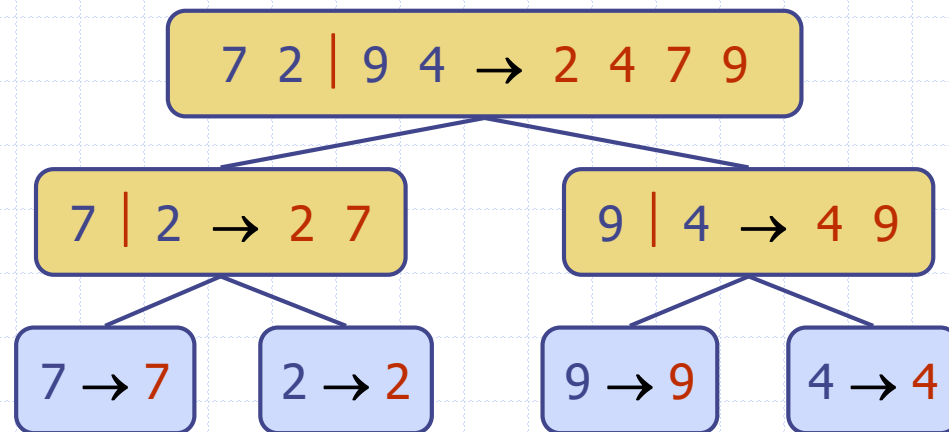


# Merge Sort



# Divide-and-Conquer (§ 10.1.1)

化整為零  
各個擊破

- ◆ **Divide-and-conquer** (分治演算法) is a general algorithm design paradigm:
  - **Divide**: divide the input data  $S$  in two disjoint subsets  $S_1$  and  $S_2$
  - **Conquer**: solve the subproblems associated with  $S_1$  and  $S_2$
  - **Combine**: combine the solutions for  $S_1$  and  $S_2$  into a solution for  $S$

- ◆ **Merge-sort**: A sorting algorithm based on divide and conquer

- ◆ Like heap-sort

- It uses a **comparator**
- It has  $O(n \log n)$  running time

Some don't!

- ◆ Unlike heap-sort

- It does not use an auxiliary **priority queue**
- It accesses data in a sequential/**local manner** (suitable to sort **data on a disk**)

Good for **external sorting**

# Merge Sort

## ◆ Merge sort

- A divide-and-conquer algorithm
- Invented by John von Neumann in 1945



約翰·馮·紐曼（John von Neumann，1903年12月28日－1957年2月8日），出生於匈牙利的美國籍猶太人數學家，現代電腦創始人之一。他在電腦科學、經濟、物理學中的量子力學及幾乎所有數學領域都作過重大貢獻，被譽為「電腦之父」。(圖及說明摘自[維基百科](#))

# Merge-Sort (§ 10.1)

- ◆ Three steps of merge-sort on an input sequence  $S$  with  $n$  elements:
- **Divide**: partition  $S$  into two sequences  $S_1$  and  $S_2$  of about  $n/2$  elements each
  - **Conquer**: recursively sort  $S_1$  and  $S_2$
  - **Combine**: merge  $S_1$  and  $S_2$  into a sorted sequence

Key  
step!

**Algorithm** *mergeSort*( $S, C$ )

**Input** sequence  $S$  with  $n$  elements, comparator  $C$

**Output** sequence  $S$  sorted according to  $C$

**if**  $S.size() > 1$

$(S_1, S_2) \leftarrow \text{partition}(S, n/2)$

*mergeSort*( $S_1, C$ )

*mergeSort*( $S_2, C$ )

$S \leftarrow \text{merge}(S_1, S_2)$

# Merging Two Sorted Sequences

- ◆ Merging two sorted sequences (implemented as linked lists) with  $n/2$  elements each, takes  $O(n)$  time.

