

Towards dynamic systems

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1 Overcoming static configurations

In the *QActor* metamodel, a software system is made of a collections of *Actors*, each included in a computational node called *Context*. A *Context* can be viewed as a *subsystem* with a unique name and a unique IP address (host,port).

In several applications, the set of *Contexts* and actors that compose the system can be statically fixed, but there are other cases in which a system must dynamically change its configuration. In particular:

1. we should allow an actor to dynamically create other actors (actor instances) within its *Context*;
2. we should allow the dynamic introduction of new *Contexts* within a given system, together with the possibility to support the interaction among all the actors, both statically defined and dynamically created.

2 Dynamic creation of actors within a Context

Let us introduce the model of a very simple actor that receives and prints 2 messages and sends a reply to the sender;

```

1 System agentprototype -regeneratesrc
2 /*
3  * =====
4  * agentprototype.qa in project it.unibo.actor.dynamic
5  * =====
6  */
7 Dispatch info : info( X )
8
9 Context agentprototype ip [ host="localhost" port=8060 ] -g yellow
10 /*
11  * -----
12  * An actor that receives and prints 2 messages
13  * acting as a prototype for dynamic creation
14  * (see agentcreation.qa)
15  * -----
16  */
17 QActor agentprototype context agentprototype -g green {
18   Plan init normal
19   [ !? actorobj(NAME) ] println( waits( NAME ) );
20   receiveMsg time(300000) ;
21   [ !? actorobj(NAME) ] onMsg info : info(X) -> replyToCaller -m info : info( reply(NAME, thanks(X)) ) ;
22   printCurrentMessage ;
23   repeatPlan 1
24 }
```

Listing 1.1. agentprototype.qa

This actor has the 'static' name `agentprototype`, but it refers to its own name with the built-in rule `actorobj/1`. The generated code provides (in the directory `src`) the class `Agentprototype` that defines the following constructor:

```

----- Constructor in class it.unibo.agentprototype.Agentprototype -----
public Agentprototype(String actorId, ActorContext myCtx, IOutputEnvView outEnvView ) throws Exception{
    ...
}
```

This constructor can be used to build new instances in a dynamical way, by using an actor-creation rule already defined in the built-in actor's `WorldTheory`:

2.1 An actor-creation rule

```
1 createActor(Name, PrototypeClass, NewActor):-
2   actorobj(CREATOR),
3   CREATOR <- getName returns CurActorName,      %%get the name of the actor prototypee
4   CREATOR <- getContext returns Ctx,             %%get the context of the actor prototypee
5   CREATOR <- getOutputEnvView returns View,      %%get the output view of the actor prototypee
6   %% CREATE A NEW ACTIR INSTANCE
7   java_object(PrototypeClass, [Name,Ctx,View], NewActor),
8   NewActor <- getName returns NewActorName,
9   actorPrintln( createActor(NewActorName, NewActor, Ctx) ).
```

Listing 1.2. createActor rule (in WorldTheory)

The rule calls the constructor of the prototype given in the argument `PrototypeClass` by using the same context and the same output view of the creator's agent. Thus each new instance is always created in the context of the creator agent.

2.2 An actor-instance creator

For example, the following actor `agentcreator` dynamically generates two instances of `agentprototype` and sends to each instance a messages, waiting for a reply:

```
1 System agentcreation -regeneratesrc
2 /*
3  * =====
4  * agentcreation.qa in project it.unibo.actor.dynamic
5  * =====
6  */
7 Dispatch info : info( X )
8
9 Context ctxAgentCreation ip [ host="192.168.43.229" port=8060 ] -g yellow
10 /*
11  * The ctxPivot declaration is required, since any instance will work in the
12  * context of the creator
13  */
14 Context ctxPivot ip [ host="192.168.43.209" port=8088 ] -standalone
15 /*
16  * -----
17  * Creates two instances of agentprototype and intercats with
18  * them by sending a message and then waiting for a reply
19  * -----
20  */
21 QActor agentcreator context ctxAgentCreation {
22   Plan init normal
23   println(starts(agentcreator)) ;
24   switchToPlan createInstance;
25   switchToPlan sendHello ;
26   switchToPlan getReply ;
27   println(ends(agentcreator))
28   Plan createInstance resumeLastPlan
29   [ !? newName(agentprototypepivot,Name,N) ]
30   solve createActor(Name,'it.unibo.agentprototypepivot.Agentprototypepivot',A) time(0) onFailSwitchTo
31   prologFailure ;
32   [ !? newName(agentprototypepivot,Name,N) ]
33   solve createActor(Name,'it.unibo.agentprototypepivot.Agentprototypepivot',_) time(0) onFailSwitchTo
34   prologFailure
35   Plan sendHello resumeLastPlan
36   [! ? instance( agentprototypepivot, 1, A ) ] forward A -m info : info( hello(world)) ;
37   [! ? instance( agentprototypepivot, 2, A ) ] forward A -m info : info( hello(world))
38   Plan getReply resumeLastPlan
39   println( waits( agentcreator, reply ) );
40   receiveMsg time(300000) ;
41   printCurrentMessage ;
42   repeatPlan 3
```

```

41   Plan prologFailure resumeLastPlan
42       println("agentcreator has failed to solve a Prolog goal" )
43   }
44   QActor pivot context ctxPivot {
45       Plan init normal
46       println("pivot place holder ")
47   }

