

LIST OF TODOS

It's not immediately obvious which relations analogous to the original R3 relations we want to choose. Here we try out several possible relations, in each case trying to prove an analogous lemma to Lemma 4.1 in Barot and Marsh's paper.

1. ATTEMPTS

1.1. Here we test out the set of relations R3' where if $i_{a_0}, i_{a_1}, \dots, i_{a_{d-1}}, i_{a_0}$ is a chordless cycle with all weights 1, then we add in the relation

$$s_0 s_1^{-1} s_2 s_3^{-1} \dots s_{d-2}^{(-1)^{d-2}} s_{d-1} s_{d-2}^{(-1)^{d-1}} \dots s_4^{-1} s_3 s_2^{-1} s_1 = s_1^{-1} s_2 s_3^{-1} \dots s_{d-2}^{(-1)^{d-2}} s_{d-1} s_{d-2}^{(-1)^{d-1}} \dots s_4^{-1} s_3 s_2^{-1} s_1 s_0$$

We then have

$$\begin{aligned} & s_{d-1} s_0^{-1} s_1 s_2^{-1} s_3 \dots s_{d-3}^{(-1)^{d-2}} s_{d-2} s_{d-3}^{(-1)^{d-3}} \dots s_4 s_3^{-1} s_2 s_1^{-1} s_0 \\ &= s_0^{-1} s_0 s_{d-1} s_0^{-1} s_1 s_2^{-1} s_3 \dots s_{d-3}^{(-1)^{d-2}} s_{d-2} s_{d-3}^{(-1)^{d-3}} \dots s_4 s_3^{-1} s_2 s_1^{-1} s_{d-1} s_{d-1}^{-1} s_0 \\ &= s_0^{-1} s_{d-1}^{-1} s_0 s_{d-1} s_1 s_2^{-1} s_3 \dots s_{d-3}^{(-1)^{d-2}} s_{d-2} s_{d-3}^{(-1)^{d-3}} \dots s_4 s_3^{-1} s_2 s_1^{-1} s_{d-1} s_{d-1}^{-1} s_0 \end{aligned}$$

...so I don't think this direction is going to work from here, simply because I don't see a way to flip all of the generators in the middle to their inverses.

Lemma 1.1. (*Analogue of 4.6*) Let W_Γ be generated by s_1, \dots, s_n . Then $s_1^{-1}, \dots, s_n^{-1}$ satisfy the relations (R2') and (R3') in $W_{\Gamma^{op}}$.

Proof. One can see that the elements satisfy (R2') in $W_{\Gamma^{op}}$ by taking the inverse of both sides of the relation in W_Γ . To see that the elements satisfy (R3') in $W_{\Gamma^{op}}$, note that for a chordless cycle in Γ with all weights equal to one, we have

$$s_0^{-1} \dots s_{d-2}^{-1} s_{d-1} s_{d-2} \dots s_0 = s_1^{-1} \dots s_{d-2}^{-1} s_{d-1} s_{d-2} \dots s_1$$

by the relation $r(0,1)$ in (R3') in W_Γ . But then applying relations from (R2'), we have that

$$s_0^{-1} \dots s_{d-1} s_{d-2} s_{d-1}^{-1} \dots s_0 = s_1^{-1} \dots s_{d-1} s_{d-2} s_{d-1}^{-1} \dots s_1,$$

and since the cycle is chordless, we then have

$$s_0^{-1} s_{d-1} \dots s_{d-3}^{-1} s_{d-2} s_{d-3} \dots s_{d-1}^{-1} s_0 = s_{d-1} s_1^{-1} \dots s_{d-3}^{-1} s_{d-2} s_{d-3} \dots s_1 s_{d-1}^{-1}.$$

Repeating this process, we find that

$$s_0^{-1} s_{d-1} s_{d-2} \dots s_2 s_1 s_2^{-1} \dots s_{d-2}^{-1} s_{d-1}^{-1} s_0 = s_{d-1} s_{d-2} \dots s_2 s_1 s_2^{-1} \dots s_{d-2}^{-1} s_{d-1}^{-1}.$$

But this can only occur if $s_1^{-1}, \dots, s_n^{-1}$ satisfies the relation $r(0, d-1)$ in $W_{\Gamma^{op}}$. Therefore, we are done. \square

An R3 that seems promising:

Definition 1.2. Using the notation as in Barot - Marsh, given a chordless cycle C in Γ so that all edges in C have weight 1, we define $r(a, a+1) = s_a s_{a+1}^{-1} s_{a+2}^{-1} \dots s_{a-2}^{-1} s_{a-1} s_{a-2} s_{a-3} \dots s_{a+1} = s_{a+1}^{-1} \dots s_{a-3}^{-1} s_{a-2}^{-1} s_{a-1} s_{a-2} \dots s_{a+1} s_a$.

