On the sensitivity of food webs to multiple disturbances

David Beauchesne 1,2,* , Kevin Cazelles 3 , Philippe Archambault 2 , Dominique Gravel 4

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<sup>1</sup>Institut des sciences de la mer, Université du Québec à Rimouski, Rimouski, QC, Canada
   <sup>2</sup>Québec Océan, Département de biologie, Université Laval, Québec, QC, Canada
   <sup>3</sup>Department of Integrative Biology, University Of Guelph, Guelph, Ontario, Canada N1G
   <sup>4</sup>Département de biologie, Université de Sherbrooke, Sherbrooke, QC, Canada
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   Correspondence:
   David Beauchesne
   david.beauchesne@ugar.ca
   1-514-553-4975
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32 Proposal letter

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\mathbf{Notes}

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- In it's current form, I believe that the contribution portion is not good enough
- I wonder whether the qualitications should be more in depth.
- Right now, the letter is 43 words over the word limit.
- Also, this text might be better than the current abstract

46 Letter

Evaluating the effects of multiple sources of stress in natural environments has become an increasingly important issue as the effects of intensifying global change and expanding human activities result in complex stress exposure regimes. Even though the non-additive effects of multiple stressors have been investigated empirically for a few decades now, there remains a general lack of theoretical understanding of their impacts on natural systems. 51 In particular, the role of species and their interactions in mediating the effects of multiple disturbances through ecological communities, although widely acknowledged, has yet to be formally explored. We propose the first such formal exploration by exhaustively simulating the impacts of all possible pathways of effects on the dynamics of 3-species motifs using 55 Lotka-Volterra models. We uncover that interaction types and species position greatly influence sensitivity to and amplification of multiple disturbances and that indirect pathways of 57 effects are the main cause of non-additive effects. In particular, predators in food chain and omnivory interactions act as both weak entry points (i.e. highly sensitive to disturbances) 59 and biotic amplifiers (i.e. affected synergistically by disturbances). We then use the simluated sensitivity and amplification scores as heuristics to infer trophic vulnerability of species 61 based on topology and realised pathways of effects in the food web of the Northern Gulf of St. Lawrence, Canada, prior to a groundfish stock collapse in the 1990s. We find that heavily 63 exploited species appear to be the most vulnerable trophically, while fisheries transitioned to insensitive or beneficiary species post-collapse. This contribution is significant and timely theoretically as the first exploration of the effects of multiple disturbances on structual properties of food webs, as well as practically by answering questions crucial to management. Our group of co-authors is singularly positioned to write this paper. D. Beauchesne and

- 69 P. Archambault both have strong backgrounds in environmental assessments in general and
- $_{70}$ cumulative impacts in particular. K. Cazelles and D. Gravel are both experts in theoretical
- ecology with strong backgrounds and recognition in the field.

2 1 Abstract

Evaluating the effects of multiple sources of stress in natural environments has become an increasingly important issue as the effects of intensifying global change and expanding human activities result in complex stress exposure regimes. Even though the non-additive effects of multiple stressors have been investigated empirically for a few decades now, there remains a general lack of theoretical understanding of their impacts on natural systems. In particular, the role of species and their interactions in mediating the effects of multiple disturbances through ecological communities, although widely acknowledged, has yet to be formally explored. We propose the first such formal exploration by exhaustively simulating trophic impacts through all possible pathways of effects on the dynamics of 3-species motifs using 81 Lotka-Volterra models. We uncover that interaction types and species position greatly influence sensitivity to and amplification of multiple disturbances and that indirect pathways of 83 effects are the main source of non-additive effects. In particular, predators in food chain and 84 omnivory interactions act as both weak entry points (i.e. highly sensitive to disturbances) 85 and biotic amplifiers (i.e. affected synergistically by disturbances). We then use the simulations results as heuristics to infer trophic vulnerability of species based on topology and realised pathways of effects in the food web of the Northern Gulf of St. Lawrence, Canada, prior to a groundfish stock collapse in the 1990s. We find that heavily exploited species appear to be the most vulnerable trophically, while fisheries transitioned to insensitive or beneficiary species post-collapse.

