Tangent planes and differentials

Math 251 Calculus 3

October 1, 2013

Recap: slices, partial derivatives, and tangent lines

We saw previously that if f(x, y) is a function of two variables, each of its partial derivatives $f_x(x, y)$ and $f_y(x, y)$ gives the slopes of tangent lines to slice curves.

If (a, b) is a point in the plane, the slice curves through (a, b) are the graphs of z = f(a, y) (in the plane x = a) and z = f(x, b) (in the plane y = b).

Partial derivatives

If the slice functions f(a, y) and f(x, b) are differentiable (in the one-variable sense), their derivatives are $f_y(a, y)$ and $f_x(x, b)$. These functions are ordinary derivatives, so they compute tangent slopes in the usual way.

► The tangent line equations:

This is the old tangent line approximation formula, just twice in different directions.

Partial derivatives

If the slice functions f(a, y) and f(x, b) are differentiable (in the one-variable sense), their derivatives are $f_y(a, y)$ and $f_x(x, b)$. These functions are ordinary derivatives, so they compute tangent slopes in the usual way.

- ► The tangent line equations:
- $z = f(a, b) + f_x(a, b)(x a)$

This is the old tangent line approximation formula, just twice in different directions.

Partial derivatives

If the slice functions f(a, y) and f(x, b) are differentiable (in the one-variable sense), their derivatives are $f_y(a, y)$ and $f_x(x, b)$. These functions are ordinary derivatives, so they compute tangent slopes in the usual way.

- ► The tangent line equations:
- $ightharpoonup z = f(a, b) + f_x(a, b)(x a)$
- $ightharpoonup z = f(a, b) + f_y(a, b)(y b)$

This is the old tangent line approximation formula, just twice in different directions.

A candidate for the tangent plane

The tangent lines in the (x, y)-direction determine a unique plane. Its equation is

$$z = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b).$$

Rearranging this a bit, we can confirm it's a plane:

$$\langle f_x(a,b), f_y(a,b), -1 \rangle \cdot \langle x-a, y-b, z-f(a,b) \rangle = 0.$$

By 12.5, this is the equation of a plane passing through the point (a, b, f(a, b)) normal to the vector $\langle f_x(a, b), f_y(a, b), -1 \rangle$.

We call the RHS L(x, y) the linearization of f at the point (a, b).

Local linearity

Having a tangent plane means the graph of the surface is *locally linear*. If we zoom way in, the surface looks flat. The algebraic criterion for this turns out to be

$$\lim_{(x,y)\to(a,b)}\frac{f(x,y)-L(x,y)}{\|\langle x,y\rangle-\langle a,b\rangle\|}=0$$

and so we adopt this as the definition of differentiability.

Three ways to say it

All of the following are equivalent:

• f(x, y) is differentiable at (a, b)

Three ways to say it

All of the following are equivalent:

- f(x, y) is differentiable at (a, b)
- f(x, y) is locally linear at (a, b)

Three ways to say it

All of the following are equivalent:

- f(x, y) is differentiable at (a, b)
- f(x, y) is locally linear at (a, b)
- ▶ the graph of L(x, y) is tangent to the graph of f at (a, b)

Criteria for differentiability

If any plane is tangent to the graph of f at (a, b), it must be the graph of $L(x, y) = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$. That's the only plane that contains the tangent lines.

Observe that L(a, b) = f(a, b) and that the x = a (resp. y = b) slice of L(x, y) is the tangent line to the slice curve in the plane x = a (resp. y = b).

How do we know the tangent plane exists?

If f_x and f_y exist and are continuous at (a, b), then the three equivalent conditions given above are all true.

The linearization approximates f

If (x,y) is near (a,b) (in other words, if the magnitude $\|\langle x,y\rangle - \langle a,b\rangle\|$ is small), then $L(x,y)\approx f(x,y)$, because f is locally linear.

Let us write

$$ightharpoonup \Delta x = x - a$$
,

The linearization approximates *f*

If (x, y) is near (a, b) (in other words, if the magnitude $\|\langle x, y \rangle - \langle a, b \rangle\|$ is small), then $L(x, y) \approx f(x, y)$, because f is locally linear.

Let us write

- $ightharpoonup \Delta x = x a$,
- $ightharpoonup \Delta y = y b$, and

The linearization approximates f

If (x,y) is near (a,b) (in other words, if the magnitude $\|\langle x,y\rangle - \langle a,b\rangle\|$ is small), then $L(x,y)\approx f(x,y)$, because f is locally linear.

Let us write

- $\triangle x = x a$
- ▶ $\Delta y = y b$, and

Introducing: differentials

Then

$$\Delta f = f(x, y) - f(a, b)$$

$$\approx L(x, y) - L(a, b)$$

$$\approx f_x(a, b)\Delta x + f_y(a, b)\Delta y,$$

at least when Δx and Δy are small.

Differentials and linearization

The approximation: $\Delta f \approx f_x(a,b)\Delta x + f_y(a,b)\Delta y$.

It is common to write

- $ightharpoonup dx = \Delta x$
- $dy = \Delta y$
- $df = L(x,y) L(a,b) = f_x(a,b)dx + f_y(a,b)dy.$

Putting it all together, we have $\Delta f \approx df$, a compact representation of the idea of the linearization. The symbols dx, dy, df are often called "differentials".

What are differentials?

It is common to write $dx = \Delta x$, $dy = \Delta y$, $df = L(x, y) - L(a, b) = f_x(a, b)dx + f_y(a, b)dy$.

For now, it's best to think of them as convenient abbreviations. The convenience lies in that while dx = x - a, the a is suppressed from the notation. So we can abbreviate even further

$$df = f_x dx + f_y dy = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy.$$

Of course, one has to remember to evaluate the partials at the appropriate point, but that detail aside, this is quite a compact form for the equation of the tangent plane (supposing it exists).

Abstract nonsense concerning derivatives

We've talked a lot by now about the *partial* derivatives of f(x, y). So what about its actual *derivative*? The best answer, for now, is that the derivative of f(x, y) is the differential df. This is a little peculiar, at first. We won't have much occasion to use this particular notion.

Nonsense, II

Another answer might be that the derivative is the vector $\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \rangle$. This is satisfying, because this vector seems related to the normal to the tangent plane, something like a "tangent slope". This vector is the *gradient vector* of the function f and we'll see a lot more of it.

▶ If the partial derivatives $f_x(a, b)$ and $f_y(a, b)$ exist, we can discuss the linearization L(x, y)

- ▶ If the partial derivatives $f_x(a, b)$ and $f_y(a, b)$ exist, we can discuss the linearization L(x, y)
- ► $L(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$ is the linearization of f at (a,b)

- ▶ If the partial derivatives $f_x(a, b)$ and $f_y(a, b)$ exist, we can discuss the linearization L(x, y)
- ► $L(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$ is the linearization of f at (a,b)
- ▶ The graph of L is a plane passing through (a, b, f(a, b))

- ▶ If the partial derivatives $f_x(a, b)$ and $f_y(a, b)$ exist, we can discuss the linearization L(x, y)
- ► $L(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$ is the linearization of f at (a,b)
- ▶ The graph of *L* is a plane passing through (a, b, f(a, b))
- ▶ If f is locally linear (=differentiable), then the graph of L is tangent to the graph of f