

Lecture 2: Maxwells Equations

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10:47 AM

Maxwells Eq.

$$\vec{\nabla} \cdot \vec{B} = 0 \quad \vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

$$\vec{\nabla} \cdot \vec{D} = \rho \quad \vec{\nabla} \times \vec{H} - \frac{\partial \vec{D}}{\partial t} = \vec{J}$$

\vec{B} : magnetic flux density webers/m²

\vec{D} : electric flux density coulombs/m²

\vec{E} : electric field strength V/m

\vec{H} : magnetic field strength A/m

\vec{J} : electric current density A/m²

ρ : charge density

Starting assumptions

- 1) medium is constant w respect to time
- 2) source free zone i.e. $\rho = 0$ $\vec{J}_s = 0$

To simplify Maxwell we can relate
 \vec{D} w/ \vec{E} and \vec{B} w/ \vec{H}
in general

$$\textcircled{1} \quad D_i / \epsilon_0 = \sum_j \epsilon_{ij} E_j + \sum_{j,k} \chi_{ijk} E_j E_k + O(E^3)$$

i, j, k are unit vectors

$\epsilon = \epsilon_0 \epsilon_{ijk}$ permittivity ϵ_0 : perm free space
 8.854×10^{-12} Farad/m

ϵ_{ijk} is a vector where each component relates
 ϵ in a direction, ϵ is a function of

ω

χ : electric susceptibility

relates ϵ & ϵ_0 via higher order terms

second set of assumptions

1) ϵ is isotropic

$$\epsilon_i = \epsilon_j = \epsilon_k = \epsilon_r$$

2) medium is linear w/ respect to field strength

i.e. behaves the same for $E = 1 \text{ V/m}$ as 1 kV/m

$$\chi = 0$$

$$\textcircled{1} \Rightarrow \vec{D} = \epsilon_0 \epsilon_r \vec{E}$$

final assumptions

1) ϵ_r is a function of frequency (material dispersion)
assume we are in a regime where

ϵ_r is constant over freq. band of interest

2) deal only w/ transparent materials

i.e. no loss or gain as light propagates

ϵ_r is purely real

now

$$\vec{D}(\vec{r}) = \epsilon_0 \epsilon_r \vec{E}(\vec{r}) \quad \text{as in most cases}$$

$$\vec{A}(\vec{r}) = \mu_0 \vec{H}(\vec{r}) \quad \mu_r = 1 \quad \rightarrow \text{...}$$

$$\vec{B}(\vec{r}) = \mu_0 \mu_r \vec{H}(\vec{r}) \quad \mu_r = 1$$

$$\mu_0 = 4\pi \times 10^{-7} \text{ Henry/m}$$

rewrite Maxwell's equations

$$\nabla \cdot \vec{B}(\vec{r}, t) = 0 \quad \nabla \times \vec{E}(\vec{r}, t) + \mu_0 \frac{\partial \vec{H}(\vec{r}, t)}{\partial t} = 0$$

$$\nabla \cdot [\epsilon(\vec{r}) \vec{E}(\vec{r}, t)] = 0 \quad \nabla \times \vec{H}(\vec{r}, t) - \epsilon_0 \epsilon_r(\vec{r}) \frac{\partial \vec{E}(\vec{r}, t)}{\partial t} = 0$$

If \vec{E} are functions of both time & space,
have equations that depend on variations of
both.

Break down \vec{E} & \vec{H} for a second

$$\vec{E}(\vec{r}) = \hat{x} E_x(\vec{r}) + \hat{y} E_y(\vec{r}) + \hat{z} E_z(\vec{r})$$

$$\vec{H}(\vec{r}) = \hat{x} H_x(\vec{r}) + \hat{y} H_y(\vec{r}) + \hat{z} H_z(\vec{r})$$

\vec{E}, \vec{H} : vectors in space E_{xijk}, H_{xijk} scalars that
of $\vec{E} + \vec{H}$ pointing in $\hat{x}, \hat{y}, \hat{z}$ respectively

Because we have assumed linearity
we can separate spatial & temporal
dependence w/ NO loss of generality

w/o loss of generality can assume time
variational component is sinusoidal
(Fourier decomp)

complex exponential $e^{-j\omega t}$

$j = \sqrt{-1}$, ω : angular
freq
 $= 2\pi f$
 f : time

$$\text{now } \vec{H}(r, t) = \vec{H}(r) e^{-j\omega t}$$

$$\vec{E}(r, t) = \vec{E}(r) e^{-j\omega t}$$

$H(r), E(r)$ spatial field profiles
"mode profiles"

