.at
- basemap.at
- mobilitydata.gv.at
- maps.google.com

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Higher accessibility to mobility	+	Equality (5,10)	Dibbelt et al., 2017
Individual	Facilitated use of public transport	+	Environmental sustainability (7,12,13,15)	European Commission, 2021a
Systemic	Accessible data on a non-discriminatory basis	+	Equality (5,10)	European Commission, 2021b
Systemic	More efficient transport system	+	Sustainable economic development (8,11)	European Commission, 2021a
Systemic	Implementation of NAPs, framework for defining and agreeing data models	+	Innovation & Infrastructure (9)	European Commission, 2021b; European Commission, n.d. b

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Collaborations of private and public sectors & global partnerships	+	Partnership & collaborations (17)	European Commission, n.d. b

Technology and societal readiness level

TRL	SRL
3-7	3-7

Open questions

1. How can bus and rail travel be made as convenient to book as flights?
2. Why Austria has not implemented the Transmodel? What's necessary for an implementation?
3. What effect has Multimodal information & route planning on energy consumption?
4. What key features are needed in multimodal trip planning apps to be accessible for disabled or elderly and how can they be implemented to be inclusive for these specific groups?

Further links

- transmodel-cen.eu
- trafi.com
- eur-lex.europa.eu
- ec.europa.eu
- mobilitydata.gv.at
- apple.com
- maps.google.com

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Chapter 7

Multimodal integrated system

7.1 First-last mile solutions

7.2 Distance or time-based fares

7.3 Mobility as a service (Maas)

Definition

In line with the principle of “*using instead of owning*”, one goal of MaaS is to make mobility available as a service anytime and anywhere with a click on one or more online platforms or apps. These digital MaaS platforms or apps should link information, booking and payment of mobility offers from different service providers and thus enable the offer of integrated mobility packages. Users should have the freedom to choose between different physical forms of mobility (Neumann & Rauch, 2021):

- public transport such as train, bus, rapid transit, tram and metro
- private services such as taxis
- services for car, ride, (e-)bike, (e-)scooter sharing or fixed route taxis
- volunteer-run community buses
- aircrafts and ships
- (in the future) autonomous, driverless vehicles

MaaS solutions can be built up in stages. The first stage consists of a bundling of information from different providers so that all available mobility offers are

displayed for the entire journey from start to destination. Stage two includes planning routes according to customers' priorities and the possibility to book and pay for all means of transport used for the journey at once. In addition, real-time information for the route is included, such as changes in journey and waiting times due to unforeseen events - such as accidents or weather conditions – as well as continuous notifications about alternative options. Stage three consists of a mobility guarantee by means of a customised mobility package based on personal needs and preferences, e.g. in the form of a monthly subscription (Neumann & Rauch, 2021). The aim of MaaS is to provide an alternative to the private use of cars, thus equally convenient, even cheaper, but more sustainable (Maas Alliance, 2015). The theory of MaaS opens up new business areas and enables mobility service providers to increase their customer base. The usage data generated by the ongoing operation can help to get to know customers better and thus to work more efficiently, as it would be easier to plan the orientation and distribution of the services. A well-functioning MaaS system requires the willingness of private and public mobility providers to cooperate with each other and with the platform operators (MaaS providers) (Neumann & Rauch, 2021). Moreover, it relies heavily on availability of high-quality data. To enforce safe and secure real-time access to data, is equally important as ensuring the clarity regarding liabilities of parties with principal control over the data (Maas Alliance, 2015). The first step towards MaaS is the harmonization of data, supported by appropriate regulations and standards (Maas Alliance, 2015). In Austria, both researchers and mobility service providers are researching how to best implement MaaS. One example is the ULTIMOB research project.

Key stakeholders

- **Affected:** Customers/Users
- **Responsible:** Transport service providers and public transport operators, MaaS operators and integrators, IT system providers, city councils, local, regional and national authorities

Current state of art in research

In order to support the cooperation between private and public mobility providers as well as platform operators (MaaS providers), the legal and organizational framework conditions as well as standards for a secure and fair exchange of data should be created at European and Austrian level (Neumann & Rauch, 2021). In 2015 the MaaS Alliance, a public-private partnership, working to establish foundations for a common approach to MaaS, was founded, with the main goal, to facilitate a single, open market and full deployment of MaaS services (Maas Alliance, 2015). The research and development project *MaaS4EU*, which is funded by the Horizon2020 research and innovation programme, brings together 17 partners from several sectors and backgrounds

to provide viable evidence and solutions about the MaaS concept. The project aims to remove barriers and enable a cooperative and interconnected EU single transport market for the MaaS concept, by addressing the four pillars:

- (1) business models
- (2) end-users
- (3) technology
- (4) policy

Therefore, the holistic *MaaS4EU* solutions are demonstrated and validated in real life via Living Labs in Greater Manchester (UK), Luxembourg-Germany, and Budapest (Hungary) (MaaS4EU, 2017). In summary, current research is mainly working on the development of different MaaS app/platform prototypes, that will offer a multimodal travel solution. One example is the project *TrønderMaaS* of Marinelli et al. (2020) who is operating a full-scale pilot test in the Trondheim-Stjørdal region, Norway. ### Current state of art in practice {-} In 2019 Berlin's public transport authority *Berliner Verkehrsbetriebe (BVG)* invented and implemented together with the Lithuanian start-up and MaaS solution leader *Trafi* the mobility app called *Jelbi*, which counts as the world's most extensive Mobility as a Service-solution (Rastenyte, 2020). The app covers assistance planning and routes discovery, real-time public transport information and shared mobility vehicle location and availability, a streamlined payment solution for any integrated mobility service, as well as the possibility to compare the duration and cost of each trip (Rastenyte, 2020).

In 2020, Switzerland followed and integrated an app called *yumuv*. *Swiss Federal Railways SBB CFF FFS*, *PTOs of Verkehrsbetriebe Zürich*, *Basler Verkehrsbetriebe (BVB)*, and *BERNMOBIL* cooperated also with the start-up *Trafi* and managed to create the first regional MaaS with subscriptions (Trafi Ltd., 2020).

Relevant initiatives in Austria

- AustriaTech.at
- maas-ready.at
- ultimob.at
- tim-oesterreich.at
- wegfinder.at
- wienerlinien.at
- anachb.vor.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Facilitated accessibility to transport	+	Equality (5,10)	Gudonavicius, 2020
Individual	Use of active transport modes increased/Fuel consumption decreased	+	Environmental sustainability (7,12,13,15)	Gudonavicius, 2020
Individual	Higher accessibility & faster travel time	+	Sustainable economic development (8,11)	Gudonavicius, 2020; Marinelli et al., 2020
Individual	Use of digitalized transport	+	Innovation & Infrastructure (9)	Gudonavicius, 2020; Marinelli et al., 2020
Systemic	Transport safety increased/Collision rates reduced	+	Health & Wellbeing (3)	Gudonavicius, 2020; Marinelli et al., 2020
Systemic	Emissions rate reduced	+	Environmental sustainability (7,12,13,15)	Gudonavicius, 2020
Systemic	Traffic efficiency	+	Sustainable economic development (8,11)	Gudonavicius, 2020
Systemic	Efficiency of transport systems, increased resilience through real-time data	+	Innovation & Infrastructure (9)	Marinelli et al., 2020

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Collaborations of private and public sectors & global partnerships	+	Partnership & collaborations (17)	Gudonavičius, 2020; Marinelli et al., 2020

Technology and societal readiness level

TRL	SRL
3-7	5-7

Open questions

1.How can a sustainability transformation be reached through MaaS and what circumstances does it require? 2.How can data protection be ensured when using MaaS? 3.How fast is MaaS going to be implemented? 4.How can bureaucratic hurdles be overcome in a timely manner?

Further links

- maas-alliance.eu
- trafi.com
- jelbi.de
- ubigo.me
- maas4eu.eu

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7.4 Park and ride

Synonyms

$P\mathcal{E}R$, P and R , $P+R$

Definition

Some of the main challenges the world is currently facing are related to population growth and urbanisation. The massive growth of cities has created major transport challenges that manifest themselves in traffic congestion in urban areas, especially in city centres. Many of the efforts to reduce congestion attempt to increase vehicle occupancy by inducing a shift from single occupancy vehicles (SOVs) to multiple occupancy vehicles or encouraging use of various transit modes. One example of such effort are park-and-ride facilities which attempt to reduce car use and increase road efficiency. Park-and-ride facilities are usually located in peri-urban areas in a proximity to bus or train station to allow drivers coming from suburban and rural areas to park their cars and transfer to public transport to reach urban destinations. Park-and-ride facilities, introduced in England in the 1970s, appear to offer a simple and cost-effective alternative to building new roads. These facilities are usually accompanied by good public transport services to urban areas (Katoshevski-Cavari, Bak and Shiftan, 2018).

Key stakeholders

- **Affected:** Car drivers coming from suburban and rural areas
- **Responsible:** National Governments, Communal Governments, City governments, Parking Companies

Current state of art in research

In terms of P&R research, existing publications address topics such as the optimal location problem of P&R facilities, the relationship between private vehicle use patterns and the number and density of P&R facilities in a city, the empirical study of P&R facility use patterns, the study of P&R motives and air quality standards in Europe, the influence of P&R facilities on vehicle kilometres travelled, the analysis of travellers' stated intention to use parking and cycling facilities (P+R, B+R), empirical analysis of P&R facility choice behaviour, attitude surveys of P&R and non-P&R users and the influence of multimodal information on the use of P&R (Gan and Ye, 2018). Studies show that some public transport users were attracted to switch to multiple modes of transport (i.e. park-and-ride), which increased the number of car trips. Nonetheless, additional car trips are made in non-congested areas, thus contributing to traffic relief (Katoshevski-Cavari, Bak and Shiftan, 2018). The exact effects of P&R are controversial. Some studies have confirmed that P&R facilities can encourage the use of public transport, relieve urban traffic and reduce car emissions in city centres. Other studies pointed to possible counter-effects of P&R. The reduction of congestion in city centres might encourage motorists to use their cars in the city again, as accessibility has increased, and motorists travelling to the city centre via P&R facilities might travel some extra kilometres to reach the P&R facility. The exact weight of these negative externalities is still debatable (and will vary from place to place), as is the direct net benefit of P&R on car traffic in the city area as a whole. However, it is undisputed that well-used P&R facilities directly reduce car traffic in the city centre (Dijk and Montalvo, 2011).

Current state of art in practice

Parking management has evolved greatly in Europe over the last decades, and P&R has emerged as one of the newest elements of urban parking management. Virtually all urban areas are facing growing parking demand. More parking spaces lead to growing problems of urban congestion and pollution from traffic. Many cities have responded with policies aimed at improving the utilisation of existing infrastructure (e.g. through pricing or automatic display of parking capacity) and building new infrastructure at structural bottlenecks. The typical development of urban parking policies can be presented in seven phases (Dijk and Montalvo, 2011):

1. **No parking measures:** This phase is sustainable until the level of parked cars has a negative impact on the attractiveness and quality of the area.
2. **Regulation and control of parking:** This means banning parking in some streets.
3. **Time restrictions (free of charge):** This leads to more efficient use of available space through increased turnover of cars.

4. **Paid parking.** Parking tariffs are used as a key to control the use of parking spaces.
5. **Resident parking schemes:** Overflow of parkers into neighbouring areas (often residential) requires resident parking regulations.
6. **P&R facilities:** These are being developed as an alternative or supplement to parking provision in the town centre.
7. **Mobility management:** It includes various activities to coordinate the combination of private and public transport to create an acceptable mobility chain for travellers.

Moreover, the results of a survey show that a quarter of the cities in Europe are intensively engaged in P + R development, while the other half are moderately engaged. Geographically, it shows that cities in north-western Europe have a higher level of engagement than cities in southern and eastern Europe. Furthermore, the understanding of P&R in European cities is strongly different, revealing current beliefs about P&R. Park-and-Ride is certainly not the only transport policy initiative in the city to improve accessibility and quality of life in the city. Most cities apply combination of measures. P&R is valued as part of such a package, but not seen as the perfect package. Most cities consider P&R as a “Plan B” (Dijk and Montalvo, 2011). In Germany, some P&R facilities were tested by the ADAC. Many P&R facilities had deficiencies - most of them were missing equipment features:

- The testers hardly found any video surveillance, and forecasts of occupancy on the Internet were also scarce;
- No car park had continuous footpaths and safe separation between pedestrians and cars;
- In 25% of facilities, there were not enough parking spaces available, showing a gap between supply and demand.
- Some of the public transport services were also unsatisfactory, with too long waiting/transfer time. The likelihood of choosing P + R facility decreases with longer public transport travel and waiting times (Islam et al., 2015).

The facilities scored best in the category of information and prices. Two thirds had clear signage and provided comprehensible information on their websites about location, size and prices. Two of them were particularly positive: they published online forecasts of available parking spaces so that drivers could estimate in advance when parking spaces would be available. The Bremen-Burg P&R facility offered additional useful service: a display board showed free parking spaces and the departure times of the next two trains. In passenger traffic, commuters do not want to wait long for their train. The frequency of public transport therefore has a significant impact on whether a P&R facility is accepted at all. In one third of the facilities, the connection to the public transport network (travel time ratio, frequency, routes to the station) was poor or very

poor. The testers checked lighting, digital or personal surveillance, recognisable separation between parking spaces and the roadway, and whether the transition from the car park to the station was safe. Overall, the study showed that current level of safety is unsatisfactory.

Recommendations for operators:

- Provide information about P&R facilities on the Internet
- Pave, regularly maintain and clean the entire P&R facility - including temporary parking spaces.
- Make parking spaces at least 2.50 metres wide so that users can get on and off without difficulty.
- Keep footpaths short and safely separated from the roadway, clearly mark parking spaces and regularly tighten faded markings.
- Provide charging infrastructure for electric vehicles
- In multi-storey car parks, provide more security through video surveillance, good visibility, functioning emergency calls and comprehensive lighting
- Manage P&R facilities at high occupancy rates (user fees, parking time restrictions) in order to avoid misuse.

