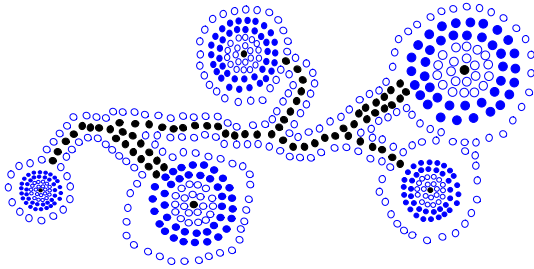


PRIORITY QUEUES

- The Priority Queue Abstract Data Type
- Implementing A Priority Queue With a Sequence



Keys and Total Order Relations

- A **Priority Queue** ranks its elements by *key* with a *total order* relation
- Keys:
 - Every element has its own key
 - Keys are not necessarily unique
- Total Order Relation
 - Denoted by \leq
 - **Reflexive:** $k \leq k$
 - **Antisymmetric:** if $k_1 \leq k_2$ and $k_2 \leq k_1$, then $k_1 = k_2$
 - **Transitive:** if $k_1 \leq k_2$ and $k_2 \leq k_3$, then $k_1 \leq k_3$
- A **Priority Queue** supports these fundamental methods:
 - `insertItem(k, e)` // element *e*, key *k*
 - `removeMinElement()` // return and remove the // item with the smallest key

Sorting with a Priority Queue

- A **Priority Queue** *P* can be used for sorting by inserting a set *S* of *n* elements and calling `removeMinElement()` until *P* is empty:

Algorithm `PriorityQueueSort(S, P):`

Input: A sequence *S* storing *n* elements, on which a total order relation is defined, and a Priority Queue *P* that compares keys with the same relation

Output: The Sequence *S* sorted by the total order relation

```
while !S.isEmpty() do
    e ← S.removeFirst()
    P.insertItem(e, e)
while P is not empty do
    e ← P.removeMinElement()
    S.insertLast(e)
```

The Priority Queue ADT

- A priority queue *P* must support the following methods:
 - `size():`
Return the number of elements in *P*
Input: None; **Output:** integer
 - `isEmpty():`
Test whether *P* is empty
Input: None; **Output:** boolean
 - `insertItem(k, e):`
Insert a new element *e* with key *k* into *P*
Input: Objects *k*, *e* **Output:** None
 - `minElement():`
Return (but don't remove) an element of *P* with smallest key; an error occurs if *P* is empty.
Input: None; **Output:** Object *e*

The Priority Queue ADT (contd.)

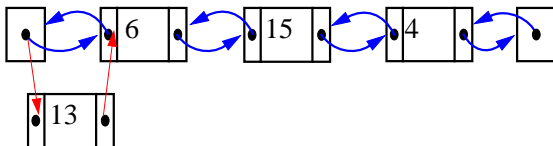
- **minKey():**
Return the smallest key in P ; an error occurs if P is empty
Input: None; **Output:** Object k
- **removeMinElement():**
Remove from P and return an element with the smallest key; an error condition occurs if P is empty.
Input: None; **Output:** Object e

Comparators

- The most general and reusable form of a priority queue makes use of **comparator** objects.
- Comparator objects are external to the keys that are to be compared and compare two objects.
- When the priority queue needs to compare two keys, it uses the comparator it was given to do the comparison.
- Thus a priority queue can be general enough to store any object.
- The comparator ADT includes:
 - **isLessThan(a, b)**
 - **isLessThanOrEqualTo(a, b)**
 - **isEqualTo(a, b)**
 - **isGreaterThan(a, b)**
 - **isGreaterThanOrEqualTo(a, b)**
 - **isComparable(a)**

Implementation with an Unsorted Sequence

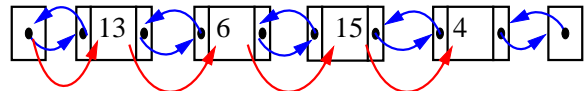
- Let's try to implement a priority queue with an unsorted sequence S .
- The elements of S are a composition of two elements, k , the key, and e , the element.
- We can implement **insertItem()** by using **insertFirst()** of the sequence. This would take $O(1)$ time.



- However, because we always **insertFirst()**, despite the key value, our sequence is not ordered.

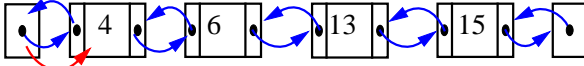
Implementation with an Unsorted Sequence (contd.)

- Thus, for methods such as **minElement()**, **minKey()**, and **removeMinElement()**, we need to look at all elements of S . The worst case time complexity for these methods is $O(n)$.

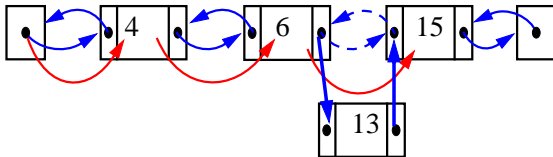


Implementation with a Sorted Sequence

- Another implementation uses a sequence S , sorted by keys, such that the first element of S has the smallest key.
- We can implement `minElement()`, `minKey()`, and `removeMinElement()` by accessing the first element of S . Thus these methods are $O(1)$ (assuming our sequence has an $O(1)$ front-removal)



- However, these advantages comes at a price. To implement `insertItem()`, we must now scan through the entire sequence. Thus `insertItem()` is $O(n)$.