Lemma 1.3. *The relation $r(a, a+1)$ for some vertex $a \in C$ implies the relation $r(b, b+1)$ for all $b \in C$.*

Proof. As in Barot-Marsh, it suffices to prove that the relation $r(0, 1)$ implies the relation $r(d-1, 0)$. So suppose W_γ satisfies the relation $r(0, 1)$. Then we have

$$\begin{aligned}
& s_{d-1}s_0^{-1}s_1^{-1} \dots s_{d-3}^{-1}s_{d-2}s_{d-3} \dots s_1s_0 \\
&= s_0^{-1}s_0s_{d-1}s_0^{-1}s_1^{-1} \dots s_{d-3}^{-1}s_{d-2}s_{d-3} \dots s_1s_{d-1}^{-1}s_{d-1}s_0 \\
&= s_0^{-1}s_{d-1}^{-1}s_0s_{d-1}s_1^{-1} \dots s_{d-3}^{-1}s_{d-2}s_{d-3} \dots s_1s_{d-1}^{-1}s_{d-1}s_0 \\
&= s_0^{-1}s_{d-1}^{-1}s_0s_1^{-1} \dots s_{d-3}^{-1}s_{d-1}s_{d-2}s_{d-1}^{-1}s_{d-3} \dots s_1s_{d-1}s_0 \\
&= s_0^{-1}s_{d-1}^{-1}(s_0s_1^{-1} \dots s_{d-3}^{-1}s_{d-2}s_{d-1}s_{d-2}s_{d-3} \dots s_1)s_{d-1}s_0 \\
&= s_0^{-1}s_{d-1}^{-1}(s_1^{-1} \dots s_{d-2}^{-1}s_{d-1}s_{d-2}s_{d-3} \dots s_0)s_{d-1}s_0 \\
&= s_0^{-1}s_{d-1}^{-1}(s_1^{-1} \dots s_{d-3}^{-1}s_{d-1}s_{d-2}s_{d-1}^{-1}s_{d-3} \dots s_0)s_{d-1}s_0 \\
&= s_0^{-1}s_1^{-1} \dots s_{d-3}^{-1}s_{d-2}s_{d-3} \dots s_1s_{d-1}^{-1}s_0s_{d-1}s_0 \\
&= s_0^{-1}s_1^{-1} \dots s_{d-3}^{-1}s_{d-2}s_{d-3} \dots s_1s_0s_{d-1}s_0^{-1}s_0 \\
&= s_0^{-1}s_1^{-1} \dots s_{d-3}^{-1}s_{d-2}s_{d-3} \dots s_1s_0s_{d-1}
\end{aligned}$$

as required. Note that line 3 is equal to 4 and line 7 is equal to line 8 since the cycle is chordless, meaning that s_{d-1} commutes with every element except s_0 and s_{d-2} . \square

Definition 1.4. Let Γ be a weighted diagram of finite type, and suppose $\Gamma' = \mu_k(\Gamma)$. If s_1, \dots, s_n are the generators in W_Γ , define:

$$t_i = \begin{cases} s_k s_i s_k^{-1} & \text{if there is arrow from } i \text{ to } k \\ s_i & \text{otherwise} \end{cases}$$

Lemma 1.5 (Generalized Lemma 5.1). *Let i and j be vertices of Γ .*

- (a) *If $i = k$ or $j = k$, then $(t_i t_j)^{m'_{ij}/2} = (t_j t_i)^{m'_{ij}/2}$.*
- (b) *If at most one of i, j is connected to k , then $(t_i t_j)^{m'_{ij}/2} = (t_j t_i)^{m'_{ij}/2}$*

Proof. We begin with case (a). Suppose that $i=k$. As in Barot-Marsh, we have that $m_{ij} = m'_{ij}$, and the only nontrivial case is when there is an arrow from j to k . Note that m_{ij} cannot be 2 in this case since there is an arrow from j to k , so suppose $m_{ij} = 3$. Then we have

$$s_j s_k s_j = s_k s_j s_k,$$

and so

$$s_k s_k s_j s_k = s_j s_k s_j s_k.$$

Multiplying both sides on the right by s_k^{-1} , we then obtain that

$$s_k s_k s_j = s_k s_j s_k s_k^{-1},$$

and so we find that

$$t_i t_j t_i = s_k s_k s_j s_k^{-1} s_k = s_k s_j s_k^{-1} s_k s_k s_j s_k^{-1} = t_j t_i t_j.$$