⁹² 2 Introduction

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Global changes and human activities result in increasingly intricate environmental stress exposure regimes that can induce complex and unpredictable effects (???; Côté et al. 2016; Bowler et al. 2019). This cocktail of environmental pressures impedes our ability to evaluate and partition the effects of interacting drivers in cumulative effects assessments (???; ???; Jones 2016). This is in part due to the breadth and interaction potential of environmental pressures operating on natural systems (Côté et al. 2016), compounding the pathways of effects through which natural systems can be impacted. Another factor is the potential for non-additive affects, when the effect of multiple interacting drivers is greater (i.e. synergism) 100 or lower (i.e. antagonism) than the sum of their individual parts, which have been found to 101 be the norm rather than the exception (e.g. Darling & Côté 2008; ???; Crain et al. 2008; 102 Jackson et al. 2016). 103 Common drivers of environmental stress include climate change, resource exploitation and 104 pollution (???; ???). Drivers have typically been described according to their effects on 105 habitats [*e.g. (???); (???)]. For instance, fisheries can destroy benthic habitats and extract 106 biomass. Focusing on habitats conveniently circumscribes assessments to a set of tractable units. It also has the drawback of aggregating processes operating at lower levels of ecological organization that we know respond differently to driver exposure (???; ???). For example, 109 hypoxia decreases overall habitat quality but has species-dependent effects, ranging from 110 well-adapted (???) to avoidance behaviour (???), reduced growth (???) and mortality 111 (???; ???; ???). As a consequence, current practice to assess the effects of multiple drivers 112 has offered little insight into underlying ecological mechanisms (Griffen et al. 2016; Jackson 113 et al. 2016; De Laender 2018; Schäfer & Piggott 2018). Focusing on ecosystem components 114 such as species and communities has thus been deemed necessary to provide a mechanistic 115 understanding of the effects of multiple drivers (???; ???) 116

At the species and community scales, drivers may be more appropriately described as eco-

logical process modifiers, which we define as natural or anthropogenic processes resulting in
a disturbance to ecological processes (Figure 1A). Drivers may disturb a variety of ecological
processes such as behaviour (e.g. ???; ???), reproduction (e.g. ???), physiology (e.g. ???),
mortality (e.g. ???), and species interactions (e.g. ???). Multiple processes may be affected
by a single driver, while multiple drivers may target a single process. Through this lens,
disturbances to cod behaviour and mortality may arise from benthic habitat destruction and
from direct extraction, respectively.

Species interactions are particularly relevant in the context of multiple disturbances, as 125 they may serve as the indirect pathways through which pressures permeate entire ecological 126 communities (Wootton 2002; Bascompte 2009; Montoya et al. 2009; Thompson et al. 2018). 127 Indirect effects, i.e. when two or more direct effects are linked by a single species involved in 128 both effects, may be as important of, and propagate faster than, direct effects (Wootton 1993, 2002; Menge 1995; Yodzis 2000). In multi-species systems, where both direct and indirect effects are operating simultaneously, it is expected that the effects of environmental pressures 131 will be amplified or dampened through biotic interactions (???; Wootton 2002; Thompson et al. 2018). Provide examples here, cite ogorman2009; ogorman2012;ghedi2015 133 Interaction strength and type (e.q. omnivory vs apparent competition) have also been linked 134 to enhanced or decreased community persistance (???; ???; Allesina & Pascual 2008). How 135 species are embedded in complex communities is therefore likely to affect their sensitivity to 136 and amplification of single and multiple disturbances. 137

The complexity of empirical food webs is however prohibitive to investigations of community dynamics. Studying smaller subgraphs - community motifs or modules - has thus emerged as an alternative to gather insights into the dynamics and stability of complex ecological communities (Holt 1997; 2001). Motifs are collections of *n*-species that, when put together, construct whole food webs (Milo *et al.* 2002; Stouffer *et al.* 2007). They form the backbone of food webs and provide a mesoscale characterization of community structure (Bascompte & Melián 2005; Stouffer *et al.* 2007). A species can be described as a function of all *n*-species

motifs it is involved in in an empirical food web (Figure 1B; Stouffer et al. 2012).

