A general method: variation of parameters

Math 352 Differential Equations

April 2, 2014

Introduction: This one goes out to all the gs

The method of undetermined coefficients is very useful when the derivatives of the terms appearing in g(t) have a regular, predictable shape and are themselves the derivatives of similar functions. But it's not too hard to find functions g(t) that would demand excessive ingenuity of us when guessing the form of Y.



Introduction: Too many functions!

Consider $y'' + y' + y = 3\csc(t)$. You can check that a particular solution Y is given by the formula

It's hard to imagine rules for undetermined coefficients that are both

- comprehensive enough to include a function like this and
- possible to commit to memory.

Introduction: Too many functions!

Consider $y'' + y' + y = 3\csc(t)$. You can check that a particular solution Y is given by the formula

$$-3\sin(t)\cos(2t) + \frac{3}{2}\ln|\csc(t) - \cot(t)|\sin(2t) + 3\cos(t)\sin(2t).$$

It's hard to imagine rules for undetermined coefficients that are both

- comprehensive enough to include a function like this and
- possible to commit to memory.

Variation of parameters: not a new thought

- ▶ How did we find *te^{rt}* in the case of a repeated root *r* of the characteristic equation?
- ▶ We promoted a constant to a function and looked for a solution of the form $v(t) \exp(rt)$.
- ▶ In other words, we allowed a parameter to vary.
- ▶ VP is the same idea, adapted to equation y'' + q(t)y' + r(t)y = g(t)
 - Requires that we have already solved the associated homogeneous equation y'' + q(t)y' + r(t)y = 0.
 - ▶ So assume we know y_1 and y_2 with $W(y_1, y_2) \neq 0$.

Variation of parameters: execution

▶ Guess: $Y = u_1y_1 + u_2y_2$ where u_1, u_2 are functions of t:

$$Y(t) = u_1(t)y_1(t) + u_2(t)y_2(t),$$

▶ Goal: solve for u_1 , u_2 . We'll be plugging this expression for Y along with its derivatives back into the inhomogeneous equation, so let's compute the derivatives now.

Assume that the fundamental solutions y_1 and y_2 and the derivatives u'_1 and u'_2 satisfy the following equation:

$$u_1'y_1 + u_2'y_2 = 0.$$

▶ This is the worst rabbit-out-of-the-hat of the term.

¹Joseph-Louis Lagrange (25 January 1736–10 April 1813), remembered for work in analysis, number theory, and mechanics. His *Mécanique Analytique* was fundamental for the physicists of the 19th century.

Assume that the fundamental solutions y_1 and y_2 and the derivatives u'_1 and u'_2 satisfy the following equation:

$$u_1'y_1 + u_2'y_2 = 0.$$

- ▶ This is the worst rabbit-out-of-the-hat of the term.
- Sorry.

¹Joseph-Louis Lagrange (25 January 1736–10 April 1813), remembered for work in analysis, number theory, and mechanics. His *Mécanique Analytique* was fundamental for the physicists of the 19th century.

Assume that the fundamental solutions y_1 and y_2 and the derivatives u'_1 and u'_2 satisfy the following equation:

$$u_1'y_1 + u_2'y_2 = 0.$$

- ▶ This is the worst rabbit-out-of-the-hat of the term.
- Sorry.
- ► The idea is evidently due to Lagrange¹, and it greatly simplifies the computation to come.

¹Joseph-Louis Lagrange (25 January 1736–10 April 1813), remembered for work in analysis, number theory, and mechanics. His *Mécanique Analytique* was fundamental for the physicists of the 19th century.

Assume that the fundamental solutions y_1 and y_2 and the derivatives u'_1 and u'_2 satisfy the following equation:

$$u_1'y_1 + u_2'y_2 = 0.$$

- ▶ This is the worst rabbit-out-of-the-hat of the term.
- Sorry.
- ► The idea is evidently due to Lagrange¹, and it greatly simplifies the computation to come.
- At no point does it cause problems of any kind.

¹Joseph-Louis Lagrange (25 January 1736–10 April 1813), remembered for work in analysis, number theory, and mechanics. His *Mécanique Analytique* was fundamental for the physicists of the 19th century.

The derivatives of Y

Since

$$Y(t) = u_1(t)y_1(t) + u_2(t)y_2(t),$$

we also have

$$Y' = u'_1y_1 + u_1y'_1 + u'_2y_2 + u_2y'_2$$
, blue terms add to 0
= $u_1y'_1 + u_2y'_2$, and so
 $Y'' = u_1y''_1 + u'_1y'_1 + u'_2y'_2 + u_2y''_2$.

Substitute back in

Now we find that Y''(t) + q(t)Y'(t) + r(t)Y(t) reduces to

$$(u_1y_1''+u_1'y_1'+u_2'y_2'+u_2y_2'')+q(t)(u_1y_1'+u_2y_2')+r(t)(u_1y_1+u_2y_2).$$

Collecting terms along u_1 , u_2 , and their derivatives, we get

$$(y_1'' + qy_1' + ry_1)u_1 + (y_2'' + qy_2' + ry_2)u_2 + y_1'u_1' + y_2'u_2'$$

= $y_1'u_1' + y_2'u_2'$,

because of the assumption $u'_1y_1 + u'_2y_2 = 0$.



Putting it all together

We have shown that if u_1 and u_2 have the desired properties, then they satisfy

$$u'_1y'_1 + u'_2y'_2 = g(t)$$

 $u'_1y_1 + u'_2y_2 = 0.$

Solving this system of equations for u_1 and u_2 (in the usual algebraic way, by either substitution or addition of equations) gives

$$u'_1 = -\frac{y_2g}{W(y_1, y_2)}, u'_2 = \frac{y_1g}{W(y_1, y_2)}.$$

Integrating each of these yields the desired functions u_1 and u_2 .



The particular solution

That is, a particular solution Y results from any choice of antiderivatives u_1 , u_2 . We have

$$Y = -y_1 \int \frac{y_2 g}{W(y_1, y_2)} dt + y_2 \int \frac{y_1 g}{W(y_1, y_2)} dt.$$

Like undetermined coefficients, this method has its own characteristics.

- ▶ It is reassuringly mechanistic. *Y* is given by a formula.
- ▶ It is also very general, since there are no conditions on g.
- On the other hand, the integrals that arise may be intractable.

Generalizations

For us, the coefficient functions q(t) and r(t) are constant. What happens when they are not?

- ► The methods of Chapter 5 are required to solve the general second-order linear homogeneous equation.
- If fundamental solutions are known, VP works just the same to determine a particular solution.
- ▶ It is only the characteristic equation and the exponential trick that fail in this case.