**Algorithm** *merge*( $A, B$ )

**Input** sequences  $A$  and  $B$  with  $n/2$  elements each

**Output** sorted sequence of  $A \cup B$

$S \leftarrow$  empty sequence

**while**  $\neg A.empty() \wedge \neg B.empty()$

**if**  $A.front() < B.front()$

$S.addBack(A.front()); A.eraseFront();$

**else**

$S.addBack(B.front()); B.eraseFront();$

**while**  $\neg A.empty()$

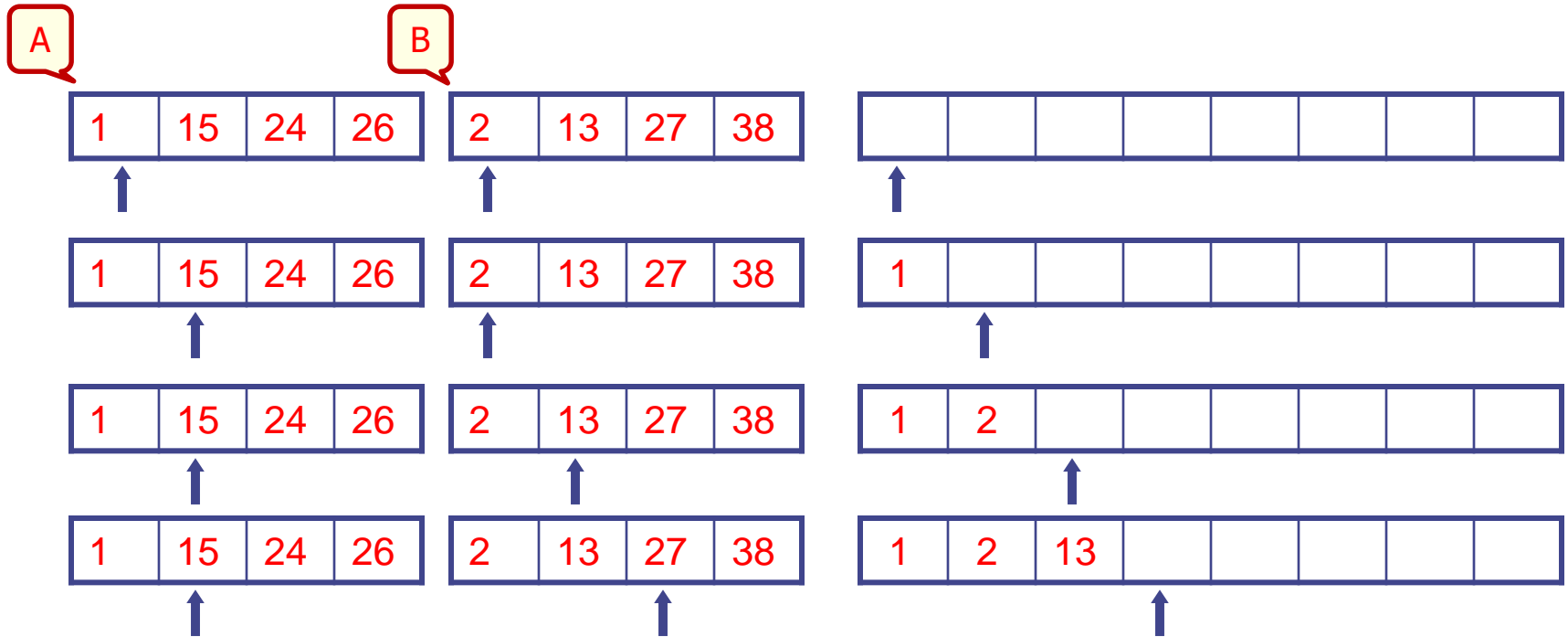
$S.addBack(A.front()); A.eraseFront();$

**while**  $\neg B.empty()$

$S.addBack(B.front()); B.eraseFront();$

**return**  $S$

# To Merge 2 Sorted Sequences



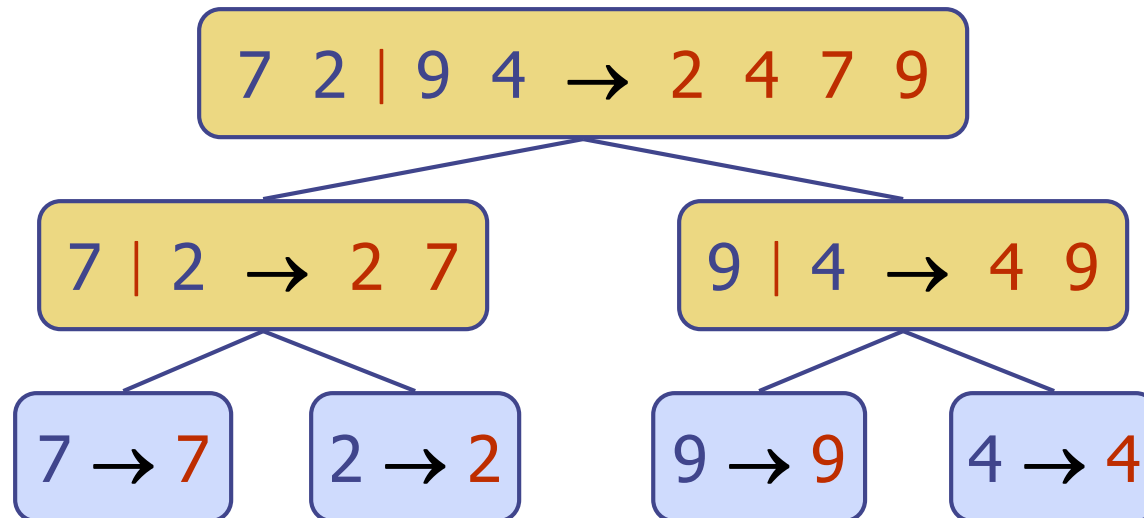
## ◆ Properties

- Need extra space to store the sorted results → Not an in-place sort
- Total time =  $O(|A| + |B|) = O(m+n)$

Also good for  
singly linked lists

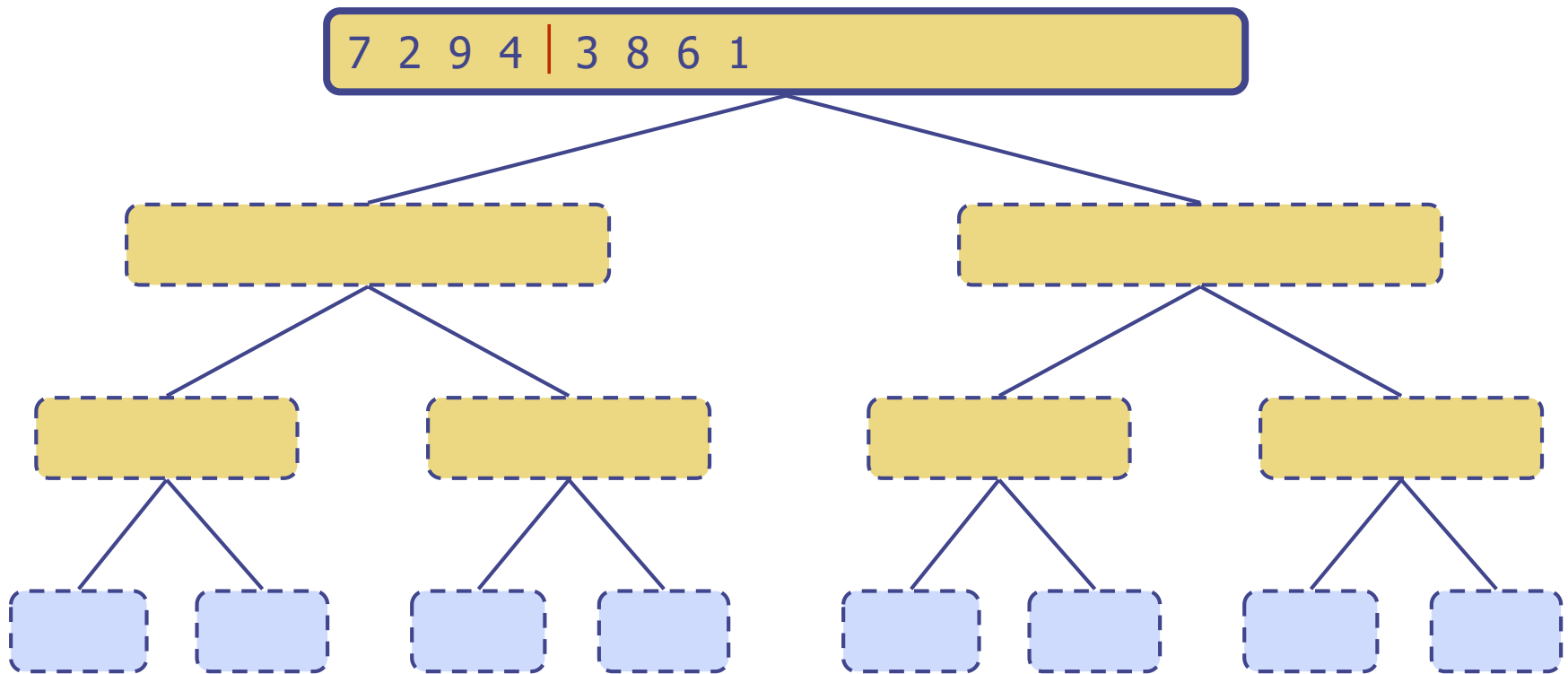
# Merge-Sort Tree

- ◆ An execution of merge-sort is depicted by a **binary tree**
  - each node represents a recursive call of merge-sort and stores
    - ◆ unsorted sequence before the execution and its partition
    - ◆ sorted sequence at the end of the execution
  - the root is the initial call
  - the leaves are calls on subsequences of size 0 or 1



