

Tracing the Development of a Haptically-enhanced Science Simulation for Teaching Phase Change

James Minogue, PhD, Associate Professor, Elementary Education, NCSU (PI) David Borland, PhD, Senior Visualization Researcher, RENCI, UNCCH (Co-PI) Marc Russo, M.A.D., Assistant Professor of Art & Design, NCSU (Co-PI) Shengyen Tony Chen., PhD student, Computer Science, NCSU

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Abstract: This poster traces the research-design-develop-test cycle of a haptically-enhanced science simulation designed to teach upper-elementary/primary students core ideas about matter, phase change, and the role of intermolecular forces.

Project Goals

- Integrate Unity® & the Novint Falcon® force-feedback device
- Reach beyond typical teaching methods to provide opportunities to learn about underlying invisible (micro) scale mechanisms.
- Pinpoint the cognitive influence of haptic force-feedback w/a framework that assesses learners' agility moving between macroscale & microscale representations, along with their mechanistic thinking.

Our Approach

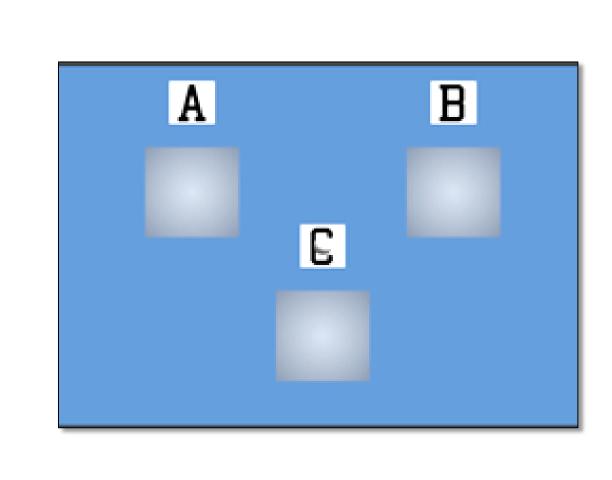
- *Informant design approach* (children, expert STEM teachers, & content experts).
- Development cycle includes *focus groups* (children & teacher feedback on low-tech versions of simulations & assessments, *usability testing* (task performance, user behaviors, & user preference), & *small scale classroom pilot testing* with 8-11 year old students.
- We designed, built, & tested a **Phase Change** & **Intermolecular Forces** haptically-enhanced simulation

Fall Student Focus Group

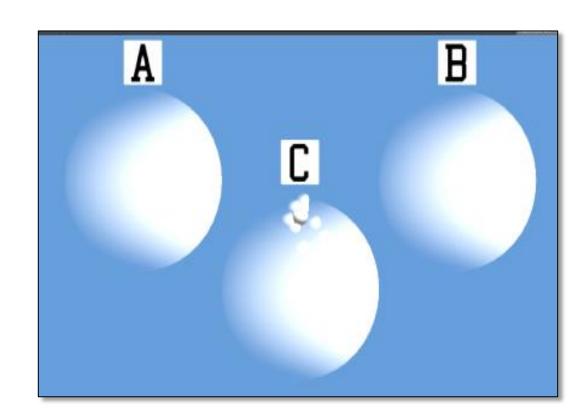
- Interviewed 12 (9-10 year olds); modified *Children's***Beliefs about Matter Interview protocol (Nakhleh & Samarapungavan, 1999)...see hand-out.
- None of the students exhibited a *macrocontinuous* view (i.e. materials cannot be broken down).
- 75% had *macroparticulate* views (i.e. made of little pieces/parts); 25% *microparticulate* (molecular view of matter)
- The bulk offered *macroprocess* explanations of *why ice melts*...recognized that temperature was part (the entity) but not the mechanism (activity)..."*if water gets cold it freezes*"; "*if ice gets warm it melts*".
- Only 2 two gave any signals of *microprocess* thinking (i.e. a molecular view of the process).
- Recognition of any sort of molecular forces at work was non-existent (Erickson & Tiberghien, 1985; Osborne& Cosgrove, 1983; Smith et al., 2006; Wiser & Carey, 1983).

Spring Focus Group

- Involved 9 (9-10 year olds); tested our **core haptic interactions** with objects that modeled *macroscopic physical properties* (viscosity & hardness/compliance) & *microscopic forces* (intermolecular and vibratory).
- **Hardness** was easier to discern; 67% correctly matched the steel, 89% correctly identified the dough & rubber; 75% correctly matched all 3 solid models with their real-world substance.
- **Viscosity** was not as accurate; 33% correctly matched the peanut butter, 44% matched the honey, & 67% recognized the oil; only 33% correctly matched all 3 liquid models with their real-world targets.
- **Phase recognition at the microscal**e...56% correctly matched all three models with its phase; 44% got only the solid correct, confusing liquid & gas.