There are 13 distinct 3-species motifs composed of 30 unique positions (Milo et al. 2002;
Stouffer et al. 2007, 2012). Four 3-species motifs have received particular attention in theoretical and empirical studies due to their roles (???) and prevalence (Camacho et al. 2007;
Stouffer & Bascompte 2010) in food webs: tri-trophic food chain, omnivory or intraguild predation, exploitative competition and apparent competition. Add some discussion here
on archetypes of each motifs, trophic cascades and compensatory dynamics. To
cite: cote1995; ogorman2010; ogorman2012;

Motif dynamics has been studied extensively to uncover how structural properties of food webs can benefit community persistence and stability (Allesina & Pascual 2008; Kondoh 154 2008; Stouffer & Bascompte 2010, 2011; Monteiro & Faria 2016) and to assess the structural 155 roles of species within food webs (Stouffer et al. 2012; Cirtwill & Stouffer 2015). These 156 provide meaningful insights for conversation efforts. For example, results from Stouffer et 157 al. (2012) suggest that species benefit whole community persistence based on their trophic 158 position and that the diversity of trophic roles found in empirical food webs does not correlate 159 to species richness. Using roles as targets may thus be valuable for community conservation 160 (Stouffer et al. 2012). Additional insights into the structural properties of food webs could 161 be gathered by studying motifs at equilibrium, i.e. when system dynamics is constrained by 162 species coexistance (Figure 1C). This is of particular relevance to managers using ecosystem-163 based approaches to manage and maintain exploited populations, rather than ensure the 164 persistance of species. 165

Here, we study the equilibrium dynamics of the most prevalent 3-species motifs in food webs

(i.e. food chain, omnivory, exploitative competition, and apparent competition) to investigate and infer the structural role of species and their interactions in mediating the effects of
individual and multiple disturbances on food webs. In doing so, we seek to answer questions
of particular significance to management: 1) should species interactions be considered in im-

pact assessments, 2) should the effects of stressors be evaluated seperately or in combination,

and 3) which species are most vulnerable to disturbances based on their trophic position?

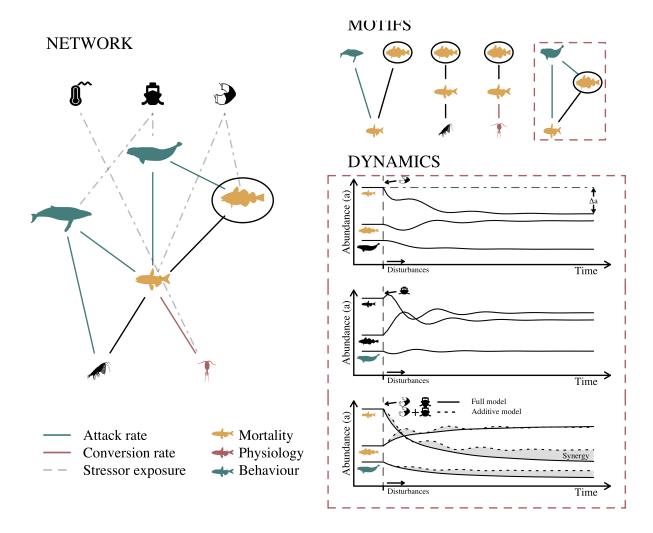


Figure 1: Conceptualization of the effects of multiple sources of environmental stress on the dynamics of a theoretical food web. A) Drivers such as sea surface temperature, marine traffic and fisheries penetrate food webs through various pathways of effects by disturbing ecological processes governing populations and communities. For instance, marine traffic disturbs whale feeding behaviour, which may lead to decreased attack rates on prey species. B) A species position in a food web can be decomposed in a suite of n-species submodules called motifs that are informative of the role played by a species in the entire food web. Different types of interaction types will lead to different types of community dynamics and a species can be described as a function of the number and types of interactions it is involved in. For instance, the interactions of the meso-predator can be decomposed into 1 exploitative competition, 2 food chains and 1 omnivory motifs. C) The dynamics of motifs can uncover if and how disturbances arising from individual and multiple drivers are propagated and amplified through different types of species interactions. Variations in species abundance due to driver induced disturbances provide an evaluation of motif species sensitivity (C1-3). The difference between the summed effects of individual drivers (i.e. additive model; C1-2) and the joint effects of multiple drivers (i.e. full model; C3) provides an evaluation of disturbance amplification.