# Execution Example

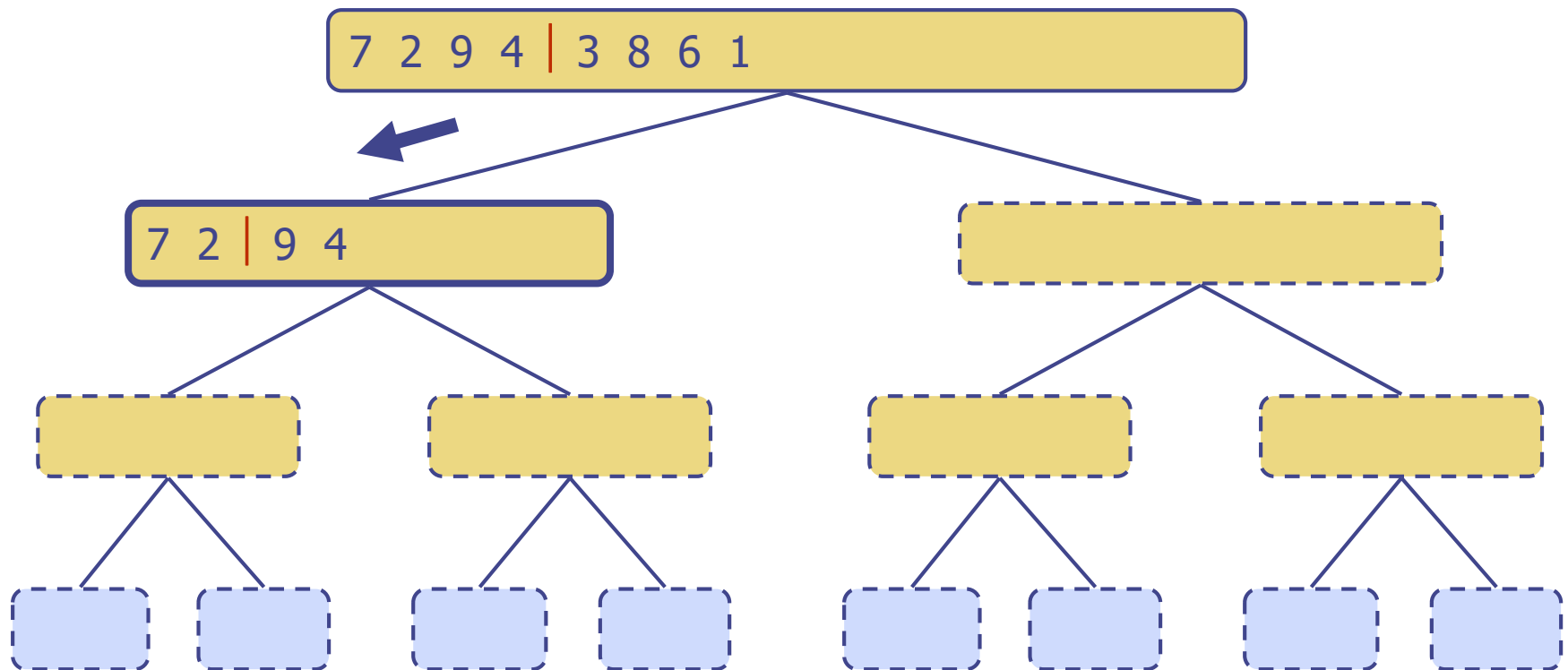
## ◆ Partition





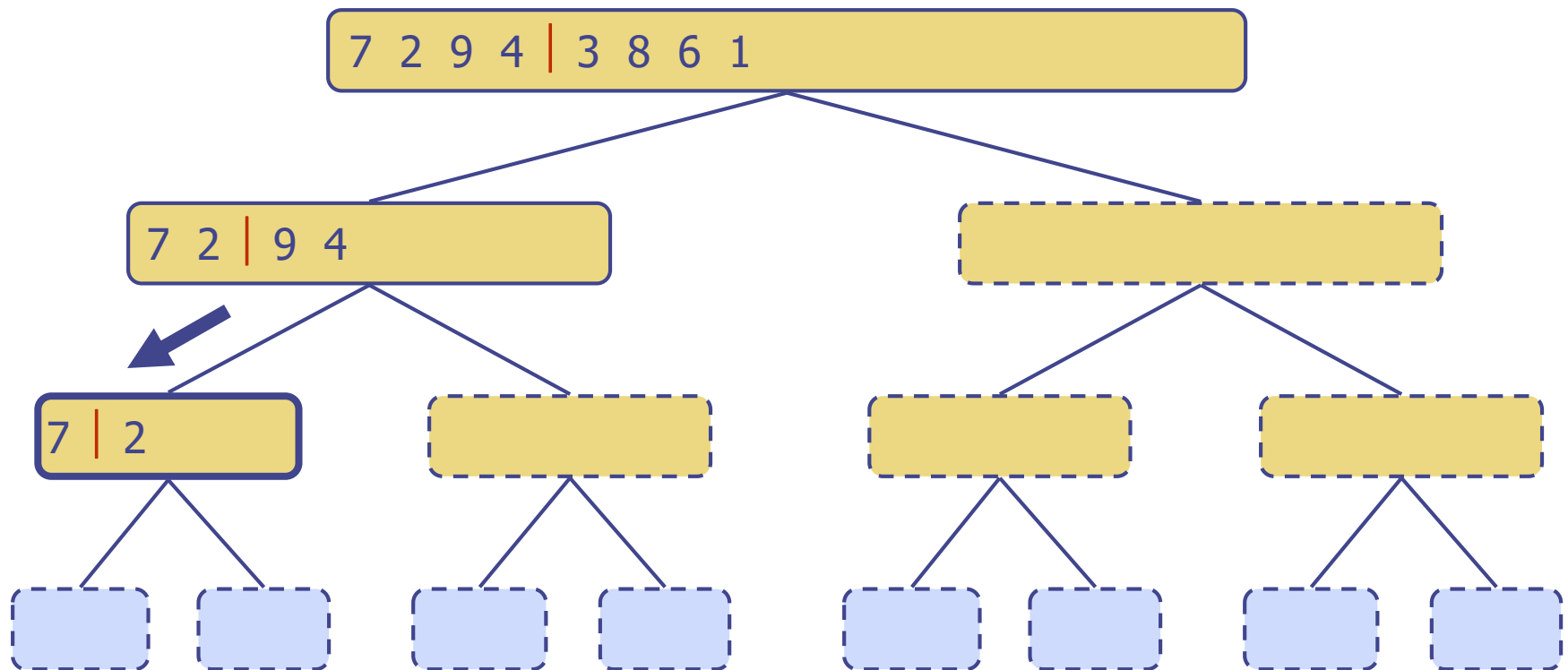
# Execution Example (cont.)