Implementation with a Sorted Sequence(contd.)

```
public class SequenceSimplePriorityQueue
implements SimplePriorityQueue {
    //Implementation of a priority queue
    using a sorted sequence
    protected Sequence seq = new NodeSequence();
    protected Comparator comp;
    // auxiliary methods
    protected Object extractKey (Position pos) {
        return ((Item)pos.element()).key();
    }
    protected Object extractElem (Position pos) {
        return ((Item)pos.element()).element();
    }
    protected Object extractElem (Object key) {
        return ((Item)key).element();
    }
    // methods of the SimplePriorityQueue ADT
    public SequenceSimplePriorityQueue (Comparator c) {
        this.comp = c; }
    public int size () {return seq.size(); }
```

Implementation with a Sorted Sequence(contd.)

```
public boolean isEmpty () { return seq.isEmpty(); }
public void insertItem (Object k, Object e) throws
InvalidKeyException {
    if (!comp.isComparable(k))
        throw new InvalidKeyException("The key is not
valid");
    else
        if (seq.isEmpty())
            seq.insertFirst(new Item(k,e));
        else
            if (comp.isGreaterThan(k,extractKey(seq.last())))
                seq.insertAfter(seq.last(),new Item(k,e));
            else {
                Position curr = seq.first();
                while (comp.isGreaterThan(k,extractKey(curr)))
                    curr = seq.after(curr);
                seq.insertBefore(curr,new Item(k,e));
            }
}
```

Implementation with a Sorted Sequence(contd.)

```
public Object minElement () throws
EmptyContainerException {
    if (seq.isEmpty())
        throw new EmptyContainerException("The priority
queue is empty");
    else
        return extractElem(seq.first());
}
```

Selection Sort

- Selection Sort is a variation of PriorityQueueSort that uses an unsorted sequence to implement the priority queue P.
- Phase 1**, the insertion of an item into P takes $O(1)$ time.
- Phase 2**, removing an item from P takes time proportional to the number of elements in P

	Sequence S	Priority Queue P
Input	(7, 4, 8, 2, 5, 3, 9)	()
Phase 1:		
(a)	(4, 8, 2, 5, 3, 9)	(7)
(b)	(8, 2, 5, 3, 9)	(7, 4)
...
(g)	()	(7, 4, 8, 2, 5, 3, 9)
Phase 2:		
(a)	(2)	(7, 4, 8, 5, 3, 9)
(b)	(2, 3)	(7, 4, 8, 5, 9)
(c)	(2, 3, 4)	(7, 8, 5, 9)
(d)	(2, 3, 4, 5)	(7, 8, 9)
(e)	(2, 3, 4, 5, 7)	(8, 9)
(f)	(2, 3, 4, 5, 7, 8)	(9)
(g)	(2, 3, 4, 5, 7, 8, 9)	()

Selection Sort (cont.)

- As you can tell, a bottleneck occurs in Phase 2. The first removeMinElement operation takes $O(n)$, the second $O(n-1)$, etc. until the last removal takes only $O(1)$ time.

- The total time needed for phase 2 is:

$$O(n + (n-1) + \dots + 2 + 1) \equiv O\left(\sum_{i=1}^n i\right)$$

- By a common proposition:

$$\sum_{i=1}^n i = \frac{n(n+1)}{2}$$

- The total time complexity of phase 2 is then $O(n^2)$. Thus, the time complexity of the algorithm is $O(n^2)$.

Insertion Sort

- Insertion sort is the sort that results when we perform a PriorityQueueSort implementing the priority queue with a sorted sequence.
- We improve phase 2 to $O(n)$.
- However, phase 1 now becomes the bottleneck for the running time. The first insertItem takes $O(1)$, the second $O(2)$, until the last operation takes $O(n)$.
- The run time of phase 1 is $O(n^2)$ thus the run time of the algorithm is $O(n^2)$.

Insertion Sort(cont.)

	Sequence S	Priority Queue P
Input	(7, 4, 8, 2, 5, 3, 9)	()
Phase 1:		
(a)	(4, 8, 2, 5, 3, 9)	(7)
(b)	(8, 2, 5, 3, 9)	(4, 7)
(c)	(2, 5, 3, 9)	(4, 7, 8)
(d)	(5, 3, 9)	(2, 4, 7, 8)
(e)	(3, 9)	(2, 4, 5, 7, 8)
(f)	(9)	(2, 3, 4, 5, 7, 8)
(g)	()	(2, 3, 4, 5, 7, 8, 9)
Phase 2:		
(a)	(2)	(3, 4, 5, 7, 8, 9)
(b)	(2, 3)	(4, 5, 7, 8, 9)
...
(g)	(2, 3, 4, 5, 7, 8, 9)	()

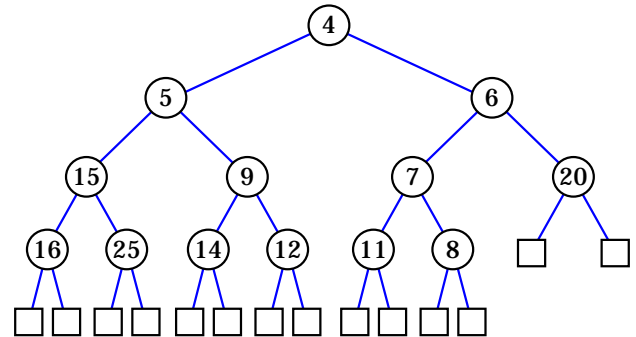
- Selection and insertion sort both take $O(n^2)$.
- Selection sort will always take $\Omega(n^2)$ time, no matter the input sequence.
- The run of insertion sort varies depends on the input sequence.
- We have yet to see the ultimate priority queue....