Now suppose $m_{ij} = 4$. Then

$$s_k s_j s_k s_j = s_j s_k s_j s_k$$

which means that

$$s_k s_k s_j s_k s_j = s_k s_j s_k s_j s_k.$$

This then gives us that

$$s_k s_k s_j s_k s_j s_k^{-1} = s_k s_j s_k s_j,$$

and so

$$t_i t_j t_i t_j = s_k s_k s_j s_k^{-1} s_k s_k s_j s_k^{-1} = s_k s_j s_k^{-1} s_k s_k s_j s_k^{-1} s_k = t_j t_i t_j t_i.$$

Finally, suppose $m_{ij} = 6$. Then we know

$$s_k s_j s_k s_j s_k s_j = s_j s_k s_j s_k s_j s_k,$$

and so

$$s_k s_k s_j s_k s_j s_k s_j = s_k s_j s_k s_j s_k s_j s_k.$$

Then

$$s_k s_k s_j s_k s_j s_k s_j m_k^{-1} = s_k s_j s_k s_j s_k s_j,$$

and so

$$t_i t_j t_i t_j t_i t_j = s_k s_k s_j s_k^{-1} s_k s_k s_j s_k^{-1} s_k s_k s_j s_k^{-1} = s_k s_j s_k^{-1} s_k s_k s_j s_k^{-1} s_k s_k s_j s_k^{-1} s_k = t_j t_i t_j t_i t_j t_i.$$

A similar argument holds when $j=k$. This concludes (a).

Now considering case (b), suppose i is connected to k . We once again have $m_{ij} = m'_{ij}$, and the only nontrivial case is when the arrow points from i to k . Suppose $m_{ij} = 2$. Then we have

$$s_i s_j = s_j s_i,$$

and so we have

$$s_k s_i s_j = s_k s_j s_i = s_j s_k s_i$$

since j is not connected to k by assumption. But then

$$t_i t_j = s_k s_i s_k^{-1} s_j = s_k s_i s_j s_k^{-1} = s_j s_k s_i s_k^{-1} = t_j t_i.$$

If $m_{ij} = 3$, then we have $s_j s_k = s_k s_j$, and so we have $s_k^{-1} s_j s_k = s_j$. This means that

$$s_i s_k^{-1} s_j s_k s_i = s_i s_j s_i = s_j s_i s_j,$$

and we then have that

$$t_i t_j t_i = s_k s_i s_k^{-1} s_j s_k s_i s_k^{-1} = s_k s_j s_i s_j s_k^{-1} = s_j s_k s_i s_k^{-1} s_j = t_j t_i t_j.$$

If $m_{ij} = 4$, we have $s_i s_j s_i s_j = s_j s_i s_j s_i$. Then

$$s_i s_k^{-1} s_j s_k s_i s_j = s_i s_k^{-1} s_k s_j s_i s_j = s_j s_i s_k^{-1} s_k s_j s_i = s_j s_i s_k^{-1} s_j s_k s_i.$$

But then conjugating the right and left sides by s_k , we find that

$$s_k s_i s_k^{-1} s_j s_k s_i s_j s_k^{-1} = s_k s_j s_i s_k^{-1} s_j s_k s_i s_k^{-1},$$

and thus by the commutativity of s_j and s_k , we have

$$t_i t_j t_i t_j = s_k s_i s_k^{-1} s_j s_k s_i s_k^{-1} s_j = s_j s_k s_i s_k^{-1} s_j s_k s_i s_k^{-1} = t_j t_i t_j t_i.$$

Finally, if $m_{ij} = 6$, we have $s_i s_j s_i s_j s_i s_j = s_j s_i s_j s_i s_j s_i$. Thus conjugating by s_k and using the commutativity of s_k and s_j , we find that

$$s_k s_i s_j s_i s_j s_i s_k^{-1} s_j = s_j s_k s_i s_j s_i s_j s_i s_k^{-1}.$$

But this occurs if and only if

$$t_i t_j t_i t_j t_i t_j = s_k s_i s_k^{-1} s_j s_k s_i s_k^{-1} s_j s_k s_i s_k^{-1} s_j = s_j s_k s_i s_k^{-1} s_j s_k s_i s_k^{-1} s_j s_k s_i s_k^{-1} = t_j t_i t_j t_i t_j t_i.$$

A similar argument holds when j is connected to k , so we are done. \square

Lemma 1.6 (Proposition 5.2 Analog). *The elements t_i , for i a vertex of Γ , satisfy the relations (R2) and (R3).*

After Lemma 1.5 we have left to check the relations (R2) when both i and j are connected to k and the relations (R3).