◆ Recursive call, partition



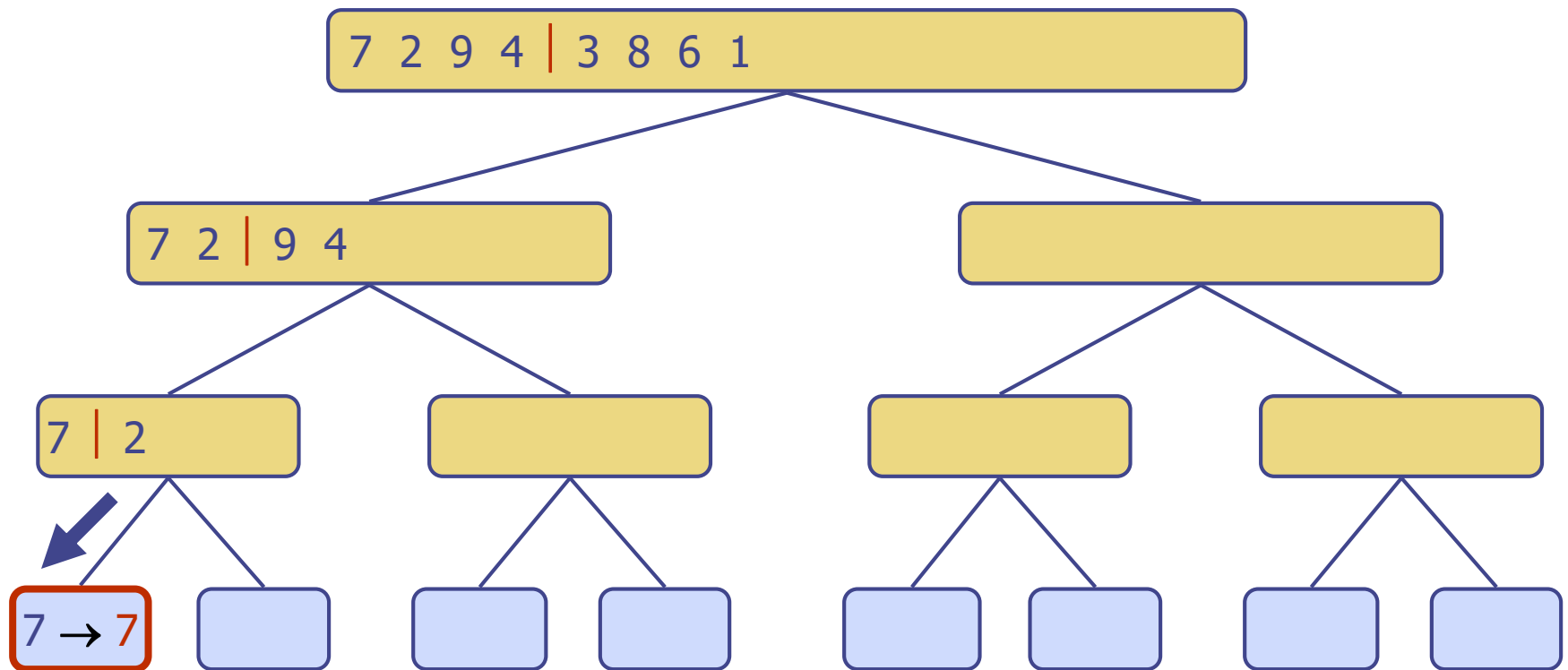
# Execution Example (cont.)

◆ Recursive call, partition



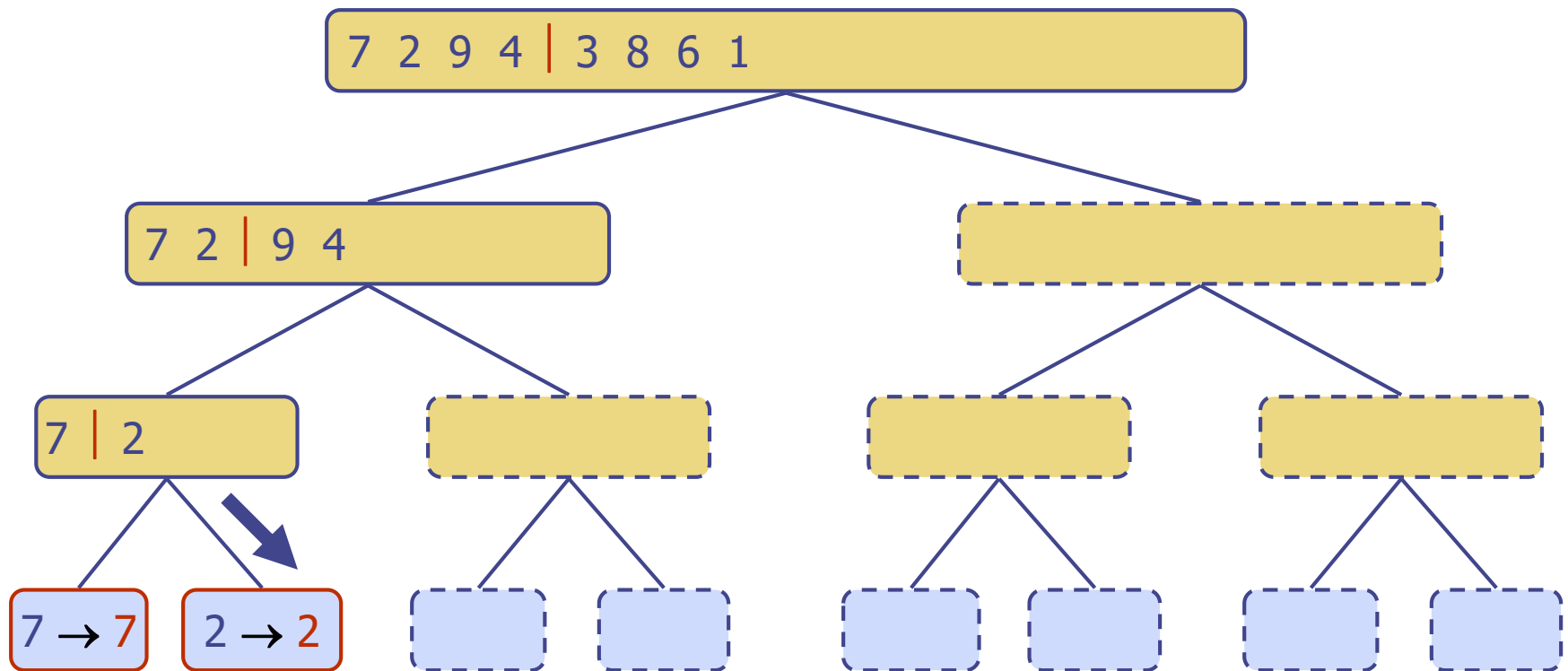
# Execution Example (cont.)