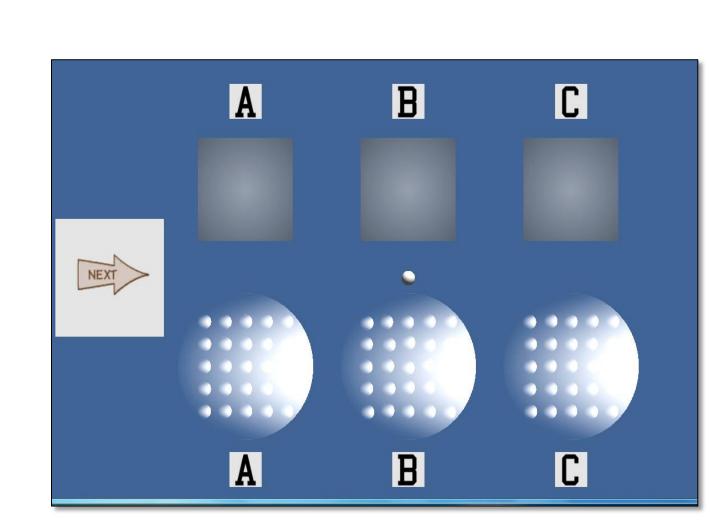






Usability Testing

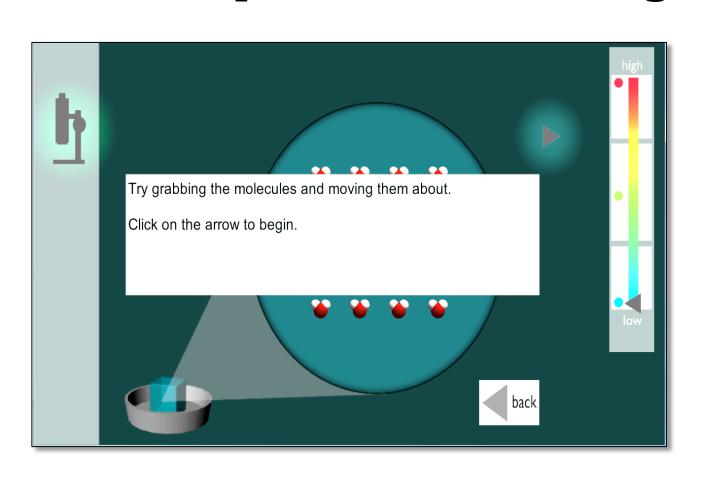
- 8 (9-10 year olds) tried out a set of more refined core haptic interactions; modeled hardness & viscosity at the *macroscale* & *microscale*.
- We were interested in users' agility moving between the two scales...feel the models & match the two different levels of representation.
- 62.5% correctly matched all three solid models; 50% matched all three viscosity models.
- In all but one case, if they got all of the solid blocks correct they also got all of the liquid spheres correct.
- Technical issues (unwanted device vibration & excessive solid surface deformation) emerged.

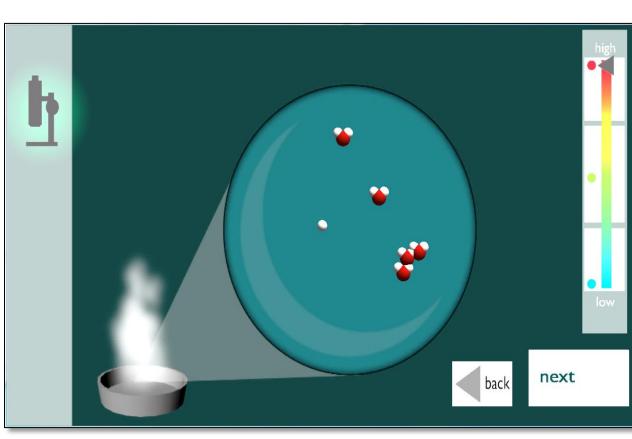




Pilot Testing the Simulation

- Convenience sample (32,10-11 year olds; 18, 8-9 year olds)
- Pretest-posttest control group design (haptic vs. no haptic)