Recommendations for municipalities & public transport:

- Planning on a large scale and regionally already when developing areas for P&R facilities.
- Where demand is particularly high and space is available, create more P&R spaces - possibly also by building parking decks.
- Ensure good public transport connections to the city centre with short intervals.
- Avoid large jumps in fares, if necessary integrate selected P&R facilities into cheaper fare groups.
- Combine Bike+Ride and P&R facilities to make it possible for residents from the immediate vicinity to reach the facility by bicycle instead of by car (Luca and Dommnich, 2018).

Relevant initiatives in Austria

ÖBB is investing 700 million euros in the expansion of infrastructure in the eastern region this year. Two thirds of rail passengers in Austria travel in Lower Austria, Vienna and Burgenland, where lines are being extended, stations renovated and new park-and-ride facilities built (Frey, 2021). In Vienna, Lower Austria and Burgenland, more than 40,000 parking spaces are available at over 200 Park/B+R facilities for easy transfers. In Vienna, most P&R facilities charge a small fee of € 3.60 per day. In Lower Austria and Burgenland, the use of P&R facilities is free of charge for public transport passengers (VOR.at, no date).

- wien.info
- wien.gv.at
- derstandard.at
- orf.at
- noe.orf.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Reduced initial congestion in city centres	~	Health & Wellbeing (3)	Dijk & Montalvo, 2011
Individual	Increased access to public transport & multimodal travel	+	Equality (5,10)	Macioszek & Kurek, 2020
Individual	Low cost or free of charge	+	Sustainable economic development (8,11)	VOR.at, no date
Systemic	New infrastructure built	+	Innovation & Infrastructure (9)	Frey, 2021
Systemic	Ambiguous impact on emissions	~	Environmental sustainability (7,12-13,15)	Moore et al., 2019; ITF, no date

Technology and societal readiness level

TRL	SRL
8-9	7-9

Open questions

1. How to encourage non-commuters to use P&R?
2. How will demand for P&R parking change over time, especially with the rapid changes associated with the introduction of autonomous vehicles?
3. What is the potential of P&R in facilitating multimodal transport at the advent of integrated travel apps?

Further links

- itf-oecd.org
- parkeninwien.at
- stadt-wien.at

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7.5 Contactless public transport cards

Synonyms

Contactless smart card, smart card ticketing

Definition

Smart card ticketing means, that the passenger's entitlement to travel is stored electronically on a chip that is usually embedded in a plastic card and validated when the card is presented to a smart reader (Turner & Wilson, 2010). On the contrary to contact smart cards, which have to be inserted into a smart card reader, contactless smart cards must only be near to the readers (about 10 cm) to exchange data (Mezghani, 2008). There are three types of standards used, called Type A, Type B (both complying with ISO 14443 standard) and FeliCa, while FeliCa provides faster transmission and is mainly used in Asian countries (Kurauchi & Schmöcker, 2017). Smart and integrated ticketing systems are expected to deliver greater flexibility and simplicity for passengers, by offering increased speed, convenience and security against loss and theft (Turner & Wilson, 2010). Economic and societal benefits from smart cards ticketing include the reduction in costs as a result of fewer paper tickets being sold, reduced queuing time, faster throughput of passengers at ticket gates, reduced boarding time for buses and reduced loss of revenue through fraud (Turner & Wilson, 2010). England's Department of Transport has planned a strategy, to introduce integrated and smart ticketing to the majority of the UK by 2020. Their research suggests that net annual benefits of over £1 billion per year to passengers, operators and local authorities can be the result (Turner & Wilson, 2010). Another advantage of using smart cards ticketing, is the large amount of data on passengers' behaviour, which can be collected with lower cost (Kurauchi & Schmöcker, 2017). In Austria smart cards have not been implemented on a large scale. Only the City of Wales has smart cards for the public transport in use (Wels Linien). ÖBB (ÖBB, 2021) and Wiener Linien (Wiener Linien, 2021) don't have smart cards in use, but online tickets for smart phones, using QR Codes. Wiener Linien are currently researching on a more efficient solution for the usage of digital tickets, since they developed, that ticket controls of digital tickets take longer than for paper tickets (Wiener Linien, 2021b).

Key stakeholders

- **Affected:** Public transport users, ticket inspectors
- **Responsible:** Public transport operators, public transport associations, public transport authorities, smart card producers, Industry suppliers

Current state of art in research

The latest research goes in the direction of using smart phones or other mobile devices for smart ticketing. An initiative, led by NFC Forum and GSMA achieved in 2015 together with global public transport representatives, the Smart Ticketing Alliance and the JR East as well as standards bodies, including CEN and ISO, harmonizing the specifications of mobile device NFC interfaces and public transport readers and cards. Together they established standards for testing mobile devices and public transport equipment (NFC Forum, 2016).

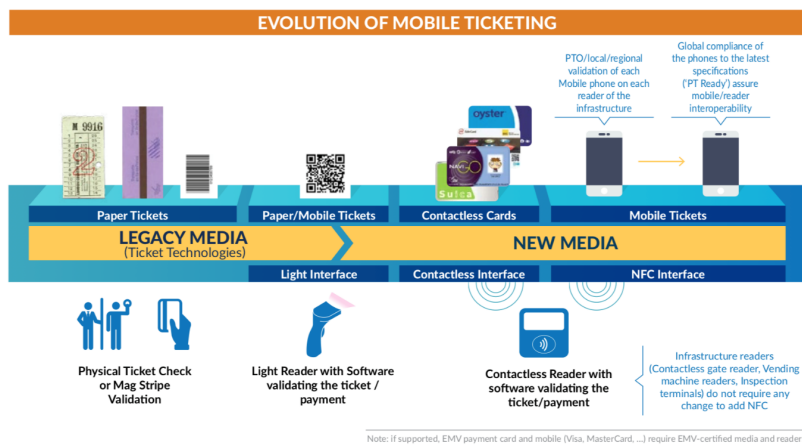


Figure 7.1: The evolution of mobile ticketing (NFC Forum, 2016)

Furthermore current research addresses the issues of big data and how collected data through contactless smart cards can be best analysed (see Kurauchi & Schmöcker, 2017).

Current state of art in practice

Many countries, regions or cities, have smart card ticketing systems in use, like the whole of Netherlands, Helsinki Region, Minsk, Berlin, Auckland, Sydney and many more (see Wikipedia contributors, 2021). The systems itself differ and depend on the local ticketing and fare systems. While London, for instance, is using an access control system, Helsinki's system is trust based. Furthermore, a

distinction can be made between pre-paid (debit) and post-paid (credit) systems (Kurauchi & Schmöcker, 2017).

Relevant initiatives in Austria

- taikai.network
- variuscard
- austriacard

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Personal, travel expenditure reduced	+	Sustainable economic development (8,11)	Turner & Wilson, 2010
Individual	Access to digitalised transport	+	Innovation & Infrastructure (9)	Turner & Wilson, 2010
Systemic	Public transport capacity increases	+	Sustainable economic development (8,11)	Turner & Wilson, 2010
Systemic	Facilitates integration of the fare systems of several operators within a city	+	Partnership & collaborations (17)	Kurauchi & Schmoecker, 2017

Technology and societal readiness level

TRL	SRL
7-9	7-9

Open questions

1. How can the large amount of provided data be best used?
2. What advantages and disadvantages would an implementation in the main cities of Austria have?

Further links

- itso

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7.6 Information and assistance for people with special needs

7.7 Mobility hubs

Chapter 8

Connected and autonomous driving

8.1 Parking infrastructure for autonomous vehicles

8.2 Connected vehicles

8.3 Automated vehicles

Chapter 9

On-board technology for connected and automated vehicles

9.1 Advanced driver assistance system (ADAS)

9.2 Parking assistance system

Definition

Nowadays, parking a car becomes an increasingly mundane task due to the growing size of the vehicles which consequently reduces visibility to the rear and front. Moreover, the number of vehicles on the road continues to increase which makes finding parking spaces more difficult. To overcome this challenge, efficient and advanced parking techniques are needed, such as finding the right parking space and parking cars efficiently (Khalid et al., 2021). While in the 1990s parking assistance systems were not considered necessary, systems that support the parking process are now standard in new vehicles and have a high acceptance rate. While parking assistance systems of the first generations were mainly informative systems, today these systems help to find a suitable parking space and support the steering during the parking manoeuvre. Future systems will become even more autonomous, up to a point where they will find their parking space without human intervention (Valet Parking) (Gotzig, 2016). With respect to safety issues, parking assistance systems can reduce insurance claims that occur during parking manoeuvres by 30% (ADAC, 2020). They also provide a useful application in the form of emergency brake assistant that prevents accidents with other road users when reversing (ADAC, 2019). Modern Parking

assistants work with two sensor concepts: ultrasonic sensors for the close range at the rear (often already installed as “parking beepers”) and radar sensors with a longer range at the side in the bumper (ADAC, 2019). Additionally, there are also new releases with 360° view around the car (Land Rover, no date; Mercedes-Benz, no date). However, there are no tests for this at the moment.

Key stakeholders

- **Affected:** Car Drivers, Traffic participants, Insurers
- **Responsible:** Car manufacturers

Current state of art in research

The research on on-board parking features is almost entirely owned by the car manufacturers. Research tends to focus on larger-scale issues such as car parking location tracking, space booking systems using IoT and congestion caused by *parking cruises*. Additionally, tests are carried out on the merger between emergency brake assistant and parking assistant to overcome the difficulties with obstacles detection and reduce the collision rates in this specific situation. The ADAC tested the AEB (Autonomous Emergency Braking) systems from Mercedes, Volvo, BMW, Seat and Skoda in three test scenarios: (1) a pedestrian dummy stands behind a car or walks past, (2) a car parks in the direction of travel and (3) cyclists as well as cars drive past crosswise. BMW was the best at reacting to all situations with radar and ultrasound - with some drop-outs, especially with moving pedestrians or cross-traffic. The Mercedes, on the other hand, only used its side radar sensors for reverse braking and thus did not recognise stationary vehicles at all. The VW system from Skoda and Seat had radar and ultrasound, but moving pedestrians were only detected randomly or not at all. Overall, these tests showed that the automatic braking parking assistants have a lot of potential, but are far from optimal. Even the system of the front-runner does not yet work 100% reliably. Even the low-cost ultrasonic sensors, however, can be very effective and even prevent pedestrian collisions, as the BMW showed in the test. Therefore, it is crucial that manufacturers equip their vehicles with an effective AEB system as a standard. The necessary technology is already available in most passenger cars where the rear ultrasonic sensors would need to be linked to the braking function (ADAC, 2019). The greatest difficulties are encountered in pedestrian detection, in the scenarios in which the risk of personal injury is potentially the highest. Some of the tested vehicles recognised the dangerous situation too late or not at all.

Current state of art in practice

Nearly 50% of the cars in Germany are now equipped with parking assistance. Nonetheless, the results of a study by HUK-Coburg, Germany’s largest motor

insurer with eleven million insured cars, show that the number of fender-benders has not decreased and the damage costs have even risen slightly. The reason for this is the damage to the expensive Park Distance Control (PDC) sensor embedded in the bumper when vehicle collides with an obstacle while parking (Focus Online, 2017). In 2017, 570 accidents with personal injury occurred in Austria when reversing with passenger cars. There were no fatalities, but around 290 people were injured, 60 of them seriously. In addition, there is a large amount of property damage due to obstacles being overlooked (ÖAMTC, 2019). According to different sources, between 23% and 46% of the cars in Germany are equipped with an on-board parking assistant (Focus Online, 2017). In contrast, only 13% of the vehicles are equipped with an emergency brake assistant that automatically brakes in the event of an imminent collision with the vehicle in front or even detects pedestrians and cyclists. Further, a survey conducted on 1000 respondents by German Road Safety Council showed that 85% of the sample found the emergency brake assistant as highly useful and 65% considered parking assistant highly beneficial (Handelsblatt, 2016). Currently, the most advanced technology with respect to parking assistance is offered by Tesla S, where the system is fully autonomous and allows the car to drive itself out of a tight space without the driver's intervention. But it is expected that the technology will be available from other manufacturers too and will improve rapidly in the coming years. One reason for this is that parking assistants with brake intervention will become part of the European vehicle test programme *Euro NCAP* from 2020. In the past, it has been shown that the inclusion of active and passive passenger car safety systems in this programme quickly increases the rate at which vehicles are equipped (ÖAMTC, 2019).

Relevant initiatives in Austria

- oeamtc.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Road accidents when parking reduced	+	Health & Wellbeing (3)	ADAC, 2019

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Higher costs in case of collision	-	Sustainable economic development (8,11)	Focus Online, 2017
Systemic	New designs tested	+	Innovation & Infrastructure (9)	Euro NCAP, 2021

Technology and societal readiness level

TRL	SRL
8-9	8-9

Open questions

1. How can acceptance and usability rates be increased in drivers especially in elderly group?
2. What are the legal implications for the use of assisted parking for both drivers and car manufacturers?

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9.3 Lane keeping

9.4 Distance keeping

9.5 Crash avoidance

9.6 Maintenance assistance

9.7 Digital maps

9.8 Electronic horizon

Synonyms

Connected horizon, e-horizon, EH

Definition

Modern vehicles are currently equipped with different sensors to increase the safety and comfort of driving. Nonetheless, these built-in sensors can usually operate for a short distance of a few hundred meters. On the other hand, digital maps within the system provide information about the road such as its geometry, number of lanes, speed limits or traffic signals. Therefore, the merger between the functions of the sensors and the data provided by the map gives rise to so-called *Electronic Horizon* applications, that are able to provide information from the sensors within an extended range and allow for earlier preparation for a situation ahead (Ress et al., 2008).