◆ Recursive call, base case



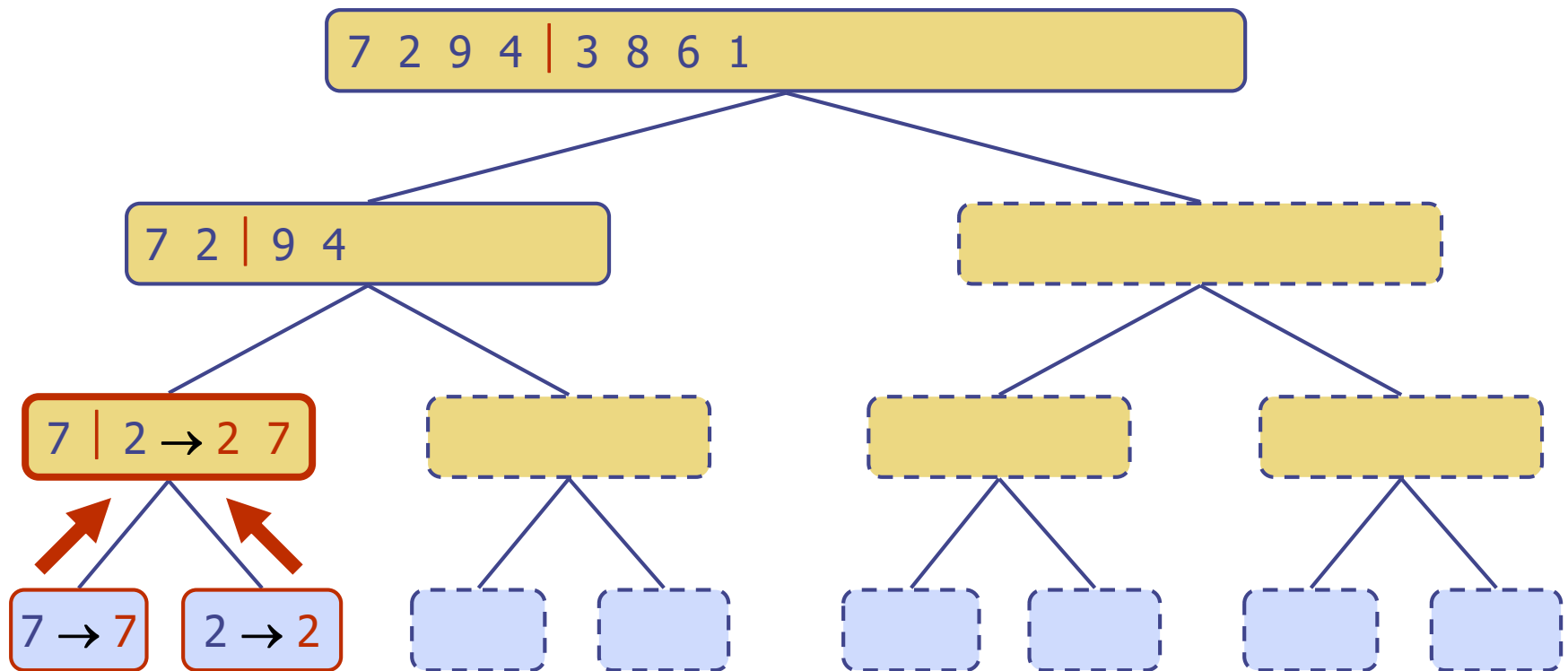
# Execution Example (cont.)

◆ Recursive call, base case



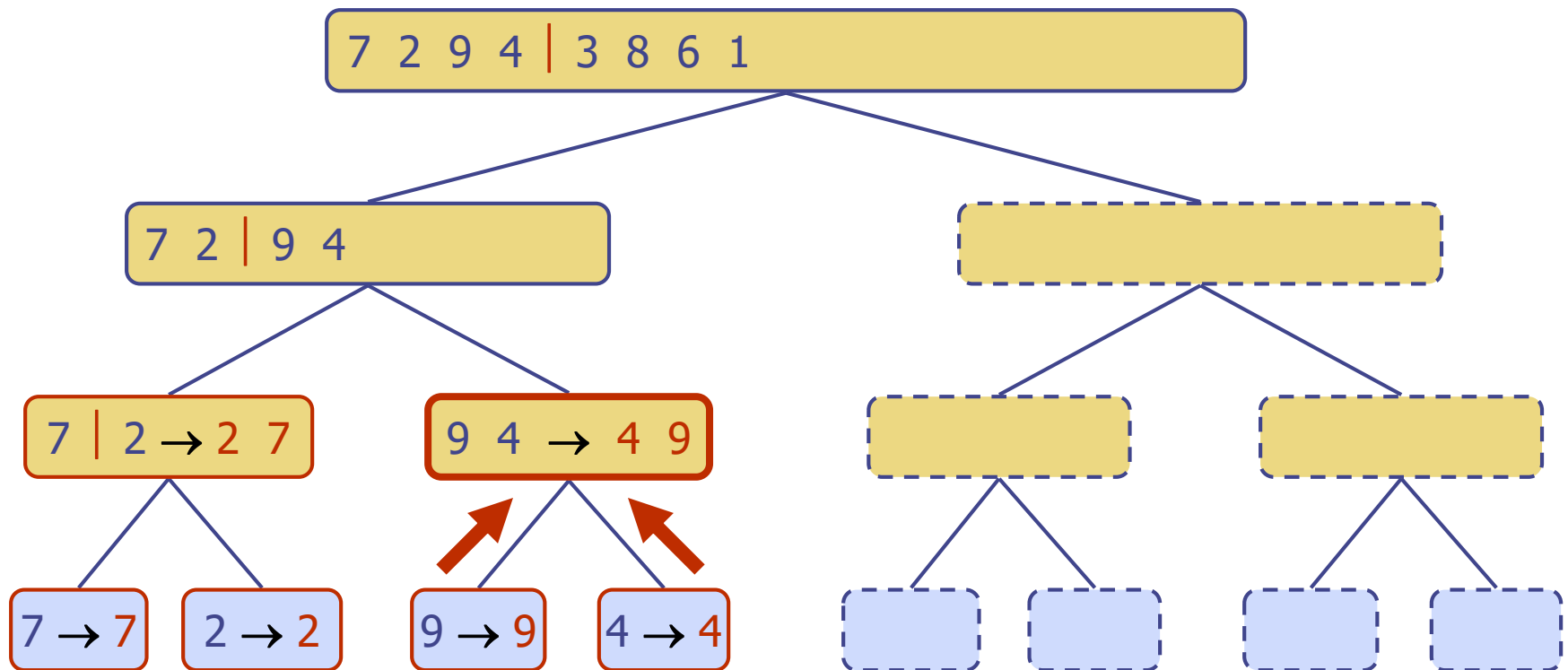
# Execution Example (cont.)

