Back-End Code Generation

 Given a list of itree fragments, how to generate the corresponding assembly code?

 Main challenges: certain aspects of itree statements and expressions do not correspond exactly with machine languages:

```
# of temp. registers on real machines are limited
real machine's conditional-JUMP statement takes only one label
high-level constructs ESEQ and CALL ---- side-effects
```

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 $C\ S\ 4\ 2\ 1 \quad C\ O\ M\ P\ I\ L\ E\ R\ S \quad A\ N\ D \quad I\ N\ T\ E\ R\ P\ R\ E\ T\ E\ R\ S$

Side-Effects

• Side-effects means updating the contents of a memory cell or a temporary register. What are itree expressions that might cause side effects?

ESEQ and CALL nodes

 ESEQ(s,e) where s is a list of statements that may contain MOVE statement

```
The natural way to generate assembly code for {\bf BINOP}({\bf op}, t_1, t_2) instructions to compute t_1 into r_i; instructions to compute t_2 into r_j; r_k < -r_i \ {\bf op} \ r_j

But it won't work for this:

BINOP(PLUS, TEMP a, ESEQ(MOVE(TEMP a, u), v))
```

• CALL(e,el) by default puts the result in the return-result register.

```
BINOP(PLUS, CALL(...), CALL(...))
```

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Itree Stmts and Exprs

• itree statements stm and itree expressions exp

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Summary: IR -> Machine Code

```
• Step #1: Transform the itree code into a list of canonical trees
```

```
a. eliminate SEO and ESEO nodes
```

b. the arguments of a CALL node should never be other CALL nodes

```
---- the parent of each CALL node should either be
```

```
EXP(...) or MOVE(TEMP t, ...)
```

- Step #2 : Perform various code optimizations on canonical trees
- Step #3: Rearrange the canonical trees (into traces) so that every
 CJUMP(cond, 1_t, 1_f) is immediately followed by LABEL(1_f).
- Step #4: Instruction Selection ---- generate the pseudo-assembly code from the canonical trees in the step #3.
- Step #5: Perform register allocations on pseudo-assembly code

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Canonical Trees

 A canonical tree is a simple itree statement in the following form (it is really a restricted-kind of itree statement):

```
datatype stm = LABEL of label

| JUMP of exp
| CJUMP of test * label * label
| MOVE of exp * exp
| EXP of exp

and exp = BINOP of binop * exp * exp
| CVTOP of cvtop * exp * size * size
| MEM of exp * size
| TEMP of temp
| NAME of label
| CONSTF of int
| CONSTF of real
| CALL of exp * exp list
```

Restrictions:

no SEQ statements, no ESEQ expressions.
each CALL node doesn't contain other CALL nodes as subtrees

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Rearranging itree statements

- Goal: rearrange the list of canonical trees so that every
 CJUMP(cond, l_t, l_f) is immediately followed by its false branch
 LABEL(l_f).
- Step #1: take a list of canonical trees and form them into basic blocks

A basic block is a sequence of statements that is always entered at the beginning and exited at the end:

```
    the first statement is a LABEL
    the last statement is a JUMP or CJUMP
    there are no other LABELs, JUMPs, or CJUMPs in between
```

basic blocks are often used to analyze a program's control flow

• Step #2: re-order the list of basic blocks into traces

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Canonicalizer

 The body of each PROC fragment is translated into an ordered list of canonical trees

```
stms: Tree.stm list
```

• Step 1: transformation on CALL nodes.

```
CALL(...) ======>
ESEQ(MOVE(TEMP t,CALL(...)),TEMP t)
```

• Step 2: elimination of ESEQ nodes. (see Appel pp 174-179)

lift them higher and higher until they become SEQ nodes ...

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Canonical Trees => Basic Blocks

- Input: a sequence of statements (i.e., canonical trees --- the body of a function);
 Output: a set of basic blocks
- Algorithm:

if a new LABEL is found, end the current block and start a new block;

if a JUMP or CJUMP is found, end the current block;

if it results a block not ending with a **JUMP** or **CJUMP**, then a **JUMP** to the next block's label is appended to the block;

if it results a block without a LABEL at the beginning, invent a new LABEL and stuck it there:

invent a new label done for the beginning of the epilogue;

put JUMP (NAME done) at the end of the last basic block.

