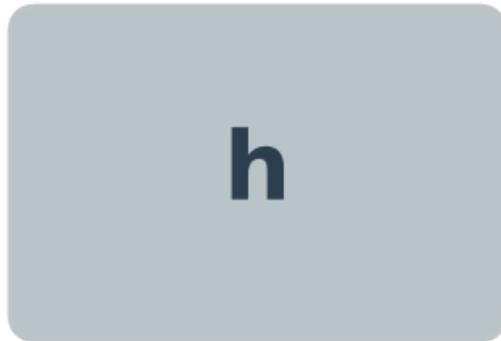


Original



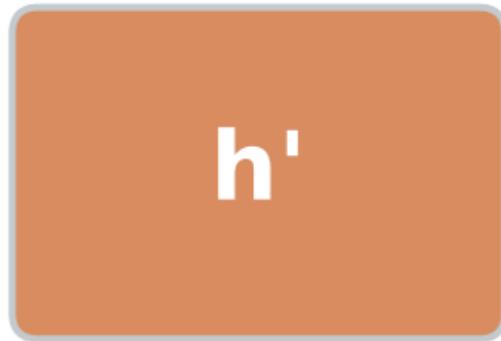
hidden state

$+ \alpha v$



*steering
vector*

Steered



modified state

$$h' = h + \alpha v$$