## ◆ Merge



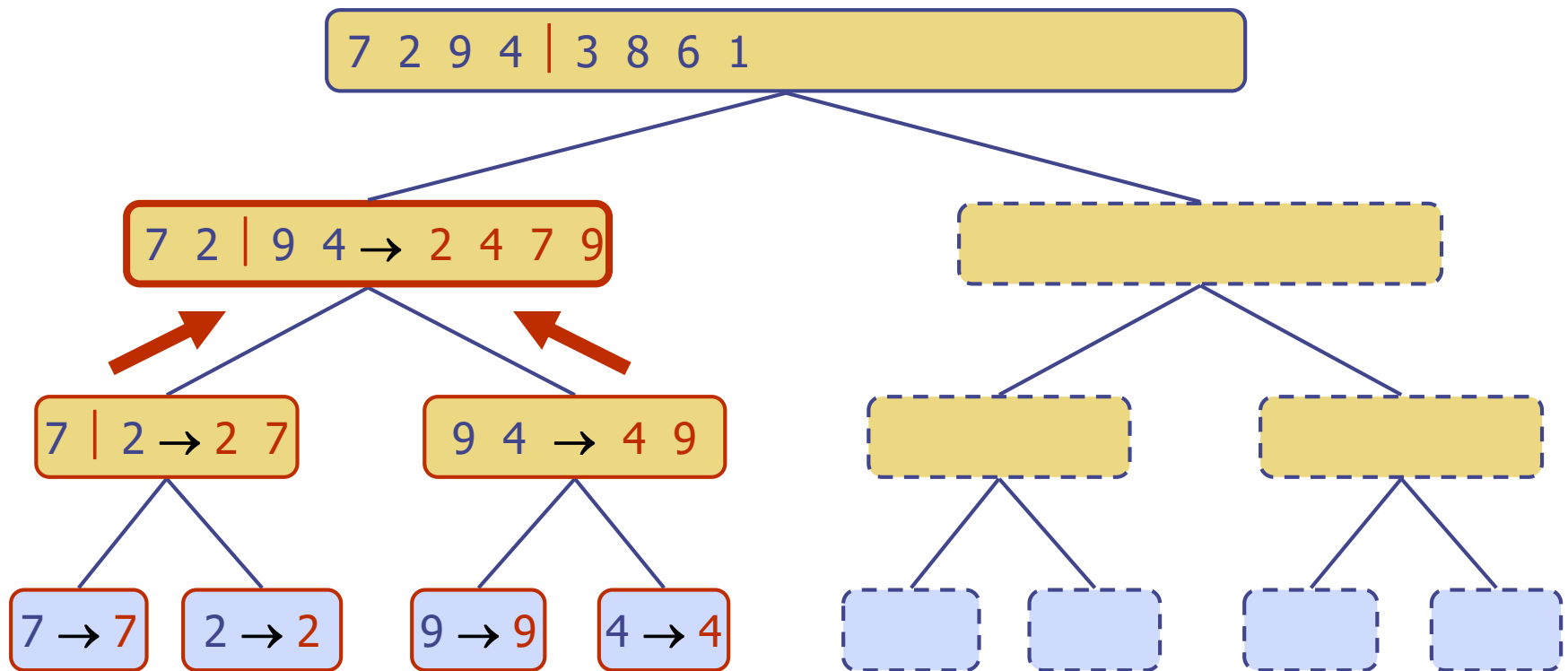
# Execution Example (cont.)

◆ Recursive call, ..., base case, merge



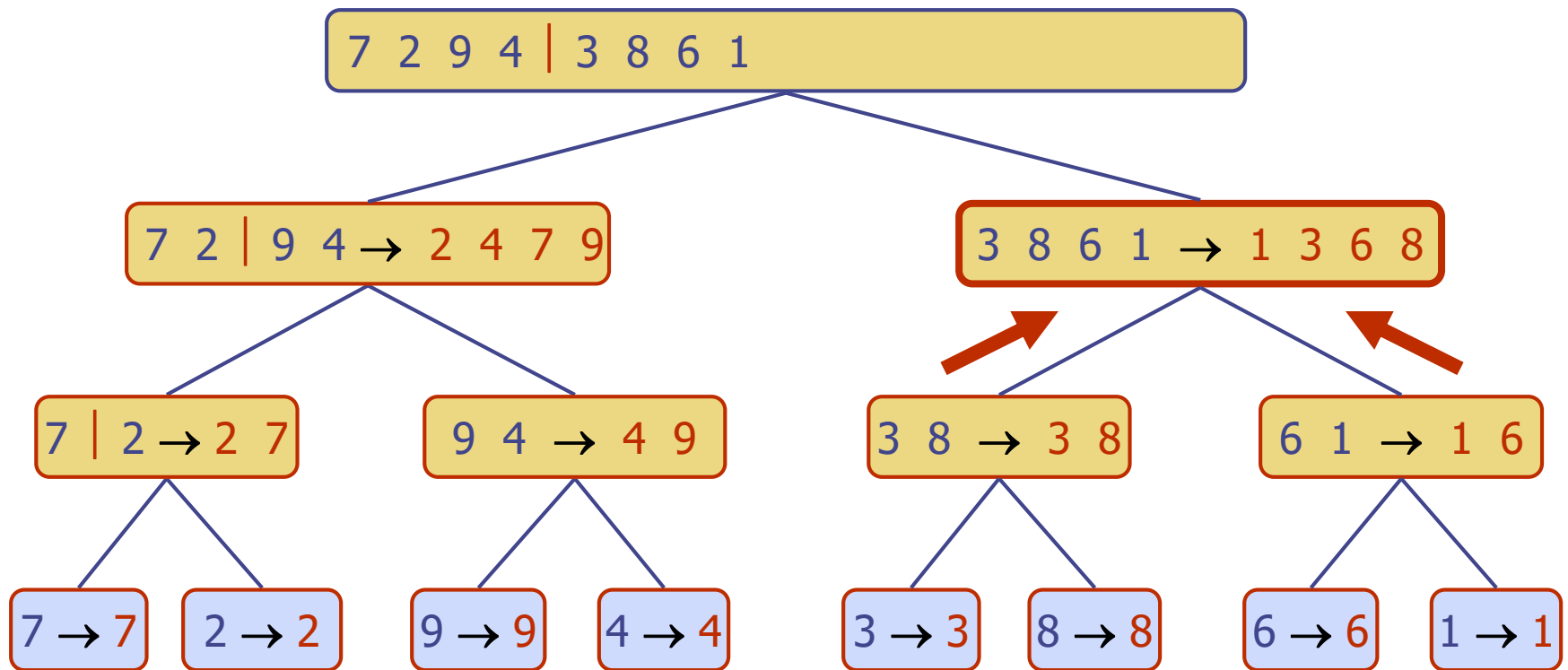
# Execution Example (cont.)