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Basic Blocks => Traces

- Control Flow Graph (CFG): basic blocks as the nodes, pairs (a,b) as the edges if block a ends with a CJUMP or JUMP statement to block b.
- Basic blocks can be arranged in any order, but we want:

each CJUMP is followed by its false label
each JUMP should be followed by its target label whenever possible

- A trace is a path in the CFG --- it characterizes some fragment of a real
 program execution.
- Algorithm for gathering traces: just do the depth-first traversal of the CFG -- (can also take advantage of branch prediction information)

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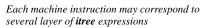
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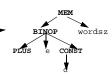
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Instruction Selection

- Input: an ordered list of canonical trees;
 Output: the pseudo-assembly code (without register assignments)
- Algorithm: translating each canonical tree into an assembly code sequence, and then concatenate all sequences together.
 Main Problem: how to map the canonical tree to the assembly code?
- Each machine instruction can be expressed as a tree pattern --- a fragment of the canonical tree:

Load the value at addr e + c in the memory!





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Traces => List of Statements

- Flatten the traces back to an ordered list of statements (canonical trees):
 - a) any CJUMP followed by its false label: do nothing;
 - b) any CJUMP followed by its **true** label: switch its **true** and **false** label, and **negate** the condition;
 - c) remove **JUMP(1)** if it is followed by its target 1;
 - d) any CJUMP (cond, l_t , l_f) followed by **neither** label: invent a new false label l_n , rewrite it into:

```
CJUMP(cond, l_t, l_n)
LABEL l_n
JUMP(NAME l_f)
```

 We are now ready to do instruction selection: generate assembly code for your favourite target machine.

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Instruction Selection via Tiling

- Express each machine instruction as a tree pattern.
- Given a canonical tree, the instruction selection is just to tile the tree using various tree patterns (for all possible machine instructions) ----- cover the canonical tree using nonoverlapping tiles.
- Optimum Tiling: ---- one whose tiles sum to the lowest possible value (suppose we give each machine instruction a cost)
- Optimal Tiling: ---- one where no two adjacent tiles can be combined into a single tile of lower cost
- Even optimum tiling is also optimal, but no vice versa.
- Algorithm: maximum munch finds the optimal tiling; dynamic programming finds the optimum tiling.

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Maximal Munch

• Algorithm --- Maximal Munch:

Start at the root of a canonical tree, find the **largest tile** that fits; the **largest tile** is the one with the most nodes (if tie, break arbitrarily)

Cover the **root** node and perhaps several other nodes near the root with this tile, leaving several subtrees; the instruction corresponding to the **tile** is generated.

Repeat the same algorithm for each subtreee.

- Maximal Munch generates the instructions in reverse order.
- Implementation: see Appel pp 190-191, 204-205.

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Code-Generator Generator

- Same as Lex and Yacc, the instruction selection phase can also be automatically built, using a code-generator generator.
- The input specification is a set of grammar rules used to specify the tree pattern for each machine instruction:

each grammar rule is associated with a cost and an action; cost is for finding optimum tiling; action is for instruction emission.

a: expressions for "addressing" d: expressions for "data"

 The code-generator generator computes the minimum-cost match at each node for each nonterminal of the grammar using dynamic programming (Appel pp 191-193) CS421 COMPILERS AND INTERPRETERS

Dynamic Programming

• the dynamic programming algorithm is used to find the optimum tiling

Main Idea: assign a cost to every node in the tree (via bottom-up)

the algorithm works bottom-up: at each node, we calculate the cost of the best instruction sequence that can tile the subtree rooted at that node.

 after the cost of the root node (thus the entire tree) is found, we do the instruction emission:

Emission(node n): for each leaves 1_{1} of the tile selected at node n, perform **Emission**(1_{1}). Then emit the instruction matched at node n.

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Instruction Selection for Tiger

- we will implement the maximal munch for instruction selection in the Tiger compiler (using ML pattern matching)
- main problem: how to deal with registers?
- solution: the register allocation will occur after instruction selection, the instruction selection phase will generate instructions with simple register templates.

first, generate the **assembly tree** --- the assembly language without register assignments;

second, do the register allocation

third, emit the procedure entry exit sequence

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Assembly Trees

• the assembly language without register assignments in ML datatype:

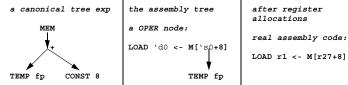
The **format** function will fill in the register information in the future.

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Tiger Assembly Trees (cont'd)

• A OPER node OPER {assem, dst, src, jump} holds an assemblylanguage instruction assem. The source registers are src, the target registers are dst; jump would be NONE if it is not a branch instruction.



 An MOVE node MOVE {assem, dst, srcs} holds an assembly-language move instruction assem that moves from src to dst.

If later in register allocation, src and dst are assigned the same register, then this instruction will be deleted.

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