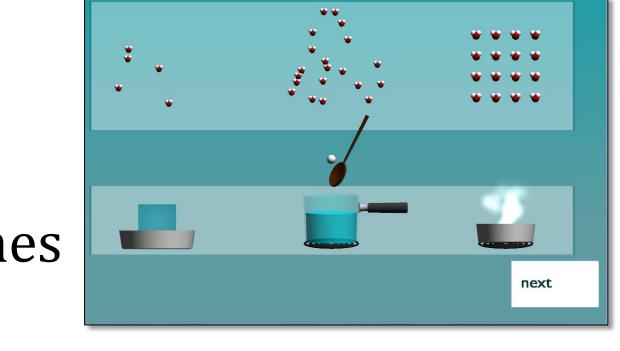


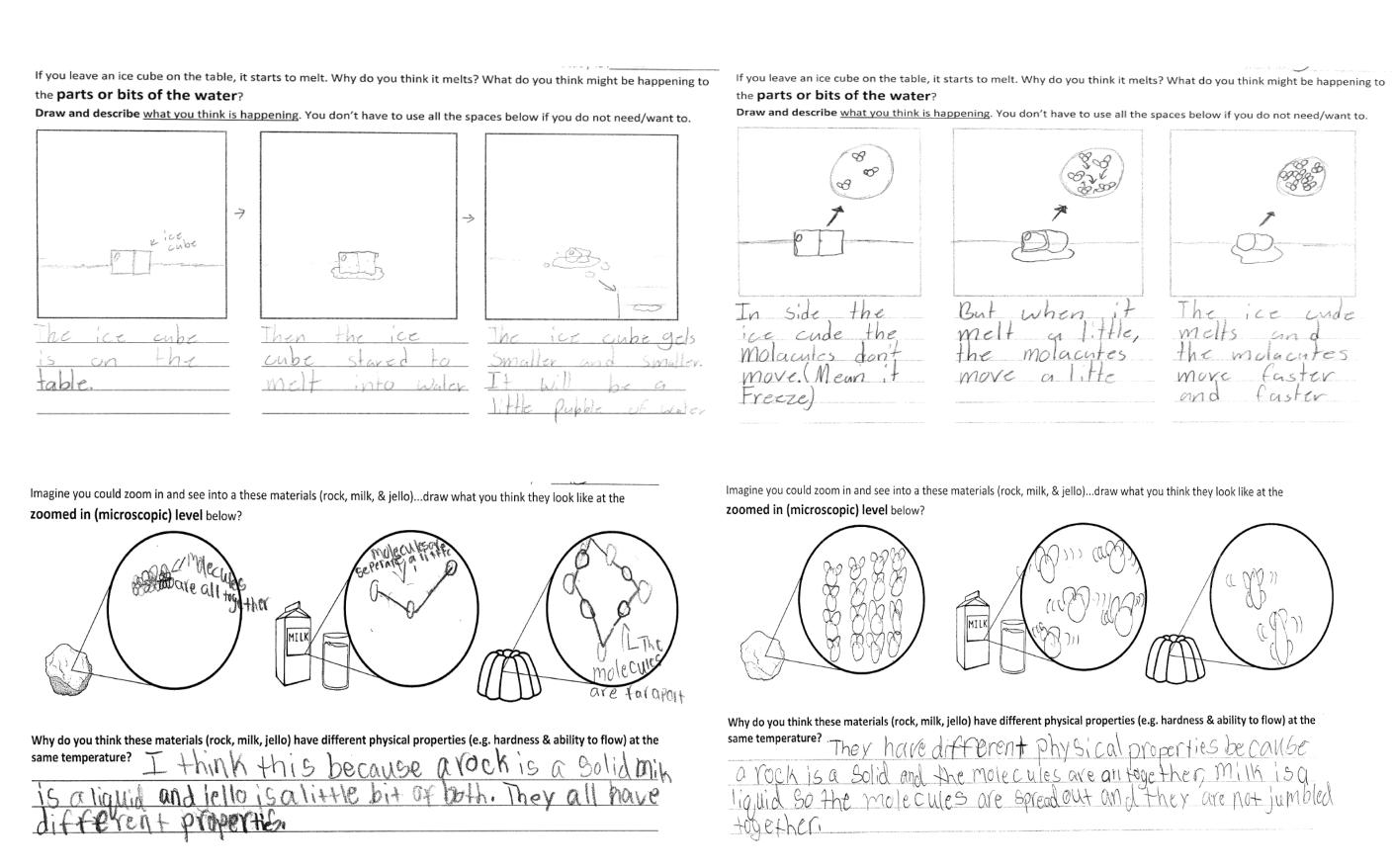


Assessments

• Open-ended Drawing & Explanation Tasks... *Ice Melting* & *Physical Properties*

- Interactive Assessment
- Fraps- User Interactions
- See handout with Scoring Schemes





Technical Work (see handout)

- Developed a Unity[®] plugin for the Novint Falcon[®] device that provides a high-level wrapper interface to Novint's [®] Haptic Device Abstraction Layer (HDAL) library.
- Enabled our simulation with various features including: microscopic forces, solid & deformable surfaces, viscosity, & a non-haptic mode.

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