## ◆ Merge



# Execution Example (cont.)

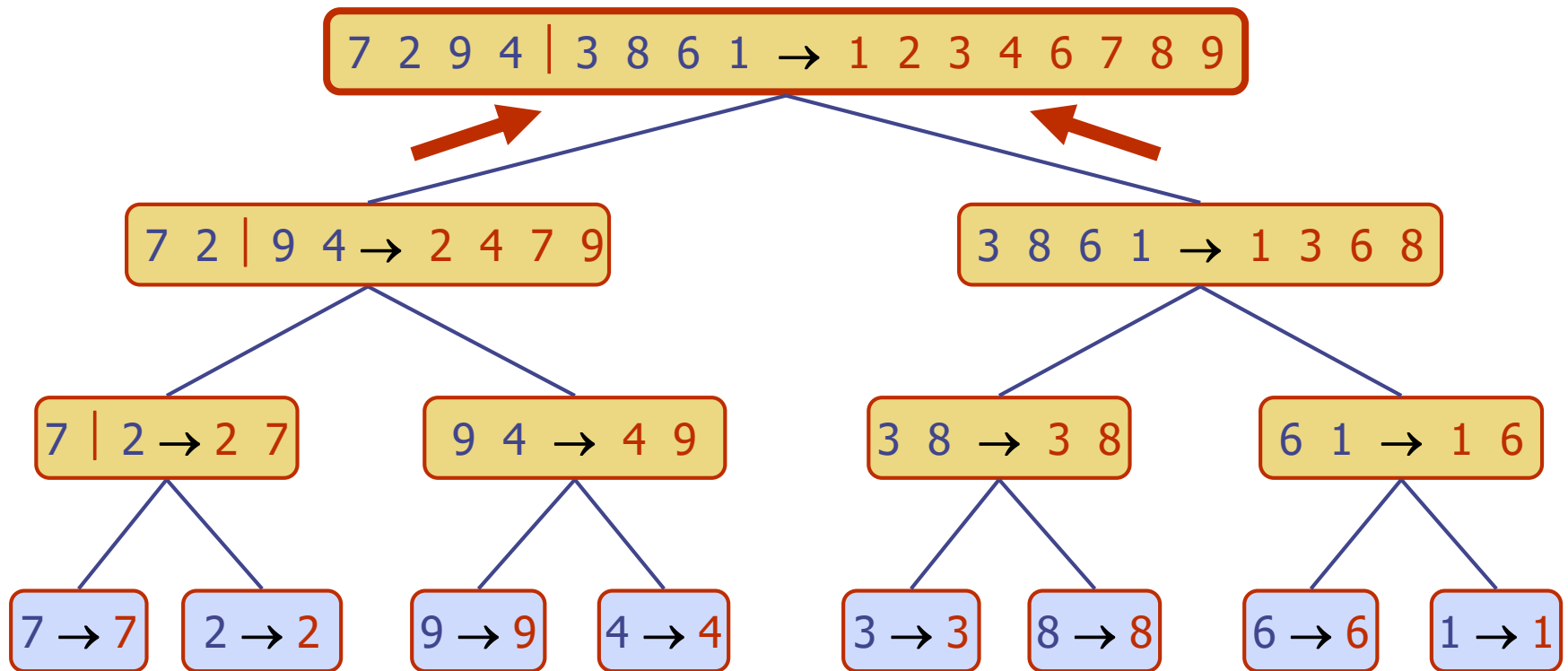
◆ Recursive call, ..., merge, merge



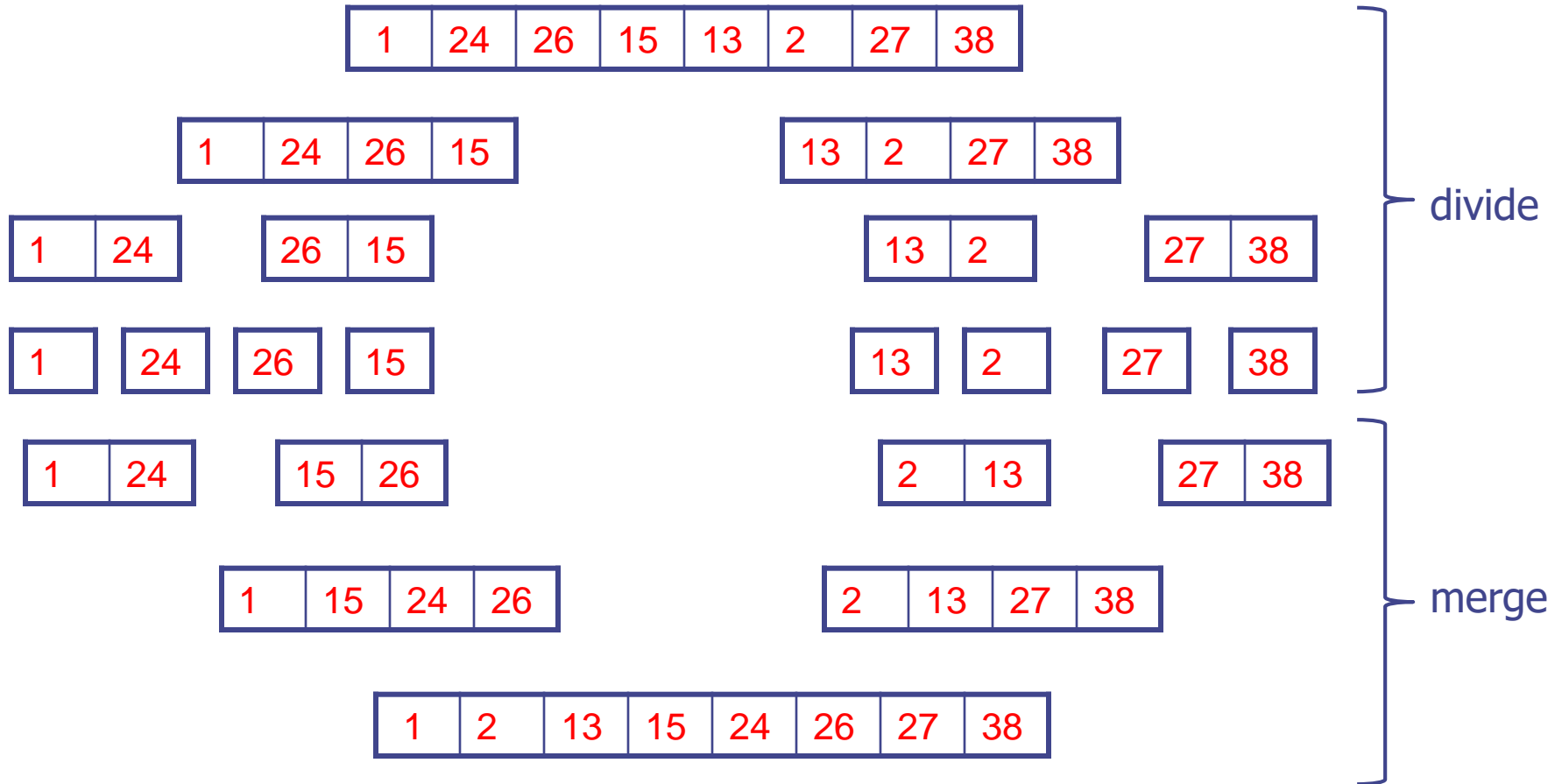


# Execution Example (cont.)

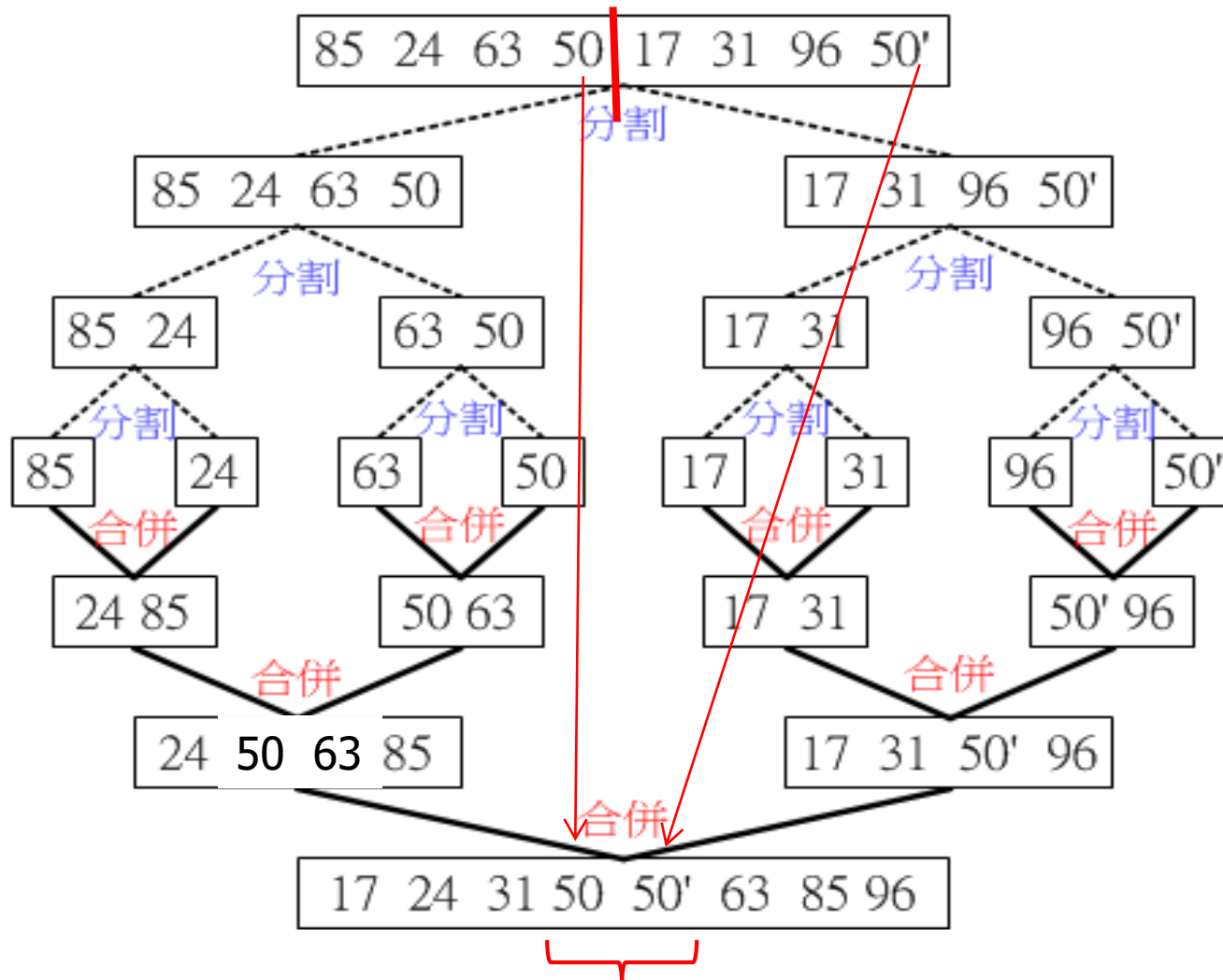
## ◆ Merge



# Merge Sort: Example



# Why Merge Sort Is Stable?



Same relative positions after merging!

# Resources on Merge Sort

## ◆ Numerous resources on merge sort

### ■ Wiki

- ◆ Animation by sorting a vector
- ◆ Animation by dots

### ■ Youtube

- ◆ Detailed explanation with pseudo code

# Analysis of Merge-Sort

- ◆ The height  $h$  of the merge-sort tree is  $O(\log n)$ 
  - at each recursive call we divide in half the sequence,
- ◆ The overall amount of work done at the nodes of depth  $i$  is  $O(n)$ 
  - we partition and merge  $2^i$  sequences of size  $n/2^i$