Heaps

- A **Heap** is a Binary Tree H that stores a collection of keys at its internal nodes and that satisfies two additional properties:
 - 1) **Heap-Order Property**
 - 2) **Complete Binary Tree Property**
- **Heap-Order Property (Relational)**: In a heap H , for every node v (except the root), the key stored in v is greater than or equal to the key stored in v 's parent.
- **Complete Binary Tree Property (Structural)**: A Binary Tree T is complete if each level but the last is full, and, in the last level, all of the internal nodes are to the left of the external nodes.

Heaps (contd.)

- An Example:



Height of a Heap

- **Proposition**: A heap H storing n keys has height $h = \lceil \log(n+1) \rceil$
- Justification: Due to H being complete, we know:
 - # i of internal nodes is at least :

$$1 + 2 + 4 + \dots + 2^{h-2} + 1 = 2^{h-1} - 1 + 1 = 2^{h-1}$$
 - # i of internal nodes is at most:

$$1 + 2 + 4 + \dots + 2^{h-1} = 2^h - 1$$
 - Therefore:

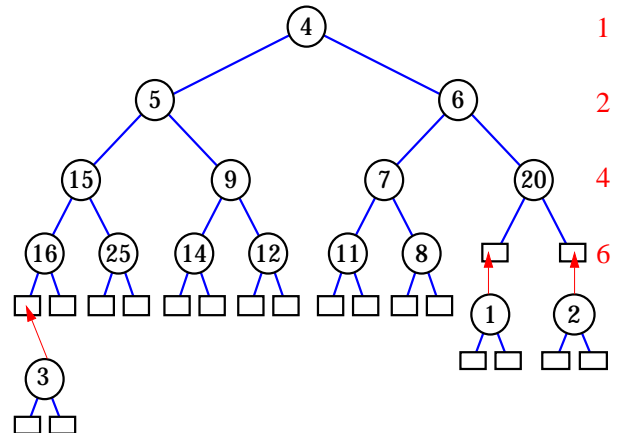
$$2^{h-1} \leq n \text{ and } n \leq 2^h - 1$$
 - Which implies that:

$$\log(n+1) \leq h \leq \log n + 1$$
 - Which in turn implies:

$$h = \lceil \log(n+1) \rceil$$
 - Q.E.D.

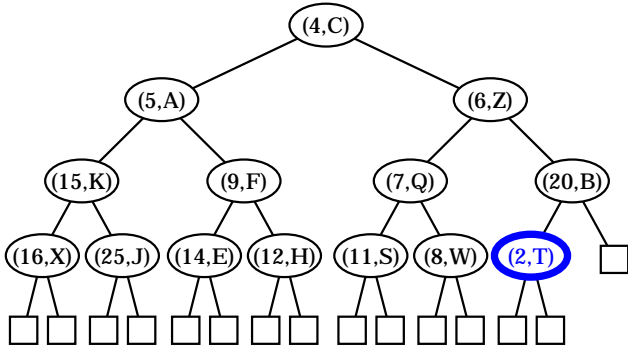
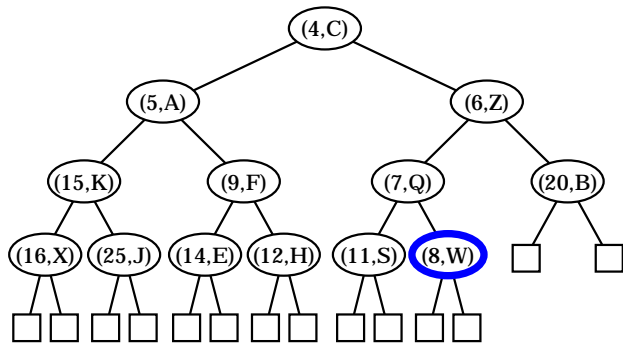
Height of a Heap (contd.)

