

## Week 6 - Introduction to ode45()

### MAT330: Differential Equations

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#### Problems:

**Problem 1:** Consider the system of differential equations  $x_1' = x_1 + 2x_2$ ,  $x_2' = 3x_1 + 2x_2$  with initial conditions  $x_1(0) = 1, x_2(0) = 1$ . Use the MATLAB `ode45()` function to solve this system of differential equations and then plot the solution on a single plot for time  $t = 0$  to  $t = 5$ . Plot  $x_1(t)$  as a solid line,  $x_2(t)$  as a dotted line, and turn on the plotting grid and legend. Make sure to label your axes. Explain what happens to the solutions as  $t \rightarrow \infty$ . Does this answer change if the initial conditions change?

```
clear all;

function dXdt = problem01ODEFunction(t,X)
    x1 = X(1);
    x2 = X(2);

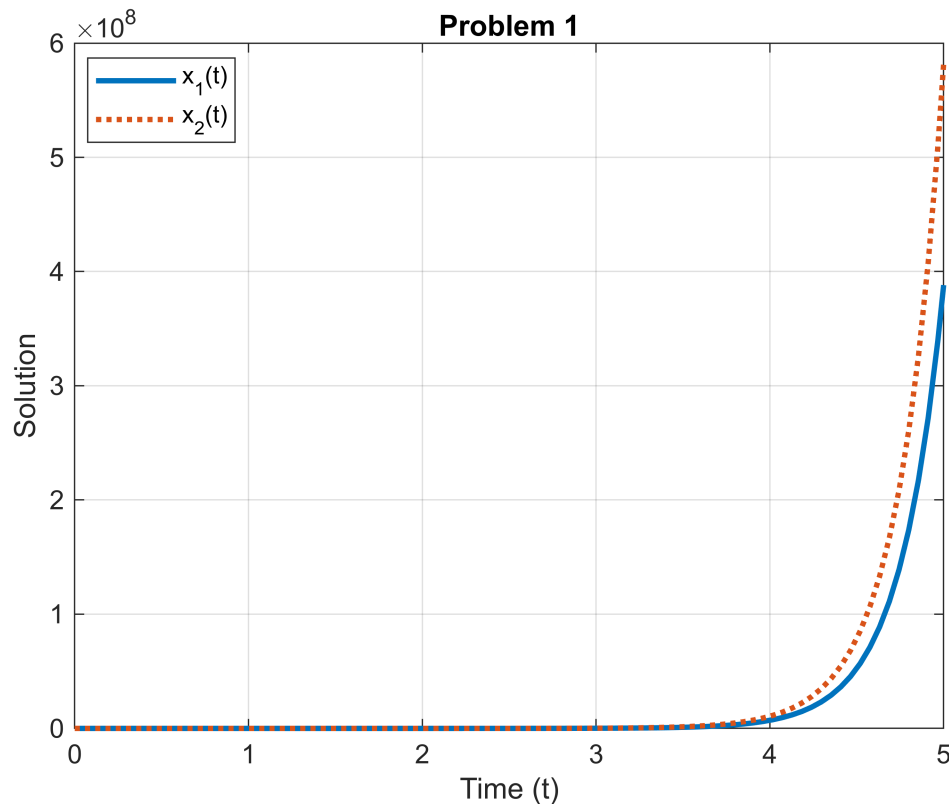
    dx1dt = x1 + 2*x2;
    dx2dt = 3*x1 + 2*x2;

    dXdt = [dx1dt; dx2dt];
end

opts = odeset('RelTol',1e-6,'AbsTol',1e-8);

soln = ode45(@problem01ODEFunction,[0 5],[1 1],opts);

figure;
plot(soln.x,soln.y(1,:), '-','linewidth',2);
hold on;
plot(soln.x,soln.y(2,:), ':','linewidth',2);
grid on;
title('Problem 1');
xlabel('Time (t)');
ylabel('Solution');
legend('x_{1}(t)', 'x_{2}(t)', 'location', 'best');
```



As  $t \rightarrow \infty$  so does the function. Both systems of equations increase positively towards infinity. By changing the initial conditions in MATLAB, I observed no change in the behavior of the system of differential equations.