The benefits of the e-horizon include increased comfort due to partially automated functions, reduced accident risk thanks to increased information about road situations ahead, lower fuel consumption through predictive driving and longer driving ranges in the case of electric and hybrid vehicles due to optimized energy management (Bosch-mobility-solutions.com, 2021). Nonetheless, the e-horizon still faces certain challenges such as (Grewe et al., 2017):

- *Speed of data*: in the high-speed mobility data or service request may not be answered or provided fast enough before the vehicle reconnects to another network entry point;
- *Amount of data*: fully automated driving is predicted to produce 4 TB of data daily (Nelson, 2016);
- *Scalability*: the system design is relatively simple for small number of participating cars but it may experience difficulties as soon as number of vehicles and/or applications rise;
- *Security and privacy issues*: as with other connected systems, the issue with data protection arises to ensure security and quality for customers.

Key stakeholders

- **Affected**: Car drivers, Traffic participants, Insurers
- **Responsible**: Car manufacturers

Current state of art in research

Profound test of software and hardware are performed under various condition such as different speed and journey breaks to gather data on the entire information chain from GPS positioning to e-Horizon generation. Based on the collected information the engineers optimize the workflow before moving to real test drive. In real test drives, the performance of the applications is frequently checked in the borderline scenarios or with deliberate errors (Ludwig, 2013). Moreover, driving simulation is used to test the effects of sensors failures (Elgharbawy et al., 2019)

Current state of art in practice

Electronic horizon is relatively well-established technology in terms of both, passenger and commercial vehicles and it is offered by several manufacturers including BOSCH, TomTom in cooperation with Electrobit and Continental working together with data technology company IBM and HERE, pioneering company in location technology (Continental, 2019).

Relevant initiatives in Austria

- gsv.co.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Accident risk reduced	+	Health & Wellbeing (3)	Bosch-mobility-solutions.com, 2021; Continental, 2019
Individual	Lower fuel consumption	+	Sustainable economic development (7,12-13,15)	Continental, 2019

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Increased driving range for hybrid and electric vehicles	+	Sustainable economic development (7,12-13,15)	Bosch-mobility-solutions.com, 2021
Systemic	Innovative research towards full automation	+	Innovation & Infrastructure (9)	Foersterling, 2015
Systemic	Collaborations between automotive and technology companies	+	Partnership & collaborations (17)	Continental, 2019; Foersterling, 2015

Technology and societal readiness level

TRL	SRL
8-9	7-9

Open questions

1. How to handle massive mobility of vehicles?
2. How do current approaches scale when the number of participants and services within this system rise?
3. How to fulfill application- or user-specific quality requirements?
4. How to ensure availability of services and data when these are deployed outside of the vehicle? (Grewe et al., 2017)

Further links

- autotechreview.com
- here.com
- scitepress.org
- bosch-mobility-solutions.com
- elektrobit.com

- itsinternational.com
- strategic-partnering.net

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9.9 Emergency call

Synonyms

Public-Safety Answering-Point (PSAP), E-call

Definition

The E-Call is a system that provides an automated message to the emergency services following a road crash which includes the precise crash location. The in-vehicle e-Call is an emergency call generated either manually by the vehicle occupants or automatically via activation of in-vehicle sensors after a crash. The aim of this system is to reduce the time between the accident and the provision of medical services. As soon as the in-vehicle eCall device is activated, it establishes an emergency call carrying both voice and data directly to the nearest emergency services (normally the nearest 112 Public Safety Answering Point, PSAP). The voice call enables vehicle occupants to communicate with the trained eCall operator. At the same time, a minimum set of data is sent to the eCall operator receiving the voice call (European Commission, 2020a). The minimum data provided during an E-call are (Kroher, 2020):

- time of accident
- the exact coordinates of the accident location
- direction of travel (important on motorways and in tunnels)
- the last two vehicle positions
- vehicle ID and vehicle class
- type of drive (e.g. petrol, electric)
- service provider ID
- number of occupants (based on seat belts worn)
- whether the emergency call was triggered automatically or manually

Key stakeholders

- **Affected:** Car Drivers, Emergency Services
- **Responsible:** Road Infrastructure Agencies, Local and National Governments, Automotive Companies, Policy Makers

Current state of art in research

The research on the emergency calls looks at its efficiency in fatalities reduction as a consequence of road accidents. For example, a Swedish study concluded that 49% of those who died in fatal road accidents could have survived. In particular, 5% of them would have survived if they had been located more quickly, 12% if they had been transported to hospital more quickly and 32% if they had been taken to an advanced trauma centre more quickly (Henriksson et al., 2001). Therefore, the evidence shows that the potential of e-calls in saving lives is significant. Moreover, a study by Virtanen et al. (2006) estimated that the use of an e-Call could reduce between 4-8% of road fatalities and 5-10% of motor vehicle occupant deaths in Finland. In other European countries, these estimates fluctuate between 2%-7%, whereas the estimate for whole EU area

with 25 member states reaches up to 15% in fatalities reduction. The European Commission estimates that a pan-European eCall system has the potential to prevent up to 2500 deaths per year in the EU-25 if fully implemented (European Commission, 2020a). Another strand of research focuses on the testing of different designs of e-Call systems and aims at its standardisation across European Union member countries. Uniform legislation concerns in particular, the communication protocol and the amount of data that is provided by an e-call, as well as its content and format (European Commission, 2020a).

Current state of art in practice

Since the end of March 2018, manufacturers in the EU have to include E-Call in all new models of passenger cars and light commercial vehicles (Bundesministerium für Verkehr, no date). However, even if the vehicles have an e-Call system installed, some car producers additionally install their own emergency call systems. The use of manufacturer-specific e-call system rather than a standardised one, gives car manufacturers an advantage and creates an opportunity to trade the data to external ‘accident related’ providers such as towing, or offer services in terms of post-accident customer care such as vehicle reparation or car replacement. Regardless of the benefits for the car producers the results of the crash tests carried out by the European new car assessment programme *Euro NCAP* at the *ADAC Technik Zentrum* are alarming. According to the tests, manufacturer emergency calls were sometimes answered by the call centre only 58 seconds after the airbags had been deployed. This shows that the use of manufacturer-specific e-call, in fact, delays the medical service provision (relative to 112 e-Call), where the position of the car must first be determined from the transmitted location data in order to then forward it to the actual responsible rescue control centre on site. After that, only the rescue centre sends out the ambulance. In the event of an accident, the valuable time would be lost due to this indirect procedure. Nevertheless, many vehicles still use this manufacturer-specific e-call, permitted by the EU, which first informs the car manufacturer’s control centre or its service provider, and not 112, directly. According to an ADAC survey, mainly the German manufacturers prefer to use a manufacturer-specific emergency call instead of 112 e-Call, while other car producers that participated in the survey relied only on 112 e-Call. On the other hand, due to data protection concerns, the system is viewed sceptically by many car drivers. However, in the view of the ADAC, there is no reason for this. 112 e-Call only logs into the mobile network after a serious accident and then sends data to the rescue coordination centre, not to the manufacturer. The 112 e-Call also does not record any data in the car. According to the ADAC, there are now the following steps for legislators and manufacturers to take (Kroher, 2020):

- 112-eCall should be mandatory for all new vehicles, not only for new type approvals.

- The manufacturer-specific emergency call already installed in many models should be convertible to 112-eCall without major effort.
- In order to better inform the driver about the differences between 112-eCall and the manufacturer's emergency call, a detailed description of the function including the content of the MSD (Minimum Set of Data, the transmitted data) should be available in the on-board manual and also in the display of the vehicle.
- If 112-eCall and manufacturer emergency call are available in parallel in the vehicle, the driver should have the right to choose his preferred service provider. As many consumers are uncertain about this, it would be advisable to pre-set 112-eCall in the car by default.
- When using the manufacturer's emergency call, there should be no delay in reporting the accident to the rescue coordination centre in order to enable the fastest possible assistance.
- The data set (MSD) transmitted in the 112-eCall should be expanded to include information (e.g. acceleration values) that enable rescue control centres to automatically predict the type and severity of injuries and thus adequately alert rescue resources.
- In order to be able to use an eCall technology installed in the vehicle fleet over the lifetime of the vehicles in an emergency, it is necessary to maintain the 2G/3G networks.

Relevant initiatives in Austria

In Austria, the handling of emergency calls falls under the responsibility of the Ministry of the Interior. In the project *E-Call Austria*, the E-Call system is to be implemented in Austria. The measures include the testing, implementation and certification of the emergency call answering points in Austria. The new Public-Safety Answering Points (PSAP) in all nine federal states will then be in line with the requirements of EU regulations (Regulation (EU) No 305/2013; provision of an EU-wide e-call service).

- bmi.gv.at
- oamtc.at
- austriatech.at
- oel.orf.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Road fatalities reduced	+	Health & Wellbeing (3)	European Commission, 2020a
Systemic	Disporportionally high fitting costs of e-Call	-	Sustainable economic development (8,11)	European Commission, 2020a
Systemic	Universal emergency number in EU (112)	+	Partnership & collaborations (17)	European Commission, 2020b

Technology and societal readiness level

TRL	SRL
7-9	6-9

Open questions

1. What is the current state of implementation in individual EU member states?
2. Are car buyers sufficiently informed about the difference between manufacturer-specific emergency call and 112 e-Call? And if not, how to tackle this?
3. What is the time horizon to see a full impact of an e-Call, given the proportion of 'older' cars on the roads which do not have e-call fitted?

Further links

-ec.europa.eu

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Chapter 10

Freight and commercial transport

10.1 Automated road freight

10.2 Freight dreyage optimisation

10.3 Tracking and tracing of dangerous goods

10.4 Intermodal Freight

10.5 Real-time disruption management and route planning

10.6 Urban Deliveries

10.7 Parcel load pooling

10.8 Intelligent truck parking

Synonyms

ITP, Information on Truck Parking

Definition

Nowadays, there is a significant increase in transport volume, especially in the international road freight transport. In particular, with the enlargement of the EU member states, the interdependence of the member states has increased as well as the ratio of the exchange of goods and thus the increase in need for transport services (Gnap and Kubíková, 2020). Consequently, the higher number of vehicles and associated traffic lead to difficulties in meeting deadlines for loading and unloading goods as well as the obligation to take mandatory safety breaks and rest periods. It also amplifies the issue with lack of parking spaces along the route for the Heavy Goods Vehicle (HGV) which has a negative impact on logistics and creates assumptions for increasing logistics costs (Lozia and Kulma, 2014). Therefore, the European Union is striving to support the development of the Trans-European Transport Network (TEN-T) through structural funds. The TEN-T network is intended to connect the member states from east to west and from north to south. Unfortunately, the rate of road construction in some countries is far below the rate of growth of transport services. The abolishment of in-vehicle resting and other upcoming changes in the so-called “road package” will increase the need for more parking spaces and associated equipment for drivers, especially on motorways. This fact will have a significant impact on the pressure on vehicle parking spaces when the maximum prescribed driving time is observed and there is a need to stop a vehicle and take a safety break or a daily/weekly rest period (Carrese et al., 2014). On top of this, there is a clear need for charging and refuelling stations for alternative fuels at rest areas to ensure smooth transit of vehicles using alternative fuels. These should be in line with the implementation of Directive 2014/94/EU of the European Parliament. Therefore, to attempt addressing these issues, an Intelligent Truck Parking (ITP) emerged which is an Intelligent Transportation Systems service concerned with the management of information related to HGV parking operations. ITP collects data about parking facilities (services and availability), processes the data, e.g. occupancy level, and communicates the information to drivers (in real time) in order to help them easily access such a facility. ITP enables efficient parking management and potentially improve the needs of transport stakeholders through the provision of information such as available parking spaces and additional services (Sochor & Mbiydzennyuy, 2013). Good examples of the efficient use of the information system can be found in Germany or Austria. These systems, as part of the intelligent transport systems, offer services that make transport easier for drivers, e.g. searching for free parking spaces at rest areas located along motorways and motorways (Gnap and Kubíková, 2020).

Key stakeholders

- **Affected:** Drivers, Transport companies, Freight forwarders, Shippers and Insurers

- **Responsible:** National Governments, Freight Companies, International authorities (eg. EU)

Current state of art in research

In the literature mostly, regional plans for specific areas in a certain country can be found. For example Carrese et al., (2014) for the Lazio Region in Italy and Gnap and Kubíková, (2020) for the Slovak Republic. However, safety aspects are also highlighted, such as a classification scheme of parking spaces for trucks in long-distance traffic. Again, the data is limited to a specific region (Peel Region in Ontario, Canada) but efforts have been made to develop a generally applicable scheme (Nevland et al., 2020).

Current state of art in practice

A common European park strategy was developed in 2014 by the European organisation SETPOS within the SETPOS project. The project had four objectives:

- The assessment and validation of the requirements of stakeholders, i.e. drivers, dispatchers, hauliers, rest area operators, insurers, authorities and shippers;
- The formulation of a common set of standards for secured parking;
- The establishment of a number of pilot parking areas in cross-border regions to validate and demonstrate the standard set;
- To set up an information, guidance and reservation platform for all types of truck parking.

The LABEL project, which follows the SETPOS, aims to increase safety and quality standards for truck parking in Europe by (Carrese et al., 2014):

- Introducing a European standard certification scheme for truck parking areas;
- developing an online database for users to provide financial benefits to certified sites.

Every day, billions of euros worth of goods are transported on the trans-European road network, the backbone of the EU economy. Despite the sector's successful performance with respect to volume, it faces a significant number of issues, including drivers' shortage, skills shortage, ageing workforce and challenges related to safety, security and connectivity. In the road haulage industry, cargo equipment is a frequent target of organised criminal groups. Consequently, cargo thefts and illegal truck boarding cause significant financial

and reputational losses for supply chain operators. Currently, there is a lack of facilities that allow for safe parking of trucks and that also provide a minimum level of services for the social well-being of drivers. By establishing a denser network of secure truck parking areas (SSTPAs) with a clear definition of security levels, it is possible to address these issues all together. Drivers, transport companies, freight forwarders, shippers and insurers, as well as society as a whole, will benefit from a sufficient supply of these facilities by protecting drivers, cargo and transport equipment. In addition, road safety through well-rested drivers is another area where such facilities can have a significant positive impact. In this context, the European Commission conducted a study on safe parking areas for trucks, which was completed in December 2018. The main findings of this study demonstrated a need for (van Weenen et al., 2019):

- A common standard and rating system for safety and service;
- Audit responsibilities and guidelines to ensure reliability;
- Comprehensive maps showing where SSTPAs are needed;
- Recommendations for the basis of a common application program interface (API) for the exchange of dynamic data between SSTPAs and information platforms;
- Manuals to support the creation of business plans for the establishment of SSTPAs.