Beginning with the relations (R2), and following cases a-f from Corollary 2.3 in Barot and Marsh:

a) i)

$$t_i t_j = s_k s_i s_k^{-1} s_k s_j s_k^{-1} = s_k s_i s_j s_k^{-1} = s_k s_j s_i s_k^{-1} = t_j t_i$$

ii)

$$t_i t_j = s_i s_j = s_j s_i = t_j t_i$$

b) i)

$$\begin{aligned} t_i t_j t_i &= s_k s_i s_k^{-1} s_j s_k s_i s_k^{-1} \\ &= s_k s_i s_j s_k s_j^{-1} s_i s_k^{-1} \\ &= s_k s_j s_i s_k s_i s_j^{-1} s_k^{-1} \\ &= s_k s_j s_k s_i s_k s_j^{-1} s_k^{-1} \\ &= s_j s_k s_j s_i s_j^{-1} s_k^{-1} s_j \\ &= s_j s_k s_i s_k^{-1} s_j \\ &= t_i t_j t_i \end{aligned}$$

ii)

$$t_i t_j = s_i s_k s_j s_k^{-1} = s_i s_j^{-1} s_k s_j = s_j^{-1} s_k s_j s_i = s_k s_j s_k^{-1} s_i = t_j t_i$$

c) i)

$$t_i t_j = s_k s_i s_k^{-1} s_k s_j s_k^{-1} = s_k s_i s_j s_k^{-1} = s_k s_j s_i s_k^{-1} = t_j t_i$$

ii)

$$t_i t_j = s_i s_j = s_j s_i = t_j t_i$$

d) i)

$$\begin{aligned}
t_i t_j t_i t_j t_i^{-1} t_j^{-1} t_i^{-1} t_j^{-1} &= s_k s_i s_k^{-1} s_j s_k s_i s_k^{-1} s_j s_k s_i^{-1} s_k^{-1} s_j^{-1} s_k s_i^{-1} s_k^{-1} s_j^{-1} \\
&= s_k s_i s_k^{-1} s_j s_k s_i s_j s_k s_j^{-1} s_i^{-1} s_j s_k^{-1} s_j^{-1} s_i^{-1} s_k^{-1} s_j^{-1} \\
&= s_k s_i s_k^{-1} s_k s_j s_k s_i s_k s_i^{-1} s_k^{-1} s_j^{-1} s_i^{-1} s_k^{-1} s_j^{-1} \\
&= s_k s_j s_i s_k s_i s_k s_i^{-1} s_k^{-1} s_i^{-1} s_k^{-1} s_j^{-1} s_k^{-1} \\
&= e
\end{aligned}$$

2. RELATIONS FOR 2,2,1 TRIANGLE, TALK TO AARON IF YOU THINK THERE'S AN ERROR

Remark 2.1. I am proposing to add the additonal $s_a s_a s_b = s_b s_a s_a$ whenever there is a 2 edge pointing to a , a 1 edge pointing from a to b , and a 2 edge pointing out of b . I'm not sure whether this helps the rest of the problem, but it allows us to deduce the analog for $R3(b)$. We can also note that this relation would definitely not show up in the coexeter groups because $s_a^2 = e$. It seems the additional relation is in fact preserved under mutations of type b or c, as in Barot and Marsh's classification. However, I couldn't get type d to work out. I think we may have to add some of these types of relations $s_a s_a s_b = s_b s_a s_a$ when there are 2's around, such that the mutation in d works out.

Lemma 2.2. (4.2 Analog) Assuming the additional relation $s_2 s_3 s_3 = s_3 s_3 s_2$. The two relations $s_1^{-1} s_2^{-1} s_3^{-1} s_2 s_1 s_2^{-1} s_3 s_2 = e$ and $s_2^{-1} s_3^{-1} s_1^{-1} s_3 s_2 s_3^{-1} s_1 s_3 = e$ are equivalent and they imply $s_3 s_1 s_2 s_1 s_3^{-1} s_1^{-1} s_2 s_1^{-1} s_3^{-1} s_1^{-1} s_2^{-1} s_1 = e$.

