

Abstract

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Inhoudsopgave

1	Inleiding	2
2	Hoofdstuk	2
2.1	Probleemstelling	2
2.2	Onderwerpalternatieven	2
2.2.1	Microsoft Kinect	2
2.2.2	Camera Kalibratie	2
2.2.3	Enkele Camera met AI	2
2.2.4	Motivatie Keuze	2
2.3	Methodologie	2
2.4	Resultaten	2
2.5	Discussie	3
2.5.1	Voorstellen Verdere Uitwerking	3
3	Besluit en Verdere Planning	3
4	Vakintegratie	3

1 Inleiding

2 Hoofdstekst

2.1 Probleemstelling

2.2 Onderwerpalternatieven

2.2.1 Microsoft Kinect

2.2.2 Camera Kalibratie

2.2.3 Enkele Camera met AI

2.2.4 Motivatie Keuze

2.3 Methodologie

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2.4 Resultaten

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2.5 Discussie

2.5.1 Voorstellen Verdere Uitwerking

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3 Besluit en Verdere Planning

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4 Vakintegratie

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Lijst van figuren

Lijst van tabellen