- Let's look at that graphically:

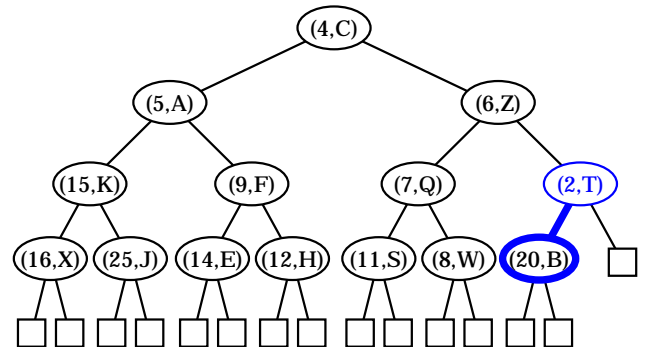
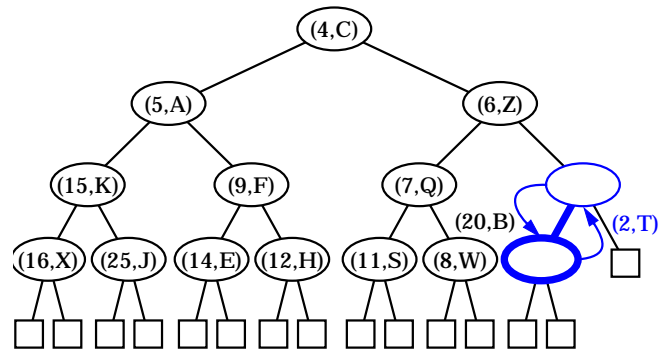


- Consider this heap which has height $h = 4$ and $n = 13$
- Suppose two more nodes are added. To maintain completeness of the tree, the two external nodes in level 4 will become internal nodes: i.e.
 $n = 15, h = 4 = \lceil \log(15+1) \rceil$
- Add one more: $n = 16, h = 5 = \lceil \log(16+1) \rceil$

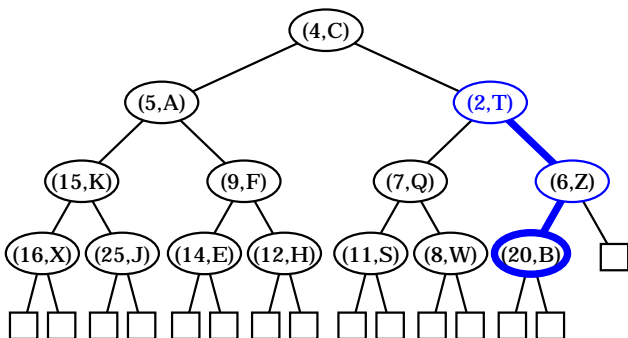
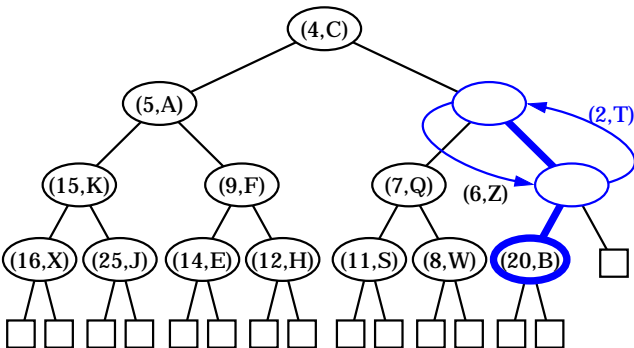
Insertion into a Heap



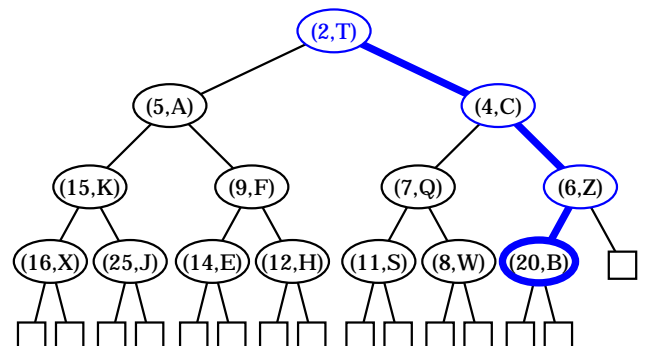
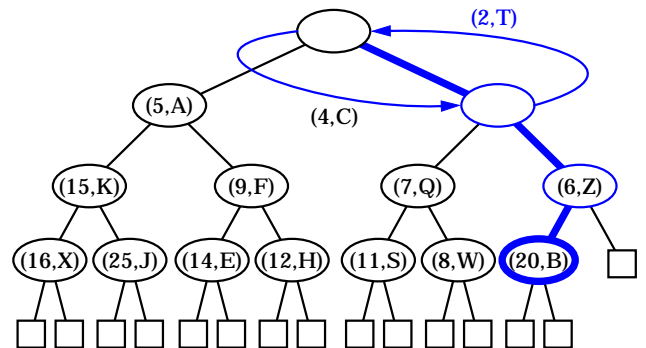
Insertion into a Heap (cont.)