3 Sumulating disturbances

$_{74}$ 3.1 Models

The dynamics of the four most abundant 3-species motifs (*i.e.* tri-trophic food chain, omnivory, exploitative and apparent competition) in empirical food webs (Stouffer & Bascompte 2010) were modeled using Lotka-Volterra equation systems (Table S1). Two additional motifs were included to serve as controls to test the importance of considering species interactions when evaluating environmental effects, *i.e.* a partially connected motifs with a disconnected species and a predator-prey interaction, and a fully disconnected motif with three independent species.

Resources were modeled using logistic growth equations of the form

$$\frac{dX_i}{dt} = X_i(r_i - \alpha_{ii}X_i - \sum \alpha_{ij}X_j)$$

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where X are species, i is the resource, j are the consumers, r_i is the intrinsic resource growth rate, α_{ii} is the density-dependent effect of the resource on itself and α_{ij} is the rate at which consumer j affects resource i, i.e. the attack rate.

187 Consumers were modeled using a Type I functional response of the form

$$\frac{dX_j}{dt} = X_j(-m_j + \sum_{i,j} e_{ij}\alpha_{ij}X_i - \alpha_{jk}X_k)$$

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where m is the mortality rate and e is the rate at which resource biomass is transformed into consumer biomass, *i.e.* the conversion rate, and is a scaling parameter of the attack rate which cannot exceed 1.

Models were solved at equilibrium to study the effects of disturbances on persistent motif dynamics. As no equilibrium exists for the exploitative competition motif with Lotka-Volterra models of the selected forms, competitive parameters of the form

$$\alpha_{jj}\alpha_{jk}X_jX_k - \alpha_{jj}X_j^2$$

were included in the consumer models to constrain their growth.

$_{96}$ 3.2 Disturbances

For each motif, a 1% change in initial equilibria equations parameter values was applied to simulate negative disturbances through all possible unique pathways of univariate and 198 multivariate effects. Parameters selected to simulate disturbances were those related to 199 population growth (r and m) and interaction rates $(e \text{ and } \alpha_{ij})$, as their effects on population 200 dynamics can readily be attributed to environmental pressure effects. For example, cod 201 mortality will increase through fishing activities, whale attack rates on krill will be altered 202 by behavioural changes induced by marine traffic, and conversion rates of copepods by capelin 203 will be reduced through physiological effects of temperature anomalies on copepods. 204 Initial parameter values for intrinsic growth (r) and resource density-dependence (α_{ii}) were 205 fixed to 1 and 0.001, respectively, to bound all resource solutions. Competitive parameters 206 for the exploitative competition motif were also fixed at 0.001 since those parameters were not to be investigated in our analyses. Conversion rates (e) were fixed to 0.5. Finally, a 208 total of 100 sets of mortality (m) and attack rates (α_{ij}) were evaluated using a simulated annealing algorithm optimizing for consumer abundance.

²¹¹ 4 Trophic sensitivity

For each 13 unique motif positions considered and all unique pathways of effects, the variation
in abundance between the 100 sets of initial conditions and disturbed conditions was used
as a proxy of trophic sensitivity $(s_{i,j})$ to disturbances:

$$s_{i,j} = \frac{a_{i,j} - a_i}{a_i}$$

where i is a motif position, j is a unique pathway of effect, a_i is the initial abundance at position i, and $a_{i,j}$ is the abundance at position i after the simulation of the pathway of effect j. Sensitivity scores are bounded negatively to -1, as abundances cannot fall below 0. The sensitivity score used for a single pathway of effect $(S_{i,j})$ is the mean of the 100 simulation using all initial conditions:

$$S_{i,j} = \frac{1}{n} \sum_{l=1}^{n} s_{i,j}$$

A score of position sensitivity (S_i) was evaluated using the mean of the set of all possible pathways of effect (K^i) for a give position i:

$$S_i = \frac{1}{|K^i|} \sum_{j \in K^i} S_{i,j}$$

We define weak entry points as particularly sensitive pathways of effect $(|S_{i,j}| > 1)$ or motif positions $(|S_i| > 1)$, while biotic sinks are insensitive pathways of effects $(|S_{i,j}| = 0)$ or motif positions $(|S_i| = 0)$.

