

David Vázquez Bermúdez

CONTACT Information

Avd. Pere Planas 5 08198 Sant Cugat del Valles, Barcelona Catalonia, Spain dvazquez@cvc.uab.es www.cvc.uab.es/~dvazquez (+34) 607665417

RESEARCH INTERESTS **Computer Vision:** Scene Understanding, Semantic Segmentation, Object Detection, Pedestrian Detection and 3D Reasoning & Reconstruction.

Machine Learning: Deep Learning, Domain Adaptation and On-line & Transfer Learning

Robotics: Autonomous Driving.

EDUCATION

PhD in Computer Vision

2013

Universitat Autònoma de Barcelona, Spain

- Thesis title: Virtual and Real World Adaptation for Pedestrian Detection
- Advisor: Prof. Antonio López
- Area of Study: Computer Vision for Advanced Driver Assistance Systems
- Scholarship: PIF Autonomous University grant

MSc in Artificial Intelligence and Computer Vision

2009

Universitat Autònoma de Barcelona, Spain

• Dissertation title: The effect of the distance in Pedestrian Detection

Undergraduate degree in Computer Science

2008

Universitat Autònoma de Barcelona, Spain

• Dissertation title: Intrusion Detection in Intelligent Surveillance Systems

Undergraduate degree in Technical Computer Science

2006

Universidade de A Coruña, Spain

Dissertation title: Face Recognition in Barajas Airport

Internships

Post Doc internship

2016-2017

Montreal Institute for Learning Algorithms (MILA) at Université de Montréal, Québec, Canada

- Scholarship: Tecniospring Marie Curie Grant
- Objective: To develop deep learning architectures for image semantic segmentation & image generation.
- Advisor: Dr. Aaron Courville

PhD internship

2011-2012

Dept. of Environment Perception at Daimler AG, Ulm, Germany

- Scholarship: PIF mobility Autonomous University Grant
- Objective: To develop a complex risk assessment and situation analysis system for pedestrian collision avoidance on-board of a Mercedes car. Confidential results.
- Advisor: Prof. Dr. Dariu M. Gavrila

Undergraduate internship

2005-2006

FRAV: Face Recognition and Artificial Vision at Universidad Rey Juan Carlos, Madrid, Spain

Scholarship: SICUE-Seneca grantAdvisor: Dr. Enrique Cabello

Undergraduate internship

2004-2005

Universidad Autónoma de Madrid, Madrid, Spain

■ Scholarship: SICUE-Seneca grant

ADDITIONAL

Self-Driving Car Engineer Nanodegree

2017

FORMATION: Udacity

Deep Learning Summer School

2016

Montreal Institute of Learning Algorithms(MILA), Montreal, Canada

Summer School on Machine Learning

2013

AERFAI, Benicàssim, Spain

Winter School on Eye Tracking Methodology

2009

AERFAI, Barcelona, Spain

Summer School on New Trends in Pattern Recognition for Motion Analysis 2008

AERFAI, Barcelona, Spain

Professional Experience

Research Scientist

2016-Now

Montreal Institute for Learning Algorithms (MILA) at Université de Montréal, Québec, Canada & Computer Vision Center, Spain

- Industrial projects: Huawei, Intel, Audi, Toyota & FiveAI
- Public projects: ACDC

Research Scientist

2012-2016

Computer Vision Center, Spain

- Industrial projects: Volkswagenm, Samsung, & IDIADA
- Public projects: Eco-Driver, ACDC, SGR, Firewatcher & MAPEA2

Assistant Professor

2008-2014

Computer Science Dept., Universitat Autònoma de Barcelona, Spain

■ Subjects: Artificial Intelligence I, Artificial Intelligence II, & AI & CV Master

Software developer (Computer Vision)

2011-2011

Computer Vision Center, Spain

■ Medical Imaging - Computer guided surgery

Software developer (Computer Vision)

2007-2008

Davantis, Spain

■ Intelligent Surveillance System - Intrusion detection

Software developer (Computer Vision)

2005-2006

Universidad Rey Juan Carlos - Face Recognition & Artificial Vision, Spain

■ Face recognition in Barajas airport

Assistant professor

2006-2006

Universidad Rey Juan Carlos, Spain

■ Subject: Excel I.