**Problem 2:** Consider the system of differential equations  $x_1' = x_1 - 15x_2$ ,  $x_2' = 2x_1 - 5x_2$  with initial conditions  $x_1(0) = 2, x_2(0) = 5$ . Use the MATLAB `ode45()` function to solve this system of differential equations and then plot the solution on a single plot for time  $t = 0$  to  $t = 5$ . Plot  $x_1(t)$  as a solid line,  $x_2(t)$  as a dotted line, and turn on the plotting grid and legend. Make sure to label your axes. Explain what happens to the solutions as  $t \rightarrow \infty$ .

```
clear all;

function dXdt = problem02ODEFunction(t,X)
    x1 = X(1);
    x2 = X(2);

    dx1dt = x1 - 15*x2;
    dx2dt = 2*x1 - 5*x2;

    dXdt = [dx1dt; dx2dt];
end
```

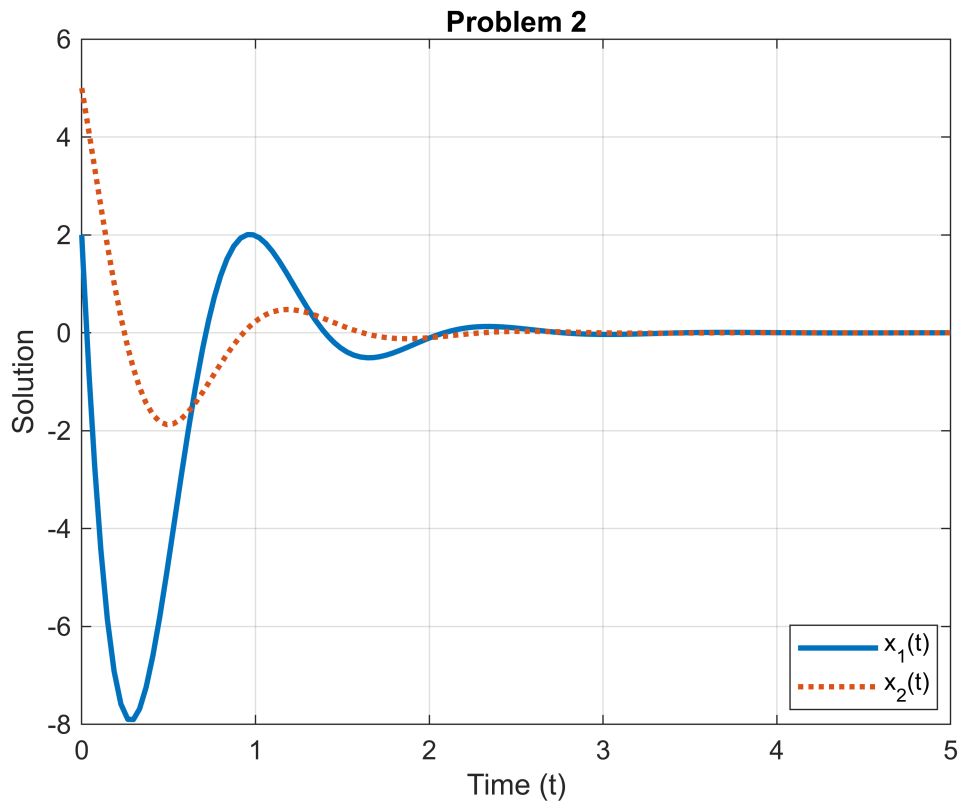
```

opts = odeset('RelTol',1e-6,'AbsTol',1e-8);

soln1 = ode45(@problem02ODEFunction,[0 5],[2 5],opts);

figure;
plot(soln1.x,soln1.y(1,:), '-','linewidth',2);
hold on;
plot(soln1.x,soln1.y(2,:), ':','linewidth',2);
grid on;
title('Problem 2');
xlabel('Time (t)');
ylabel('Solution');
legend('x_{1}(t)', 'x_{2}(t)', 'location', 'best');

```



As  $t \rightarrow \infty$  the solutions to the system of differential equations approach zero. They fluctuate rising above zero and falling below zero for a bit but they slowly increase positively towards zero from the negative half of the y-axis.