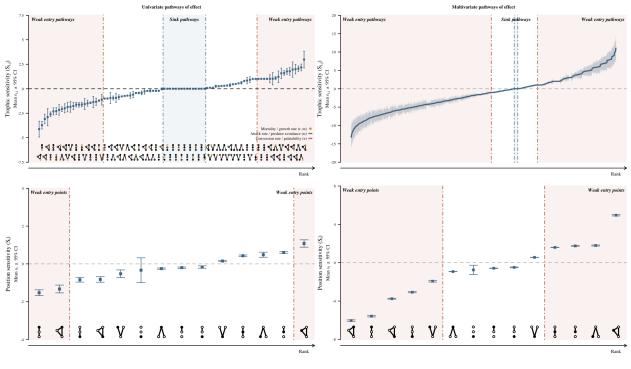


Figure 2

5 Trophic amplification

To evaluate whether the effects of disturbances should be investigated in combination, a score of trophic amplification was evaluated to

A score of trophic amplification $(A_{i,j})$ was measured to evaluate the potential of pathways of effects to result in non-additive effects:

$$A_{i,j} = S_{i,K_j} - \sum_{k_j \in K_j} S_{i,j}$$

where K_j is a multivariate pathway of effect j and k_j are unitary pathways of effect composition j. The amplification score evaluates the deviance of a multivariate pathway of effect and the sum of the univariate effects composing the pathway of effect, i.e. the additive model. Thus, a value of 0 identifies a null of additive effect, a value below 0 identifies an

234 antagonistic effect, and a value over 0 identifies synergistic effects.

A score of position amplification (A_i) was evaluated using the mean of the set of all possible pathways of effect (K^i) for a give position i:

$$A_i = \frac{1}{|K^i|} \sum_{j \in K^i} A_{i,j}$$

We define biotic amplifiers as multivariate pathways of effect or motif positions that are more affected than expected from an additive model $(A_{i,j} > 0.0005, A_i > 0.0005)$. Biotic buffers are multivariate pathways of effect or motif positions that are less affected than expected from an additive model $(A_{i,j} < 0.0005, A_i < 0.0005)$.

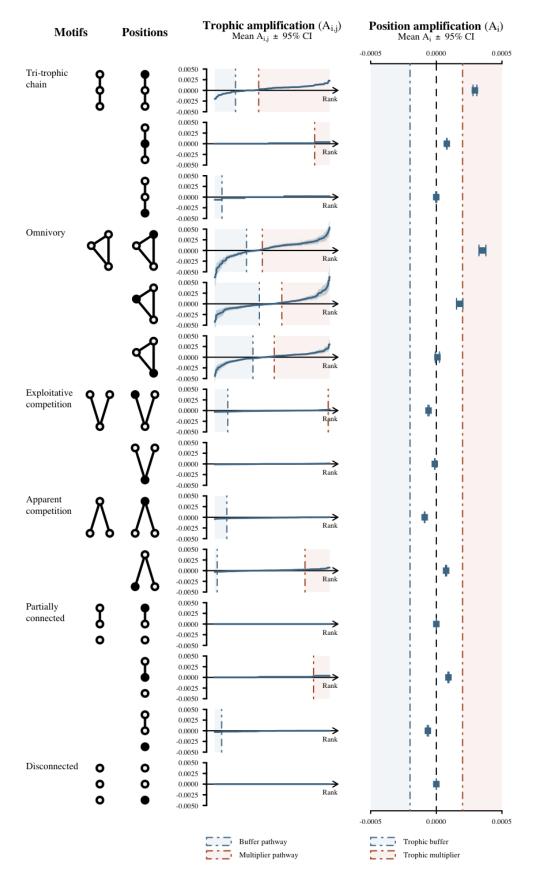


Figure 3

²⁴¹ 6 Species vulnerability

We define two sets of scores at the species level. The first requires no information on realised pathways of effect and provides a general evaluation of a species sensitivity and amplification potential based on the frequency of times it occupies a position in a food web:

$$S_m = \sum_i f_m i S_i$$

$$A_m = \sum_i f_m i A_i$$

where S_m and A_m are the sensitivity and amplification scores of species m, respectively, $f_m i$ is the frequency at which species m occupies position i in a food web, and S_i and A_i are the sensitivity amplification scores at position i, respectively.