A gap analysis to compare secure truck parking demand and supply at the European level and in more detail along the core network identified a number of issues, including (van Weenen et al., 2019):

- The total night parking demand is 400,000 truck parking spaces per night;
- Only 300,000 truck parking spaces are available, which means a deficit of about 100,000 additional spaces;
- The deficit in certified secure parking spaces is much greater, as only 7,000 spaces are available in a few countries. In some countries and on certain corridors, motorists cannot rely on the availability of certified secure parking spaces;
- The current supply of non-secure parking spaces is more evenly distributed across the network. However, these spaces are not certified and do not offer guaranteed services to drivers.

Truck Parking Europe helps transport companies ensure the safety of drivers and freight. Inspection reports provide information on the safety features in truck parking areas. These audit reports help safety and planning managers to approve safe parking areas across Europe (in line with the standardised safety framework created by the EU). They provide a detailed overview of the facilities that each truck parking area offers (Truck Parking Europe, no date).

Relevant initiatives in Austria

One of the European Amazon drone development centres is localised in Austria (Marshall, 2020). Moreover, a new drone law came into force in the EU on 31 December 2020 to standardise the rules. It requires a CE marking on the drone and a drone licence for drones weighing 250g or more.

- truckparkingeurope-austria

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Increase safety and security of drivers	+	Health & Wellbeing (3)	van Weenen et al., 2019
Systemic	Reduced losses related to cargo thefts	+	Sustainable economic development (8,11)	van Weenen et al., 2019
Systemic	Additional focus on the alternative fuel infrastructure	+	Innovation & Infrastructure (9)	Gnap and Kubikova, 2020

Technology and societal readiness level

TRL	SRL
8-9	7-9

Open questions

1. How to attract the interest of motorway companies, both private and public, to facilitate data provision, upgrading of parking sites for security and reservation, and encourage the infrastructure construction to capture dynamic data?

2. What software infrastructure is needed to allow for in-vehicle up-to-date information about the occupancy and reservation of truck parking areas?

Further links

- truckparkingeurope.com-1
- truckparkingeurope.com-2
- ec.europa.eu-1
- ec.europa.eu-2
- ec.europa.eu-3
- tis-gdv.de
- unece.org

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10.9 Delivery space booking

10.10 Delivery drones

Synonyms

urban air mobility (UAM), vertical take-off and landing (VTOL), unmanned aerial vehicles (UAVs), Unmanned Traffic Management (UTM)/U-Space

Definition

In the recent year, online shopping and the demand for same-day deliveries has grown exponentially, with more and more people preferring online shopping instead of buying items stationary (Di Puglia Pugliese et al., 2020). At the same time, the last mile is the most expensive process in distribution logistics, contributing to 13% - 73% of the total distribution cost. As a result there is an increased pressure for more efficient solutions in the field. The answer to this problem could be drones, or unmanned aerial vehicles (UAVs). Drones combine three key principles of technological modernity - computing, autonomy and limitless mobility. Capabilities that until now could only be used by the military are becoming accessible to most of the population. Potential use for drones ranges from surveillance and reconnaissance missions to novel forms of logistics and personal transport. The commercial use of drones is associated with enormous economic opportunities. Even though drones are already common as surveillance/sensing devices in security services, geodesy or agriculture, their use as a means of transport is still at the beginning. Delivery drones are currently able to lift weights of up to 2-3 kg and carry out flight assignments in an urban space (Kellermann et al., 2020). What is more, an accelerated progress is expected in the near future, where the European Commission estimates the economic impact of the wider use of drones at €10 billion annually until 2035 and foresees the creation of more than 100,000 direct jobs. Taking into account indirect macroeconomic effects in drone-related industries, the Commission even projects 250,000 to 400,000 additional jobs (SESAR, 2016).

Key stakeholders

- **Affected:** Mobile citizen, delivery companies and truck drivers, customers of online shops
- **Responsible:** National governments, city government, private companies, online shops

Current state of art in research

Current research shows that drones reduce noise, congestion in urban areas and CO₂ emissions. Multiple studies showed that the use of drones in logistics processes can reduce the lead time (defined as the latency between the beginning and the completion of the process), time span and transport costs of the delivery process (Di Puglia Pugliese et al., 2020; Wang et al., 2017; Di Puglia Pugliese & Guerriero, 2017). However, it is also important that drones have lower capacity and working time (low flight endurance) than classic vehicles. Besides all the benefits that drones can bring, there are also some potential drawbacks associated with an increased use of drones. These include safety and security issues, aerial collisions, crashes, malfunctioning of software and hardware components, misuse of drones for criminal purposes, dangers to wildlife and privacy violations, among others (Kellermann et al., 2020). Moreover, the media analysis about drones for parcel and passenger transportation found the following thematic priorities in relevant literature (see table below):

Topics	Percentage	Number of studies
General Surveys	18.9%	21
Logistics (general)	18.0%	20
Attitude and Acceptance Research	13.5%	15
Law and Regulations	11.7%	13
Ethics and Technology Assessment	10.8%	12
Sustainability Assessment	8.1%	9
Urban and Transportation Planning	7.2%	8
Political agenda/strategies	6.3%	7
Passenger Transportation	2.7%	3
Humanitarian Logistics	2.7%	3

The research proposes two approaches in terms of the incorporation of drones into delivery process, either as a sole delivery option or as a support system for trucks. Calculation results show the disadvantage of the exclusive use of drones in the delivery process. Overall, the vehicle routing that uses a combination of trucks and drones is the transport system offers the best trade-off between transport costs, CO₂ emissions and congestion (Di Puglia Pugliese et al., 2020). For example, with 2 drones per truck, the delivery completion time can be reduced by 75% in the best case scenario (Wang et al., 2017).

Current research also examines the potential of drones in food delivery services due to COVID-19 (Kim et al., 2021). A study on choice-model-based analysis of consumer preference for a drone delivery service concludes the following (Kim, 2020):

- Drone delivery service competes with truck delivery service for clothing

and powder formula, and with motorbike delivery service for urgent documents.

- Potential customers' preferences for drone delivery service depend on the price and type of goods.
- Consumers are concerned about the reliability of the drone delivery service for expensive items.
- In all models, it is observed that young people are more likely to choose drone delivery service than old people.

Current state of art in practice

Several large companies, such as *Amazon* (Amazon.com, 2021), *DHL* (Di Puglia Pugliese et al., 2020), *UBER*, *Wing* (Bonnington, 2012), *UPS* (UPS, 2021) and some more have started using delivery drones for parcel delivery. However, governments and experts fear the misuse of drones. In particular, after their concerns materialised with the incident at London Airport (Keane, 2018). To protect against misuse, work is being carried out internationally on a digital remote ID so that the drone operators can always be assigned to the drone (Boyle, 2020). In the USA, the Federal Aviation Administration (FAA) has allowed drone flights as long as the drone is within an operator's line of sight. However, companies are working on developing drones to fly without this requirement (Fox Rubin, 2019). Further, UPS is already carrying out drone deliveries between WakeMed's main hospital campus in Raleigh, North Carolina, and its neighbouring laboratory centre to send laboratory samples back and forth. The company is also planning flights between hospitals to provide easier access to life-saving drugs like anti-venom (Fox Rubin, 2019). The fact that the first drone experiments have focused on business-to-business deliveries in the health-care sector is not a coincidence. Firstly, funding is available in this sector, and secondly, the speed of the drones can bring considerable benefits in this field (Marshall, 2020). Moreover, Amazon announced back in 2013 that they would start delivering with drones within years and in 2019, alongside the unveiling of their new drone, they announced that they would start drone delivery "within months" (Kolodny & Feiner, 2019). Nonetheless, it is currently claimed that even with all the test flights and announcements, it will be several years before a drone can deliver (Marshall, 2020).

Relevant initiatives in Austria

One of the European Amazon drone development centres is localised in Austria (Marshall, 2020). Moreover, a new drone law came into force in the EU on 31 December 2020 to standardise the rules. It requires a CE marking on the drone and a drone licence for drones weighing 250g or more.

- www.oesterreich.gv.at-1

- www.oesterreich.gv.at-2
- www.oesterreich.gv.at-3
- oeamt.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Faster provision of time-sensitive goods (eg. pharmaceuticals)	+	Health & Wellbeing (3)	Fox Rubin, 2019
Individual	Drone deliveries offered at no extra cost	+	Sustainable economic development (8,11)	Amazon.com, 2021
Individual	New delivery options available	+	Innovation & Infrastructure (9)	Kim, 2020; Amazon.com, 2021
Systemic	Reduced time of completion of logistics processes	+	Sustainable economic development (8,11)	Wang et al., 2017
Systemic	Standardised drones legislation across the EU	+	Partnership & collaborations (17)	EASA, 2021

Technology and societal readiness level

TRL	SRL
5-8	3-5

Open questions

1. Will private companies work together and share their technologies?
2. What other areas of application will there be?
3. What will be the thematic priorities for development in the coming years?
4. Will freight drones automatically communicate with other drones such as surveillance, geodesy and agricultural drones?

Further links

- easa.europa.eu

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10.11 Commercial vehicle on-board safety systems

10.12 Rail telematics for freight services

Definition

With increasing digitalisation and automation in rail operations, many applications are being developed that will make it possible to significantly increase the attractiveness and efficiency of rail freight transport. Telematics applications are a functional subsystem of the railway system. This subsystem comprises two elements:

- Applications for passenger services
- Applications for freight transport

In the area of freight transport, this includes the following (European Commission, 2021):

- information systems (real-time monitoring of goods and trains),
- marshalling and allocation systems,
- reservation,
- payment and settlement systems,
- management of connections with other modes of transport and production of electronic accompanying documents

The basis for a smart and connected freight wagon is, in addition to telematics for geolocation and communication (satellite navigation, inertial and mobile radio systems), the use of sensors for condition recording and intelligent validation of driving and operating conditions (Ußler et al., 2019). In road transport, about 85% of trucks are equipped with telematics systems that monitor the condition of the vehicle, track its position and provide a direct communication with the driver via mobile phone. Fleet management receives real-time information and has redundant ways to communicate with the transport in case of problems. Rail freight traditionally operates its transports with infrastructure-based information sources. Therefore, wagons are usually not equipped with wagon-based monitoring and communication devices such as telematics systems and sensors. The result is a constant loss of time-critical goods to road transport (Behrends et al., 2016).

Key stakeholders

- **Affected:** Mobile citizen, delivery companies and truck drivers, customers of online shops
- **Responsible:** National governments, private companies, public rail provider

Current state of art in research

Single wagonload transport (SWL) that refers to a situation where individual wagons or groups of wagons from different consignors are bundled together to form one train, is an important component in the European rail transport system and in the logistics of various industries such as steel, chemicals and automotive. However, changing framework conditions and increasingly demanding market requirements have led to dramatic losses of market share and in some countries even to the complete discontinuation of the SWL business. As this business segment is also seen as an important part of the European co-modal transport system in the future, significant improvements are necessary. With on-board communication technology, freight operators can improve wagon dispatching and rescheduling processes in case of disruptions. Based on reliable

online telematics data, dispatchers will be able to inform their customers about changes in the transport plan earlier, which will increase reliability and satisfaction of stakeholders. Cost-efficient and intelligent telematics-based information services allow wagons to be tracked in real time and automatically present wagon mileage information. The telematics data service generates the necessary information required for reliable quality recording. This additional information optimises the current six-year life cycle of freight wagons.

Current state of art in practice

A group of freight rail industry stakeholders in the US announced the formation of Rail Pulse, a joint venture in late 2020 to create a technology platform which will facilitate and accelerate the adoption of GPS and other telematics technologies in the North American railcar fleet. Rail Pulse partners are focused on promoting the adoption of telematics on two fronts:

- Rail safety, with the early phase of the platform focused on handbrake and impact data, which they believe could provide important safety data points for railways, car owners and shippers, coupled with a forward-looking approach to telematic features such as on-board bearing temperature and wheel impact detection sensors;
- Improve the competitive position of rail compared to other modes by improving visibility of the status, location and condition of individual wagons, with telematic capabilities including data collection to support real-time track-level visibility of whether doors or hatches are open, whether the wagon is loaded or partially loaded and other key performance indicators.

Development of the Rail Pulse platform was expected to begin by the end of 2020, with a full service platform available to the North American railcar industry by the end of 2022 (Berman, 2020). An investment in wagon telematics results in lower costs and higher turnover. One of the critical indications for a large implementation of telematics seems to be the fact that all three parties - shippers, railways and wagon keepers - will share the benefit of “lower costs”. But this distribution of benefits may also lead to a “wait and see” behaviour of many railway stakeholders compared to their competitors on the road (Behrends et al., 2016).

Thus far, a significant cost reduction was achieved with new GSM and GPS modules. Interfaces for supplementary sensors such as impact detection, digital/analogue inputs/outputs, etc. were integrated. Furthermore, based on the analysis of user requirements, the development of a reliable load-sensing technology for freight wagons was started. This requirement emerged from the fact that today most freight wagons in railway operation do not use their full load

capacity, as there is no cost-effective way to measure the load, especially during the filling process, e.g. in the area of bulk goods. If the wagons were to be overloaded and then moved by a train, all wheelsets would have to be replaced during costly inspection in a workshop. As a result, the freight wagon is not filled to its maximum payload, which leads to lower capacity and higher costs. To optimise the dispatching processes, the wagons transmit their loading status so that the dispatchers can re-dispatch the wagon in a short time after unloading, resulting in shorter downtimes and higher efficiency of the wagons (Behrends et al., 2016).