Computer assistance

2005-2006

Fundación Académica Aula Más, Spain

• Computer assistance (Web, DB,...), customer attendance and teaching

TEACHING

Machine Learning for Computer Vision

2013-2017

EXPERIENCE Master of Computer Vision at UAB, UOC, UPC and UPF universities, Spain

Software Design

2014-2016

Bachelor of Computer Science at Universitat Autònoma de Barcelona, Spain

Image Classification

2015

MOOC at Coursera

Object detection

2015

MOOC at Coursera

Software Design

2015

Course for a company at Dezac, Barcelona, Spain

Artificial Intelligence II

2010-2012

Bachelor of Computer Science at Universitat Autònoma de Barcelona, Spain

Artificial Intelligence I

2008-2010

Bachelor of Computer Science at Universitat Autònoma de Barcelona, Spain

PARTICIPATION IN **RETEVI Network - Red Temática en Vehículos Inteligentes** RESEARCH

PROJECTS

Vehicle Autònom Connectat (VEC)

2016-2017 2016-2017

Principal Investigator: Fundació Parc de Recerca UAB (PRUAB)

Spanish Project (Catalunya Empren) PIFE-079-16

ACDC: Autonomous Cooperative Drivers in the City

2015-2018

Principal Investigators: Antonio M. López and David Vázquez

Spanish Project TRA2014-57088-C2-1-R

MAPEA2: Movimiento Acostumbrado de los Peatones: Estudio para

2015

Atajar los Accidentes. \mathbf{DGT}

Principal investigator: A.M. López

MIPRCV Network - Multimodal Interaction in Pattern Recognition and

Computer Vision Network of Excellence

2015-2018

Vehicle automation and localization

2014-Present

VISIT project by CVC-ADAS and ASCAMM

	CVC-ADAS, UPC-IRI, UMH-UWICORE and APPLUS-IDIA	DA
	eCo-DRIVERS: Ecologic Cooperative Driver and Road Intelligent Visual Exploration for Route Safety Spanish Project TRA2011-29454-C03-00-00	2011-Present
	FireWATCHER: Fire Warning by Aerial Terrain Control of Hot Embers Regions Spanish Project TIN2011-29494-C03-02	2011-Present
	Co-DRIVERS: Cooperative Driver and Road Intelligent Visual Exploration for Route Safety Spanish Project TRA2010-21371-C03-00	2011-2012
	MIPRCV: Consolide Ingenio Spanish Project CSD200700018	2010-2013
	Computer vision based detection and tracking of vehicles and pedestrians for ADAS Spanish Project	2008-2010
PARTICIPATION IN INDUSTRIAL PROJECTS	Audi II Principal investigators: A.M. López	2016-2017
PROJECTS	Audi I Principal investigators: A.M. López	2016
	Toyota Principal investigators: A.M. López	2016
	Five AI Principal investigators: A.M. López	2016
	HUAWEI II Principal investigators: A.M. López	2017
	HUAWEI I Principal investigators: A.M. López	2016-2017
	Yandex Principal investigators: A.M. López	2016-2017
	Intel Principal investigators: A.M. López	2016-2017
	APPLUS+ IDIADA and Toyota Korea Principal investigators: D. Vázquez and A.M. López	2016
	Volkswagen and Seat Principal investigator: A.M. López	2015

Autonomous vehicle development

2014-Present

	APPLUS+ IDIADA and Toyota Korea Principal investigators: D. Vázquez and A.M. López	2015	
	Dezac Principal investigator: J. Serrat & D. Vázquez	2015	
	APPLUS+ IDIADA and Toyota Korea Principal investigators: D. Vázquez and A.M. López	2014	
	Samsung Poland Principal investigators: D. Vázquez and A.M. López	2014	
	Galimplant Principal investigators: José M. Álvarez	2009	
PARTICIPATION IN TEACHING INNOVATION PROJECTS	Empleo de herramientas informáticas para monito de aprendizaje en la asignatura compiladors Principal Investigator: Jorge Bernal	rizar el proceso 2016	
LANGUAGES	Spanish: Native Language Galician: Native Language	English: Fluent proficiency Catalan: Fluent proficiency	
Publications	Books		
	Computer vision Trends and Challenges J. Bernal & D. Vázquez	2013	
	Book Chapters		
	From Virtual to Real World Visual Perception using The DPM as Example A.M. Lopez, J. Xu, J.L. Gomez, D. Vazquez and G. Ros In Domain Adaptation in Computer Vision Applications	ng Domain Adaptation – 2017	
	Semantic Segmentation of Urban Scenes via Domain Adaptation of SYNT-HIA 2017 G. Ros, L. Sellart, G. Villalonga, E. Maidanik, F. Molero, M. Garcia, A. Cedeño, F. Perez, D. Ramirez, E. Escobar, J.L. Gomez, D. Vazquez and A.M. Lopez In Domain Adaptation in Computer Vision Applications		
	Vision-Based Advanced Driver Assistance Systems D. Geronimo, D. Vazquez and A. de la Escalera In Vision-Based Advanced Driver Assistance Systems	s 2017	
	Interactive Training of Human Detectors D. Vázquez, A. López, D. Ponsa & D. Gerónimo In Multimodal Interaction in Image and Video Application rence Library	2013 ons Intelligent Systems Refe-	

