

# **General solutions to second-order homogeneous equations**

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# Introduction

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$$ay'' + by' + cy = 0$$

- We saw how to find solutions of exponential type  $y = ce^{rt}$  of the homogeneous equation  $ay'' + by' + cy = 0$ .

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- ▶ We saw how to find solutions of exponential type  $y = ce^{rt}$  of the homogeneous equation  $ay'' + by' + cy = 0$ .
- ▶ We pass to the characteristic equation  $ar^2 + br + c = 0$ . Its real zeroes, if there are any, give values of  $r$  that “work”.
- ▶ Because the equation is linear and homogeneous, *linear combinations of solutions are also solutions*.

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Therefore, in the case when  $\sqrt{b^2 - 4ac}$  is positive, we get two real roots  $r_1$  and  $r_2$ . These correspond to solutions

$$y_1 = e^{r_1 t}, \quad y_2 = e^{r_2 t},$$

we obtain a 2-dimensional family of solutions

$$c_1 y_1 + c_2 y_2.$$

## Question

Are there more? How can we be sure we have found them all?

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There is an existence and uniqueness theorem for second-order equations that is similar to Theorem 2.4.1. Once again, to apply it, we have to know the coefficient functions are continuous: but in our special case today, they are constants, hence continuous everywhere.

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## **Theorem 3.2.1.**

The initial value problem

$$y'' + p(t)y' + q(t)y = 0, \quad y(t_0) = y_0, \quad y'(t_0) = y'_0$$

admits a unique solution provided that  $p$  and  $q$  are continuous at  $t_0$ . This solution is twice differentiable throughout the largest interval containing  $t_0$  on which both  $p$  and  $q$  are continuous.

# Getting Solutions

The existence and uniqueness theorem says nothing about how to find the solution of an initial value problem. But we have access to what feels like a very large class of solutions to the homogeneous linear equation.

$$c_1 y_1 + c_2 y_2$$

Perhaps it is the case that we can always choose  $c_1$  and  $c_2$  so that the corresponding linear combination is a solution of the *initial value problem*: namely, so that

$$\begin{aligned} c_1 y_1(t_0) + c_2 y_2(t_0) &= y_0 \\ c_1 y_1'(t_0) + c_2 y_2'(t_0) &= y_0'. \end{aligned}$$



# Getting Solutions

In solving this system by adding and subtracting equations, one eventually is required to divide by the expression

$$W(y_1, y_2)(t_0) = y_1(t_0)y_2'(t_0) - y_1'(t_0)y_2(t_0).$$

It is called the *Wronskian determinant* (*Wronskian* for short) of  $y_1$  and  $y_2$  evaluated at  $t_0$ . If this quantity is nonzero, then  $c_1$  and  $c_2$  can indeed be chosen so that the associated linear combination is a solution of the initial value problem, and in fact they can be chosen in exactly one way.

# Getting Solutions

If  $W(y_1, y_2)(t_0) = 0$ , however, then the answer depends on  $y_0$  and  $y'_0$ . Most of the time, it will not be possible to choose  $c_1$  and  $c_2$ . If  $y_0$  and  $y'_0$  are related in exactly the right way, however, then there will be infinitely many choices that “work”. We are less interested in this case. It is comparatively rare.

# Wronskians and the General Solution

We are only justified in using the term “general solution” if every solution to  $ay'' + by' + cy = 0$  is of the form  $c_1y_1 + c_2y_2$ .

## Theorem 3.2.4

Suppose that  $y_1$  and  $y_2$  are *any* two solutions of  $y'' + p(t)y' + q(t)y = 0$ . Then the family of solutions  $y = c_1y_1 + c_2y_2$  includes every solution of the differential equation if and only if there is at least one point  $t_0$  for which  $W(y_1, y_2)(t_0) \neq 0$ .

# Abel's Theorem

We close with an interesting formula concerning Wronskians. It is due to the Norwegian mathematician Niels Henrik Abel (1802–1829).

## Abel's Theorem

If  $y_1$  and  $y_2$  are solutions of the differential equation as before, then

$$W(y_1, y_2)(t) = c \exp \left( - \int p(t) dt \right)$$

where  $c$  is independent of  $t$ .