

# David Kooi

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## Education

### **Masters of Science Computer Engineering**

**University of California Santa Cruz**

**Fall 2018 – 2020**

**Research Interests:** Hybrid Model Predictive Control and Hybrid Controller Synthesis from Formal Specifications

**Organizations:** Hybrid Systems Lab

### **Bachelors of Science Computer Engineering 2018**

**University of California Santa Cruz** GPA 3.81

**Fall 2016 – 2018**

**Extracurricular Involvement**

UCSC Tau Beta Pi Member, UCSC IEEE Member, UCSC Rocket Club Member,

## Experience

### **SGT at NASA Ames, Moffet Field CA**

**July - September 2019**

Worked in the Robust Software Engineering group to add temporal logic features to the FRET formal verification tool.

### **Jet Propulsion Laboratory, Pasadena CA**

**June - September 2018**

Worked within the Autonomous Systems Division for the Mars 2020(M2020) Vision Compute Element(VCE). The VCE will perform terrain relative navigation during M2020's entry, descent and landing. During this summer I worked on flight software running on the VCE computer. My tasks involved:

- Creating a static source code analyzer to auto-code a binary image representing the on-board parameter structure.
- Creating an auto-coder taking as input memory segment specifications and outputting flight verified C code.
- Extending the memory mapping auto-coder to support bad-page remapping.

### **UC Santa Cruz Senior Design Project:**

**Fall 2017 - Spring 2018**

**Title:** Automated Stockpile Moving: Experimental Validation of a Vision-Based Front Loader ( Sponsored by Topcon Corporation )

**Objective:** Use a computer vision to locate and traverse to a stockpile; use stereo cameras to calculate an optimal approach vector; fill bucket and verify fill; maneuver to dump site; return and repeat.

### **Jet Propulsion Laboratory, Pasadena CA**

**June - September 2015-2017**

For three summers worked in the Autonomous Systems Division under the Small Scale Flight Software group. Work was performed within the open source, model based NASA JPL FPrime flight software framework. Worked involved:

- 2017:** FPrime Ground Server System redesign using ZeroMQ middleware to support a dynamic, many-many, publish-subscribe system. Developed C++ “ZmqRadio” to support robust communication between embedded systems and the new server. Server supports ‘pluggable’ packet protocol translation
- 2016:** FPrime Ground System UI and API development and maintenance. Created real-time telemetry visualization with multiple channels. Created a C++ signal generator for telemetry visualization testing.
- 2015:** FPrime autocoder maintenance and development.

## Skills

**Autonomous Systems:** Hybrid System methodology; path planning techniques like RRT\* and D\*; MPC based planning

**Programming Languages:** Python, C, C++, Java, Matlab, Unix Shell Scripting, Verilog, PLC Ladder Logic

**Software Frameworks:** ZeroMQ, PointCloudLibrary, ROS, Numpy, Matplotlib, Tkinter, Git, Nose, Android SDK,

**Software Methodologies:** Functional Programming, AST Traversal, OOP Design Patterns, Model Based Design, UML modeling

**Electrical:** Basic circuit design, analysis, fabrication. Troubleshooting with multimeters, oscilloscopes, and logic analyzers

References available upon request.