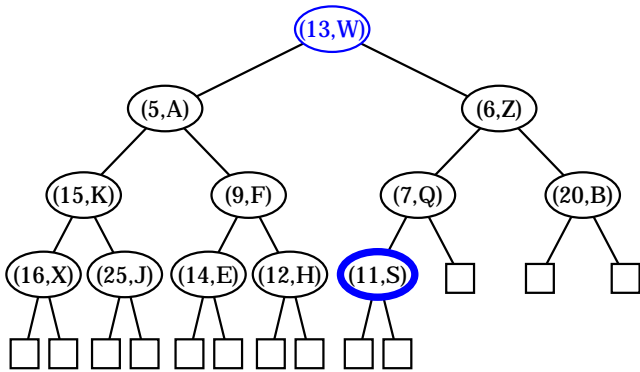
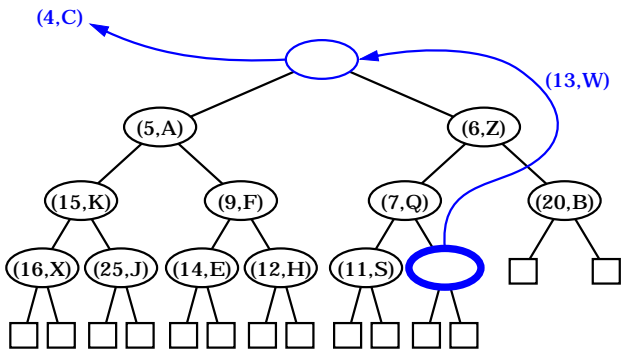
Insertion into a Heap (cont.)



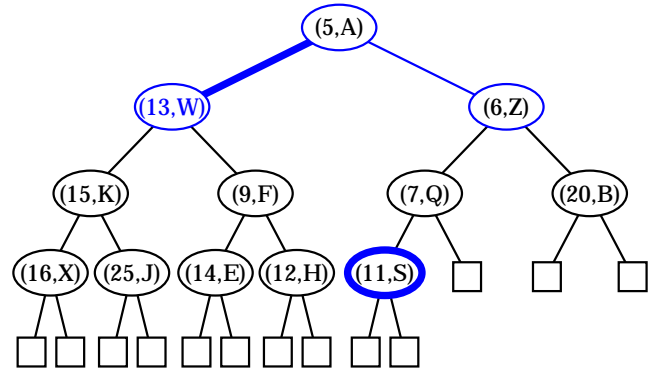
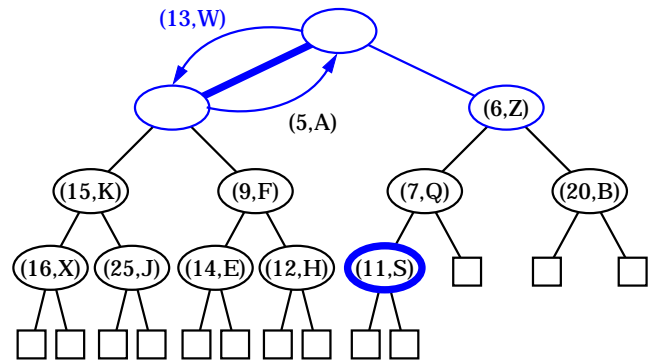
Insertion into a Heap (cont.)



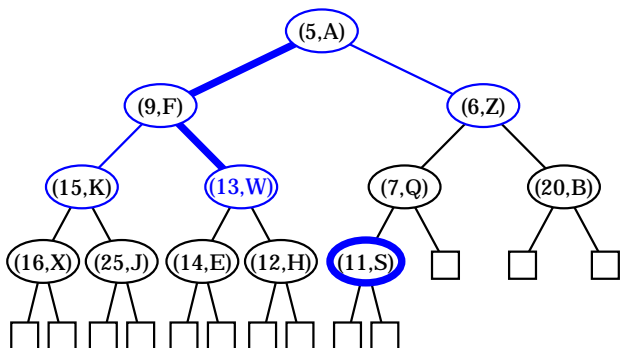
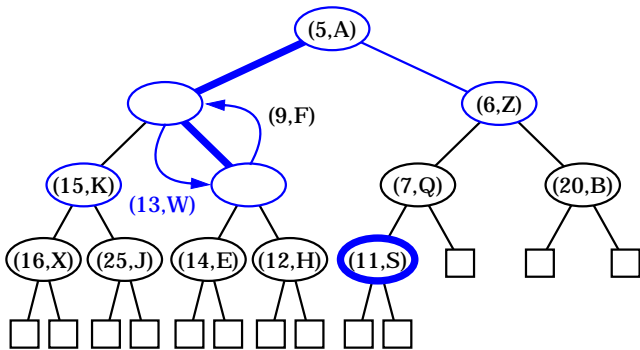
Removal from a Heap



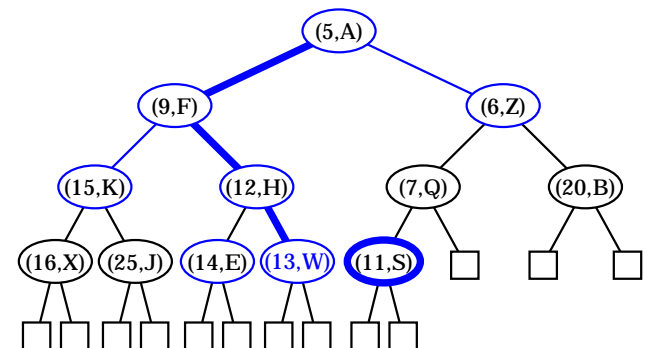
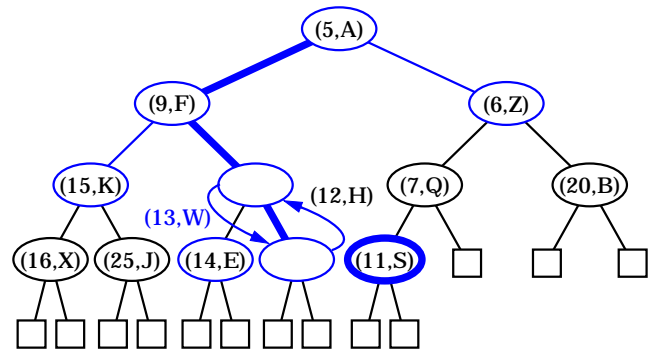
Removal from a Heap (cont.)