The second set of scores at the species level uses a list of realised pathways of effect:

$$S_m = \sum_{j \in K^{i*}}^{position} S_{i,j}$$

$$A_m = \sum_{j \in K^{i*}}^{position} A_{i,j}$$

where S_m and A_m are the sensitivity and amplification scores of species m, respectively, jare pathways of effect, K^{i*} is the set of realised pathways of effects for position i, and $S_{i,j}$ and $A_{i,j}$ are the sensitivity and amplification scores for pathway of effect j on position i

6.1 Empirical food webs

We used empirical food web data from the Estuary and Gulf of St. Lawrence, in eastern
Canada, to evaluate the sensitivity and amplification scores of its constituent species. The

food webs come from different regions of the St. Lawrence and different time periods, and contain different yet overlapping functional groups. The Northern (???) and Southern (???)

St. Lawrence food webs were for the mid-1980s, prior to the groundfish stock collapses of the early 1990s, and contain the same functional groups. The Estuary food web, meanwhile, contains more functional groups and represents the beginning of the 2010s (???). See supplementary materials for a description of the food webs used for this analysis.

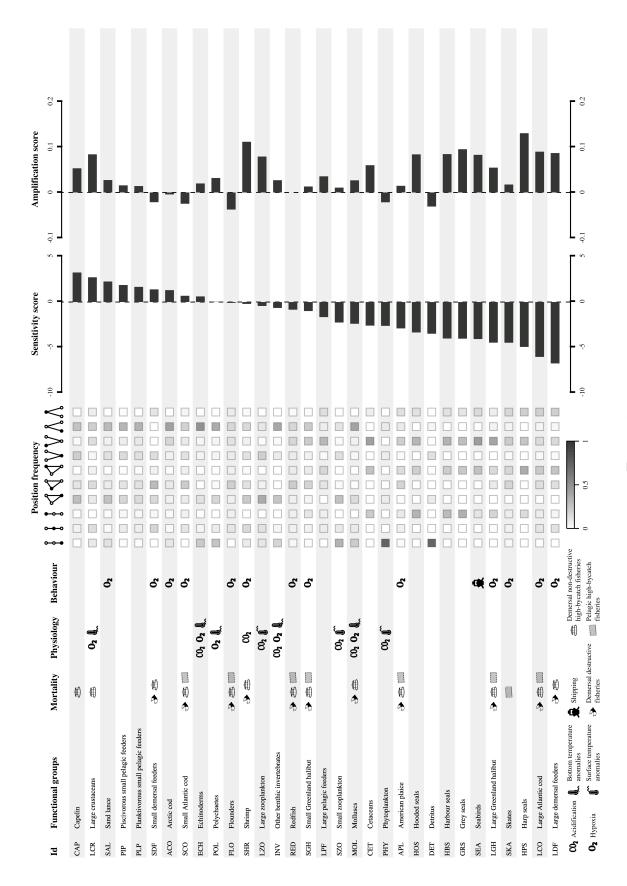


Figure 4

⁶¹ 7 Supplementary Material

7.1 Models

Motifs	Equation systems	Initial parameters values
Tri-trophic food chain	$ \frac{\frac{dX_i}{dt}}{\frac{dX_j}{dt}} = X_i(r_i - \alpha_{ii}X_i - \alpha_{ij}X_j) $ $ \frac{\frac{dX_j}{dt}}{\frac{dX_j}{dt}} = X_j(e_{ij}\alpha_{ij}X_i - \alpha_{jk}X_k - m_j) $ $ \frac{dX_k}{dt} = X_k(e_{jk}\alpha_{jk}X_j - m_k) $	$r_{i} = 1$ $\alpha_{ii} = 0.001$ $\alpha_{ij}, \alpha_{jk} \in [0.0001, 0.01]$ $e_{ij}, e_{jk} = 0.5$ $m_{j}, m_{k} \in [0.01, 0.5]$