2012

Pedestrian detection: exploring virtual worlds

J. Marín, D. Gerónimo, D. Vázquez, & A. López In <i>Handbook of Pattern Recognition: Methods and Applications</i> , i-Concept Press	
Sistemas de Videovigilancia Inteligente E. Cabello, C. Conde, I. Martín, L.J. Rodríguez, D. Vázquez & J. González In Aplicaciones en el Aeropuerto de Barajas, IUISI	2008
Journal Papers	
A Benchmark for Endoluminal Scene Segmentation of Colonoscopy Images	2017
D. Vazquez, J. Bernal, F.J. Sanchez, G. Fernandez-Esparrach, A.M. Lopez, A. Rom. Drozdzal, A. Courville In <i>Journal of Healthcare Engineering</i> (JHE), . IF= 0.912, 75/88 in Health Careces & Services (Q4)	
Hierarchical Adaptive SVM for Domain Adaptation.	2016
J. Xu, S. Ramos, D. Vázquez & A. López In <i>International Journal on Computer Vision</i> (IJCV), 119(2), 159-178. IF= 10/130 in Computer Science, Artificial Intelligence (Q1)	4.270
Pedestrian Detection at Day/Night Time with Visible and FIR Cameras: A Comparison.	2016
A. González, Z. Fang, Y. Socarrás, J. Serrat, D. Vázquez, J. Xu & A. López In Sensors Journal (Sensors), 16(6), 820. IF= 2.033, 12/56 in Instruments & Imentation (Q1)	nstru
On-Board Object Detection: Multi-cue, Multi-modal and Multi-view Random Forest of Local Experts	2016
A. González, D. Vázquez, A. López & J. Amores In <i>IEEE Transactions on cybernetics</i> (CYBER), 99(), 1-11. IF= 4.943, 6/130 in puter Science, Artificial Intelligence (Q1), 1/22 in Computer Science, Cybernetics	
Domain Adaptation of Deformable Part-Based Models	201 4
J. Xu, S. Ramos, D. Vázquez & A. López In <i>IEEE Transactions on Pattern Analysis and Machine Intelligence</i> (T-PAMI), 3 2367–2380. IF= 5.694, 4/121 in Computer Science, Artificial Intelligence (Q1), in Engineering, Electrical & Electronic (Q1).	
Learning a Part-based Pedestrian Detector at Virtual World J. Xu, D. Vázquez, A. López, J. Marín & D. Ponsa	201 4
In <i>IEEE Transactions on International Transportation Systems</i> (T-ITS), Vol. pp:2121-2131. IF: 3.064, 2/30 (Q1) in Transportation Science & Technology, 3/122 in Engineering, Civil, 20/242 (Q1) in Engineering, Electrical & Electronic.	
Virtual and Real World Adaptation for Pedestrian Detection D. Vázquez, A. López, J. Marín, D. Ponsa & D. Gerónimo	2013
In Transactions on Pattern Analysis and Machine Intelligence (T-PAMI), Vol. pp:797-809. IF= 5.694, 4/121 en Computer Science, Artificial Intelligence (Q1), en Engineering, Electrical & Electronic (Q1).	, ,

Occlusion Handling via Random Subspace Classifiers for

2J. Marín, D. Vázquez, A. López, J. Amores & L. I. Kuncheva

Human Detection

2013

Conference Papers	
PixelVAE: A Latent Variable Model for Natural Images I. Gulrajani, K. Kumar, F. Ahmed, A. Ali Taiga, F. Visin, D. Vazquez and A. Cou In International Conference of Learning Representations (ICLR)	2017 urville
Embedded Real-time Stixel Computation D. Hernandez, A. Espinosa, D. Vazquez, A.M. Lopez and J.C. Moure In GPU Technology Conference (GTC)	2017
GPU-accelerated real-time stixel computation D. Hernandez, A. Espinosa, D. Vazquez, A.M. Lopez and J.C. Moure In Winter Applications of Computer Vision (WACV)	2017
A Benchmark for Endoluminal Scene Segmentation of	2017
Colonoscopy Images D. Vazquez, J. Bernal, F.J. Sanchez, G. Fernandez-Esparrach, A.M. Lopez, A. Ro M. Drozdzal, A. Courville In Computer Assisted Radiology and Surgery (CARS)	omero,
The SynthCity Dataset: A Large Collection of Synthetic Images for Semantic Segmentation of Urban Scenes G. Ros, L. Sellart, J. Materzynska, D. Vázquez & A. López In IEEE Computer Vision and Pattern Recognition (CVPR)	2016
Comparison of two non-linear model-based control strategies for autonomous vehicles E. Alcala, L. Sellart, V. Puig, J. Quevedo, J. Saludes, D. Vázquez, A. López In <i>IEEE Mediterranean Conference on Control and Automation</i> (MED)	2016
GPU-based pedestrian detection for autonomous driving V. Campmany, S. Silva, J.C. Moure, T. Espinosa, D. Vázquez, A. López In International Conference on Computational Science (ICCS)	2016
Embedded real-time stereo estimation via Semi-Global Matching on the GPU D. Hernández, A. Chacón, J.C. Moure, T. Espinosa, D. Vázquez, A. López In International Conference on Computational Science (ICCS)	2016
GPU-based pedestrian detection for autonomous driving V. Campmany, S. Silva, J.C. Moure, T. Espinosa, D. Vázquez, A. López In GPU Technology Conference (GTC). (Best poster award)	2016
Real-time 3D Reconstruction for Autonomous Driving via Semi-Global Matching D. Hernández, J.C. Moure, T. Espinosa, A. Chacón, D. Vázquez, A. López In GPU Technology Conference (GTC)	2016
Hierarchical online domain adaptation of deformable part-based models	2016