**Problem 3: Consider the system of differential equations**

$x_1' = x_1 - 15x_2 + 20 \cos(6\pi t)u(t - 3)$ ,  $x_2' = 2x_1 - 5x_2$  with initial conditions

$x_1(0) = 10, x_2(0) = 0$ . Use the MATLAB ode45() function to solve this system of

differential equations and then plot the solution on a single plot for time  $t = 0$  to

$t = 10$ . Plot  $x_1(t)$  as a solid line,  $x_2(t)$  as a dotted line, and turn on the plotting grid and legend. Make sure to label your axes. Explain what happens to the solutions as  $t \rightarrow \infty$ .

```
clear all;

function dXdt = problem03ODEFunction(t,X)
    x1 = X(1);
    x2 = X(2);

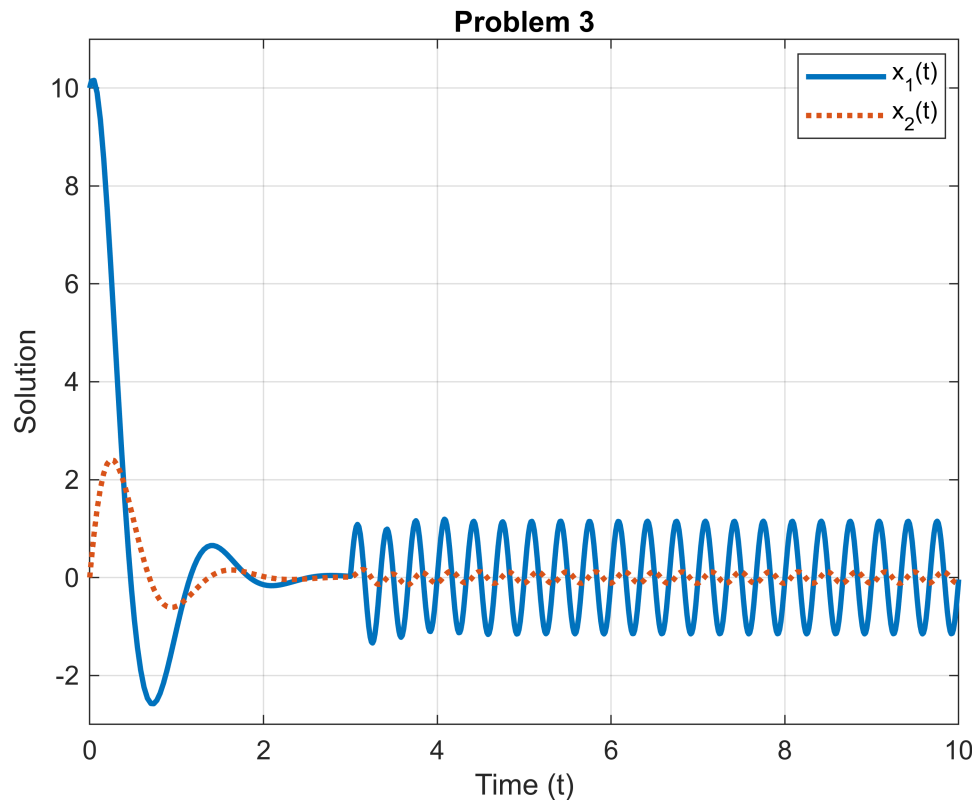
    dx1dt = x1 - 15*x2 + 20*cos(6*pi*t)*heaviside(t-3);
    dx2dt = 2*x1 - 5*x2;

    dXdt = [dx1dt; dx2dt];
end

opts = odeset('RelTol',1e-6,'AbsTol',1e-8);

soln2 = ode45(@problem03ODEFunction,[0 10],[10 0],opts);

figure;
plot(soln2.x,soln2.y(1,:), '-','linewidth',2);
hold on;
plot(soln2.x,soln2.y(2,:), ':','linewidth',2);
grid on;
title('Problem 3');
xlabel('Time (t)');
ylabel('Solution');
legend('x_{1}(t)', 'x_{2}(t)', 'location', 'best');
ylim([-3,11]);
```



As  $t \rightarrow \infty$  the solutions the each function has a different outcome. The solution to the function  $x_1$  oscillates between approximately -1 and 1. By zooming in on our plot produced by MATLAB, we can obtain the information that the solution for  $x_2$  oscillates between approximately -0.1 and 0.1.