```

Listing 1.3. agentcreation.qa

The guard `[!? newName(agentprototype,Name,N)]` in Plan `createInstance` makes reference to the built-in `newname` rule for instance-names creation, that stores in the actor's knowledge base a fact `instance/3`:

```

1 instance( PROTOTYPE_NAME, INSTANCE_COUNTER, INSTANCE_NAME )

```

Listing 1.4. instance fact

2.3 The name-creation rule

The `newname/3` name creation rule is defined in the *WorldTheory* as follows:

```

1 newName( Prot, Name,N1 ) :-
2     inc(nameCounter,1,N1),
3     text_term(N1S,N1),
4     text_term(ProtS,Prot),
5     text_concat(ProtS,N1S,Name),
6     assert( instance( Prot, N1, Name ) ),
7     actorPrintln( newname(Name,N1) ) .
8
9 value(nameCounter,0).
10
11 inc(I,1,N):-
12     value( I,V ),
13     N is V + 1,
14     assign( I,N ).

```

Listing 1.5. newName rule (in WorldTheory)

3 Dynamic addition of Contexts

In this section we give an example of a dynamic system that starts from a single actor (and thus from a single node) called `pivot`. Other actors can interact with `pivot` by asking it to perform two basic operations:

- **register(NickName,Name)**: the actor of name `Name` informs `pivot` of its existence by providing a *NickName* that can be used by other actors to find the actor;
- **getactor(NickName)**: the actor makes a query to `pivot` in order to obtain the (name of the) actor that corresponds to the given *NickName*. The answer given by `pivot` can be used as destination in message-passing operations.

With these two basic operations, we can extend a system with new actors working in different nodes and we can allow an actor to interact with another one, just knowing its nickname.

3.1 A first dynamic actor

In the following example:

1. an actor (`agent1`) registers itself to the `pivot` with the nickname `zorro`;
2. `agent1` makes a request to `pivot` for an actor with nickname `batman`;
3. `agent1` forwards a *dispatch* to the actor given in the answer to its request.

```
1 System agent1 -regeneratesrc
2 /*
3  * =====
4  * agent1.qa in project it.unibo.actor.dynamic
5  * =====
6  */
7 Event alarm : alarm(X)
8
9 Request register : actorname( NICKNAME, NAME )
10 Request getactor : nickname( NAME )
11 Dispatch answer : answer( X )
12 Dispatch info : info( X )
13 /*
14  * -----
15  *
16  * -----
17  */
18 Context ctxPivot ip [ host="192.168.43.209" port=8088 ] -standalone
19 Context ctxAgent1 ip [ host="192.168.43.229" port=8040 ] -g white
20 EventHandler evh for alarm -print ;
21
22 QActor pivot context ctxPivot {
23     Plan init normal
24     println("pivot place holder ")
25 }
26
27 QActor agent1 context ctxAgent1 {
28     Plan init normal
29     println(agent1(zorro, starts)) ;
30     switchToPlan register ;
31     switchToPlan interact ;
32     println(agent1(ends))
33     Plan register resumeLastPlan
34     println(agent1(zorro, register)) ;
35     demand pivot -m register : actorname(zorro,agent1) ;
36     receiveMsg time(300000) ;
37     onMsg answer : answer(R) -> println( R )
38     Plan interact resumeLastPlan
39     println(agent1(lookat,batman)) ;
40     demand pivot -m getactor : nickname(batman) ;
41     receiveMsg time(300000) ;
42     // printCurrentMessage ;
43     onMsg answer : answer(R) -> println( agent1(found,batman,R) ) ;
44     // onMsg answer : answer(R) -> forward R -m info : info(learned(1,R)) ;
45     onMsg answer : answer(R) -> forward R -m info : info(learned(2,R))
46 }
```

Listing 1.6. `agent1.qa`

Of course, this kind of system can work only if all the dynamic agents share a common knowledge about the messages that can exchange among them.

3.2 A second dynamic actor

Each dynamic agent starts from a system composed of two actors (and contexts): itself and `pivot`.