In IEEE Transactions on Systems, Man, and Cybernetics Part B: Cybernetics, Vol. 44(3), pp:342-354. IF: 3.236. 12/14 in Computer Science, Artificial Intelligence, (Q1), 1/21 in Computer Science, Cybernetics, (Q1), 4/58 Automation & Control Systems,

(Q1).

J. Xu, D. Vázquez & A. López In <i>IEEE International Conference on Robotics and Automation</i> (ICRA)	
Vision-based Offline-Online Perception Paradigm for Autonomous Driving G. Ros, S. Ramos, M. Granados, A. Bakhtiary D. Vázquez & A. López In IEEE Winter Conference on Applications of Computer Vision (WACV)	2015
Multiview Random Forest of Local Experts Combining RGB and LI data for Pedestrian Detection A. González, G. Villalonga, D. Vázquez, J. Amores, & A. López In IEEE Intelligent Vehicles Symposium (IV)	DAR 2015
3D-Guided Multiscale Sliding Window for Pedestrian Detection A. González, G. Villalonga, G. Ros, D. Vázquez, & A. López In <i>Iberian Conference on Pattern Recognition and Image Analysis</i> (IbPRIA)	2015
Spatiotemporal Stacked Sequential Learning for Pedestrian Detection A. González, S. Ramos, D. Vázquez, A. López, & J. Amores In Iberian Conference on Pattern Recognition and Image Analysis (IbPRIA)	2015
Incremental Domain Adaptation of Deformable Part-based Models J. Xu, S. Ramos, D. Vázquez & A. López In British Machine Vision Conference (BMCV)	2014
Cost-sensitive Structured SVM for Multi-category Domain Adaptation J. Xu, S. Ramos, D. Vázquez & A. López In International Conference on Pattern Recognition (ICPR)	201 4
Random Forests of Local Experts for Pedestrian Detection J. Marín, D. Vázquez, A. López, J. Amores & B. Leibe In <i>IEEE International Conference on Computer Vision</i> (ICCV)	2013
Learning a Multiview Part-based Model in Virtual World for Pedestrian Detection J. Xu, D. Vazquez, A. Lopez, J. Marin, & D. Ponsa In IEEE Intelligent Vehicles Symposium (IV)	2013
Unsupervised Domain Adaptation of Virtual and Real Worlds for Pedestrian Detection D. Vázquez, A. López & D. Ponsa In International Conference on Pattern Recognition (ICPR)	2012
Improving HOG with Image Segmentation: Application to Human Detection Y. Socarrás, D. Vázquez, A. López, D. Gerónimo & T. Gevers In Int. Conference on Advanced Concepts for Intelligent Vision Systems (ACIV	2012 S)
Virtual Worlds and Active Learning for Human Detection D. Vázquez, A. M. López, D. Ponsa, & J. Marín In International Conference on Multimodal Interaction (ICMI)	2011
Color Contribution to Part-Based Person Detection in Different Types of Scenarios	2011

In Int. Conference on Computer Analysis of Images and Patterns (CAIP)
Opponent Colors for Human Detection M. Rao, D. Vázquez & A. M. López In Iberian Conference on Pattern Recognition and Image Analysis (IBPRIA)
Learning Appearance in Virtual Scenarios for Pedestrian Detection J. Marín, D. Vázquez, D. Gerónimo, & A. López In IEEE Conference on Computer Vision and Pattern Recognition (CVPR)
Workshop Papers
Multi-task Bilinear Classifiers for Visual Domain Adaptation J. Xu, S. Ramos, X. Hu, D. Vázquez & A. M. López In Advances in Neural Information Processing Systems (NIPS) Workshop
Adapting Pedestrian Detection from Synthetic to Far Infrared Images 2013 Y. Socarrás, S. Ramos, D. Vázquez, A. M. López & T. Gevers In International Conference of Computer Vision (ICCV) Workshop
Adapting a Pedestrian Detector by Boosting LDA Exemplar Classifiers 2013 J. Xu, D. Vázquez, S. Ramos, A. López, & D. Ponsa In <i>IEEE Conference on Computer Vision and Pattern Recognition</i> (CVPR) Workshop
Weakly Supervised Automatic Annotation of Pedestrian Bounding 2013 Boxes D. Vázquez, J. Xu, S. Ramos, A. López, & D. Ponsa In IEEE Conference on Computer Vision and Pattern Recognition (CVPR) Workshop
Cool world: domain adaptation of virtual and real worlds for human detection using active learning D. Vázquez, A. M. López, D. Ponsa, & J. Marín In Advances in Neural Information Processing Systems (NIPS) Workshop
Technical Reports
A Benchmark for Endoluminal Scene Segmentation of Colonoscopy Images 2017 David Vazquez, Jorge Bernal, F. Javier Sanchez, Gloria Fernandez-Esparrach, Antonio Lopez, Adriana Romero, Michal Drozdzal, Aaron Courville In $ArXiv$ (ArXiv)
The One Hundred Layers Tiramisu: Fully Convolutional DenseNets for Semantic Segmentation 2016 Simon Jégou, Michal Drozdzal, David Vazquez, Adriana Romero and Yoshua Bengio In Arxiv ()
Stereo Matching using SGM on the GPU Daniel Hernandez, Alejandro Chacon, Antonio Espinosa, David Vazquez, Juan Carlos