Removal from a Heap (cont.)

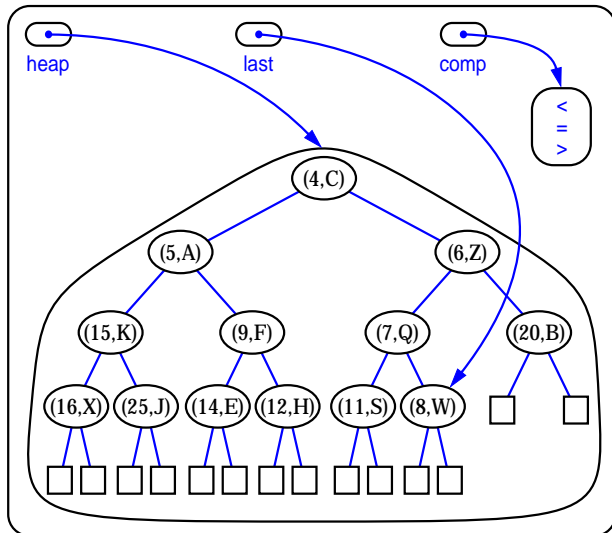


Removal from a Heap(cont.)



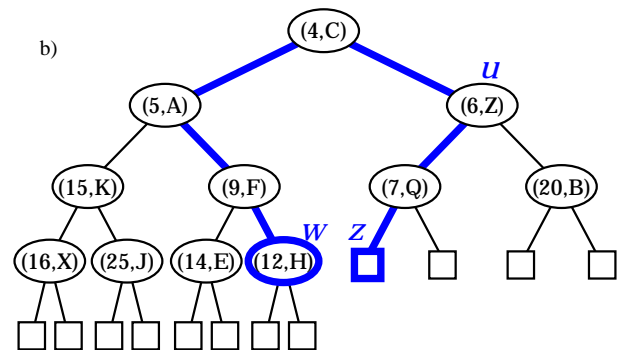
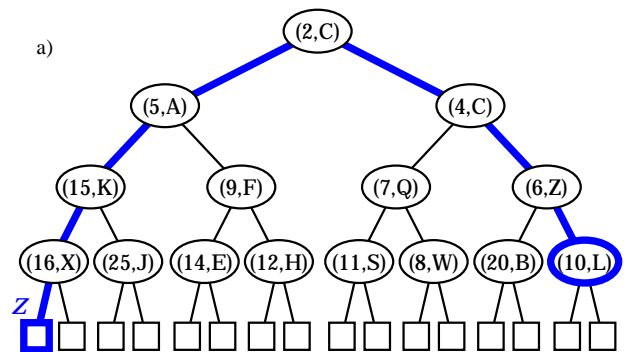
Implementation of a Heap

```
public class HeapSimplePriorityQueue implements
SimplePriorityQueue {
    BinaryTree T;
    Position last;
    Comparator comparator;
    ...
}
```



Implementation of a Heap(cont.)

- Two ways to find the insertion position z in a heap:



Heap Sort

- All heap methods run in logarithmic time or better
- If we implement PriorityQueueSort using a heap for our priority queue, `insertItem` and `removeMinElement` each take $O(\log k)$, k being the number of elements in the heap at a given time.
- We always have n or less elements in the heap, so the worst case time complexity of these methods is $O(\log n)$.
- Thus each phase takes $O(n \log n)$ time, so the algorithm runs in $O(n \log n)$ time also.
- This sort is known as **heap-sort**.
- The $O(n \log n)$ run time of heap-sort is much better than the $O(n^2)$ run time of selection and insertion sort.

Bottom-Up Heap Construction

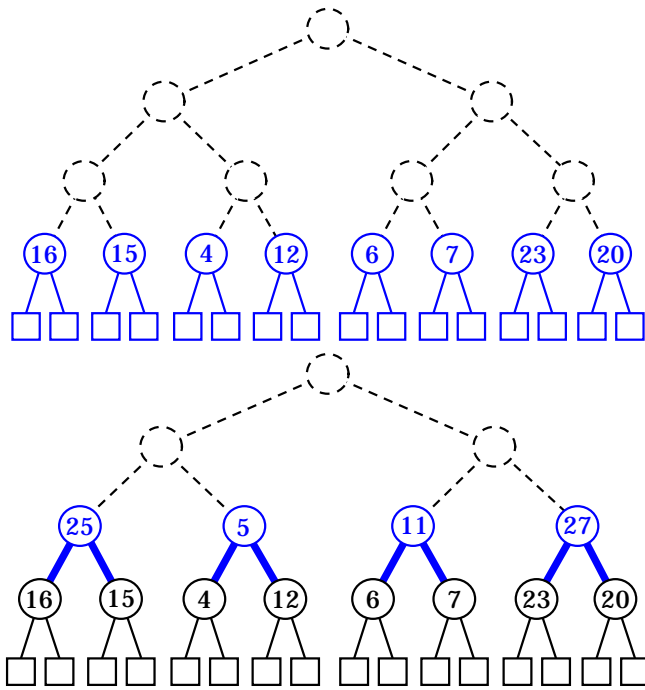
- If all the keys to be stored are given in advance we can build a heap **bottom-up** in $O(n)$ time.
- Note: for simplicity, we describe bottom-up heap construction for the case for n keys where:

$$n = 2^h - 1$$

h being the height.

- Steps:
 - Construct $(n+1)/2$ elementary heaps with one key each.
 - Construct $(n+1)/4$ heaps, each with 3 keys, by joining pairs of elementary heaps and adding a new key as the root. The new key may be swapped with a child in order to preserve heap-order property.
 - Construct $(n+1)/8$ heaps, each with 7 keys, by joining pairs of 3-key heaps and adding a new key. Again swaps may occur.
 - ...
 - In the i th step, $2 \leq i \leq h$, we form $(n+1)/2^i$ heaps, each storing $2^{i-1}-1$ keys, by joining pairs of heaps storing $(2^{i-1}-1)$ keys. Swaps may occur.

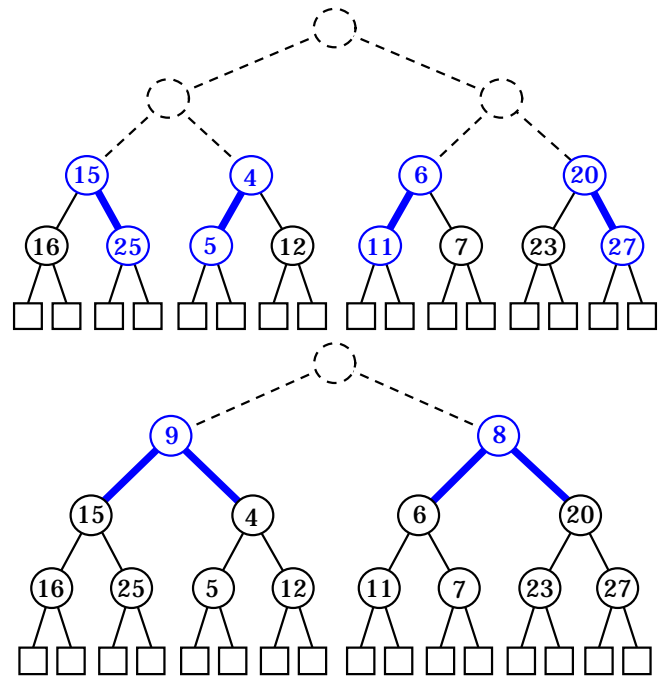
Bottom-Up Heap Construction (cont.)



Priority Queues

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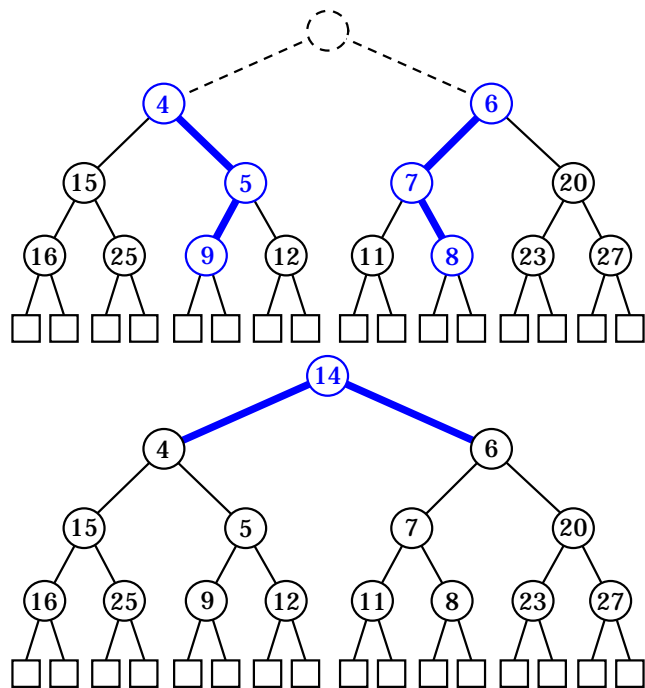
Bottom-Up Heap Construction (cont.)



