

view_frames Result

Recorded at time: 19699.262

odom

Broadcaster: /gazebo
Average rate: 20.320 Hz
Most recent transform: 19699.250 (0.012 sec old)
Buffer length: 3.248 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10.312 Hz
Most recent transform: 19699.202 (0.060 sec old)
Buffer length: 3.200 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.312 Hz
Most recent transform: 19699.202 (0.060 sec old)
Buffer length: 3.200 sec

right_wheel