M. Rao, D. Vázquez & A. M. López

Node-Adapt, Path-Adapt and Tree-Adapt:Model-Transfer Domain Adapta-

In Programming and Tuning Massively Parallel Systems (PUMPS)

Moure and Antonio M. Lopez

tion for Random Forest Azadeh S. Mozafari, David Vazquez, Mansour Jamzad and Antonio M. Lopez In <i>Arxiv</i> ()	2016
Spatiotemporal Stacked Sequential Learning for Pedestrian Detection 2 A. González, S. Ramos, D. Vázquez, A. M. López, & J. Amores In (ArXiv)	2011
Hierarchical Adaptive Structural SVM for Domain Adaptation J. Xu, S. Ramos, D. Vázquez, & A. M. López In (ArXiv)	2011
Thesis	
Domain Adaptation of Virtual and Real Worlds for Pedestrian Detection D. Vázquez In Ph.D. thesis, Ediciones Gráficas Rey, Barcelona	2013
·	2000
The Effect of the distance in Pedestrian Detection D. Vázquez In Master Thesis, Autonomous University of Barcelona	2009
Elektra Autonomous Vehicle G. Villalonga, G. Ros, J.L. Gómez, S. Silva, D. Hernández, A. M. Lopez Demo at the UAB for NVIDIA 2016, Barcelona	2016
Photo-realistic Virtual Worlds to Boost Video Understanding and Autonomous Driving: Introducing SYNTHIA & Virtual KITTI A. Gaidon, G. Ros, A. M. Lopez, E. Vig, D. Vázquez, Q. Wang Demo at the Computer Vision and Pattern Recognition Conf. (CVPR) 2016, Las V	2016
Autonomous Vehicle Simulator A. Gonzalez, G. Villalonga, A. Shuvin, L. Sellart, D. Vázquez, G. Ros & A. M. Ló Nit de la recerca 15, Barcelona	2015 ópez
Autonomous Vehicle Simulator A. Gonzalez, G. Villalonga, A. Shuvin, L. Sellart, D. Vázquez, G. Ros & A. M. Ló CERCA 15, Barcelona	2015 ópez
3D Pedestrian Detection via Random Forest A. Gonzalez, G. Villalonga, G. Ros, D. Vazquez & A. M. Lopez. Demo at Iberian Pattern Recognition and Image Analysis (IbPRIA), Santiago de Opostela	2015 <i>Com-</i>
Autonomous Vehicle Simulation A. Gonzalez, G. Villalonga, A. Shuvin, L. Sellart, G. Ros, D. Vazquez & A. M. Lo	2015 opez.