Priority Queues

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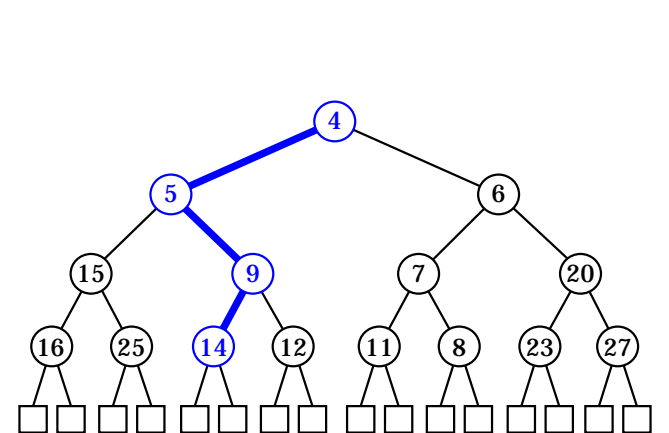
Bottom-Up Heap Construction (cont.)



Priority Queues

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Bottom-Up Heap Construction (cont.)



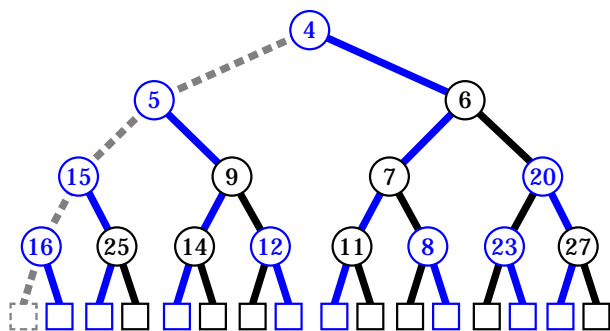
The End

Priority Queues

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Analysis of Bottom-Up Heap Construction

- **Proposition:** Bottom-up heap construction with n keys takes $O(n)$ time.
 - Insert $(n + 1)/2$ nodes
 - Insert $(n + 1)/4$ nodes
 - Upheap at most $(n + 1)/4$ nodes 1 level.
 - Insert $(n + 1)/8$ nodes
 - ...
 - Insert 1 node.
 - Upheap at most 1 node 1 level.



- n inserts, $n/2$ upheaps of 1 level = $O(n)$

Locators

- Locators can be used to keep track of elements in a container
- A locator sticks with a specific key-element pair, even if that element “moves around”.
- The Locator ADT supports the following fundamental methods:

element():	Return the element of the item associated with the Locator. Input: None; Output: Object
key():	Return the key of the item associated with the Locator. Input: None; Output: Object
isContained():	Return true if and only if the Locator is associated with a container. Input: None; Output: boolean
container():	Return the container associated with the Locator. Input: None; Output: boolean

Priority Queue with Locators

- It is easy to extend the sequence-based and heap-based implementations of a Priority Queue to support Locators.
- The Priority Queue ADT can be extended to implement the Locator ADT
- In the heap implementation of a priority queue, we store in the locator object a key-element pair and a reference to its position in the heap.
- All of the methods of the Locator ADT can then be implemented in $O(1)$ time.

A Java Implementation of a Locator

```

public class LocItem extends Item implements Locator
{
    private Container cont;
    private Position pos;
    LocItem (Object k, Object e, Position p, Container c) {
        super(k, e);
        pos = p;
        cont = c;
    }

    public boolean isContained() throws
    InvalidLocatorException {
        return cont != null;
    }

    public Container container() throws
    InvalidLocatorException { return cont; }

    protected Position position() { return pos; }
    protected void setPosition(Position p) { pos = p; }
    protected void setContainer(Container c) { cont = c; }
}

```

A Java Implementation of a Locator-Based Priority Queue

```
public class SequenceLocPriorityQueue
    extends SequenceSimplePriorityQueue implements
    PriorityQueue {
    //priority queue with locators implemented
    //with a sorted sequence

    public SequenceLocPriorityQueue (Comparator
    comp) { super(comp); }

    // auxiliary methods

    protected LocItem locRemove(Locator loc) {
        checkLocator(loc);
        seq.remove(((LocItem) loc).position());
        ((LocItem) loc).setContainer(null);
        return (LocItem) loc;
    }
}
```

Locator-Based PQ (contd.)

```
protected Locator locInsert(LocItem locit) throws
InvalidKeyException {
    Position p, curr;
    Object k = locit.key();
    if (!comp.isComparable(k))
        throw new InvalidKeyException("The key is not valid");
    else
        if (seq.isEmpty())
            p = seq.insertFirst(locit);
        else if
            (comp.isGreaterThan(k,extractKey(seq.last())))
            p = seq.insertAfter(seq.last(),locit);
        else {
            curr = seq.first();
            while (comp.isGreaterThan(k,extractKey(curr)))
                curr = seq.after(curr);
            p = seq.insertBefore(curr,locit);
        }
    locit.setPosition(p);
    locit.setContainer(this);
    return (Locator) locit;
}
```

Locator-Based PQ (contd.)

```
public void insert(Locator loc) throws
InvalidKeyException {
    locInsert((LocItem) loc);
}

public Locator insert(Object k, Object e) throws
InvalidKeyException {
    LocItem locit = new LocItem(k, e, null, null);
    return locInsert(locit);
}

public void insertItem (Object k, Object e) throws
InvalidKeyException {
    insert(k, e);
}

public void remove(Locator loc) throws
InvalidLocatorException {
    locRemove(loc);
}

public Object removeMinElement () throws
EmptyContainerException {
    Object toReturn = minElement();
    remove(min());
    return toReturn;
}
```