**Problem 4:** Consider the system of differential equations  $x_1' = x_1 - 5x_2 + e^{-0.2t}u(t-1)$ ,  $x_2' = 2x_1 - 5x_2 - 0.5x_1' + 10(1 - e^{-0.5(t-5)})u(t-5)$  with initial conditions  $x_1(0) = -7, x_2(0) = 2$ . Use the MATLAB `ode45()` function to solve this system of differential equations and then plot the solution on a single plot for time  $t = 0$  to  $t = 30$ . Plot  $x_1(t)$  as a solid line,  $x_2(t)$  as a dotted line, and turn on the plotting grid and legend. Make sure to label your axes. As  $t \rightarrow \infty$ , what do  $\frac{dx_1}{dt}$  and  $\frac{dx_2}{dt}$  converge to? Explain.

```
clear all;

function dXdt = problem04ODEFunction(t,X)
    x1 = X(1);
    x2 = X(2);
```

```

dx1dt = x1 - 5*x2 + exp(-0.2*t)*heaviside(t-1);
dx2dt = 2*x1 - 5*x2 - 0.5*x1' + 10*(1 - exp(-0.5*(t-5)))*heaviside(t-5);

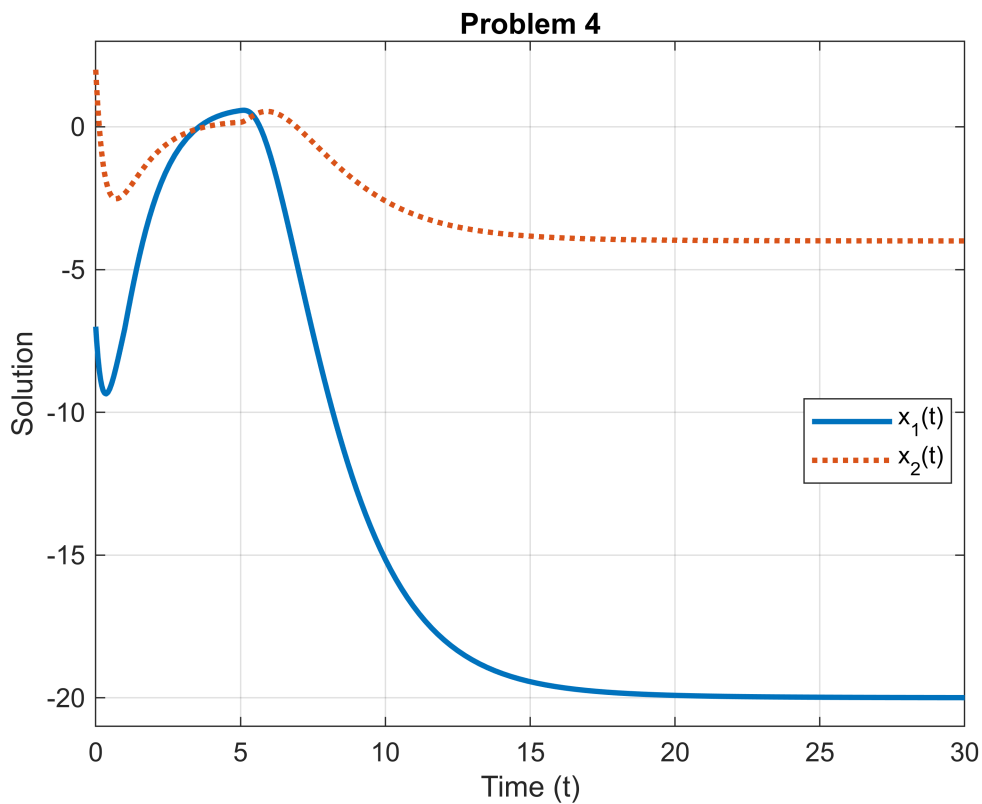
dXdt = [dx1dt; dx2dt];
end

opts = odeset('RelTol',1e-6,'AbsTol',1e-8);

soln3 = ode45(@problem040DEFunction,[0 30],[-7 2],opts);

figure;
plot(soln3.x,soln3.y(1,:), '-','linewidth',2);
hold on;
plot(soln3.x,soln3.y(2,:), ':','linewidth',2);
grid on;
title('Problem 4');
xlabel('Time (t)');
ylabel('Solution');
legend('x_{1}(t)', 'x_{2}(t)', 'location', 'best');
ylim([-21,3])

```



For  $x_1$ , as  $t \rightarrow \infty$ , the solution approaches -20. For  $x_2$ , as  $t \rightarrow \infty$ , the solution approaches -4. Since both  $x_1$  and  $x_2$  approach constant values, their derivatives will approach zero. Therefore,  $\frac{dx_1}{dt}$  and  $\frac{dx_2}{dt}$  converge to zero.