Demos

MEMEnginy 15, feast of engineering school (\boldsymbol{ETSE}), Barcelona

A. Gonzalez, G. Villalonga, A. Shuvin, L. Sellart, D. Vázquez, G. Ros & A. M. López

 ${\bf Autonomous\ Vehicle\ Simulator}$

NOVUM 15, Science feast of Barcelona

INVITED TALKS

3D Pedestrian Detection A. Gonzalez, G. Villalonga, G. Ros, D. Vazquez & A. M. Lopez. Saló del Ensenyament, Barcelona	2015
3D Pedestrian Detection via Random Forest G. Villalonga, S. Ramos, G. Ros, D. Vazquez & A. M. Lopez. Demo at European Conference on Computer Vision (ECCV), Zurich	2014
3D Pedestrian Detection G. Villalonga, S. Ramos, G. Ros, D. Vazquez & A. M. Lopez. MEMEnginy 14, feast of engineering school (ETSE), Barcelona	2014
Real-time Pedestrian Detection via Random Forest J. Marin, S. Ramos, D. Vazquez, A. M. Lopez, J. Amores, B. Leibe & G. Ro Demo at British Machine Conference (BMVC)	2013
Eco-Driver project D. Vázquez, S. Ramos, J. Xu, G. Ros & A. M. López Barcelona Party [Science + Technology]	2013
Eco-Driver project D. Vázquez, J. Marín & A. M. López MIPRCV Industry day	2013
Eco-Driver project D. Vázquez & A. M. López Mobility and transport in the Smart Cities	2012
Eco-Driver project D. Vázquez & A. M. López Expoelectric Fórmula-E	2012
Artificial Intelligence Techniques for Data Mining & Big Data, P Spain Elektra autonomous vehicle & Deep Learning basics	amplona, 05.04.2017
Zoox, San Francisco The SYNTHIA Dataset: A Large Collection of Synthetic Images for Semant tation of Urban Scenes	01.07.2016 ic Segmen-
MyCore – TELSEA Workshop, Barcelona GPU optimization for Autonomous Driving	05.02.2016
Auniversity of Alcalá, Madrid Learning to See in a Virtual World	26.11.2015
Pint of Science, Barcelona Autonomous Vehicles	21.04.2015
ST Dynamics, Singapore Advanced Driver Assistance Systems and Autonomous Vehicles	07.11.2014

	Samsung Research, Poland Random Forest of Local Experts for Pedestrian Detection	15.06.2014
	Rey Juan Carlos University (URJC) Face Recognition and Artificial Vision (FRAV), Madrid (Spain) Domain Adaptation of Virtual and Real Worlds for Pedestrian Detection	31.10.2013
	Daimler AG, Research & Development Environment Perception Group, Sindelfingen (Germany) Domain Adaptation of Virtual and Real Worlds for Pedestrian Detection	23.09.2013
	University of Zaragoza Robotics and Real Time Group, Zaragoza (Spain) Autonomous Driving: when 3D Mapping meets Semantics	06.11.2013
SELECTED MEDIA COVERAGE	Virtual and Real World Adaptation for Pedestrian Detection In Autonomous University of Barcelona News	2014
	How Self-Driving Cars Will Sneak Onto Our Roads In $IEEE\ Spectrum$	2014
	Report at Connexió Barcelona program about Eco-Driver projec In $Barcelona\ Televisió$ - BTV	t 2013
	News report about Eco-Driver project In $Euskal\ Telebista$ - ETB	2013
	News report about Eco-Driver project: Technology can help avoi accidents produced by human errors In $Televisi\acute{o}$ de $Catalunya$ - $TV3$	ding 2013
	Note: For a complete list of media events follow this link	
ACADEMIC SERVICES	Journal editor: ELCVIA Electronic Letters on Computer Vision and Image Analysis (ELC cial Issue on Recent PhD Thesis Dissemination, 2016.	CVIA). Spe-
	IET Computer Vision journal (IET-CV). Special Issue on Deep Learning i Vision, with Dr. Tim Hospedales, 2016.	n Computer

Reviewing conferences: ECCV/ICCV(2016-2017), CVPR(2017), BMVC(2016-2017), ICPR(2012-2016), IV (2015-2017), IbPRIA(2015), WSCG(2015), & WACV(2015-2017)

Reviewing journals: Elisever Pattern Recognition Letters (2015), Robotics (2013), IEEE TCSVT (2014-2015), Elisever ELCVIA (2014-2015), Elisever Knosys (2014-2015), Elisever Image Communication (2014-2015), Elisever Eng. Application of AI (2015), Elisever Infrared Physics & Technology (2014), Sensors Journal (2014-2015), Int. Transport. Systems (2014-2015) & World J. of Computer Application and Technology

Program commite: Robot(2015)

Session chair: IbPRIA(2015)

Thesis commite: UAB - Bachelor Thesis (2013-2016), UAB - Master Thesis (2014-2016)

Ph.D. Thesis of **Carolina Redondo** from Universidad de Alcalá, Madrid, Spain. Object Classification, Detection and Pose Estimation

Co-chair conferences:

7th Iberian Conference on Pattern Recognition and Image Analysis (**IbPRIA**). Demos chair with X. R. Fdez-Vidal and D. L. Vilariño. In conjunction with **AERFAI** & **APRP** 2015.

Co-chair workshops:

International Workshop on Transferring and Adapting Source Knowledge in Computer Vision (**TASK-CV**) with K. Saenko, B. Usman, X. Peng, J. Hoffman, D. Wang, A. M. López, W. Li, F. Orabona, T. Tommasi. In conjunction with **ECCV** 2017.

International Workshop on Computer Vision in Vehicular Technology (CVVT) with J. M. Álvarez, A. M. Lopez M. Enzweiler, T. Pajdla and G. Villalonga. In conjunction with CVPR 2017.

Virtual/Augmented Reality for Visual Artificial Intelligence (**VARVAI**) with A. M. López, A. Gaidon, G. Ros, E. Vig, H. Su, and F. Perronnin. In conjunction with **ECCV** 2016.