Relevant initiatives in Austria

- www.a1.digital
- blog.railcargo.com
- statistik.at
- railcargo.com

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Rail safety improved	+	Health & Wellbeing (3)	Berman, 2020
Systemic	Potential for lower costs for all involved parties	+	Sustainable economic development (8,11)	Behrends et al., 2016
Systemic	Digitalisation implemented	+	Innovation & Infrastructure (9)	Behrends et al., 2016
Systemic	Potential for <i>wait and see</i> behaviour	-	Partnership & collaborations (17)	Behrends et al., 2016

Technology and societal readiness level

TRL	SRL
8-9	8-9

Open questions

1. What are the barriers that prevent the implementation of digital solutions?
2. What should be changed to enable an effective use of digital solutions?

Further links

- wascosa.ch
- bearingpoint.com
- ec.europa.eu
- blog.railcargo.com
- taf-jsg.info

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10.13 Electric vehicle delivery fleets

10.14 Multimodal transport management systems

10.15 Freight hubs

Chapter 11

Collective mobility vehicles

11.1 Demand responsive transit

11.2 Personal rapid transit

Synonyms

Automated Transit Networks, ATN, PRT, Podcars

Definition

Personal rapid transit is a public transportation option in urban areas where fully automated vehicles provide on-demand, origin-to-destination service over an area network. PRT belongs to a larger family of automated guideway transit (AGT). It is a unique mode of transport that has the following features (Furman et al., 2014; Juster & Schonfeld, 2013):

- Direct service from origin to destination
- Small vehicles that can be used exclusively by an individual or a small group
- Service based on the needs of the user (on demand rather than fixed schedules)
- Travelling speed up to 30 mph (48 km/h)
- Fully automated vehicles
- Vehicles restricted to a route reserved for their exclusive use, along the guideways
- Small driveways that are usually elevated at or near ground level

The components of the personal rapid transit system are:

- **Software:** integrates all elements of the systems and ensures its flawless functioning
- **Hardware:** includes electric and electronic components along the rails and at the stations
- **Vehicles:** are crucial for passenger experience. In some countries, eg. the USA, PRT vehicles must be suitable for use by disabled people
- **Stations and guideways:** are the most important elements from the perspective of planners because they influence the urban architecture and invade significantly in the aesthetic of the urban environment. Guideways are physical structures that support and guide an AGT vehicle, consisting of rails and columns. This is the most expensive element of the PRT system
- **Power sources:** all PRT are powered electrically
- **Operations and maintenance facilities:** are necessary for control centre, vehicle and equipment storage and maintenance areas

PRT can be considered a more environmentally friendly, lighter and quieter alternative to light rail transport (LRT) or bus rapid transport (BRT). It also travels slower than typical LRT or BRT, however, it compensates the time by only stopping at the requested stations. This, in turn, saves significant amount of deceleration and acceleration time. The capacity of PRL reaches 10 000 passenger per hour per direction, which is slightly lower compared to LRT and BRT.

Key stakeholders

- **Affected:** Citizen, Airport Passengers
- **Responsible:** City government, Private Companies, Transport Planners

Current state of art in research

Recent research on PRT is scarce, where the majority of studies have been conducted around 2010. They mainly focused on the cost-benefit analysis and comparisons to LRT and BRT (Juster & Schonfeld, 2013). Furthermore, they considered the potential of different integration designs such as construction of guideways above the pavement with and without trees, above the parking lane, in the middle of the road, adjacent to building or integrated into the buildings or tunnels. Special considerations are required due to grade separation which can interfere with trees or cause obstruction at the pavements (Furman et al., 2014). An important aspect is also the aesthetic side of PRT which intrudes significantly into the urban landscape due to elevated rails. Therefore,

concerns arise about social acceptability of PRT, where it is expected to affect adversely land use, property values, obstruct light and air as well as create unused spaces underneath the guideways (Staniscia, 2018). The most recent studies focus on the PRT in the context of airport shuttles where this concept has already been proven functional. For example, study by Mobolaji et al., (2021) explored the potential of extension of PRT to connect parking facilities and terminal at Budapest Airport, taking into account user expectations and system architecture.

Current state of art in practice

The concept of PRT is more than 50 years old, nevertheless, they are only available in few places around the world. About 30% of the PRT are located at the airports, 30% in the institutional context such as university campus and the final 30% is a mass transit. The examples of existing PRTs are (Furman et al., 2014, p.12):

- The Morgantown PRT at West Virginia University
- The Parkshuttle Rivium metro-feeder outside Rotterdam
- The Terminal 5 shuttle at London Heathrow Airport
- The nature park shuttle in Suncheon Bay, South Korea
- The Masdar City PRT in Abu Dhabi

The reasons for such a limited appearance are scarce technical capabilities and scalability of PRT systems along with high capital and operating costs (Furman et al., 2014, p. 36).

Relevant initiatives in Austria

- 17th International Conference on Personal Rapid Transit and System Design in 2023

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Adverse impact on visual aspect of urban spaces	-	Health & Wellbeing (3)	Staniscia, 2018
Systemic	Grade separation increases safety	+	Health & Wellbeing (3)	Juster & Schonfeld, 2013; Furman et al., 2014
Systemic	Electric power used	+	Environmental sustainability (7,12,13,15)	Juster & Schonfeld, 2013
Systemic	Limited adoption worldwide	-	Innovation & Infrastructure (9)	Furman et al., 2014

Technology and societal readiness level

TRL	SRL
5-8	5-7

Open questions

1. More research is needed on actual analysis of costs and benefits associated with the construction of PRT.
2. Can PRT infrastructure be considered and used as a attractive urban furniture? How can art community be engaged in its development?
3. What are the major barriers for more widespread adoption of PRT?

Further links

- MIT Report

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11.3 Bus rapid transit

11.4 Light rail transit

11.5 Passenger drones

Synonyms

urban air mobility (UAM), vertical take-off and landing (VTOL), unmanned aerial vehicles (UAVs)

Definition

Drones or unmanned aerial vehicles (UAVs) could become the most iconic technology of the 21st century. Drones combine three key principles of technological modernity - computing, autonomy and limitless mobility. Capabilities that until now could only be used by the military are becoming accessible to most of the population. Potential use cases for drones range from surveillance and reconnaissance missions to novel forms of logistics and personal transport. The commercial use of drones is associated with enormous economic opportunities. However, even though drones are already common as surveillance/sensing devices in security services, geodesy or agriculture, their use as a means of transport is still at the beginning (Kellermann et al., 2020). Delivery drones are currently able to lift weights of up to 2-3 kg and carry out flight missions in an urban space (Kellermann et al., 2020). However, passenger drones have also already demonstrated the technical ability to transport passengers within or between cities (LeBeau, 2016; Holt, 2018; Hawkins, 2018). It is not only a historic

turning point in aviation, but the beginning of a new era in which flat airspace could become the “third dimension” of transport (Kellermann et al., 2020). The name of the new type of vehicle is still far from being agreed internationally. There are several names to choose from, such as passenger drone, manned multicopter, Passenger Air Vehicle (PAV), Electric Vertical Take-off and Landing Aircraft (EVTOL), autonomous air taxis, unmanned aerial taxis, flying cars or even a new term (Pramer & Somavilla, 2020). The autonomous air taxis will be a mixture of helicopter and drone. But this also means that they will be vertical take-off and landing (VTOL) vehicles. There are several reasons why drone-related industries are being supported significantly. One of the reasons is that the airspace is still fairly free of traffic. The risk of collisions is (relatively) low and autopilots for aircraft have long been established. Industry experts therefore suspect that we could see self-flying air taxis even before self-driving cars. Being able to do without pilots would make an air taxi service even cheaper and make it possible for more people to afford it (UNIQA, 2019). The European Commission estimates the economic impact at €10 billion annually until 2035 and foresees the creation of more than 100,000 direct jobs. Taking into account indirect macroeconomic effects in drone-related industries, the Commission even projects 250,000 to 400,000 additional jobs (SESAR, 2016).

Key stakeholders

- **Affected:** Citizen, Insurers
- **Responsible:** National Governments, City government, Private Companies

Current state of art in research

Since all prototypes are owned by private companies and the technology is not really shared due to competition, there are few technical research papers. The media analysis about drones for parcel and passenger transportation shows that currently the research is focused in the following areas (see table below):

Topics	Percentage	Number of studies
General Surveys	18.9%	21
Logistics (general)	18.0%	20
Attitude and Acceptance Research	13.5%	15
Law and Regulations	11.7%	13
Ethics and Technology Assessment	10.8%	12
Sustainability Assessment	8.1%	9
Urban and Transportation Planning	7.2%	8
Political agenda/strategies	6.3%	7
Passenger Transportation	2.7%	3

Topics	Percentage	Number of studies
Humanitarian Logistics	2.7%	3

And although there are currently no autonomous air taxis, there is an initial research examining the factors of consumer willingness to fly in autonomous air taxis. This study identified four factors that turned out to be significantly positive: Familiarity, Value, Fun Factor, Sense of Happiness and two as significantly negative: Aversion to New Technology and Fear (Winter et al., 2020). When comparing the GHG emissions of conventional cars with VTOL passenger drones, the passenger drone actually performs a little better than the ordinary car from 35 km onwards. The reasons for this break-even point are, on the one hand, the energy-intensive take-off and landing hover mode and, on the other hand, the enormous efficiency of flying from point A to point B. Given the expected significant time savings over flying, passengers may have an incentive to share VTOL journeys. Therefore, it seems likely that the average occupancy of VTOLs will be greater than that of conventional passenger cars (Kasliwal et al., 2019).

Current state of art in practice

There are quite a few providers working to develop the unmanned aerial taxis. Munich-based start-up *Lilium* successfully launched a one-and-a-half-ton prototype vertically into the air and hovered in place in early May 2019. It sounds like a helicopter, but it doesn't look like one: The Lilium Jet has wings and 36 all-electric jet motors. That makes it quieter and more energy efficient (and makes it look more futuristic) than a helicopter. Lilium expects to be able to start commercial everyday operation not before 2025. But *Lilium* is far from the only manufacturer. *Joby Aviation*, *Volocopter*, *AeroMobil*, *Kittyhawk* and *Zee.Aero* are just a few of the companies hoping to place the most successful model on the market. Already established companies are also taking the concept very seriously. Mobility company *Uber*, aircraft manufacturers *Airbus* and *Boeing*, and car companies such as *Daimler* and *Porsche* are in the race (UNIQA, 2019). Some manufacturers such as Boeing (LeBeau, 2016), Airbus (Hawkins, 2018) and Volocopter (Holt, 2018) have already conducted the first flight tests of their prototypes. The European Union proposes that support services such as flight planning, flight permits and clearances, and dynamic airspace information will be available for drone flight from 2022. From 2027, services such as collision avoidance and capacity management in congested areas will follow. From 2035, according to the European Commission's timetable, the full integration of unmanned aerial vehicles into controlled airspace with manned aviation should be completed (Wiener Zeitung, 2019). The air taxi will not be shuttling crowds of tourists between Schwechat and Stephansplatz in the next ten years. But thanks to the decreasing noise levels of the rotors, which are no longer noticeable in the "normal city noise", as Volocopter claims, they will be used more

and more often in one or the other metropolis with millions of inhabitants - possibly also in Vienna (Pramer & Somnavilla, 2020).

The first approved test track in Austria for an unmanned aerial taxi is located in Linz. There is already a functioning prototype in Austria that was developed by *Ehang* in China and built by *FACC* in Innviertel. The aircraft costs around 300,000 euros, weighs 360 kilos, is equipped with 16 electric motors and 16 rotors and is designed to autonomously transport two people. The batteries of the eight-armed drone are sufficient for about 50 kilometres. In its own production line in Ried, 300 units are to be delivered by the end of next year. In order for them to be able to take off in Europe and also for Linz AG, they are working with Austro Control on the “approval regulations”, explains FACC board member Robert Machtlinger. In Linz it was once again said that this type of passenger transport is seen as a supplement to bus and train. The air enables the fastest connection from A to B in urban areas. However, before the first test route is set up in the Upper Austrian capital for this autonomous transport, 5G mobile radio must first be installed, which was planned for spring 2020 (DerStandard, 2019).

Relevant initiatives in Austria

- derbrutkasten.com
- derstandard.at-1
- derstandard.at-2

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	It is expected to be too costly for general use	-	Equality (5,10)	Pramer & Somnavilla, 2020
Individual	The flight price is expected to settle in the range of a very expensive taxi	-	Sustainable economic development (8,11)	Pramer & Somnavilla, 2020

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Slightly reduced GHG emissions compared to conventional cars from 35 km onwards	~	Environmental sustainability (7,12,13,15)	Kasliwal et al., 2019
Systemic	Increased investment until 2035 and creation of job opportunities	+	Sustainable economic development (8,11)	SESAR, 2016
Systemic	Stationary areas for safety checks	~	Innovation & Infrastructure (9)	Pramer & Somavilla, 2020

Technology and societal readiness level

TRL	SRL
5-6	1-3

Open questions

1. Who will develop the regulations for passenger drones?
2. How much space is needed for take-off and landing, and will this differ between the various providers?
3. What types of routes will be replaced with flying taxis?
4. Will some companies work together and share their technologies?
5. What other areas of application will there be?
6. What will be the thematic priorities for development in the coming years?
7. What name will be agreed internationally for this type of vehicles?

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11.6 Automatic train operations

Chapter 12

Big data

12.1 Automatic identification system for maritime transport

12.2 Big data lifecycle

12.3 Location-based data

12.4 Aircraft tracking system

12.5 Big data tools for mapping and forecasting travel behaviour

Chapter 13

Shared mobility

13.1 Car sharing

Synonyms

Car-Sharing scheme, CSS

Definition

In recent years, the growth of car sharing services as a new and more sustainable way of travelling has led to a shift in private mobility from ownership to use of services. The basic idea of car sharing is quite simple: the sharing of a fleet of vehicles by members to make trips on a per-trip basis. Although, the first car sharing scheme for economic reasons dates back to 1948 in the city of Zurich, Switzerland, other attempts at public car sharing schemes in the following years were not successful. Several successful car sharing schemes were launched in the 1980s, with a consolidation in the early 1990s, thanks to an increasing awareness of citizens and a real boom due to a greater diffusion of ICT and mobile services in the 2000s. Car sharing increases the mobility of community members to reach destinations otherwise inaccessible by public transport, walking or cycling, while raising citizens' awareness of the social and environmental impacts of using private cars. It encourages and supports multimodal communities by providing an additional transport option. From the point of view of building a sustainable city, the vehicles used in car sharing are usually fuel efficient and lead to positive effects in reducing urban emissions and urban congestion (Martin and Shaheen, 2011).

