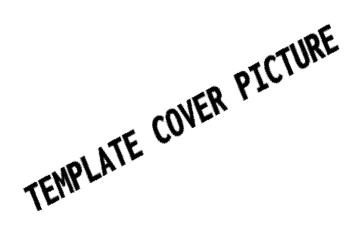
# Glossary



#### INSTITUTO SUPERIOR DE ENGENHARIA DE LISBOA

### Área Departamental de Engenharia de Electrónica e Telecomunicações e de Computadores



## **Electric Vehicle X Driving Range Prediction – EV X DRP**

### David Alexandre Sousa Gomes Albuquerque

(Grau do candidato)

[Dissertação | Projecto Final] para obtenção do Grau de Mestre em Engenharia Informática e de Computadores

Orientadores: Professor adjunto David Pereira Coutinho

Professor adjunto Artur Jorge Ferreira

Júri:

Presidente: [Grau e Nome do presidente do juri]

Vogais: [Grau e Nome do primeiro vogal]

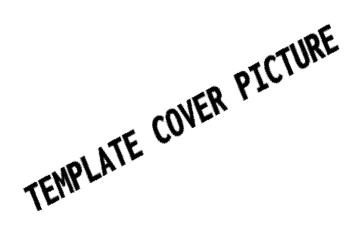
[Grau e Nome do segundo vogal]

Janeiro, 2022



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Aos meus ...

# Acknowledgments

TODO: acknowledgements

## **Abstract**

The increase of electric vehicle (EV) use as a reliable and eco-friendly means of transportation has increased rapidally over the past few years. When choosing an EV, the vehicle's performance is a decisive factor to be taken into account. An EV's driving range prediction depends on multiple factors that must be factored in to accurately infer results. Previous work has covered a history-based method on an adaptive model for EV's driving range prediction. The present project explores the implementation of a machine learning based model to learn from existing data, adapting with changes and aiming to provide more real and accurate results.

Keywords: electric vehicle; range prediction; energy consumption; machine learning

## Resumo

TODO: resumo em português

#### Palavras-chave:

TODO: Palavras-chave do resumo em português

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## **List of Tables**

## Acronyms

**EVs** Electric Vehicles. 1

**SOC** state of charge. 1

# Glossary

**eRange** electric range. 1, 2

**machine learning** a branch of AI focused on learning from data. 2

## Introduction

#### Electric vehicles are the future

On today's day and age, the global concern on climate change has been a major focus on recent international agreements, such as the Paris Agreement [3], incentivating many car manufacturers to introduce Electric Vehicles (EVs) as the eco-friendly solution for sustainable transport for the future.

As EVs have been increasing in popularity in recent years , car manufacturers have citar increased competitiveness on vehicle's performance, a decisive factor for consumers [2].

A vehicle's autonomy alson knwon as eRange, can be estimated through many driving data parameters, such as vehicle design, driver's behavior, wheather, road inclination and most importantly, an accurate state of charge (SOC) estimation.

The eRange accuracy allows consumers to rely on its vehicle for longer travel time and efficient charging plans , eRange estimation however, is a complex problem whitch has prompted previous studies in the past to provide a solution [1, 4].

Prior work [1] on eRange estimation demonstrated that using an history-based algorithm on am adaptive model provides a more reliable eRange prediction than a basic SOC - manufacturer data relation, this is mainly due to taking into account the vehicle's driving history.

#### TODO: Mensionar IA na atualidade

#### 1. Introduction

This project approaches the eRange estimation problem with the use of machine learning based model to increase its accuracy.

TODO: Falar da project structure

## References

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