International Workshop on Transferring and Adapting Source Knowledge in Computer Vision (TASK-CV) with Wen Li, A. M. Lopez, F. Orabona, T. Tommasi, H. Larochelle, and J. Xu. In conjunction with ECCV 2016.

International Workshop on Computer Vision in Vehicular Technology (CVVT) with J. M. Álvarez, A. M. Lopez and T. Pajdla. In conjunction with CVPR 2016.

International Workshop on Transferring and Adapting Source Knowledge in Computer Vision (**TASK-CV**) with A. M. Lopez, F. Orabona, T. Tommasi, H. Larochelle, E. Rodner and J. Xu. In conjunction with **ICCV** 2015.

International Workshop on Computer Vision in Vehicular Technology (CVVT) with J. M. Álvarez, A. M. Lopez, T. Pajdla and S. Ramos. In conjunction with CVPR 2015.

International Workshop on Scene Understanding for Autonomous Systems (SUAS) with S. Ramos, R. Urtasun, A. Torralba, N. Barnes, M. Enzweiler and A. Lopez In conjunction with ACCV 2014

International Workshop on Transferring and Adapting Source Knowledge in Computer Vision (**TASK-CV**) with A. M. Lopez, K. Saenko, F. Orabona, S. Ramos and J. Xu. In conjunction with **ECCV** 2014.

International Workshop on Computer Vision in Vehicular Technology with Special Session in Micro Aerial Vehicles (CVVT) with F. Fraundorfer, D. Geronimo, D. Scaramuzza, H. Bischof, A. Imiya, A. M. Lopez, T. Pajdla, M. Pollefeys and S. Ramos. In conjunction with ECCV 2014.

Annual Catalan Meeting in Computer Vision 2014 (ACMCV) with M. Vanrell, X.

Binefa, V. Vilaplana, D. Masip, J. Vázquez and R. Morros, (CVC) Barcelona.

Workshop on Computer Vision Trends and Challenges 2013-2014 (CVCRD), (CVC) Barcelona.

Vision Reading Group 2013-2015 with J. van de Weijer, A. D. Bagdanov and S. Ramos at the Computer Vision Center (CVC) Barcelona.

ADAS Reading Group 2012 with G. Ros at the Computer Vision Center (\mathbf{CVC}) Barcelona.

Mentoring Ph.D Students

Daniel Hernández, Ph.D. Student, UAB 2015-now

Ph.D. Thesis: Real-time Autonomous Driving on GPGPU

Gabriel Villalonga, Ph.D. Student, UAB 2015-now

Ph.D. Thesis: End-to-End Autonomous Driving via DCNNs

Zhijie Fang, Ph.D. Student, UAB 2014-now

Ph.D. Thesis: Pedestrian intention analysis

Alejandro González, Ph.D. Student, UAB

2013-2015

Ph.D. Thesis: SpatioTemporal Information for pedestrian detection (Exelent Cum Laude)

Master Students

Eugenio Alcalá, M.Sc. Student, UPC 2015-2016

M.Sc. Thesis: Autonomous vehicle control and planning

Jordi Frias, M.Sc. Student, UAB 2015-2016

M.Sc. Thesis: Semantic Segmentation with Deep Learning

Albert Mosella, M.Sc. Student, UAB 2015-2016

M.Sc. Thesis: Deep Learning for Autonomous Driving

Akhil Gurram, M.Sc. Student, UAB 2015-2016

M.Sc. Thesis: Monocular Depth Estimation via Deep Learning

Ashraful Alam Milton, M.Sc. Student, UAB 2015-2016

M.Sc. Thesis: Pedestrian detection with Deep Learning based on Theano

Gabriel Villalonga, M.Sc. Student, UAB 2014-2015

M.Sc. Thesis: Georeferenciate objects detected by stereo vision (Best thesis award by IEEE-ITSS.)

Manuel Granados, M.Sc. Student, UAB

2013-2014

M.Sc. Thesis: Semantic Scene Understanding for Urban Scenarios

Undergraduate Students - Thesis

Ferran Rey Jornet, B.Sc. Student, UAB

2016-2017

Thesis: Pedestrian and vehicle counting: Intelligent Traffic Lights

Cristian García, B.Sc. Student, UAB

2016-2017

Thesis: Vehicle-To-X Communications: Intelligent Traffic Lights

Cristian Gómez, B.Sc. Student, UAB

2015-2016

Thesis: Vehicle-To-X Communications: Intelligent Traffic Lights

Fracisco Molero, B.Sc. Student, UAB

2015-2016

Thesis: Dimension Defender: Desarrollo de un videojuego en 3D

Victor Campmany, B.Sc. Student, UAB

2015-2016

Thesis: Real-time Pedestrian Detection on GPGPU

Marcos Molero, B.Sc. Student, UAB

2015-2016

Thesis: Deep Learning Region based Classification

Javier Rodríguez, B.Sc. Student, UAB

2015-2016

Thesis: Region based Classification

Joanna Materzynska, B.Math. Student, UAB

2014-2015

Thesis: Semantic Segmentation with Convolutional Neural Networks (with Honors)