Nowadays, there are different variants of car sharing available on the market. These include:

- Station based

In station-based CarSharing, the cars are parked in fixed parking spaces as close to home as possible. Customers pick up the car there and return it after the journey. Only with this variant, the reservations are possible several days or weeks in advance, but the end time of the booking must also usually be planned in advance. This ensures a high degree of predictability in vehicle availability. Station-based CarSharing is also the cheapest CarSharing variant. The largest providers in Germany (by fleet size) are stadtmobil, cambio, teilAuto and book-n-drive.

- Free-floating

With free-floating CarSharing, the cars are randomly distributed within a defined business area. Users locate and book them via smartphone. The booking is only possible shortly before the start of the journey and until booking, availability and exact location of the vehicle are uncertain. After the journey, the cars can be parked within the business area. All bookings are open-ended. With this variant, reservations in advance are not possible. Both the availability and the location of the vehicle are therefore difficult to predict. Free-floating, however, allows one-way journeys within the business area. Prices are higher than those of station-based CarSharing. The largest providers in Germany are ShareNow, Sixt share and We share.

- Combined sharing

Since 2011, combined CarSharing offers were established that offer station-based and free-floating vehicles from a single source. Combined offers in Germany are available, for example, from stadtmobil, book-n-drive, teilAuto and cambio. The prices are usually based on the lower prices of station-based CarSharing. Free-floating users, on the other hand, largely keep their car. Their motorisation at the time of the study was 485 private cars per 1,000 inhabitants (Bundesverband CarSharing e.V., 2020).

Key stakeholders

- **Affected:** Citizens
- **Responsible:** Authorities, Municipalities, International lobbyists, Private Companies

Current state of art in research

The CarSharing variants have different traffic-reducing effects. The EU research project STARS investigated the traffic-relieving effect of different CarSharing

variants under uniform framework conditions. The study shows that many users of station-based and combined CarSharing get rid of private cars shortly before or during CarSharing participation. At the time of the study, the households, therefore, only had a motorisation rate of 108 and 104 cars per 1,000 people in the surveyed households. These values are already below the target of 150 cars per 1,000 people recommended by the Federal Environment Agency Germany for climate and environmentally friendly urban transport in the future.

The replacement rates in different CarSharing studies from Germany vary. On the one hand, this is due to different survey methods. Only in the studies since 2018 have used a largely uniform survey method in Germany. On the other hand, the latest research has shown that the replacement rate depends strongly on the CarSharing variant studied. For station-based CarSharing and combined CarSharing, there are exclusively positive replacement rates. For pure free-floating CarSharing, both positive and negative replacement rates can be observed. In some cases, fewer private cars were removed by free-floating CarSharing than were put on the road by the CarSharing service.

According to calculations made by Finanztip together with the ADAC, car sharing is already profitable if the number of kilometres driven per year is less than 10,000, or less than 800 kilometres per month. The costs for a private vehicle with 10,000 annual kilometres driven are identical to the costs that would be incurred for car sharing. Other studies see the limit only at 11,250 kilometres (Hoyer, 2013) or 15,600 kilometres (Seipp, 2014). At 5,000 kilometres per year with one's own medium-sized vehicle, one would save on average between 900 and 1,500 euros per year with a car-sharing provider. In summary, according to Evers (2018) car sharing is profitable, if one:

- does not depend on a car every day
- does not regularly drive longer distances over 100 kilometres
- drives a total of less than 10,000 kilometres a year

Current state of art in practice

Europe is currently the most important market for car sharing providers. In 2016, 5.8 million people used the 68,000 carsharing vehicles here. Recently, car manufacturers also started to enter the market directly, such as Daimler, BMW and the FCA Group, which are directly involved in car sharing activities, in order to find new channels to market the cars they produce. The market is growing fast and with this increasing demand comes the need for better understanding and control of the system. In fact, car sharing is not just a matter of business or fleet optimisation, but forms a complex system consisting of different actors, including citizens, authorities and municipalities, businesses. The system becomes complex because of the strong links between the actors as well as the impact on the governance of a city when a large car sharing service is introduced, such as the integration with the existing public transport network

and the policies that allow different companies to compete in the same urban area (Ferrero et al., 2018).

Relevant initiatives in Austria

- VCÖ
- ÖBB

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Uniform access to car in the population	+	Equality (5,10)	VCOE - Mobilität mit Zukunft, 2018
Individual	Cost reduced	+	Sustainable economic development (8,11)	Evers, 2018
Systemic	Reduced traffic and improved air quality	+	Health & Wellbeing (3)	Martin & Shaheen, 2011
Systemic	Car-free households are no longer disadvantaged	+	Equality (5,10)	VCOE - Mobilität mit Zukunft, 2018
Systemic	Reduced emissions	+	Environmental sustainability (7,12,13,15)	Martin & Shaheen, 2011
Systemic	Car sharing fleet grows steadily	+	Innovation & Infrastructure (9)	Stadt Wien, no date

Technology and societal readiness level

TRL	SRL
7-9	5-7

Open questions

1. What is the role of policymakers and municipalities in supporting car sharing in addressing challenges associated with long-term strategic decisions such as operation area, parking locations or size and type of the fleet, considering specific characteristics of a given city?

Further links

- `share_now`

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13.2 Bicycle and e-bicycle hire

Synonyms

bike-sharing schemes (BSS), station-based bike-sharing schemes (SBBSS), free-floating bike-sharing schemes (FFBSS)

Definition

Bike-sharing schemes have become a key component of urban transport policy over the past decade, as shown by the increase in the number of bicycles recently seen in major cities around the world. The concept of bike-sharing is a service for individuals to get around comfortably by bike without owning one. The bicycle is an energy-efficient, safe, CO₂-neutral and space-saving means of transport. It has a low environmental footprint (when used). In urban areas it is a good alternative to the car for short journeys. For longer journeys or for getting to work in an urban environment, it is an excellent complement to public transport. Although at the beginning of the 21st century most BSSs were docked, today's BSSs consist of both docked and dockless BSSs, which have recently emerged in several cities such as London, New York, San Francisco, Beijing and many others (El Arbi and Stephane, 2020). Modern urban short-term bicycle rental systems or public BSSs offer 24-hour access to bicycles, can be picked up and returned at self-service docking stations, and are distributed throughout the city (Midgley, 2011). As technology advances, global positioning systems (GPS) allow operators to track the bikes and reposition them if necessary, while user registration and credit card identification reduce anonymity and theft. The development of, mainly European, BSSs has typically been categorized into four different generations, which in some properties merge into each other. The use of the 1965 “White Bikes” in Amsterdam was possible without personal registration and the bikes could be found all over the city without fixed stations. The model collapsed within a few days due to vandalism and theft. The second generation used locks and heavy bikes. Vandalism rates decreased, but bikes were still stolen because of the anonymity of the customers (DeMaio, 2009). The third generation became smarter and more attractive through technological improvements such as automated smart cards, electronic bike locks and payment systems. Users received a code via SMS to unlock the bikes. The current fourth generation, could include movable solar-powered docking stations, GPS-based real-time availability apps on mobile phones and more electric bikes (Zademach and Musch, 2018).

Key stakeholders

- **Affected:** Mobile citizen, pedestrians,
- **Responsible:** National Governments, International lobbyists, (Public) Transport Agency, Non-Profit-Organizations, Private For-Profit Companies, Private Companies (e. g. outdoor advertising companies)

Current state of art in research

Research mostly focuses on customer behaviour such as trip length or travel time and behavioural influences on the use of bike-sharing systems, for example, road density, traffic density or bicycle infrastructure.

For example, study by Ma et al. (2020) shows that suburban commuters are very likely to use SBBSS to travel to the nearest public transport hub quickly while avoiding long walks or waiting for buses. Moreover, the study by Li et al., (2019) demonstrated that introduction of bikes for hire near points of interest and tourists attractions can significantly increase their use in urban areas while discouraging in suburban locations. Further, it was showed that discount programs such as discounts for regular users, compensation incentives or discounted prices for the elderly increase the attractiveness of this form of transport among different population segments.

In terms of general system functioning, a study by Fishman et al., (2014) shows that one of the major inconvenience of bike-sharing systems are fixed, docked stations. Therefore, to improve the flexibility, attempts are made to introduce shared bikes with locks (Zhang et al., 2019). Furthermore, the maintenance of the dockless system is also problematic, where on one hand, the high maintenance cost reduced the profit margin of the companies while on the other hand, defective bikes can reduce the satisfaction of the customers and decrease the uptake. Therefore, current research focuses on the development of the mechanisms to monitor the condition of the bicycles while maintaining cost efficiency.

Current state of art in practice

Public bike-share systems are one of the world's fastest growing public transport modes, with an average annual growth of 37% since 2009. The fastest increase takes place in China, a country that is experiencing a rapid uptake of electric bicycles (e-bikes). Sales of e-bikes are outpacing all other motorized modes. The figure 14.1 shows the rapid growth of the two emerging technologies, e-bikes and bike-share systems (Campbell et al., 2016).

Private BSS operators from China (*Mobike*, *Ofo*) and Shanghai (*oBike*) are currently introducing large fleets of station-less rental bikes in cities worldwide. The roll-out, especially in European cities, has encountered problems as city

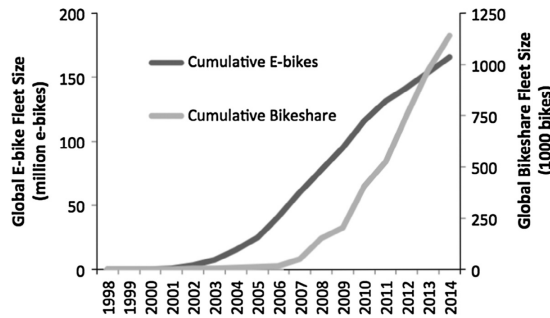


Figure 13.1: Growth in personal e-bike and public bikeshare systems (Campbell et al., 2016)

governments have not been able to coordinate the introduction (Zademach and Musch, 2018). Many bikes have been found abandoned around the cities. In addition, there are fears in some cases that the private companies introduced the BSS with the sole reason of tapping into private user data (Schöffel et al., 2017). Furthermore, the company Montreal introduced “BIXI”, fixed, portable, solar-powered and modular stations. They are self-contained and the stations can be placed, moved and relocated to desired locations within 20 minutes. “Mega” docking stations are available for special events (Midgley, 2011). The number of BSSs has grown to over 800 units worldwide (Fishman, 2016). The public-private partnership model has been the most widespread, and the implementation of BSSs has been possible in cities with limited public funds (Zademach and Musch, 2018). In Austria, there are multiple companies currently offering bicycle or e-bicycle sharing services such as *Citybike*, *Ofo* or *oBike*. Nevertheless, about a year after their launch, the Asian providers of stationless rental bikes in Vienna (start-ups *Ofo* and *oBike*) have been in retreat from the federal capital (Rachbauer, 2018b). This has been a result of strict rules with respect to stationless rental bikes in Vienna announced on 1st August 2018. A failure to comply with the rules resulted in the bikes being removed for a fee. Previously, the traffic road act (*StVO*) allowed the placement of rental bikes in public spaces and the city lacked the means of action against the providers. With the help of a so-called local police ordinance, the city hall required that the bike-sharing companies pick up objectionable bikes on weekdays within four hours and at night and on weekends within twelve hours after notification. If they did not comply, the bikes were removed for a fee. In addition, administrative fines of up to 700 euros were possible. Moreover, a limit of maximum 1500 bicycles per provider was also set. Now, the bikes are given a number and each one has to be registered with the city. According to Blum, setting up several companies to circumvent the upper limit is not allowed. The rental companies themselves also have to meet certain criteria, for instance, there must be a company headquarters in Vienna and a service hotline. *Ofo* and *oBike* already meet these requirements (Rachbauer, 2018d). Across Austria the situation with

rental bikes differs significantly, for example in Innsbruck, rental bikes were first introduced in 2014 and are successfully operating. Meanwhile, in Linz rental bike system has been approved in 2017 and the docking stations are currently under construction. Further, in Salzburg the S-Bike rental system is operating and linked to federal funding (Affenzeller, 2020, Citybike Salzburg, no date a). On the other hand in Graz there is no uniform bike rental system and these services are provided by shops and hotels (Rachbauer, 2016).

Relevant initiatives in Austria

- citybikewien
- citybikesalzburg
- nextbike
- tps.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Often first 30-60 minutes free of charge	+	Equality (5,10)	Citybike Salzburg, no date b; Citybike Wien, no date; Nextbike Niederoesterreich, no date
Individual	Continuous advancement in bike features	+	Innovation & Infrastructure (9)	Zademach & Musch, 2018
Systemic	Wider access to this cheap or free mobility service	+	Equality (5,10)	El Arbi & Stephane, 2020

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Air pollution, noise pollution and congestion reduced	+	Environmental sustainability (7,12,13,15)	El Arbi & Stephane, 2020
Systemic	Investment in bike sharing infrastructure	+	Innovation & Infrastructure (9)	der Grazer, 2019; Hillebrand, 2019; Affenzeller, 2020; Tech & Nature, 2020
Systemic	48% of all systems are operated as public-private partnerships	+	Partnership & collaborations (17)	Midgley, 2011

Technology and societal readiness level

TRL	SRL
7-9	5-7

Open questions

1. What measures can be implemented to tackle the vandalism of the bikes?
2. Which bike system (docked vs. free-floating) is more sustainable in the long-term?