Omnivory	$ \frac{dX_i}{dt} = X_i(r_i - \alpha_{ii} - \alpha_{ij}X_j - \alpha_{ik}X_k) $ $ \frac{dX_j}{dt} = X_j(e_{ij}\alpha_{ij}X_i - \alpha_{jk}X_k - m_j) $ $ \frac{dX_k}{dt} = X_k(e_{ik}\alpha_{ik}X_i + e_{jk}\alpha_{jk}X_j - m_k) $	$r_{i} = 1$ $\alpha_{ii} = 0.001$ $\alpha_{ij}, \alpha_{ik}, \alpha_{jk} \in [0.0001, 0.01]$ $e_{ij}, e_{ik}, e_{jk} = 0.5$ $m_{j}, m_{k} \in [0.01, 0.5]$
Exploitative competition	$\frac{\frac{dX_i}{dt}}{\frac{dX_j}{dt}} = X_i(r_i - \alpha_{ii} - \alpha_{ij}X_j - \alpha_{ik}X_k)$ $\frac{\frac{dX_j}{dt}}{\frac{dX_k}{dt}} = X_j(e_{ij}\alpha_{ij}X_i - \alpha_{jj}\alpha_{jk}X_k - \alpha_{jj}X_j - m_j)$ $\frac{dX_k}{dt} = X_k(e_{ik}\alpha_{ik}X_i - \alpha_{kk}\alpha_{kj}X_j - \alpha_{kk}X_k - m_k)$	$r_{i} = 1$ $\alpha_{ii}, \alpha_{jj}, \alpha_{kk}, \alpha_{jk}, \alpha_{kj} = 0.001$ $\alpha_{ij}, \alpha_{ik}, \in [0.0001, 0.01]$ $e_{ij}, e_{ik} = 0.5$ $m_{j}, m_{k} \in [0.01, 0.5]$
Apparent competition	$ \frac{dX_i}{dt} = X_i(r_i - \alpha_{ii}X_i - \alpha_{ik}X_k) $ $ \frac{dX_j}{dt} = X_j(r_j - \alpha_{jj}X_j - \alpha_{jk}X_k) $ $ \frac{dX_k}{dt} = X_k(e_{ik}\alpha_{ik}X_i + e_{jk}\alpha_{jk}X_j - m_k) $	$r_{i}, r_{j} = 1$ $\alpha_{ii}, \alpha_{jj} = 0.001$ $\alpha_{ik}, \alpha_{jk} \in [0.0001, 0.01]$ $e_{ik}, e_{jk} = 0.5$ $m_{k} \in [0.01, 0.5]$
Partially disconnected	$ \frac{\frac{dX_i}{dt}}{\frac{dX_j}{dt}} = X_i(r_i - \alpha_{ii}X_i - \alpha_{ik}X_k) $ $ \frac{\frac{dX_j}{dt}}{\frac{dX_k}{dt}} = X_j(r_j - \alpha_{jj}X_j) $ $ \frac{dX_k}{dt} = X_k(e_{ik}\alpha_{ik}X_i - m_k) $	$r_{i}, r_{j} = 1$ $\alpha_{ii}, \alpha_{jj} = 0.001$ $\alpha_{ik} \in [0.0001, 0.01]$ $e_{ik} = 0.5$ $m_{k} \in [0.01, 0.5]$
Disconnected	$ \frac{dX_i}{dt} = X_i(r_i - \alpha_{ii}X_i) \frac{dX_j}{dt} = X_j(r_j - \alpha_{jj}X_j) \frac{dX_k}{dt} = X_k(r_k - \alpha_{kk}X_k) $	$r_i, r_j, r_k = 1$ $\alpha_{ii}, \alpha_{jj}, \alpha_{kk} = 0.001$

Table 1: Systems of Lotka-Volterra equations used to model the effect of multiple disturbances

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