Alexandre Shubin, B.Sc. Student, UAB

2014-2015

Thesis: Autonomous Navigation Simulator

Jordi Frías, B.Math. Student, UAB

2014-2015

Thesis: High Level Representation for Autonomous Navigation (with Honors)

Sergi Canyameres, B.Sc. Student, UAB

2014-2015

Thesis: Deep Learning for Object detection (with Honors)

Javier Gómez Domínguez, B.Sc. Student, UAB

2014-2015

Thesis: Lane Departure Warning

Laura Sellar, B.Sc. Student, UAB

2014-2015

Thesis: Generation of Synthetic Data for Autonomous Driving Applications. With Honors. Best thesis award by UAB.

Andrea Álvarez, B.Sc. Student, UAB 2013-2014 Thesis: 3D Semantic Segmentation 2013-2014 Gabriel Villalonga, B.Sc. Student, UAB Thesis: 3D Pedestrian Detection. With Honors. Best thesis award by UAB. Undergraduate Students - Projects 2015-2016 Sergio Silva, B.Sc. Student, UAB Project: Object detection implementation in CUDA 2014-2015 Cristian Gómez, B.Sc. Student, UAB Project: Autonomous Driving maps Victor Campmany, B.Sc. Student, UAB 2014-2015 Project: Object detection implementation in CUDA 2014 Gerard Clotet, B.E.E. Student, UAB Project: Integration of Autonomous Driving Algorithms in ROS 2014 Jordi Frias, B.Math. Student, UAB Project: 3D Ground Plane Estimation 2012-2013 Sergi Canyameres, B.Sc. Student, UAB Project: Virtual World for ADAS High School Students Javier Domingo Sierra, H.S. Student, UAB 2014-2015 Thesis: Driver Monitoring (with Honors) 2014-2015 Alejandro Daniel Noel, H.S. Student, La Salle Bonanova Thesis: Autonomous Driving (with Honors) Invitation to participate at Dagstuhl Seminar on Vision for 2015

Invited CONFERENCES

Autonomous Vehicles and Probes - Dagstuhl brings together the world's leading researchers, practitioners, and young talents to discuss their ideas for fostering new directions and fields in computer science

The Future of Urban Mobility Series: Automotive trends in 2015 urban mobility. IESE Bussines School. Barcelona, Spain

Salón Internacional del automóvil. 2015 Technical Simposium on Intelligent Vehicles. Barcelona, Spain

	GPU Technology Conference. San Jose, EEUU	2015
	Mobile World Congress. Barcelona, Spain	2015
FELLOWSHIP	Tecniospring - Marie Curie - Postdoctoral fellowship	2016-2018
	Juan de la Cierva - Postdoctoral fellowship	2015-2018
	PIF-UAB - Doctoral fellowship	2008-2012
	${\bf SICUE\text{-}SENECA\ -\ Mobility\ undergraduate\ fellowship\ (URJC)}$	2005-2006
	${\bf SICUE\text{-}SENECA\text{-} Mobility undergraduate fellowship (UAM)}$	2004-2005
Awards	GTC 2016 Awards - Best poster award at NVIDIA GTC 2016 GPU-based pedestrian detection for autonomous driving	2016
	IEEE Awards - Best PhD Thesis Award by IEEE Intelligent Transportation Systems Society Spanish section	2015
	AERFAI Awards - Best PhD Thesis Award by Spanish Comput Vision Association	er 2015
	UAB Awards - Best PhD Thesis Award by UAB	2015
	PIONER Awards - Best PhD Thesis Award by CERCA	2014
	RMRC Challenge (ECCV) - Second position in Pedestrian Dete	ction 2014
	RMRC Challenge (ICCV) - Winners in Pedestrian Detection	2013
	Google award for the article: Cool world: domain adaptation of virtua and real worlds for human detection using active learning In NIPS Domain Adaptation Workshop: Theory and Application	al 2011
	ICMI Doctoral Consortium award for the article: Virtual Worlds of Active Learning for Human Detection In ACM International Conference on Multimodal Interaction	and 2011
SCIENTIFIC SOCIETIES:	Spanish Chapter – IEEE Intelligent Transportation Systems Society Position: Treasurer	2016-now
	AERFAI: Spanish Association of Pattern Recognition and Image Analysis Position: Member	2011-now
	IEEE Computer Society Position: Member	2011-now

Teaching	AQU - Certified by AQU as "Profesor Lector"	2015
CREDENTIALS:		
	UAB - Teaching courses - 7 different teaching courses	2013-2015