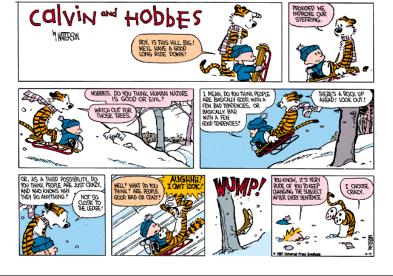
Review



How many AI researchers does it take to change a lightbulb?

The Problem Space Group

- One to define the goal state
- One to define the operators
- One to describe the universal problem solver
- One to hack the production system
- One to indicate about how it is a model of human lightbulb-changing behavior
- One to call the Lisp hackers

[Rich and Knight, 1991]

The Lisp Hackers

- One to bring up the network
- One to order the Chinese food
- Four to hack on the Lisp debugger, compiler, window system, and microcode
- One to write the lightbulb-changing program

How many AI researchers does it take to change a lightbulb?

The Logic Group

- One to figure out how to describe lightbulb changing in predicate logic
- One to show the adequacy of predicate logic
- One to show the inadequacy of predicate logic
- One to show that lightbulb logic is nonmonotonic
- One to show that it isn't nonmonotonic
- One to incorporate nonmonotonicity into predicate logic
- One to determine the bindings for the variables
- One to show the completeness of the solution
- One to show the consistency of the solution
- One to hack a theorem prover for lightbulb resolution
- One to indicate how it is a description of human lightbulb-changing behavior
- One to call the electrician

The Fuzzy Logic Group

 One to point out that, in the real world, a lightbulb is never "on" or "off", but usually somewhere in between

How many AI researchers does it take to change a lightbulb?

The Robotics Group

- One to build a vision system to recognize the dead bulb
- One to build a vision system to locate a new bulb
- One to figure out how to grasp the lighbulb without breaking it
- One to figure out the arm solutions that will get the arm to the socket
- One to organize the construction teams
- One to hack the planning system
- One to indicate how the robot mimics human motor behavior in lightbulb changing

The Game-Playing Group

- One to design a two-player game tree with the robot as one player and the lightbulb as the other
- One to write a minimax search algorithm that assumes optimal play on the part of the lightbulb
- One to build special-purpose hardware to enable 24-ply search
- One to enter the robot in a human lightbulb-changing tournament
- One to state categorically that lightbulb changing is "no longer considered AI"

How many AI researchers does it take to change a lightbulb?

The Learning Group

- One to collect thirty lightbulbs
- One to collect thirty "near misses"
- One to write a concept-learning program that learns to identify lightbulbs
- One to show that the program found a local maximum in the space of lightbulb descriptions

The Neural Network Group

- One to claim that lightbulb changing can only be achieved through massive parallelism
- One to build a backpropagation network to direct the robot arm
- One to assign initial random weights to the connections in the network
- One to train the network by showing it how to change a lightbulb (training shall consist of 500,000 repeated epochs)
- One to tell the media that the network learns "just like a human"
- One to compare the performance of the resulting system with that of symbolic learning approaches (optional)

Strong Al Position

- Machines that act intelligently can have real, conscious minds
- Weak Al doubts can be refuted
 - Locate a task thought impossible, design a program to accomplish task
 - Helps identify and remove Al researcher assumptions
- Strong Al doubts are difficult to refute
 - Hard to define
 - Hard to prove or disprove

Weak AI Position

- Machines can be made to act as if they were intelligent
 - There are things that computers cannot do, no matter how we program them
 - Certain ways of designing intelligent programs are bound to fail in the long run
 - The task of constructing the appropriate programs is infeasible

What if we Succeed?

- Legal responsibility
- Should intelligent agents have rights?
- How some perceive the future of AI
 - HAL
 - Matrix
- What do you think?
- How should we use this technology?







Topics

- Al Overview and Intelligent Agents
 - Definition of AI
 - Types of agents
 - Classification of environments
- Search
 - Generic search algorithm
 - Uninformed Search: DFS, BFS, UCS, IDS
 - Informed Search: Best-FS, Hill Climbing, Beam Search, A*, IDA*
 - Heuristics
 - f(n), g(n), h(n)
 - Global (e.g. BFS) vs. Local Search (e.g. Hill-Climbing)

Topics

- Constraint Satisfaction Problems
 - Defining CSPs
 - General search for CSP
 - Backtracking
 - Forward checking
 - Heuristics
- Game Tree Search
 - Zero-Sum Games
 - Game Trees
 - Minimax, Alpha-Beta Minimax
 - Evaluation functions
 - Variations:
 - 3-player games
 - Nondeterministic games

Topics

- Representation and Reasoning
 - Types of formal logic
 - Entailment
 - Proof methods: model checking, inference
 - Propositional logic
 - Normal forms
 - First-Order Predicate Calculus (FOPC)
 - ∀ and ∃
 - Unification
 - Conversion to CNF and resolution
 - Green's trick

Topics

- Planning
 - Stanford Research Institute Problem Solver (STRIPS) Operators
 - State-space planning
 - Plan-space planning
 - Partial-order planning
 - Graphplan algorithm
 - Scheduling

Topics

- Uncertainty Reasoning
 - Dealing with uncertainty
 - Probability basics
 - Axioms of probability
 - Bayes' Rule
 - Normalization
 - Bayes' Networks
 - Independence and conditional independence
 - Solving Bayes' Networks
 - Inference by enumeration
 - Summing out
 - Variable elimination
 - Tree method
 - Inference through stochastic simulation

Topics

- Markov Decision Processes (MDPs)
 - Defining an MDP
 - Markov Assumption
 - Expected utility
 - Bellman equation for utility
 - Value iteration
 - Policy iteration
 - Policy evaluation
 - Difference between MDPs and reinforcement learning