  - we make  $2^{i+1}$  recursive calls
- ◆ Thus, the total running time of merge-sort is  $O(n \log n)$

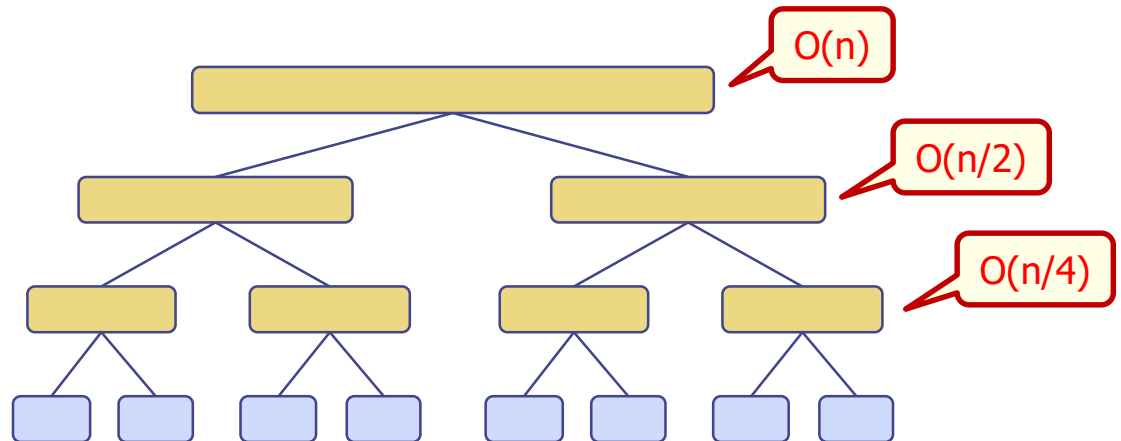
depth #seqs size

0 1  $n$

1 2  $n/2$

2 4  $n/4$

... ... ...



# Summary of Sorting Algorithms

Algorithms	Time	Notes
selection-sort	$O(n^2)$	<ul style="list-style-type: none"> <li>slow</li> <li>in-place</li> <li>for small data sets (&lt; 1K)</li> </ul>
insertion-sort	$O(n^2)$	<ul style="list-style-type: none"> <li>slow</li> <li>in-place</li> <li>for small data sets (&lt; 1K)</li> </ul>
heap-sort	$O(n \log n)$	<ul style="list-style-type: none"> <li>fast</li> <li>in-place</li> <li>for large data sets (1K — 1M)</li> </ul>
merge-sort	$O(n \log n)$	<ul style="list-style-type: none"> <li>fast</li> <li>Not in-place</li> <li>sequential data access</li> <li>for huge data sets (&gt; 1M)</li> </ul>