

September 11, 2013

Due: Friday, September 13

Name: \_\_\_\_\_

## 1 Workshop 01

This workshop will confirm what is, to varying degrees for various people, intuitively clear: that all the nonempty slices of a sphere by planes are circles (we adopt the severely reasonable convention that a circle of radius 0 is a point). Be ready to submit this paper on Friday. Workshop grades are mostly participation: if you appear in class, make an honest effort, and submit on time, you receive all or nearly all of the points.

### 1.1 Warm-up

Recall that the *unit sphere* in  $\mathbf{R}^3$  is the sphere of radius 1 centered at  $(0, 0, 0)$ . Its equation is

$$x^2 + y^2 + z^2 = 1.$$

1. Give equations of all the planes parallel to the  $(y, z)$ -plane that miss the unit sphere.
2. How many planes parallel to the  $(y, z)$ -plane meet the sphere at one point? Give equations for all of them.

### 1.2 Brute force

You read in [Module 03][m03] that it is possible to prove algebraically that the intersection of a sphere and a plane is a circle (provided the intersection contains more than one point). After enough mental aerobics, this certainly seems *plausible*. But is it completely, unambiguously obvious that it's impossible to get an elliptical cross-section?

A completely coordinatized approach to this problem involves choosing a sphere with arbitrary center and radius and an arbitrary plane. Using a result about the classification of planes (we shall do this after we have more vector technology ready to deploy), this will involve solving a system of two simultaneous nonlinear equations in eight variables:

$$\begin{aligned}(x - a)^2 + (y - b)^2 + (z - c)^2 &= r^2 \\ Ax + By + Cz &= D\end{aligned}$$

This approach is easy to set up, but a pain in the rear to work out the details, and not very illuminating. Instead, we'll unleash the kung fu of symmetry to deal with this complicated geometric situation.

### 1.3 Symmetry and WLOG

The idea behind a symmetry argument is that a special case might not really be all that special. For us, the special case will be:

The sphere is the unit sphere and the plane is of the form  $z = A$ .

It seems very special: after all, there are many, many spheres other than the unit sphere, and many planes that are not horizontal. But think of it like a videographer: the right angle and zoom turns any situation into this special one.

That's what we mean by symmetry, or the mathematical abbreviation WLOG. This stands for **Without Loss Of Generality**. The phrase signifies the idea encapsulated above: that what appears to be a special case is in fact sufficiently general.

### 1.4 The unit sphere and a horizontal plane

1. Draw a big, beautiful picture of the unit sphere sliced by a horizontal plane. Remember the drawing tips:
  - Get the angles right. Make the parallelogram of your plane parallel to the  $x$ - and  $y$ -axes.
  - Draw a \*big\* picture. Big pictures have more room for labels.
  - Don't be afraid to erase.

2. Now, we're still solving two equations. What are they? (Hint: you're intersecting two surfaces.)
3. Explain why this situation is algebraically preferable to the brute-force solution outlined above.
4. Write down two equations that all the points in the intersection of the sphere and the plane satisfy. (Hint: one equation involves  $x$  and  $y$  only, and the other involves  $z$  only.)
5. Identify the flaw in this attempted use of WLOG.

*Consider the cylinder of radius 1 with axis the  $x$ -axis and the  $(y, z)$ -plane. The intersection is evidently the circle of radius 1, centered at  $(0, 0, 0)$ , and contained in the  $(y, z)$ -plane.*

*Therefore, we can say that WLOG, whenever a cylinder is cut by a plane, the intersection is a circle. This is because we can always "rotate and zoom" to place the cylinder so that its radius is 1 and its axis is the  $x$ -axis.*