Proof. To show the first, equivalence, note

$$s_1^{-1} s_2^{-1} s_3^{-1} s_2 s_1 s_2^{-1} s_3 s_2 =$$

We only have to show the first two imply the third. We can use the first two identities to deduce $s_2 s_3^{-1} = s_3^{-1} s_1 s_3 s_2 s_3^{-1} s_1^{-1}$, $s_2^{-1} s_3^{-1} = s_3^{-1} s_1^{-1} s_3 s_2^{-1} s_3^{-1} s_1$. Indeed, we can see

$$\begin{aligned}
e &= s_2 s_3 s_2 s_3^{-1} s_2^{-1} s_3^{-1} \\
&= s_2 s_3 (s_3^{-1} s_1 s_3 s_2 s_3^{-1} s_1^{-1}) (s_3^{-1} s_1^{-1} s_3 s_2^{-1} s_3^{-1} s_1) \\
&= s_2 s_3 (s_3^{-1} s_1 s_3 s_2 s_3^{-1} s_1^{-1}) (s_3^{-1} s_1^{-1} s_3 s_2^{-1} s_1 s_1^{-1} s_3^{-1} s_1) \\
&= s_2 s_3 (s_3^{-1} s_1 s_3 s_2 s_3^{-1} s_1^{-1}) (s_1 s_3 s_1^{-1} s_3^{-1} s_1^{-1} s_2^{-1} s_1 s_1^{-1} s_3^{-1} s_1) \\
&= s_2 s_3 (s_3^{-1} s_1 s_3 s_2 s_1^{-1} s_1 s_3^{-1} s_1^{-1}) (s_1 s_3 s_1^{-1} s_3^{-1} s_1^{-1} s_2^{-1} s_1 s_1^{-1} s_3^{-1} s_1) \\
&= s_2 s_3 (s_1 s_3 s_1 s_3^{-1} s_1^{-1} s_2 s_1^{-1} s_1 s_3^{-1} s_1^{-1}) (s_1 s_3 s_1^{-1} s_3^{-1} s_1^{-1} s_2^{-1} s_1 s_1^{-1} s_3^{-1} s_1)
\end{aligned}$$

Next, I claim $s_2 s_3 = s_1^{-1} s_3 s_1 s_3 s_1 s_2 s_3^{-1} s_1^{-1}$. This should be easy to verify by manipulating the equation $s_2^{-1} s_3^{-1} s_1^{-1} s_3 s_2 s_3^{-1} s_1 s_3 = e$, if we can use the relation $s_2 s_3 s_3 = s_3 s_3 s_2$, we can obtain $s_2 s_3 = s_1^{-1} s_3 s_1 s_3 s_1 s_2 s_3^{-1} s_1^{-1}$.

Plugging this in yields

$$\begin{aligned}
e &= (s_1^{-1} s_3 s_1 s_3 s_1 s_2 s_3^{-1} s_1^{-1}) (s_1 s_3 s_1 s_3^{-1} s_1^{-1} s_2 s_1^{-1} s_1 s_3^{-1} s_1^{-1}) (s_1 s_3 s_1^{-1} s_3^{-1} s_1^{-1} s_2^{-1} s_1 s_1^{-1} s_3^{-1} s_1) \\
&= (s_1^{-1} s_3 s_1 s_3 s_1 s_2 s_1 s_1^{-1} s_3^{-1} s_1^{-1}) (s_1 s_3 s_1 s_3^{-1} s_1^{-1} s_2 s_1^{-1} s_1 s_3^{-1} s_1^{-1}) (s_1 s_3 s_1^{-1} s_3^{-1} s_1^{-1} s_2^{-1} s_1 s_1^{-1} s_3^{-1} s_1) \\
&= (s_1^{-1} s_3 s_1 s_3 s_1 s_2 s_1) (s_3^{-1} s_1^{-1} s_2 s_1^{-1} s_1 s_3^{-1} s_1^{-1}) (s_1 s_3 s_1^{-1} s_3^{-1} s_1^{-1} s_2^{-1} s_1 s_1^{-1} s_3^{-1} s_1) \\
&= (s_1^{-1} s_3 s_1 s_3 s_1 s_2 s_1) (s_3^{-1} s_1^{-1} s_2 s_1^{-1}) (s_3^{-1} s_1^{-1} s_2^{-1} s_1 s_1^{-1} s_3^{-1} s_1) \\
&= (s_1^{-1} s_3 s_1 s_3 s_1 s_2 s_1) (s_3^{-1} s_1^{-1} s_2 s_1^{-1}) (s_3^{-1} s_1^{-1} s_2^{-1} s_1 s_1^{-1} s_3^{-1} s_1)
\end{aligned}$$

So, since $e = s_1^{-1} s_3 s_1 s_3 s_1 s_2 s_1 s_3^{-1} s_1^{-1} s_2 s_1^{-1} s_3^{-1} s_1^{-1} s_2^{-1} s_1 s_1^{-1} s_3^{-1} s_1$, cancelling three terms from both sides, we get $e = s_3 s_1 s_2 s_1 s_3^{-1} s_1^{-1} s_2 s_1^{-1} s_3^{-1} s_1^{-1} s_2^{-1} s_1$, as claimed. \square