Further links

- cyclocity.com

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13.3 E-scooters

Synonyms

electric scooter

Definition

E-scooters are electrically powered scooters which move at a similar speed to bicycles. They are one of micro-mobility solutions which is growing trend in urban mobility. It encompasses all human-powered micro-vehicles, such as bicycles and scooters, but also new micro-vehicles such as e-scooters, e-bikes and some other small, electrically powered vehicles (Oeschger, Carroll and Caulfield, 2020). Most of the modern vehicles of this type are available for both shared and private use and are gaining wide acceptance. E-scooters have promised a solution to the last mile problem since their introduction in 2017 (Siegfried et al, 2021). They are seen as alternatives to cars and provide potential for reducing traffic congestion, noise and pollution. Initial results suggest that e-scooters are mainly used for distances between 1 and 6 km. Empirical evidence shows that e-scooters can substitute walking rather than driving for these short distances (James et al., 2019; Portland Bureau of Transportation, 2019). In addition to the potential positive environmental impact of e-scooters on the transportation system, some safety concerns have been raised. Most e-scooter users who had an accident have ridden without a helmet (Liew et al, 2020). In general, e-scooters are almost exclusively issued without protective equipment (Allem and Majmundar, 2019). The safety issues do not only affect the riders themselves, but also have an impact on other road users, especially pedestrians (Sikka et al., 2019). It has even been criticised that technology follows the idea of “sell first, safety later” (Choron and Sakran, 2019).

Key stakeholders

- **Affected:** Mobile citizens, pedestrians, insurers
- **Responsible:** National governments, city government, private Companies

Current state of art in research

Since e-scooters are already well-established technology, most research focuses on safety and accidents, user behaviour and potential environmental impact of uptake of this micro-mobility option. Some studies advocate e-scooters as an environmentally friendly solution for crowded cities, others report contradictory results and point to safety issues. Moreover, research also explores whether the presence of e-scooters reduces bicycle thefts (Gössling, 2020). In Gothenburg, Sweden, the police reported that the number of bicycle thefts halved after the introduction of e-scooters and rental bikes (Sydsvenskan, 2019).

Current state of art in practice

E-scooter providers such as *Lime* and *Bird*, which launched operations in California in 2017, can now be found in over 100 cities worldwide and have since recorded millions of rides. E-scooter provider *VOI* has experienced similar growth in Europe and entered the market in 10 countries in just one year after launching in Sweden and has recorded over 16 million rides (Oeschger et al., 2020). The results of a survey indicate that e-scooters are primarily seen as entertainment and not as a means of transport (Siegfried et al., 2021). Maximum speed limits are an important issue and internationally there are different approaches. Los Angeles and Dallas, for example, have no speed limit, as far as can be deduced from the news; while the limit in Vienna is 25 km/h (Schwarz, 2019). Paris is discussing reducing the speed limit to 20 km/h on cycle paths and 8 km/h in parks and pedestrian areas (Négroni, 2019). One problem with the maximum speeds is that some of the e-scooter models can go much faster than 25 km/h (Le Figaro, 2018). To counteract the negative consequences of the introduction of e-scooters, cities have evaluated and implemented various rules and guidelines. Media analysis suggests that the city councils should introduce the following rules as a minimal requirement: speed limits, restrictions on the exclusive use of bicycle infrastructure and a designation of parking spaces for rental and return. Behavioural campaigns and fines, are needed to limit negative consequences of e-scooter use (Gössling, 2020). In Vienna, only very few e-scooters are used on bicycle paths (between 4.9% and 7.1% compared to other bicycle path users). Given the modal split of Vienna (7% cycling), it can be concluded that e-scooters do not yet have a significant role in Vienna's transport system (Laa and Leth, 2020).

Relevant initiatives in Austria

- autorevue.at
- stadt-wien.at
- wien.gv.at
- oeamt.at
- oesterreich.gv.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	E-scooter trips replace mainly walking trips	-	Health & Wellbeing (3)	Laa & Leth, 2020
Individual	More expensive compared to public transport	-	Sustainable economic development (8,11)	Widholm, 2021; Wiener Linien, 2021
Individual	Increase in participants on existing road infrastructure	~	Innovation & Infrastructure (9)	Laa & Leth, 2020
Systemic	Highest user share among young males	-	Equality (5,10)	Laa & Leth, 2020
Systemic	E-scooter trips replace more sustainable transport modes	-	Environmental sustainability (7,12,13,15)	Laa & Leth, 2020
Systemic	Growth in micromobility sector	+	Sustainable economic development (8,11)	Goessling, 2020

Technology and societal readiness level

TRL	SRL
7-9	7-9

Open questions

1. Will an increasing presence of e-scooters on the bicycle infrastructure or in pedestrian zones require separate solution in urban road infrastructure?

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13.4 Ride-hailing

Chapter 14

Alternative power sources

14.1 Hydrogen fuel cell

Synonyms

hydrogen fuel cell electric vehicles, FCEV

Definition

Hydrogen Fuel Cells are systems that use hydrogen as fuel to generate electrical energy in a Fuel Cell and drive the vehicle with electrical structure. In a technical manner, they show similarities with electric vehicles. The advantages of Fuel Cell Electrical Vehicles (FCEV) are emission-free (water only), fast refuelling, noiseless driving, more economical fuel consumption and efficiency, easy maintenance. Regardless of these benefits, FCEV has some disadvantages, such as limited range, lack of hydrogen refuelling stations, safety problems, low profitability for car manufacturers, high prices and lower awareness and acceptance (Tanç et al., 2019; Borgstedt et al., 2017; Iribarren et al., 2016). Moreover, FCEVs have higher energy density than electric batteries which enables them to drive further with heavier loads. At the same time, it raises constraints on weight and size of the energy storage in the vehicles. Consequently, FCEVs are more suitable for freight transport, commercial vehicles, buses, trains, ships and aircrafts, where the performance requirements are higher. Prototypes of all the examples mentioned already exist (Eichseder et al, 2018). In terms of private cars, the FCEVs are likely to provide advantage for long-distance travelling (Roadmap Europe, 2019).

Key stakeholders

- **Affected:** Conventional Cars' Drivers, Citizen
- **Responsible:** National Governments, Car Manufacturers, International lobbyists, Private Companies

Current state of art in research

The goal of alternative propulsion systems is to minimize or eliminate completely the climate-damaging CO₂ emissions, consequently the European Community Research Program proposes electromobility as a priority research area. In particular, the most substantial research is carried out on methods of hydrogen production using biological and photochemical processes because 95% of hydrogen currently produced on an industrial scale comes from fossil hydrocarbons and only 5% from water by electrolysis. Where the only emission-free production process of hydrogen is the electrochemical water splitting in electrolysis, when the required electricity is generated from wind-, water or solar energy. This process results in high degrees of purity and usually achieves efficiencies of up to 85% (Eichlseder et al., 2018). Moreover, the electric vehicle policy aims at technology optimization, market development, durability and capacity of the batteries and charging stations (Alvarez-Meaza et al., 2020).

Current state of art in practice

Hydrogen in transport is only at the beginning of its development (in 2013 the first light FCEVs were introduced for leasing only). Compared to other alternative propulsion systems such as battery electric vehicles (BEVs), which were introduced to the vehicle market earlier, FCEVs show a similar upward trend. At the end of 2017, the total number of FCEVs in Europe reached 799 vehicles, of which 602 were passenger cars and 197 light commercial vehicles, while the total number of BEVs reached 447,150 vehicles. At the end of 2018, the number of FCEVs in Europe rose to about 1,110 (Apostolou and Xydis, 2019). At the end of October 2019, 41 fuel cell passenger cars were registered in Austria. Worldwide, about 12,900 fuel cell vehicles were in operation at the end of 2018, 11,200 of them passenger cars. 46 percent of the vehicles are on the road in the USA, 43 percent in Asia and 11 percent in the EU (1,110 cars). In terms of commercial vehicles, China dominates with over 400 buses, followed by the USA with 55 and the EU with around 80 (Eichlseder et al., 2018). In terms of the number of hydrogen refuelling stations (HRS) worldwide, just about 375 stations are in operation today, compared to 320 in 2017. Most of these are publicly available, the rest are demonstration/research projects and are used to supply hydrogen to private fleets. At the end of 2018, Europe was the region with the most HRS in operation with more than 170 HRS, while Asia (mainly Japan) was second with about 130 HRS and America (mainly the US) third

with more than 70 stations installed. Figure below shows the number of HRS by country at the end of 2018 (Apostolou and Xydis, 2019):

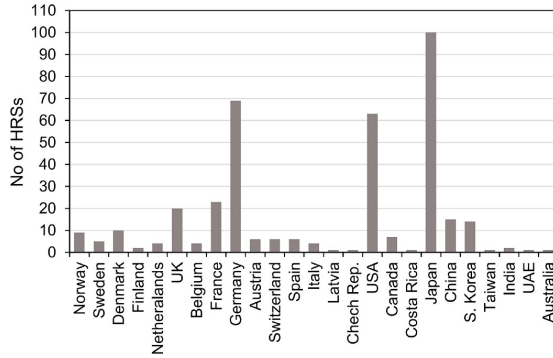


Figure 14.1: Number of hydrogen refuelling stations worldwide (Apostolou and Xydis, 2019)

The European Strategic Energy Technology Plan proposes hydrogen and fuel-cell technologies as crucial for obtaining green-house gases reduction goals by 2050 (Roadmap Europe H., 2019; Alvarez-Meaza et al., 2020).

Relevant initiatives in Austria

- hydrogen train

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Improved air quality	+	Health & Wellbeing (3)	Colella, Jacobson & Golden, 2005
Individual	High prices of hydrogen cars and hydrogen fuel	-	Equality (5,10)	Kanna & Paturu, 2020
Individual	Cost for individuals	~	Sustainable economic development (8,11)	Apostolou & Xydis, 2019

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Emissions reduced, improved air quality	+	Health & Wellbeing (3)	Colella, Jacobson & Golden, 2005
Systemic	Distribution and allocation of goods worsens	-	Equality (5,10)	Kanna & Paturu, 2020
Systemic	Reduced emissions, replacement of fossil fuels, energy transition	+	Environmental sustainability (7,12-13,15)	Colella, Jacobson & Golden, 2005
Systemic	Not yet profitable for manufacturers	+	Sustainable economic development (8,11)	Roadmap Europe, 2019
Systemic	Number of hydrogen refuelling stations increases	+	Innovation & Infrastructure (9)	Apostolou & Xydis, 2019
Systemic	Sharing technologies internationally	+	Partnership & collaborations (17)	International Partnership for Hydrogen and Fuel Cells in the Economy, no date

Technology and societal readiness level

TRL	SRL
7-8	6-8

Open questions

1. Who will drive the progress of hydrogen technology in heavy duty mobility in the future?
2. How to store large amounts of energy at low weight and in a restricted space within the vehicle? (Roadmap Europe, 2019)

Further links

- europarlament
- ec.europa
- fch.europa

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14.2 Battery electric

Synonyms

Battery electric vehicle (BEV)

Definition

Transport contributes up to 30% of climate-relevant greenhouse gas emissions in Austria, with CO₂ playing the largest role here (Bundesministerium für Umwelt, 2019). While the average engine power of vehicles sold annually is increasing (Kreuzer, 2020), the total emissions from the transport sector are also rising (Bundesministerium für Umwelt, 2019). Without a change in mobility behaviour, only a switch to locally emission-free drive technologies, such as BEVs, can help this situation. BEVs are emission-free in operation (apart from tyre wear and minimal brake dust) and have a battery storage/accumulator installed that is charged at an external charging station. The power conversion takes place in an electric motor. The benefits and drawbacks of BEVs are presented in the table below.

Advantages	Disadvantages
<p>Lower noise: Electric motors operate far more quietly than combustion engines. However, in car traffic, most noise is not generated by the engine, but by the interaction of tyres and road surface or - at high speeds - by aerodynamic noises. In these cases, there is no difference between an electric car and a conventional vehicle. It is only above about 25 kilometres per hour that rolling noises are decisive when driving a car. Below this speed, the engine noise is the determining noise source. Therefore, electric cars are quieter in low-speed areas such as residential areas or when starting at intersections and traffic lights.</p> <p>Locally emission-free: BEVs emit no air pollutants when in use. The reduction of greenhouse gases is strongly dependent on the energy sources with which the electricity was produced beforehand and the resulting emissions. The Austrian electricity mix already has a high proportion of renewable energy. The additional electricity demand caused by electromobility is covered many times over by the expansion plans until 2020 for electricity generation from renewable energy sources. This represents an excellent situation for electromobility in Austria.</p>	<p>Range currently varies from approx. 120 to ~ 600 km. According to the manufacturer, Tesla Model S can drive up to 610 km and thus has the longest possible range among e-cars, the car costs just under 80,000 euros. The range depends on many factors, such as differences in driving style, weather conditions (it only reaches its full capacity in a temperature range between 20 and 40 degrees Celsius), air conditioning usage. Nevertheless, 94% of all car journeys by the Austrian population are shorter than 50 km.</p> <p>Electricity requirement: With an increasing numbers of electric vehicles on Austrian roads, there may be varying loads on the low-voltage grid, which can lead to voltage fluctuations and interruptions. If, consequently, controlled charging is necessary in the medium to long-term, this should be included in the planning and construction of charging points. However, care must be taken to ensure that the control system corresponds to customer interests.</p>

Advantages	Disadvantages
<p>Acquisition costs: the cheapest electric cars are already available from 16,000 euros.</p> <p>Charging costs: If the electric car is charged on household electricity, the costs are just under 28 cents/kWh, at public charging stations they vary between 30-60 cents. For 100 km in an e-car, electricity costs about 4.50 for charging. The corresponding costs for petrol and diesel in comparison: with a consumption of 6 litres of petrol and 5 litres of diesel respectively, currently 8.40 euros and 6.70 euros (Michael, 2020).</p> <p>Charging stations: The number of charging stations and charging points is steadily increasing in Austria and currently stands at 5,000 publicly accessible charging points. By comparison, there are just under 2800 petrol stations in Austria (Sitte, 2019).</p>	<p>System of fast charging is cost-intensive as well as challenging in terms of safety and is particularly demanding for the electricity grid due to the high power required (> 20 kW per connection). Such charging stations should primarily be installed where it is compatible with the grid and where they are economical. Therefore, a cost-benefit assessment is advisable before installing fast charging stations.</p> <p>Charging time depends on battery capacity and charging power. At public fast charging stations, the duration is about half an hour to an hour. At a household socket 8-14 hours.</p> <p>-</p>

Key stakeholders

- **Affected:** Conventional Cars' Drivers, Car Manufacturers, Insurers
- **Responsible:** National Governments, City Government, Private Companies, International Lobbyists

Current state of art in research

Research on this topic focuses mainly on technology performance, component sizing, charging stations and life cycle assessment (LCA). LCA is a tool to assess the environmental footprint of a product, process or activity throughout its life cycle (Roy et al., 2009). The main factors influencing the LCA of BEVs are the production of the vehicle and the provision of electricity for its operation. No direct emissions are produced during operation, but the source of electricity supply influences the amount of indirect emissions. Old batteries can be reused as stationary electricity storage units. Recycling the batteries makes it possible to use them again as a source of raw materials. The following raw materials are necessary in the production of battery electric drives: Lithium for the lithium-ion battery, cobalt also for the battery, although the demand is decreasing, and copper as a conductor material. Rare earths are also needed, in particular neodymium and dysprosium for permanent magnets; these are no longer needed when replaced by another motor technology (Doppelbauer, 2020).

