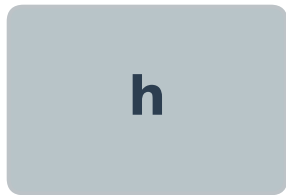


**Original**

**Steered**

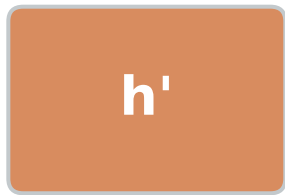


*hidden state*

**+  $\alpha v$**



*steering  
vector*



*modified state*

$$\mathbf{h}' = \mathbf{h} + \alpha \mathbf{v}$$