Thus, the structural part of the model of the 'batman' agent is quite similar to that of `agent1` above; as regards the behaviour, we suppose here that 'batman' first registers itself to the `pivot` and then waits for messages:

```

1 System agent2 -regeneratesrc
2 /*
3  * =====
4  * agent2.qa in project it.unibo.actor.dynamic
5  * =====
6  */
7 Event alarm : alarm(X)
8
9 Request register : actorname( NICKNAME, NAME )
10 Request getactor : nickname( NAME )
11 Dispatch answer : answer( X )
12 Dispatch info : info( X )
13 /*
14  * -----
15  *
16  * -----
17  */
18 Context ctxPivot ip [ host="192.168.43.209" port=8030 ] -standalone
19 Context ctxagent2 ip [ host="192.168.43.229" port=8050 ] -g green
20 EventHandler evh for alarm -print ;
21
22 QActor pivot context ctxPivot {
23     Plan init normal
24         println("pivot place holder ")
25 }
26
27 QActor agent2 context ctxagent2 {
28     Plan init normal
29         println(agent2(batman, starts)) ;
30         switchToPlan register ;
31         switchToPlan interact ;
32         println(agent2(ends))
33     Plan register resumeLastPlan
34         println(agent2(batman, register)) ;
35         demand pivot -m register : actorname(batman,agent2) ;
36         receiveMsg time(300000) ;
37         onMsg answer : answer(R) -> println( R )
38     Plan interact resumeLastPlan
39         println( agent2(batman, waits) ) ;
40         receiveMsg time(300000) ;
41         printCurrentMessage ;
42         repeatPlan 1
43 }

```

Listing 1.7. agent2.qa

Of course, `agent2` must run before `agent1` since `agent1` must find it already registered in the system.

4 The pivot

Let us introduce now a possible model for the `pivot` :

```

1 System pivot -regeneratesrc
2 /*
3  * =====
4  * pivot.qa in project it.unibo.actor.dynamic.pivot
5  * =====
6  */
7 Event alarm : alarm(X)
8
9 Request register : actorname( NICKNAME, NAME )

```

```

10 Request getactor : nickname( NAME )
11 Dispatch answer : answer( X )
12 Dispatch info : info( X )
13 /*
14  * -----
15  *
16  * -----
17  */
18 Context ctxPivot ip [ host="192.168.137.2" port=8088 ]
19 EventHandler evh for alarm -print ;
20
21 QActor pivot context ctxPivot {
22   Plan init normal
23     solve consult("./pivotTheory.pl") time(0) onFailSwitchTo prologFailure ;
24     switchToPlan acceptRequest
25   Plan acceptRequest
26     println( pivot(waits) ) ;
27     receiveMsg time(300000) ; //tout=5 min
28     memoCurrentMessage ;
29   //
30     printCurrentMessage ;
31     onMsg register : actorname( _,_ ) -> switchToPlan register ;
32     onMsg getactor : nickname( _ ) -> switchToPlan getactor ;
33     repeatPlan 0
34   Plan register resumeLastPlan
35     [ ?? msg( register, MSGTYPE, SENDER, RECEIVER, actorname(NICKNAME, NAME), SEQNUM ) ]
36     solve register(NICKNAME, NAME, RESULT) time(0) onFailSwitchTo prologFailure ;
37     [ !? goalResult(register(NICKNAME,NAME,RESULT))] replyToCaller -m answer:answer(RESULT)
38   Plan getactor resumeLastPlan
39     [ ?? msg( getactor, MSGTYPE, SENDER, RECEIVER, nickname(NICKNAME), SEQNUM ) ]
40     solve getactor(NICKNAME, RESULT) time(0) onFailSwitchTo prologFailure ;
41     [ !? goalResult(getactor(NICKNAME,NAME))] replyToCaller -m answer:answer(NAME)
42   Plan prologFailure resumeLastPlan
43     println("pivot has failed to solve a Prolog goal" )
44 }

```

Listing 1.8. pivot.qa

4.1 The pivot application theory

Several operations of the pivot actor are implemented as tuProlog rules by means of the user-defined *pivotTheory*:

```

1  /*
2  =====
3  pivotTheory.pl
4  =====
5  */
6  register( NICKNAME , NAME, alreadyRegistered(NICKNAME) ):-
7    retract( registered(NICKNAME,_) ),!.
8  register( NICKNAME, NAME, doneRegistered(NICKNAME,NAME) ):-
9    actorPrintln( registered(NICKNAME,NAME) ),
10    assert( registered(NICKNAME,NAME) ).
11
12
13  getactor(NICKNAME, NAME):-
14    registered(NICKNAME,NAME),
15    actorPrintln( getactor(NICKNAME,NAME) ),
16    !.
17  getactor(NICKNAME,null).
18
19  /*
20  -----
21  initialize
22  -----
23  */
24  initialize :-
25    actorPrintln("pivotTheory started ...") .

```

```
26  
27 :- initialization(initialize).
```

Listing 1.9. pivotTheory.pl

4.2 The pivot at start-up

```
----- Startup -----  
sudo crontab -u root -e  
  
@reboot cd /home/pi/nat/pivot && screen sh -c './pivot.sh ; read'  
  
#!/bin/bash  
echo hello pivot  
sudo java -jar MainCtxPivot.jar  
exec bash
```