Table below compares the CO₂ emissions (in tonnes) during the production of cars with an internal combustion engine (ICE) and battery-powered, considering size of the car. It is clear that during the production process of BEV generates from 3 to 9 tonnes of CO₂ more than ICE (Doppelbauer, 2020).

	ICE			BEV		
	Small	Medium	Large	Small (30 kWh)	Medium (60 kWh)	Large (90 kWh)
Body of the car	2.5	3.8	5.0	2.5	3.8	5.0
Additional components	0.5	0.65	0.8	0.5	0.65	0.8
HV System	-	-	-	0.3	0.55	0.7
Propulsion	0.4	0.6	0.8	0.2	0.25	0.3
Production	1.5	1.5	1.5	1.5	1.5	1.5
Battery	-	-	-	3	6	9
Total	4.9	6.6	8.1	8	12.8	17.3

This life cycle assessment also takes into account current data on the production of battery systems for electric vehicles. Although the production of batteries requires a significant amount of energy and is therefore associated with high emissions, electric vehicles do not have components such as gearboxes and exhaust gas after-treatment and their production-related emissions. The decisive factor for the greenhouse gas balance of vehicles is, above all, the energy used to operate the vehicle. While the use of fossil energy in petrol and diesel vehicles results in high greenhouse gas emissions, electric vehicles have no direct greenhouse gas emissions in their balance sheet. Taking into account direct and indirect emissions, the use of an electric car powered by electricity from renewable sources can save 80% of GHG emissions compared to a fossil fuel-powered car. In addition, the use of renewable electricity also significantly reduces nitrogen oxide emissions. Particulate matter emissions, on the other hand, increase

slightly, depending on the source of electricity. The advantages of electric drives are also evident in the cumulative energy consumption, depending on the quality of the electricity. The lower specific consumption compared to fossil-fueled vehicles should be emphasised. This is due to the high efficiency of the electric motor (Fritz et al., 2018). The negative environmental and social impacts of extracting the rare raw materials needed to produce the battery are already being reduced. The German government supports research into the economic use and recovery of raw materials and the reuse of batteries (Second Life). Batteries that require significantly less cobalt are now also available. Industry is also becoming increasingly involved in initiatives for the sustainable supply of the raw material (responsible mining) (Kurzempa, 2018). In terms of the efficiency of this technology, the well-to-wheel efficiency in Austria is about 69%. This is a significant efficiency gain as compared to a fuel cell car with an average well-to-wheel efficiency of about 27% and a petrol-powered car at about 20% (Bundesministerium für Umwelt Naturschutz und nukleare Sicherheit, no date). The losses in the electricity grid in Austria are very low and can be estimated in the range of 5%, which results in a well-to-tank efficiency of 95% based on 100% green electricity. In the course of the charging process, charging losses of 10% occur due to resistances in the charging cable and the battery. However, an AC/DC voltage converter (rectifier) is connected upstream of the traction battery, which causes a further 5% energy loss. In order to get the stored energy onto the road, it now flows through a DC/AC voltage converter (inverter) with 5% energy loss and can finally be transferred to the wheel by an electric motor with 90% efficiency. The tank-to-wheel efficiency is therefore 73%. The overall well-to-wheel efficiency of a BEV is 69%.

Current state of art in practice

The number of e-cars registered worldwide has reached a new record level. At the same time, however, the growth in new registrations weakened. Around 7.9 million e-cars were registered worldwide in 2019. That is almost 2.3 million more than in 2018 - an increase of 40%. The number of new electric cars registered worldwide in 2019 was just over 2.3 million - only 4% or 90,000 cars more than the previous year. In 2018, the increase compared to 2017 was still around 74%. According to the Centre for Solar Energy and Hydrogen Research Baden-Württemberg (ZSW), this development is primarily due to a reduction in e-car subsidies in China and the USA. Nevertheless, the previous year's level of new registrations was almost reached in these countries: 1,204,000 new registrations were registered in China (52,000 less), and 329,500 in the USA (31,800 less). With around 230,000 registered vehicles, Germany is in seventh place in terms of the total number of e-cars after China, the USA, Norway, Japan, France and the UK (Prack, 2020). But electric power is not just an alternative for personal modes of transport. Increasingly more vehicles in the commercial and public transport sectors are being electrically powered. The larger and heavier a vehicle is, the more difficult it is to electrify it due to the enormous mass of

the larger batteries. However, battery technology is constantly developing, and the ranges are increasing. Even heavy semi-trailer trucks could be electrified in the near future. However, they would need batteries and overhead lines on motorways for fast charging along their routes. This is now being tested in Germany. Three routes in Hesse, Schleswig-Holstein and Baden-Württemberg are currently being equipped with overhead lines (see more in section on Electric Road Systems). In many cities, such as Cologne, Berlin and Hamburg, electric buses are already part of regular service. Their electricity needs are met by fast, occasional charging at bus stops and by charging at night in depots. Many German cities plan to use all-electric buses in the near future (Kurzempa, 2018).

Relevant initiatives in Austria

- oeamt.at
- beoe.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Lower noise	+	Health & Wellbeing (3)	Bundesministerium fuer Umwelt, 2019
Individual	Locally emission-free	+	Environmental sustainability (7,12,13,15)	Bundesministerium fuer Umwelt, 2019
Individual	Reduced travel cost	+	Sustainable economic development (8,11)	Michael, 2020
Systemic	Emission free but high emissions in production	~	Environmental sustainability (7,12,13,15)	Fritz et al., 2018
Systemic	Increasing number of charging stations	+	Innovation & Infrastructure (9)	Sitte, 2019

Impact level	Indicator	Impact direction	Goal description and number	Source
Systemic	Electric Vehicles Initiative accelerating the introduction and adoption of electric vehicles worldwide	+	Partnership & collaborations (17)	IEA, 2020

Technology and societal readiness level

TRL	SRL
8-9	7-9

Open questions

1. How can supply bottlenecks along the value creation chain be addressed?
2. What is the potential shift in dependency from oil-producing to lithium producing countries? What is the expected timeframe?
3. What is the role of secondary use of vehicle batteries?
4. How can local governments increase consumer awareness about BEVs?

Further links

- bmu.de
- publik.tuwien.ac.at
- isi.fraunhofer.de
- kleinezeitung.at
- volkswagen.at
- adac.de
- ec.europa.eu

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14.3 Plugin hybrid vehicles

Synonyms

Hybrid, HEV, PHEV

Definition

Plug-in hybrid vehicles effectively combine the electric drive with either a conventional combustion engine or other engines that use alternative fuels. This has the advantage that the vehicles can travel long distances, but consumption and emissions are reduced. An energy management system ensures that the optimum amount of energy is drawn from the two energy sources while driving. The ratio of energy consumption is influenced by the driving cycle. The faster the vehicle drives, the more energy is needed (Aswin and Senthilmurugan, 2018).

A hybrid vehicle is superior in terms of the reduced carbon footprint, better mileage than conventional vehicles, financial assistance for purchase, lower annual cost and a regenerative braking system. At the same time, the disadvantages include high purchasing cost, lower fuel efficiency because the extra parts installed take up more space and add weight, and higher maintenance costs due to the dual engine. Additionally, some concerns have been risen about the risk that the battery may explode in the event of an accident (Aswin and Senthilmurugan, 2018).

However, the safety aspect referred to above can be neglected, as the results in the EuroNCAP crash test show that hybrid vehicles are just as safe as vehicles with conventional drive systems. Toyota's Hybrid Synergy Drive technology (HSD) also serves as an example, where Toyota's hybrid system - based on the airbag trigger signal - immediately switches off all electrical systems in the event of an accident and interrupts the battery contact (ADAC, 2019).

Currently, there are several types of hybrid vehicles available on the market:

- Series hybrid

The series hybrid model consists of an internal combustion engine that drives a generator instead of driving the wheels directly. The wheels of the car get their power from the electric motors. The generator powers both the charging battery

and the wheels of the car. Series hybrids generate the maximum energy at the time of acceleration and return the energy at the time of regenerative braking. The electric vehicles are designed in such a way that a motor is connected to each wheel. The combination of motor and wheel has the disadvantage of increasing mass and thus affecting handling, but the advantage of improved traction control.

- Parallel hybrid

The parallel hybrid vehicle is an integration of an electric motor and an internal combustion engine connected in parallel to the mechanical transmission. The parallel hybrid architecture incorporates both the engine and the electric generator into one unit located between the transmission and the combustion engine. The battery is recharged by regenerative braking. There is a mechanical coupling between the engine and the wheel, recharging the battery cannot occur when the car is moving.

- Combine hybrid

The combined hybrid vehicle is a fusion of parallel and series hybrid (series-parallel hybrid). There is a double connection (electrical and mechanical) between the drive axle and the engine. The power transmission to the wheels can be either electric or mechanical. At low speeds it behaves like a series hybrid electric vehicle, but at higher speeds series drive trains are less likely to be preferred and the vehicle motor takes over. This model is significantly more expensive than parallel models as they require a mechanically split drive system, an additional generator and high computing power for dual control (Aswin and Senthilmurugan, 2018).

Key stakeholders

- **Affected:** Conventional Cars' Drivers
- **Responsible:** National Governments, Car Manufacturers, International lobbyists, Private Companies

Current state of art in research

Current research efforts focus on the reduction of battery size while maintaining the electric driving performance. Therefore, the study by Song et al. (2018) suggest 30.4 kWh as an optimal battery capacity. Another, large research developments are performed with respect to reduction of emissions and continuous testing of environmental efficiency in comparison to conventional cars. In an ADAC test of plug-in hybrids, just two cars scored well in the Ecotest, namely

Hyundai Ioniq and Volvo V60. The Hyundai was very energy-efficient, while the Volvo consumed more energy and emitted more carbon dioxide, but its exhaust gases were cleaner. This allowed it to score well in terms of pollutants. However, the test results leave no doubt that large and heavy cars like the BMW X5 and Mercedes GLE, even as plug-in hybrids, consume a lot of energy and therefore cannot be counted as eco-mobiles (Kroher, 2020). Interestingly, recent test conducted on the newest models of PHEV showed that they pollute the environment two to four times more than the manufacturers claim which undermined the public opinion on the environmental advantages offered by the PHEV (Plötz et al., 2020; Bannon, 2020).

Current state of art in practice

The development of the hybrid electric vehicle is evolving into the next generation of the mode of transport, in line with EU's policy aims of reduction of greenhouse gas emissions. Nevertheless, current market penetration is still relatively low, contributing to 1% of total car registrations (as of 2019). In Europe, the leaders in the uptake of plug-in hybrid vehicles are Finland and Sweden followed by the United Kingdom (European Environment Agency, 2020).

In Austria the number of plug-in hybrid vehicles quadrupled in 2020 from January to October compared to the same period last year. By the end of October, about 5,500 new vehicles of this type had been registered. Of the approximately 14,700 applications for e-car subsidies so far this year, 90 percent are purely electric, ten percent are plug-in hybrids and range extenders (Ortner, 2020). The results of a study by the Fraunhofer Institute show that the actual climate balance of plug-in hybrid passenger cars is poor, the real CO₂ emissions are twice as high as the values determined in the test cycle, for company cars the real CO₂ emissions are even three to four times as high. The VCÖ calls for a rapid change in the subsidies for plug-in hybrid cars in Austria (VCÖ, 2020).

By 2020, there are already 800 public e-charging points in Vienna, with number close to a thousand, Vienna is one of the leading e-mobility cities in Europe (Fischer, 2020). The Austrian energy companies - members of the BEÖ - have driven the expansion of the public charging infrastructure in recent years. With over 5,000 charging points between Vienna and Bregenz, Austria provides one of the densest charging networks in Europe (Sitte, 2020b). Until now, all building owners had to agree to the installation of an e-charging station. This unanimity is to fall soon. Accordingly, the installation of charging stations in apartment buildings will be made easier from autumn onwards (Sitte, 2020a).

Relevant initiatives in Austria

- oesterreich.gv
- vcoe.at

Impacts with respect to Sustainable Development Goals (SDGs)

Impact level	Indicator	Impact direction	Goal description and number	Source
Individual	Carbon dioxide emissions reduced	+	Health & Wellbeing (3)	Koellner, 2020
Individual	Number of e-charging points increases	+	Innovation & Infrastructure (9)	Sitte, 2020a
Systemic	Emissions reduced for small and light vehicles only	~	Environmental sustainability (7,12-13,15)	Kroher, 2020; VCOE, 2020
Systemic	Exhaust gas treatment strategies are developed	+	Innovation & Infrastructure (9)	Schaefer, 2020

Technology and societal readiness level

TRL	SRL
8-9	7-9

Open questions

Further links

- [europarlament](#)
- [ec.europa](#)
- [fch.europa](#)

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Chapter 15

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