Plug into Maxwell

$$\nabla \cdot H(r, t) = \nabla \cdot \vec{H}(r) e^{-j\omega t} = 0$$

$$\nabla \cdot E(r, t) = \nabla \cdot \vec{E}(r) e^{-j\omega t} = 0$$

again utilize Fourier to create spatial modes of plane waves

$$\vec{H}(r) = \vec{a} e^{j\vec{k} \cdot \vec{r}}$$

\vec{a} : vector of ^{field} values in directions

\vec{k} : wave vector, unit vector in direction of propagation

\vec{r} : position vector i.e. "where am I"

$$\nabla \cdot \vec{a} e^{j\vec{k} \cdot \vec{r}} = 0$$

$$\left(\frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial z} \right) \cdot (a_x \hat{x} + a_y \hat{y} + a_z \hat{z}) e^{j\vec{k} \cdot \vec{r}} = 0$$

$$\left(\frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial z} \right) \cdot (a_x \hat{x} e^{j\vec{k} \cdot \vec{r}} + a_y \hat{y} e^{j\vec{k} \cdot \vec{r}} + a_z \hat{z} e^{j\vec{k} \cdot \vec{r}}) = 0$$

$$\frac{\partial}{\partial x} a_x \hat{x} e^{j k_x \hat{x} + j k_y \hat{y} + j k_z \hat{z} \cdot \vec{r}} + \quad +$$

$$\frac{\partial}{\partial x} a_x \hat{x} e^{j k_x \hat{x} + j k_y \hat{y} + j k_z \hat{z} \cdot \vec{r}} + \quad +$$

$$+ a_x k_x \hat{x} e^{j k_x \hat{x} + j k_y \hat{y} + j k_z \hat{z} \cdot \vec{r}} +$$

$$\begin{aligned}
 & j a_x k_x e^{j(k_x \tilde{x} + k_y \tilde{y} + k_z \tilde{z})} + \\
 & j a_y k_y e^{j(k_x \tilde{x} + k_y \tilde{y} + k_z \tilde{z})} + \\
 & j a_z k_z e^{j(k_x \tilde{x} + k_y \tilde{y} + k_z \tilde{z})} = 0
 \end{aligned}$$

only way for this to be true is if all terms are true. Only way for all terms $= 0$ is if either a_i or $k_i = 0$
 trivial cases $a_x = a_y = a_z = 0$ i.e. no field

$k_x = k_y = k_z = 0$ no movement

or if $a_i \neq 0$ $k_i = 0$

no field strength in the direction of propagation!

known as Transverse Waves

mathematically stated $\vec{a} \cdot \vec{k} = 0$

as we move forward we will use this to enforce boundary conditions

now move on to curl equations

$$\nabla \times \vec{E}(r) e^{j\omega t} + \mu_0 \frac{\partial H(r) e^{j\omega t}}{\partial t} = 0$$

$$\nabla \times \vec{H}(r) e^{j\omega t} - \epsilon_0 \epsilon_r \frac{\partial E(r) e^{j\omega t}}{\partial t} = 0$$

lets pick on the first one

$$\nabla \times \vec{E}(r) e^{j\omega t} = -\mu_0 \frac{\partial H(r) e^{j\omega t}}{\partial t} = 0$$

$$① \nabla \times \vec{E}(r) - j\omega \mu_0 \vec{H}(r) = 0$$

$$② \nabla \times \vec{H}(r) + j\omega \epsilon_0 \epsilon_r \vec{E}(r) = 0$$

decouple $H(r)$ & $E(r)$ dependence

$$\frac{2}{\epsilon_r} \nabla \times \frac{1}{\epsilon_r} H(r) + j\omega \epsilon_0 \vec{E}(r) = 0$$

take curl

$$\nabla \times (\nabla \times \frac{1}{\epsilon_r} H(r)) + j\omega \epsilon_0 \nabla \times E(r) = 0$$

$$① \nabla \times \vec{E}(r) = j\omega \mu_0 \vec{H}(r)$$

$$\nabla \times (\nabla \times \frac{1}{\epsilon_r} H(r)) - \omega^2 \epsilon_0 \mu_0 H(r) = 0$$

$$c = \frac{1}{\sqrt{\epsilon_0 \mu_0}} \therefore \epsilon_0 \mu_0 = \frac{1}{c^2}$$

$$\boxed{\nabla \times \left(\frac{1}{\epsilon_r} \nabla \times \vec{H}(r) \right) = \left(\frac{\omega}{c} \right)^2 \vec{H}(r)} \quad \star$$

the strategy for crystal analysis will be to find solutions to this equation that satisfy transversality

w/ $H(r)$ it is easy to find $E(r)$
use Maxwell

for shorthand rewrite N.E. as a Hermitian operator

$$\nabla \times \left(\frac{1}{\epsilon_r} \nabla \times H(r) \right) = \hat{\Theta} : \text{eigenfunction}$$

$$\hat{O} \psi(r) = \left(\frac{\omega}{c}\right)^2 \psi(r)$$

\uparrow \uparrow
 eigenvector eigenvalue

eigen problems: any operator that when it acts on a function returns the function times a constant

\hat{O} : is Hermetian which formally mean $(\vec{F}, \hat{O} \vec{G}) = (\hat{O} \vec{F}, \vec{G})$

but we won't go through the proof

Hermetian operators are well studied & have compelling properties

1) \hat{O} is positive semi-definite
 $\omega \geq 0$ & purely real

2) 2 modes of $\psi(r)$ $\psi_1(r)$ $\psi_2(r)$ that have different ω are orthogonal

These will come in handy later

Scaling Properties of Maxwell

Maxwell's equations are scale invariant

no dependency on length anywhere

M.E. also is scale invariant. This means

that if we scale a system, as long as we scale the dimensions of interest the same as ω the relation is still valid

there is also no set value for $\epsilon(r)$
if determine solution for $\epsilon(r)$ then
increase all $\epsilon(x, y, z)$ by constant
then $\omega \rightarrow \sqrt{\epsilon} \omega$